



**SMARTSCAN | NG<sup>2</sup>**

# Operator's Guide for BNSF

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Because products evolve and system configurations change, this manual may not be an exact representation of the products and systems that you are using.

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## **WARNING!**

Contact with electrically active parts could result in sparks, burns, and electric shock. Because of this, you should avoid all electrical hazards when installing, wiring, operating, and maintaining the SmartScanNG<sup>2</sup> system. Failure to do so could result in damage to the equipment or serious injury to you.

### **NOTICE:**

If equipped with an AEI subsystem, the user is required to obtain a Part 90 site license from the FCC to operate in the United States. See product label for FCC ID number. Access the FCC Web site at [www.fcc.gov/Forms/Form601/601.html](http://www.fcc.gov/Forms/Form601/601.html) for additional information concerning licensing requirements.

Users in all countries should check with the appropriate local authorities for licensing requirements.

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# 1.0 Introduction

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This section summarizes the purpose of this guide, describes the SmartScanNG<sup>2</sup> system, tells how to comment on this guide, and tells how to order more copies of this guide. It also covers the cautions and disclaimers of which the customer should be aware of.

## 1.1 Purpose of This Guide

The technical staff at Southern Technologies Corporation (STC) created the SmartScanNG<sup>2</sup> system. This guide describes that system.

The SmartScanNG<sup>2</sup> system monitors moving trains and reports certain conditions detected on these trains. Parts of the system, like the bearing scanners, are installed on the tracks. Other parts of the system, like the controller module, are installed near the tracks. Most nontrackside components are factory-installed inside a wayside enclosure (aka bungalow). Therefore, the installation of these already installed components isn't covered in this guide.

The SmartScanNG<sup>2</sup> system is modular and firmware-driven. Hardware and firmware can be changed to meet the unique needs of a given railroad. Thus, some of the components that make up a SmartScanNG<sup>2</sup> system differ from railroad to railroad.

This guide is for those who purchase, install, maintain, troubleshoot, manage, or use the SmartScanNG<sup>2</sup> system as configured for BNSF Railway.

## 1.2 SmartScanNG<sup>2</sup>

The SmartScanNG<sup>2</sup> system is a full-featured detection and reporting system. It monitors moving trains, providing real-time detection of:

- Overheated bearings
- Overheated wheels, when wheel scanners are installed and enabled
- Dragging equipment, when dragging-equipment detectors are installed and enabled
- Shifted loads, when wide-load detectors are installed and enabled
- Oversized loads, when high-load detectors are installed and enabled
- Automatic Equipment Identification (AEI) tags, when AEI hardware and firmware are installed and enabled
- Direction of the train
- Exit speed of the train

The SmartScanNG<sup>2</sup> system runs well in the harsh environments found along right of ways. It runs under the most adverse weather conditions, functioning over a temperature range of -40°F to +160°F (-40°C to +71°C). It runs in high-vibration situations. It runs unattended, carrying out all tasks without human intervention.

The SmartScanNG<sup>2</sup> system monitors trains traveling from 7 to 90 mph (11.3 to 145 kph). It monitors trains heading in either direction on the track.

When the SmartScanNG<sup>2</sup> system detects a defect, it informs the crew of the affected train. This is done by a voice transmission over an assigned radio channel. The voice is computer-generated from previously digitized human speech. It tells the crew the milepost of the reporting SmartScanNG<sup>2</sup> system, a warning that a defect has been detected, and other defect-related information. When no defect is detected, the voice tells the crew that the train was scanned and found free of defects.

There are three types of messages. Real-time messages are announced as the train is passing over the site. Post-train messages are announced after the train has left the site, and all the recorded train data has been processed by the SmartScanNG<sup>2</sup> system. When enabled, there are also arrival messages. Arrival messages are announced as the train enters the site. The content and use of these three message types are railroad-specific.

The results of train scans are also stored for later use. With this stored data, the system can create formatted reports. To get them at the site, you need a computer. With a modem and a computer, you can retrieve them remotely.

## 1.3 General Specifications - SmartScanNG<sup>2</sup>

<b>Maximum Train Length</b>	Successfully scanned computer-simulated trains with axle counts greater than 4000 axles.
<b>Input Voltage - DC</b>	Controller Module and Chassis: 10 to 30 VDC. Maximum system current, including two bearing scanners and two wheel scanners, with train present and radio transmitting approximately 11.7 amps. Idle current 900mA.
<b>Input Voltage - AC</b>	100 – 130 Volts @ 15 Amps, 50-60Hz
<b>Input Voltage Protection</b>	Circuit Breaker, Self-Restoring Fuses, Metal Oxide Varistors, Reverse Polarity Protected
<b>Processors</b>	Two Embedded Processor Modules, each with the following features: Motorola ColdFire® Processor, 32-bit, 250MHz clock (125MHz bus), 64MB DDR2 RAM, 32MB non-volatile Flash, 16GB Micro SD. Non-volatile time/date, system configuration, and train storage.
<b>Serial Communications Ports</b>	Up to six RS-232 ports available, depending on internal options, and one RS-485 port – all with standard male D-Sub 9 connectors.
<b>User Accessible Inputs</b>	2 Bearing Scanner, 2 Wheel Scanner, 2 Wheel Gating Transducer, 2 Wheel Advanced Transducer, 8 Opto-Isolated Digital, 1 Precision Ambient Temperature Probe, 1 Train Presence Detection - Internal 2-Wire Audio Overlay Track Circuit
<b>Network</b>	One 10/100 Mbps Ethernet port with a standard RJ45 connector for networking capabilities. One RJ45 connector for access to the optional internal Velocity Module.
<b>Voice Communications</b>	Internal VHF Radio Transceiver: Ritron DTX-160 – 8 channels, 6 watts, narrowband, 134MHz to 176MHz. Additionally equipped with a radio interface for customer-specified analog or NXDN™ digital mobile radio
<b>Dual-tone Multi-frequency Decoder</b>	DTMF decoder recognizes all standard digits – 0 through 9, #, *, A, B, C, D. (Reception of a customer-specified sequence of digits triggers a rebroadcast of the last voice announcement.)
<b>Secure Wireless</b>	The NG <sup>2</sup> supports wireless standards IEEE 802.11 b/g/n with 2.4GHz RF band power amplifier. Secure data communications with 128-bit WEP, WPA-PSK (TKIP), WPA2-PSK Authentication. Secure Wireless can be enabled/disabled from the keypad.
<b>Operating Temperature</b>	-40°C to +71°C, Fanless Operation, Industrial Temperature Range
<b>Size</b>	15.5"W x 22.0"H x 4.5"D
<b>Weight</b>	31 lbs.
<b>Finish</b>	White powder coat over stainless steel.
<b>Manufacturer</b>	Southern Technologies Corporation, Chattanooga, Tennessee

## 1.4 Cautions

Contact with electrically active parts could result in sparks, burns, and electric shock. Because of this, you should avoid all electrical hazards when installing, wiring, operating, and maintaining the SmartScanNG<sup>2</sup> system. Failure to do so could result in damage to the equipment or severe injury to you.

In operation, batteries generate and release flammable hydrogen gas, which, if ignited by a burning cigarette, naked flame, or spark, may cause a battery explosion with a dispersion of casing fragments and corrosive liquid electrolyte. So, carefully follow the manufacturer's instructions. Keep all sources of gas ignition away from the batteries and do not allow metallic articles to contact the negative and positive terminals of a battery at the same time.

## 1.5 Disclaimers

The correct use of this guide, the environmental conditions at the time of installation, the method of the installation itself, and the installation of customer-supplied components are beyond the control of STC. So too, are the correct use and maintenance of all or part of the SmartScanNG<sup>2</sup> system. Therefore, the installer, user, and maintainer must assume the risk of any injury that might occur during installation, use, and maintenance of all or part of the SmartScanNG<sup>2</sup> system. STC assumes no risk, liability, or responsibility for errors and omissions on the part of the installer, user, or maintainer.

## 1.6 How to Comment on This Guide

We want to hear from you. Tell us what you like or don't like about this guide. Send your comments to:

Southern Technologies Corporation  
Technical Publications Department  
6145 Preservation Drive  
Chattanooga, Tennessee 37416-3638  
USA

All comments become the sole property of STC, and none will be returned.

## 1.7 How to Order More Copies of This Guide

When placing an order for more copies of this guide, refer to the order number shown on the cover of this guide. To request pricing and delivery, call 423-892-3029, fax 423-499-0045, or send an email to [email@southern-tech.com](mailto:email@southern-tech.com). Electronic copies of this guide are also available.

## **1.8 Standard Warranty**

Systems manufactured by Southern Technologies Corporation carry a 14-month warranty from the date of shipment. Warranty is limited to repair or replacement at the sole discretion of STC, of any goods found to be defective in either materials or workmanship during the 14-month period following shipment. Warranty does not apply to a product with signs of blatant abuse, or product that has been improperly installed.

STC warrants that goods represented by this warranty statement have been designed and manufactured with all reasonable care and attention to appropriate regulatory documents. STC makes no representation that the goods covered by this warranty are suitable for the application they are used for. Application of the goods is at the sole discretion of the purchaser.

Purchaser is responsible for shipment of the defective product to STC. STC will pay the return shipping charges.

Products purchased from others but included in STC systems carry the original manufacturer's warranty, typically 12 months. Warranty claims for these products must be made directly to the original equipment manufacturer.



## 2.0 Defect Detection

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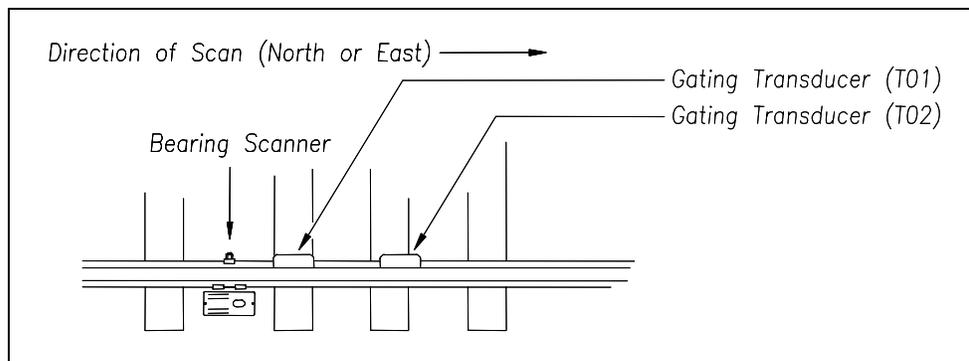
This section describes the Exception Alarms (aka defect alarms, aka train alarms) and how they are detected. Also covered are miscellaneous train scanning features.

### 2.1 System Activation

System activation is the process used to detect train presence and to prepare for train scanning. It is during the scanning process that the system checks for defects.

The SmartScanNG<sup>2</sup> system is equipped with one of two primary means of train arrival detection, which are the track circuit or advance transducers. In case of a failure in the primary detection method, the gating transducers act as a backup to detect train arrival. Once the system senses a train's presence, it enters scanning mode. In other words, the system has activated. It then opens the scanner's shutters and disables their heaters. It then waits for further evidence of a train at the site in the form of gating transducer activity.

Once the system is active, it reads pulses from the two rail-mounted gating transducers, which are designated TO1 and TO2. On the rail nearest the wayside enclosure, these transducers are mounted near and to the north or east of the bearing scanners. **TO1** is the gating transducer closest to the bearing scanner. **TO2** is the one farthest from the bearing scanner.



The signals from these gating transducers indicate to the system that passing wheels are in view of the scanners. Furthermore, the speed of the train is determined by using the known distance between TO1 and TO2 versus the time required for a given wheel to pass over them.

Four axles must pass over the gating transducers for the system to consider the event a valid train. This prevents maintenance equipment from generating alarms and causing unwanted voice messages on the road channel.

## 2.2 System Deactivation

System deactivation is the process used to detect the moment that the train exits the site. This happens in one of two ways, which is dependent upon whether the track circuit or one of the transducers has activated the system.

If the track circuit activated the system, the system waits for the track-circuit signal to be absent for ten seconds before deactivating. Likewise, if a transducer activated the system, the system waits for ten seconds of inactivity from the gating transducers before deactivating.

## 2.3 Speed Calculation

A train's minimum, maximum, average, and exit speeds in miles per hour are shown on the reports. The system calculates speed by knowing the distance between the two transducers versus the time that it takes a given wheel to pass over them. Calculated speeds over 99 mph (159 kph) are reported as 99 mph. If a train has fewer than eight axles, its speed is reported as 0 mph.

Trains traveling at less than 7 mph (11.3 kph) are considered "very slow." If a passing train drops below this speed threshold, the detection of Differential alarms, Pyrometer Saturation alarms, and Carside Slope alarms isn't performed. After the passage of these trains, the phrase "train too slow" is appended to the post-train message (when the Announce Slow Train option is enabled), and a diagnostic message is noted on the Train Detail and Exception Detail reports. Also, after the passage of these trains, axle count, exit speed, length of train, and total number of cars aren't announced. This is true even when the Announce Axles option, Announce Speed option, Announce Train Length option, and Announce Number of Cars option are enabled.

The report fragment below, from the header section of a Train Detail report, shows the location of this message.

```
Southern Technologies Corporation
Next Generation Detector System
TRAIN DETAIL
-----
                                .
                                .
System Alarms
-----
VERY Slow Train
                                .
                                .
                                .
```

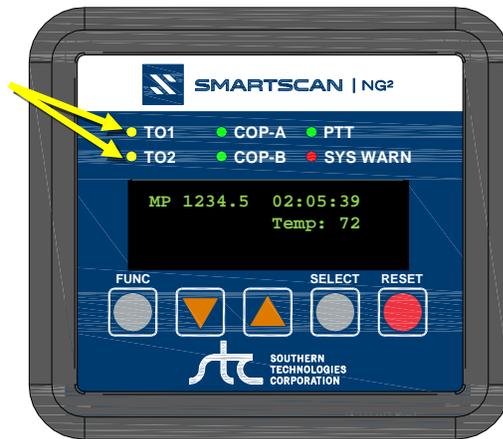
## 2.4 Train Direction

Train direction is based on whether TO1 or TO2 generated the first gating transducer pulse.

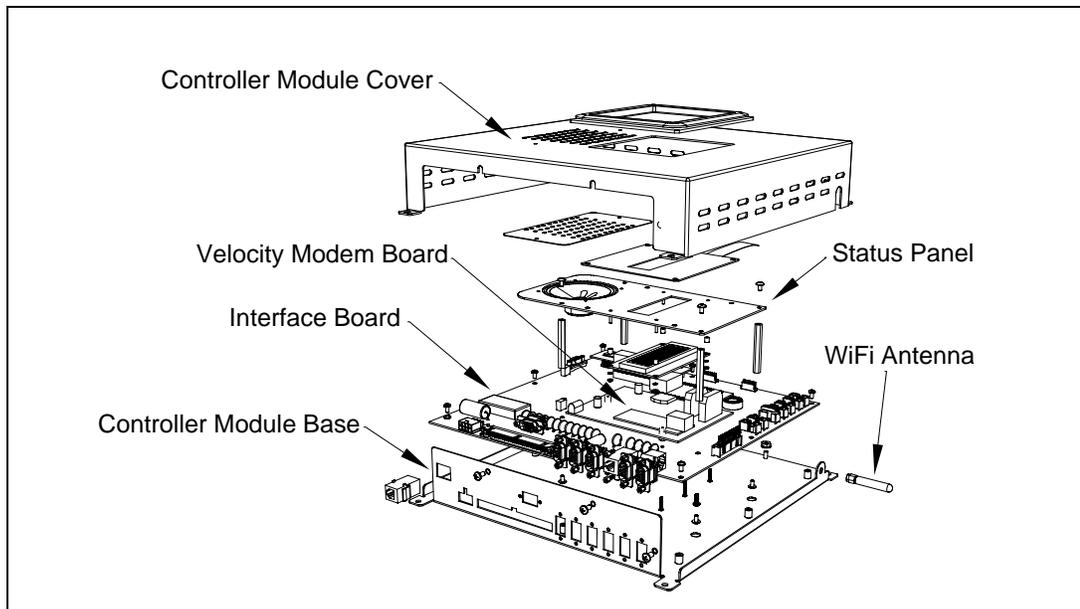
## 2.5 Transducer Pulse Processing

As a wheel enters the sensing range of a transducer, the transducer should respond with a positive-going pulse. The polarization of the two wires from the transducer determines if this pulse is positive or negative.

Here is a simple test that you can use to verify the correct polarization of the gating transducers. While watching the TO1 and TO2 LEDs on the display panel, have someone lay a metal wrench on one of the gating transducers. The corresponding LED should briefly light as the wrench touches the transducer. Then, lift the wrench up. The LED shouldn't light as the wrench is lifted away. Repeat the test for the other transducer.



On the Interface board (in the Controller module), the transducer signals undergo RF filtering and amplification with a gain of 30. For validation, the amplified signals are fed into comparators, which create 5-VDC pulses lasting the period of time that the amplified signals remain above 620 millivolts. Processor-A receives these 5-VDC pulses through ports PA0 (TO1) and PA1 (TO2).



A firmware-controlled feature of the comparator circuit allows adjustment of the threshold voltage based on the speed of the train. Trains traveling less than 20 mph (32 kph) use the 620-millivolt threshold setting for maximum sensitivity. However, faster trains cause the transducers to generate a higher signal voltage, which allows the system to increase the threshold voltage. This improves the signal-to-noise ratio, resulting in better signal validation.

Processor-A internally generates interrupts on the positive-going and negative-going edges of each transducer pulse coming from the comparator. The positive edge of each comparator pulse starts a timer. The timer stops with the detection of a negative-going edge. The width of each pulse is a determining factor of signal validity. Three milliseconds or greater is considered to be a valid signal. The firmware rejects any pulse width shorter than 3-milliseconds. Rejected pulses don't increment the transducer counters.

In normal operation, the gating transducers fire in sequence, first one, then the other. With 24-inch (61-centimeter) gating-transducer spacing, a wheel passes over both gating transducers before the next wheel passes over a gating transducer. Therefore, two consecutive pulses on the same gating transducer are not physically possible. However, in the unlikely event that a gating transducer is ever caused to fire by another source, such as electrical interference from a locomotive's traction motor, a spike-counter for the gating transducer that misfired will be incremented by one. To increment the axle counter, one pulse from each gating transducer must occur in sequence.

## 2.6 Axle Scanning

When the train first enters the site, the SmartScanNG<sup>2</sup> system begins reading the scanners for a heat signal when the wheel is at the center of the first gating transducer. Thereafter, it starts reading the scanners 16 inches (40.6 centimeters) before the center of the first gating transducer. (See **Appendix F - Predictive Gate Scanning** for more information about this 16-inch (40.6-centimeter) pre-gate scanning.) The system continues reading until the wheel is at the center of the second gating transducer. This is the period that the axle is in view of the scanner. A negative-going edge of a transducer signal is an indication that the wheel is in the center of that transducer.

The firmware uses Dynamic Scan Rate sampling between the centers of the two transducers (that is, between the gate), which means that heat readings taken every 1/2 inch (1.27 centimeters) of wheel movement are used to detect alarms, regardless of the speed of the train. As a result, the system takes 48 evenly spaced samples as the wheel rolls through the 24-inch (61-centimeter) detection zone that is established by the distance between the gating transducers.

## 2.7 Hot Bearing Alarms

The SmartScanNG<sup>2</sup> system checks for hot bearings during the scanning process. It detects and records every Hot Journal alarm that occurs. However, it only announces a maximum of four per train. For example, if a train contains seven Hot Journal alarms, the Train Detail report will show all seven, but only the first four will be announced.

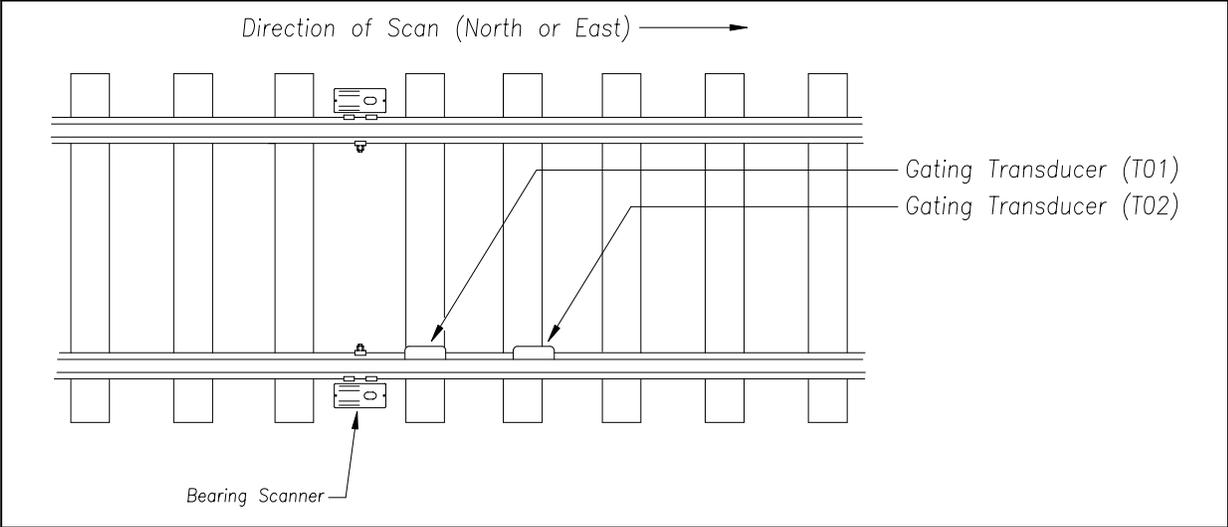
There are four types of Hot Journal alarms.

- **Absolute.** To trigger an Absolute alarm, a bearing temperature must exceed the limit that was established using the Absolute option. This alarm limit is an offset, in degrees Fahrenheit, above the ambient temperature.
- **Differential.** To trigger a Differential alarm, a bearing temperature must exceed the opposite side bearing temperature of the same axle by a differential amount established using the Differential option.
- **Pyrometer Saturation.** To trigger a Pyrometer Saturation alarm, an interaxle bearing temperature must exceed the limit that was established using the Absolute option. If an Absolute alarm or a Differential alarm has already been triggered for the axle, a Pyrometer Saturation alarm isn't generated.
- **Carside Slope.** To trigger a Carside Slope alarm, a bearing temperature must meet or exceed a calculated alarm level and a minimum heat value. The bearing temperature must also be at least twice the opposite bearing's temperature. If an Absolute alarm or a Differential alarm has already been triggered for the axle, a Carside Slope alarm isn't generated. The minimum heat value is established using the Carside Minimum option.

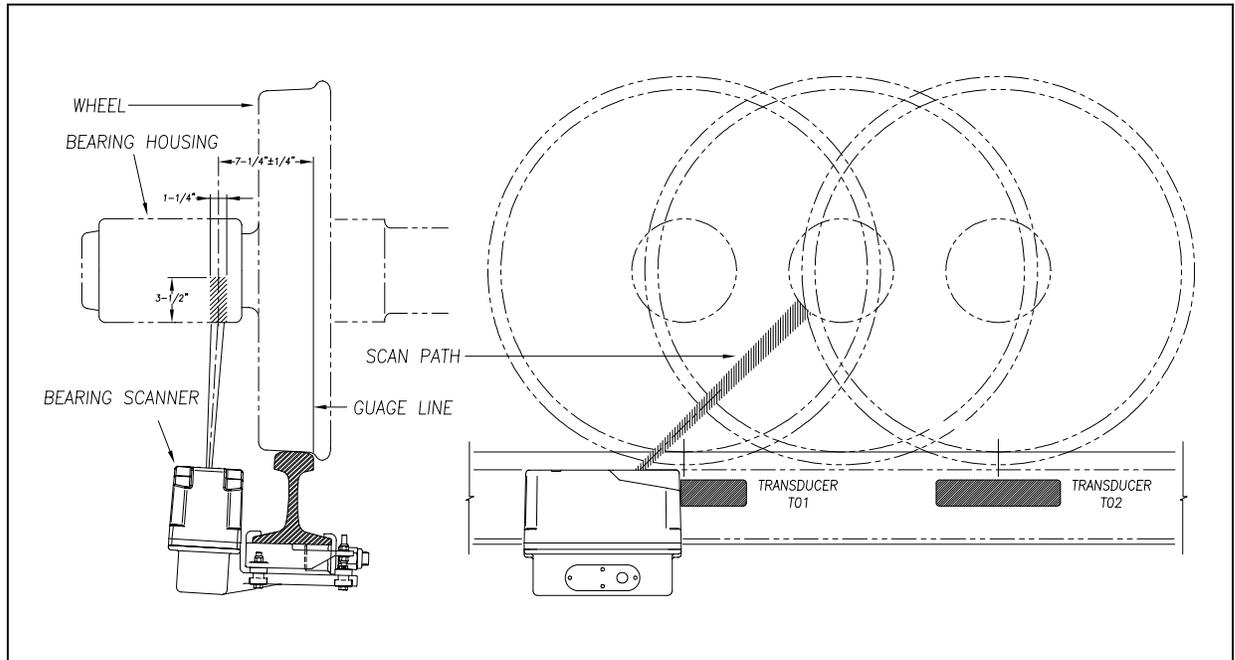
The system always checks for Absolute alarms. The system also checks for Differential alarms and Pyrometer Saturation alarms. However, their detection stops when the speed of the train drops below 7 mph (11.3 kph). In order for Carside Slope alarms to be processed, they must be enabled using the Carside Slope option on the Equipment Settings menu. The detection of Carside Slope alarms also stops when the speed of the train drops below 7 mph (11.3 kph).

### 2.7.1 Bearing Scan Process

Bearing scanners are mounted in the center of the crib of two ties spaced at least 14 inches (35.6 centimeters) apart. Both bearing scanners are mounted in the crib immediately ahead of the gating transducers (that is, in the crib immediately to the south or west of the gating transducers). They are mounted directly opposite each other, one on each rail of the track. The hole on the top of the scanner covers faces north or east.



The Type III bearing scanners are aligned to scan the bottom 3.5 inches (8.9 centimeters) of the bearing housing about 7.25 inches (18.4 centimeters) from the gauge line.



Bearing temperatures are sampled for a short period before the gate opens to support the detection of Pyrometer Saturation alarms, and while the gate is open.

## 2.7.2 Referencing System

Pyrometers measure rapid changes in infrared energy emitted from objects passing through their field of view. The rail-mounted scanners are aligned to take advantage of this characteristic.

When no axle is present between the gating transducers, the scanner typically sees only the undersides of the cars passing over the site. The undersides of the cars are at or near ambient temperature, thus establishing the reference from which the elevated temperatures of bearings are measured. The pyrometers normalize during this time, producing a zero-level signal.

Occasionally, the scanners are exposed to infrared emissions that are colder than the underside of the cars. Typically, this occurs in the gaps between cars when the scanners may reference on clear sky. This could present an erroneous reference if a bearing were scanned immediately following a sky shot, resulting in an abnormally high reading for the bearing. The pyrometers have internal circuitry to prevent the reference from shifting below the established zero reference.

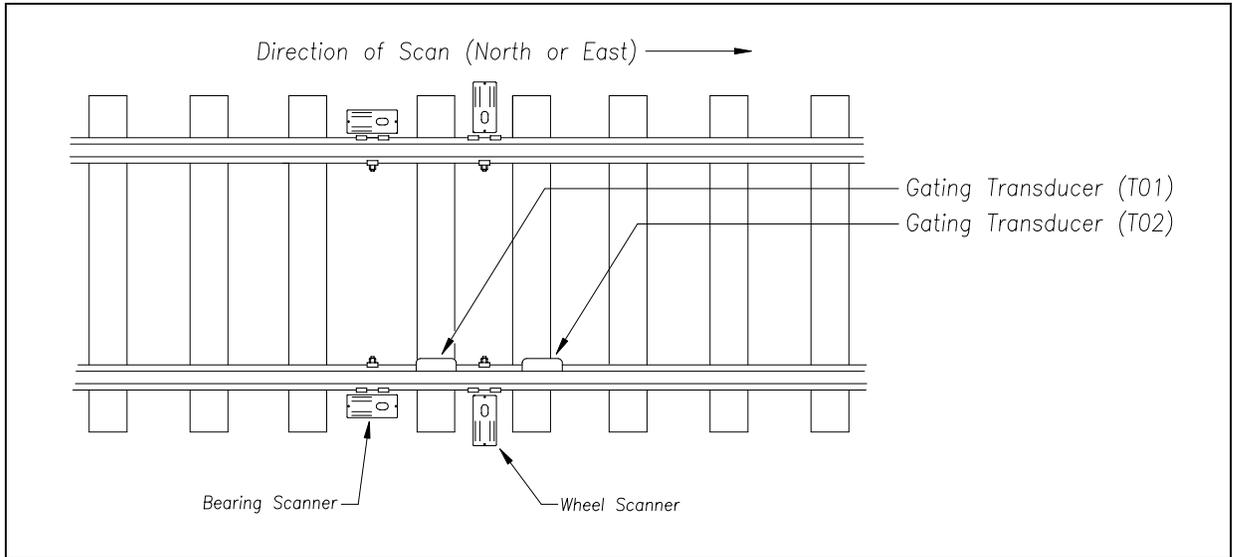
When a bearing passes through the field of view of the scanner, a rapid change in temperature is presented to the internal lithium tantalate crystal. This causes the signal level from the pyrometer to increase proportionally to the amount of exposed infrared energy. When an axle is between the gating transducers, the pyrometer signal is sampled at every 1/2 inch (1.27 centimeters) of wheel movement for a total of 48 samples, and the maximum signal level is stored. This signal level measured in volts is converted to a digital value and expressed in degrees Fahrenheit above ambient temperature. This value is the basis for the alarm analysis done by the system.

## 2.7.3 Pyrometer Linearity

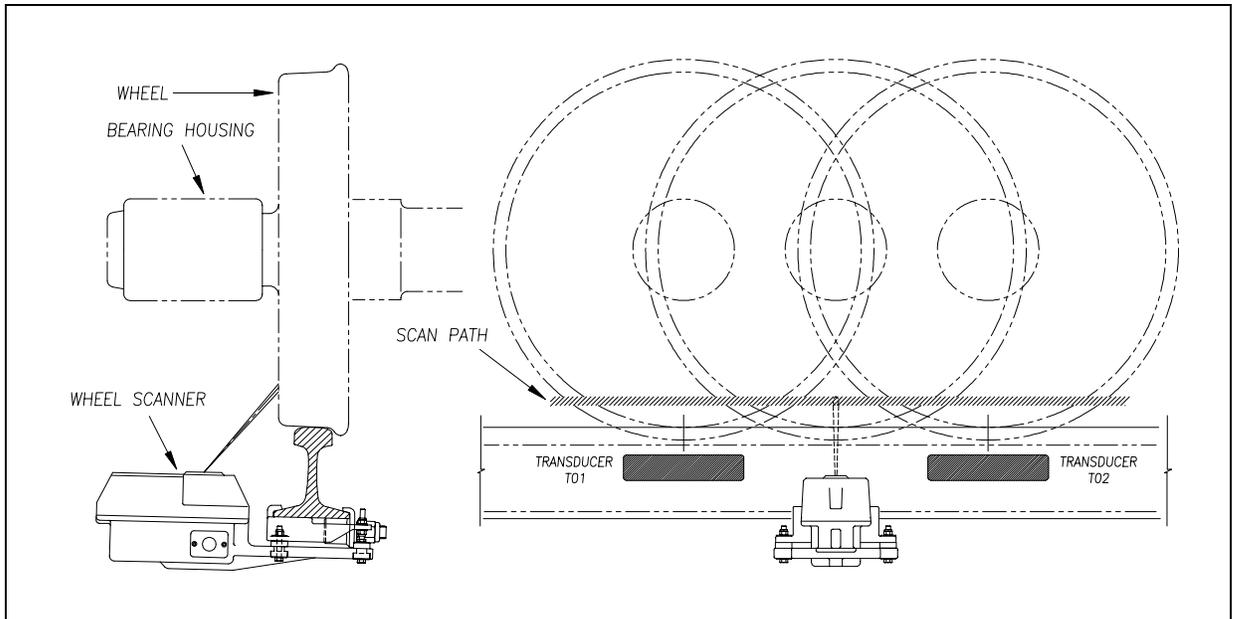
The output of the pyrometers is linear across most of the operating speed range of the system. However, the output of the pyrometers is nonlinear at either end of the operating speed range. To compensate for this nonlinear output, the firmware applies a correction factor to the sampled heat value. The correction factor applied to each bearing sample is based on the speed of the bearing (axle's ON time) as it passed through the gate and on the actual value read by the pyrometer. The correction factor is derived from a table that is keyed by the axle's ON time and heat value. Due to the fast nature of this lookup table, linearity compensation is done real-time so that detected alarms reflect the heat value after the linearity step has been done.

## 2.8 Hotwheel Alarms

When used, wheel scanners are mounted in the center of the crib of two ties spaced at least 14 inches (35.6 centimeters) apart. Both wheel scanners are mounted in the crib between the two gating transducers. They are mounted directly opposite each other, one on each rail of the track. The hole on the top of the scanner covers faces the center of the track.



Wheel scanners are aligned to scan about 4 inches (10 centimeters) above the rail.



The SmartScanNG<sup>2</sup> system checks for hotwheels during the scanning process. Scan timing is controlled the same as for the bearing scanners.

Wheel scanning alarms are limited to absolute only. To trigger a Hotwheel alarm, wheel scanners must be properly installed, hotwheel detection must be enabled, and a wheel temperature must exceed the limit that was established using the Hotwheel option on the Alarm Settings menu. This alarm limit is an offset, in degrees Fahrenheit, above the ambient temperature. Hotwheel detection is enabled using the Hotwheel option on the Equipment Settings menu. When enabled, the SmartScanNG<sup>2</sup> system detects and records every Hotwheel alarm that occurs. However, it only announces a maximum of four per train. For example, if a train contains nine Hotwheel alarms, the Train Detail report will show all nine, but only the first four will be announced.

## 2.9 Auxiliary Alarms

The SmartScanNG<sup>2</sup> system can support input from as many as four external alarm devices. Any device that provides an open relay contact upon alarm detection can be supported by the system. Auxiliary alarms supported by the SmartScanNG<sup>2</sup> system are:

- **Dragging Equipment.** To trigger a Dragging-Equipment alarm, a dragging-equipment detector must be properly installed, dragging-equipment detection must be enabled, and the SmartScanNG<sup>2</sup> system must sense an open relay contact from the dragging-equipment detector. Dragging-equipment detection is enabled using the Dragger option on the Equipment Settings menu. When enabled, the SmartScanNG<sup>2</sup> system detects and records every Dragging-Equipment alarm that occurs on a given train. However, it only announces the first two.
- **High-Load (oversized loads).** To trigger a High-Load alarm, a high-load detector must be properly installed, high-load detection must be enabled, and the SmartScanNG<sup>2</sup> system must sense an open relay contact from the high-load detector. High-load detection is enabled using the High-Load option on the Equipment Settings menu.

When a high-load detector is configured for tripwire operation, the SmartScanNG<sup>2</sup> system only records one High-Load alarm, regardless of the high-load signal status. This is because you can only break a wire once.

When a high-load detector is configured for light-beam operation, the SmartScanNG<sup>2</sup> system records every High-Load alarm that occurs. This involves a caveat that the system won't flag High-Load alarms on consecutive axles. At least one unalarmed axle must separate the alarmed axles. Regardless of the number of detected High-Load alarms, it only announces a maximum of two.

The mode of operation (light beam or tripwire) isn't relevant when the SmartScanNG<sup>2</sup> system finds a Stuck High-Load Detector Pretrain alarm. When this occurs, the system flags the pretrain condition as an integrity failure, disables high-load scanning for the remainder of the train, and doesn't assign a high-load condition to any of the axles.

- Wide-Load (shifted loads). To trigger a Wide-Load alarm, two wide-load detectors (one on each side of the track) must be properly installed, wide-load detection must be enabled, and the SmartScanNG<sup>2</sup> system must sense an open relay contact from either of the wide-load detectors. Wide-load detection is enabled using the Wide-Load option on the Equipment Settings menu.

When a wide-load detector is configured for tripwire operation, the SmartScanNG<sup>2</sup> system only records one Wide-Load alarm, regardless of the wide-load signal status. This is because you can only break a wire once.

When a wide-load detector is configured for light-beam operation, the SmartScanNG<sup>2</sup> system records every Wide-Load alarm that occurs. This involves a caveat that the system won't flag Wide-Load alarms on consecutive axles. At least one unalarmed axle must separate the alarmed axles. Regardless of the number of detected Wide-Load alarms, it only announces a maximum of two.

The mode of operation (light beam or tripwire) isn't relevant when the SmartScanNG<sup>2</sup> system finds a Stuck Wide-Load Detector Pretrain alarm. When this occurs, the system flags the pretrain condition as an integrity failure, disables wide-load scanning for the remainder of the train, and doesn't assign a wide-load condition to any of the axles.

Both high-load detectors and wide-load detectors must be either tripwire detectors or light-beam detectors. The selection of tripwire or light beam is done using the Clearance Type option on the Equipment Settings menu.



## 3.0 Display Panel

Located on the front of the SmartScanNG<sup>2</sup> Controller Module is the Display Panel. Its status indicators and display module provide a snapshot of the overall system health. As a convenience, the Display Panel also provides a user interface to execute some frequently used system functions (i.e., Auto Cal, Radio Test, etc.).



SmartScanNG<sup>2</sup> Display Panel

### 3.1 LED Indicators

There are six LED status indicators located above the OLED display.

LED	Meaning when Lit
TO1	Indicates wheel sensor TO1 is active.
TO2	Indicates wheel sensor TO2 is active.
COP-A	Indicates the status of Processor-A. If the CPU is running its program correctly, the LED blinks on and off. If the program isn't operating as expected, the LED is lit solid or isn't lit at all.
COP-B	Indicates the status of Processor-B. If the CPU is running its program correctly, the LED blinks on and off. If the program isn't operating as expected, the LED is lit solid or isn't lit at all.
PTT	Indicates the radio PTT is active.
SYS WARN	Indicates that a system warning has been detected.

## 3.2 Keypad & Display

The display assembly includes a 4-line 20-character OLED display and a five key membrane switch panel. If unused for five minutes, the display will time out to conserve power. Press any key to turn the display back on.

Keypad Switch	Function
FUNC	The function key toggles from home screen to the Main Menu. It also serves as a “Back” key in the system submenus to return to the previous menu level.
▼ (Arrow Down)	Scroll down menu options.
▲ (Arrow Up)	Scroll up menu options.
SELECT	Selects the highlighted menu option.
RESET	Initiates system reset.

The home screen displays milepost, time, and temperature.

```
MP 1234.5  02:05:39
                Temp: 72
```

If a system warning has been detected, the display will indicate “Check Sys. Health Menu” at the bottom of the screen.

### Menu Navigation:

- Press the **FUNC** key to toggle from home screen to the Main Menu or to back out of submenus.
- Use the **▲UP** and **▼DOWN** keys to move the **▶** pointer next to the desired menu option.
- Press the **SELECT** key to choose the menu option. The “↓” symbol on the display screen indicates that there are more options available if you scroll down. Likewise, the “↑” symbol indicates more options are available if you scroll up.

```
Main Menu
▶Sys. Health Menu
  Reset Sys. Health
↓ Radio Test
```

### 3.3 System Health Menu

The System Health Menu provides a snapshot of the system's general health. Each system health check displays a status of "GOOD" or "BAD" based on trending information derived from system alarms, integrity failures, and other monitored data. If a system warning has been flagged, the **SYS WARN** LED will be lit, and the "Check System Health" message will be displayed on the bottom text line of the home screen.

1. From the Main Menu, place the ► pointer next to **Sys. Health Menu**.

```
Main Menu
  ►Sys. Health Menu
    Reset Sys. Health
  ↓ Radio Test
```

2. Press the **Select** key. The status of the following system health checks is displayed:  
NumTrains, LowMiscount, HighMiscount, AvgTemp0, AvgTemp1, AvgTemp2, AvgTemp3, ColdRail0, ColdRail1, ColdRail2, ColdRail3, Avg Miscount, and Batt. prcnt.

```
Sys. Health Menu
  ►NumTrains      Good
    LowMiscount   Good
  ↓ HighMiscount  Good
```

If any of these system health checks indicate a "Bad" status, select that item to display more detailed information.

3. To reset system health, navigate to the Main Menu and place the ► pointer next to the **Reset Sys. Health**.

```
Main Menu
  Sys. Health Menu
  ►Reset Sys. Health
  ↓ Radio Test
```

4. Press the **Select** key. When prompted, select **Yes** to reset system warnings and zero all health check counts.

```
Are You Sure?
  ►Yes
    No
```

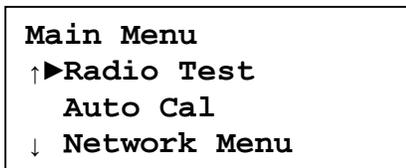
## 3.4 System Functions

Several system functions can be performed from the display panel. Available options are:

- System Health Menu
- Reset System Health
- Radio Test
- Auto Cal
- Network Menu
- Radio Menu
- Volume Menu

### 3.4.1 Radio Test

To perform a radio test, go to the Main Menu and select **Radio Test**



The Radio Test option is used to broadcast a short message through the speaker and through the radio. Using this option lets you verify that the speaker and radio are working properly.

At single-track sites, the text of the message is usually "Testing, BNSF, milepost (milepost number), testing, one, two, three, four, five, four, three, two, one, testing." At multitrack sites, the text of the message is usually "Testing, BNSF, milepost (milepost number), track (track designation), testing, one, two, three, four, five, four, three, two, one, testing."

If the system isn't currently making any other voice announcements, it begins the Radio Test announcement. After the announcement finishes, the System Functions menu reappears.

If the system is currently making a voice announcement, the firmware displays the message "System Is Currently Making Voice Announcements! Try Again Later" and redisplay the System Functions menu.

While listening to the message, look at the PTT LED on the display panel.

The **PTT LED** should be lit. If this LED isn't lit, the system's ability to send a message to the radio might be inhibited by the Radio Inhibit option on the System Functions menu. If the radio is inhibited, the results of this check are invalid.

### 3.4.2 Auto-Calibration

The SmartScanNG<sup>2</sup> system self-calibrates its pyrometer interface circuitry. You need only put a preheated calibrated heat source on a scanner and place the system in autocalibration mode. The system then scans all pyrometer inputs until the signal from the calibrated heat source is located. The necessary adjustments to the related interface circuitry are automatically made while the system monitors its own progress by analyzing changes in the heat signals.

From the Main Menu, select **Auto Cal**. This prompt appears.

```
Searching for heat...
Searching, 150 sec.
```

Once the procedure has been completed, autocalibration mode is disengaged and the calibration results are displayed.

For a detailed description of the auto-calibration procedures, go to **Appendix D Calibrating of Type III Scanners**.

### 3.4.3 Network Menu

From the Main Menu, select **Network Menu** option to view/change network settings.

Available options are:

DHCP server, Secure Wireless (on/off), IP Address, DHCP (on/off), TELNET port, HTTP port, HTTPS port, and Laptop Direct

When configured for **Laptop Direct**, the SmartScanNG<sup>2</sup>'s Ethernet port is configured in such a way it can connect directly to a laptop computer with a single network cable and access the system's telnet and web interfaces using [www.wired.stc](http://www.wired.stc) or [192.168.3.4](http://192.168.3.4).

**NOTE:** Laptop Direct mode uses the SmartScanNG<sup>2</sup>'s built-in DHCP server. To avoid potential IP address conflicts, Laptop Direct mode polls every five seconds for the existence of other DHCP servers on the network attached to the Ethernet port. If another DHCP server is discovered, Laptop Direct mode will shut down.

### 3.4.4 Radio Menu

From the Main Menu, select Radio Menu to view the radio screen. This screen will display certain radio status information such as:

- "PTT Disabled" if Radio Inhibit is active
- "Holdoff Active" if holdoff is enabled
- "CD active" when radio has detected an active carrier signal

Press SELECT key to initiate Radio Test.

### 3.4.5 Volume Menu

From the Main Menu, select **Volume Menu** to view/change speaker volume.

```
Vol: 5 [||||| ]
Up/Down = change
Select = Radio test
Func = Back
```

There are ten volume settings (0 – 9), with level 9 being the maximum volume. Press the ▲UP key to increase the volume level. Press the ▼DOWN key to decrease the volume level.

Pressing the **SELECT** key while in Volume Menu will initiate a radio test.

The Radio Test is used to broadcast a short message through the speaker and the radio. Using this option lets you verify that the speaker volume is at a sufficient level. At single-track sites, the text of the message is usually "Testing, BNSF, milepost (milepost number), testing, one, two, three, four, five, four, three, two, one, testing." At multitrack sites, the text of the message is usually "Testing, BNSF, milepost (milepost number), track (track designation), testing, one, two, three, four, five, four, three, two, one, testing. "Press the **FUNC** key to back out of the menu.

## 4.0 Serial Interface

---

The serial interface allows **on-site** and **off-site** communication with the system. This interface is the only way to view reports and to modify system parameters.

Most sites are equipped with either Ethernet or telephone service that provides remote communications capabilities. If not, you cannot communicate with the system **off-site**.

To use the interface locally, you need:

- A computer
- Communications software, which is installed on the computer
- A cable from the computer to a communications port on the Controller module

For remote access via telephone:

- A computer with communications software
- A modem, which is connected to the computer
- A nonswitched analog telephone line, which is connected to the computer's modem
- Another modem, which is connected to COM3 on the Interface board (internally) or COM3 on the Controller module (externally)
- Another nonswitched analog telephone line, which is connected to the SmartScanNG<sup>2</sup>'s modem

For remote access via network (Telnet connection):

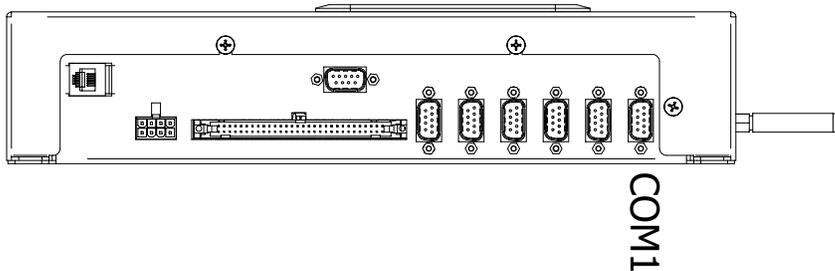
- A computer with communications software and internet connectivity
- An Ethernet connection at the SmartScanNG<sup>2</sup> controller

If your site uses an external modem, it must be attached to COM3 on the Controller module. But before attaching it, you must first disconnect P14 on the Interface board from the internal modem. You must next route COM3 on the Interface board to the external connector COM3 on the SmartScanNG<sup>2</sup> chassis (that is, the Controller module).

This section describes the serial interface for the BNSF SmartScanNG<sup>2</sup> system. It covers how to enter or change the system parameters. It is necessary to go through a complete setup the first time a SmartScanNG<sup>2</sup> system is installed at a new site. (If this is a double-track site, you also need to do this for the other SmartScanNG<sup>2</sup> system.) After that, the processor (in the Controller module) retains the setup information in flash memory. During a power outage, no setup information is lost.

## 4.1 Main Menu

- 1 If **on-site**, plug your computer into COM1.



- 2 Turn on your computer.
- 3 Be sure that your computer has installed communications software, that it is set to use full-duplex, and that the baud rate is set to 19,200.  
Use your communications software to open a LOG file and capture the whole session to the file. When your session is complete, you may then view what you have done with an editor, print it with a printer, or store it for later retrieval.
- 4 On your computer, open a LOG file.
- 5 If **off-site**
  - a From your computer, initiate a remote connection to the site modem.
  - b Wait for the "connect" message from your modem or your Telnet terminal.

To display the **Main Menu**:

- 6 Press **[Esc]**.

If the system has been set up with security passwords, this prompt appears.

```
Enter password:
```

- 7 Type the appropriate password to display Main Menu.

System login with an administrative password allows all access to system menus.

System login with user password allows access to report menus and system functions menu but restricts access to the setup menu and security menu.

## 8 The Main Menu

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event log
[K] - System Functions Menu
[L] - Replay train
[M] - Security Menu
[X] - Exit
```

By selecting an option at the above prompt, you can:

- Produce a report.
- Replay an EOT announcement.
- Access the Setup menu. From the Setup menu, you can set system parameters.
- Access the System Functions menu.

If a train is at the site when the Main menu is generated, "\*\*\* Train Is Present \*\*\*" is displayed just above the menu header for the Main menu and for every other menu.

**9** When done, close the LOG file.

**10** To exit the serial interface and return the system to normal operation, type **X**.

When a session ends, if a modem was used, the system sends various commands to the modem to prepare it for future use. If, at any time during the disconnect procedure, lines such as "+++ATH0" appear on your screen, these are merely commands preparing the modem for further use. They shouldn't be construed as anything that is meant for the user.

## 4.2 Setup Menu

To display the Setup menu:

- 1 Be sure that the Main menu is displayed.

The Main menu looks like this.

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event log
[K] - System Functions Menu
[L] - Replay train
[M] - Security Menu
[X] - Exit
```

- 2 Select the **Setup** to view menu options.

If the Setup menu is password protected, this prompt appears.

```
You are not logged in with admin privileges
Enter password:
```

You are given three chances to type the correct password. When you don't type the correct password in three tries, the system returns to the Main menu.

If the password is less than 20 characters long, press **[Enter]** after typing the last character. If the password is the full 20 characters in length, pressing **[Enter]** isn't necessary.

The password entry is **not** case-sensitive. For example, the password "abc#123" can be entered "ABC#123," "aBc#123," and so forth.

```
Setup Menu
-----
[A] - Date and Time
[B] - MP/KP
[C] - Track Designation ..... Single
[D] - Track Direction ..... N/S
[E] - Alarm Settings
[F] - Equipment Settings
[G] - Message Settings
[H] - AEI Settings
[I] - Load Default Setup Parameters
[J] - COM Port Settings
[K] - Network Settings
[L] - Talker Mode ..... Talk Freely
[M] - N/E Integ Mode ..... 5B-Integ Fail
[N] - S/W Integ Mode ..... 5B-Integ Fail
[O] - Velocity ..... Enabled
[P] - Customer Initials ..... BNSF
[X] - Exit
```

To access any of the Setup menu options, type the letter that corresponds to the desired menu option.

At any prompt, a timeout mechanism is in place to prevent the system from remaining in that state indefinitely. When a timeout occurs, the serial interface regresses to the previous menu. For example, if a timeout occurs in the Equipment Settings menu, the system reverts to the Setup menu. If this menu times out, the system reverts to the Main menu. If this menu times out, the system disconnects the modem connection and resumes normal operation. At the Main menu, the timeout is set for five minutes. For all other prompts, the system uses several different timeout values.

If a train is at the site when the Setup menu is generated, "\*\*\*\* Train Is Present \*\*\*\*" is displayed just above the menu header for the Setup menu.

**3** To return to the Main menu, type **X**.

Changes to the system parameters aren't reflected until after you have exited the Setup menu.

## 4.2.1 Date and Time

To set or change the date, the time, or both:

- 1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
Setup Menu
-----
[A] - Date and Time
[B] - MP/KP
[C] - Track Designation ..... Single
[D] - Track Direction ..... N/S
      .
      .
      .
```

- 2 Select the Date and Time submenu.

A prompt like this appears.

```
Current Date: 07/04/2024
Enter New Date (mm/dd/yyyy):
```

Dates are in **mm/dd/yyyy** format, where **mm** is month, **dd** is day, and **yyyy** is year. Type the current date. You must include slashes. For days and months from 1 through 9 you must type leading zeros. Thus, for 8 July 2024, type **07/08/2024**.

If you want to keep the displayed date, press **[Enter]**. If you don't, type a new date.

- 3 Type a new date or press **[Enter]**.

A prompt like this appears.

```
Current time is: 22:47:34
Enter new time:
```

Time is in 24-hour **hh:mm:ss** format, where 8 a.m. is 08:00:00, noon is 12:00:00, 8 p.m. is 20:00:00, and midnight is 00:00:00. Thus, for 17 seconds past 3:42 p.m., type **15:42:17**. You must include colons. For hours, minutes, and seconds from 0 through 9, type leading zeros.

If you want to keep the displayed time, press **[Enter]**. If you don't, type a new time.

- 4 Type a new time or press **[Enter]**.

A prompt like this appears.

```
Current Time Zone: Eastern
Enter New Time Zone (E-Eastern,C-Central,M-Mountain,P-Pacific):
```

If you want to keep the displayed time zone, press **[Enter]**. If you don't, type the letter that corresponds to the time zone you want.

- 5 Type the letter that corresponds to the time zone you want, or press **[Enter]**.

A prompt like this appears, stating whether the daylight-saving-time adjustment is currently disabled or enabled. Daylight-saving time is the period during which clocks are set one hour ahead of local standard time.

```
Daylight Savings Time Enabled OK (Y/N)?
```

If disabled, all times throughout the year are in standard time. If enabled, all times between the second Sunday in March and the first Sunday in November are in daylight-saving time. All other times are in standard time. Any change takes effect immediately. Later, if enabled, at 2:00 a.m. on the second Sunday in March, the system will adjust the system's clock forward an hour to 3:00 a.m., and at 2:00 a.m. on the first Sunday in November, the system will adjust the system's clock backward to 1:00 a.m.

At this point, you can type **Y** (yes), type **N** (no), or press **[Enter]**. Pressing **[Enter]** has the same effect as typing **Y**. Typing **N** doesn't change the displayed time.

- 6 If you want to modify the adjustment, type **N**.

Typing the letter **N** toggles between disabled or enabled. A message like this appears, stating whether the daylight-saving-time adjustment is now disabled or enabled.

```
Daylight Savings Time Disabled OK (Y/N)?
```

- 7 If you don't want to modify the daylight-saving-time adjustment, type **Y**.

The Setup menu reappears. Information like this appears on line two of the Setup menu, where EDT is the abbreviation for Eastern Daylight Time. If it were EST instead, it would be Eastern Standard Time.

```
06/30/2024 22:47 EDT
```

## 4.2.2 Milepost/Kilometer Post (MP/KP)

To set or change the milepost/kilometer post (MP/KP) setting:

- 1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
Setup Menu
-----
[A] - Date and Time
[B] - MP/KP
[C] - Track Designation ..... Single
[D] - Track Direction ..... N/S
      .
      .
      .
```

- 2 Select the MP/KP submenu.

A prompt like this appears.

```
Enter the milepost in the form ####.# (use leading zeros):
```

MP/KP is in **nnnn.n** format. If the desired MP/KP has less than five digits, type leading zeros. If the desired MP/KP is an integer, type a trailing zero. Thus, for MP/KP 30, type **0030.0**.

- 3 To keep the displayed MP/KP:

- a Press **[Enter]**.

The Setup menu reappears.

- b Skip the remaining steps.

- 4 To change the displayed MP/KP, type the new five-digit MP/KP, including the decimal point.

The Setup menu reappears.

### 4.2.3 Track Designation

To set or change the track designation:

- 1 Select Track Designation from the Setup Menu.

A prompt like this appears.

```
Select a track designation:  
[A] - Single  
[B] - North  
[C] - South  
[D] - East  
[E] - West  
[F] - Middle  
[G] - Main 1  
[H] - Main 2  
[I] - Main 3  
[J] - Track 233
```

- 2 Choose the appropriate designator.
- 3 To leave the Alarm Settings menu and return to the Setup menu:
  - a Press **[Esc]** or type **X**.  
The Setup menu reappears.
  - b Skip the remaining steps.

### 4.2.4 Track Direction

To set or change the track direction:

- 1 Select Track Direction from the Setup Menu.

Track direction will toggle from N/S to E/W.

```
Setup Menu  
-----  
[A] - Date and Time  
[B] - MP/KP  
[C] - Track Designation ..... Single  
[D] - Track Direction ..... E/W  
[E] - Alarm Settings  
      .  
      .  
      .
```

- 2 To leave the Alarm Settings menu and return to the Setup menu:
  - a Press **[Esc]** or type **X**.  
The Setup menu reappears.
  - b Skip the remaining steps.

## 4.2.5 Alarm Settings

To set or change one or more of the alarm settings (alarm limits):

- 1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
Setup Menu
-----
[A] - Date and Time
[B] - MP/KP
[C] - Track Designation ..... Single
[D] - Track Direction ..... N/S
[E] - Alarm Settings
      .
      .
      .
```

- 2 Select the Alarm Settings menu.

A menu and prompt like this appears.

```
Alarm Settings
-----
[A] - Absolute ..... 170
[B] - Differential ..... 150
[C] - Hot Wheel ..... 900
[D] - Cold Rails ..... 3
[E] - Cold Rail Temp ..... 10
[F] - Cold Res Counter ..... 3
[G] - Differential Enabled ..... Yes
[H] - Advanced
[X] - Exit
```

This menu option allows you to change the various alarm limits that affect system operations. The current setting for each limit is displayed. To change one of the alarm limit settings, start by typing the letter corresponding to the desired option.

- 3 To leave the Alarm Settings menu and return to the Setup menu:

- a Press **[Esc]** or type **X**.

The Setup menu reappears.

- b Skip the remaining steps.

4 To change the displayed **Absolute-alarm limit** :

The number after the word Absolute (on the Alarm Settings menu) is an offset in degrees Fahrenheit above ambient temperature. When a bearing temperature exceeds this value, the system generates an Absolute alarm.

```
Alarm Settings
-----
[A] - Absolute ..... 170
[C] - Differential ..... 150
      :
      :
```

- a Select **Absolute** from the Alarm Settings menu.

This prompt appears.

```
Absolute alarm setting (default = 170)
Enter a value between 1 and 300:
```

If the new limit has less than three digits, type leading zeros to make it three digits long or press **[Enter]** after typing one or two digits.

- b To not change the limit, press **[Esc]** and return to the Alarm Settings Menu.
- c Type the new limit.

5 To change the displayed **differential-alarm limit** :

The number after the word Differential (on the Alarm Settings menu) is an offset in degrees Fahrenheit between rail1 and rail2. A bearing temperature is compared to the bearing temperature on the opposite end of the same axle. When the difference in temperatures exceeds the value on the screen, the system generates a Differential alarm. Checking for Differential alarms stops when the speed of the train drops below 7 mph (11.3 kph).

```
Alarm Settings
-----
[A] - Absolute ..... 170
[C] - Differential ..... 150
      :
      :
```

- a Select **Differential** from the Alarm Settings menu.

This prompt appears.

```
Differential alarm setting (default = 150)
Enter a value between 1 and 300:
```

If the new limit has less than three digits, type leading zeros to make it three digits long or press **[Enter]** after typing one or two digits.

- b To not change the limit, press **[Esc]** and return to the Alarm Settings menu.
- c Type the new limit.

**6 To change the displayed **hotwheel-alarm limit** :**

The number after the words Hot Wheel (on the Alarm Settings menu) is an offset in degrees Fahrenheit above ambient temperature. When a wheel temperature exceeds this value, the system generates a Hotwheel alarm. However, when the Hotwheel option on the Equipment Settings menu is disabled, Hotwheel alarms aren't generated.

```
      :
      :
[D] - Hot Wheel ..... 600
[E] - Cold Rails ..... 9
[F] - Cold Rail Temp ..... 10
[G] - Cold Res Counter ..... 9
      :
      :
```

**a** Select **Hot Wheel** from the Alarm Settings menu.

This prompt appears.

```
Hot Wheel alarm setting (default = 900)
Enter a value between 1 and 900:
```

If the new limit has less than three digits, type leading zeros to make it three digits long or press **[Enter]** after typing one or two digits.

- b** To not change the limit, press **[Esc]** and return to the Alarm Settings menu.
- c** Type the new limit.

**7 To change the displayed **number of allowed consecutive cold rail events**:**

The number after the words Cold Rails (on the Alarm Settings menu) is the maximum number (per rai<sup>s</sup>ide) of consecutive trains having:

- Cold Rail alarms needed to generate a Successive Cold Rails Exceeded alarm.
- Cold Resistor alarms needed to generate a Successive Cold Resistors Exceeded alarm.
- Cold Wheel Scanner alarms needed to generate a Successive Cold Wheels Exceeded alarm.
- Cold Wheel Scanner Resistor alarms needed to generate a Successive Cold Wheel Resistors Exceeded alarm.

```
      :
      :
[D] - Hot Wheel ..... 600
[E] - Cold Rails ..... 3
[F] - Cold Rail Temp ..... 10
[G] - Cold Res Counter ..... 9
      :
      :
```

- a Select **Cold Rails** from the Alarm Settings menu.

This prompt appears.

```
New Value ? Rails alarm setting (default = 3)
Enter a value between 1 and 9:
```

If the new value has less than three digits, type leading zeros to make it three digits long or press **[Enter]** after typing one or two digits.

- b To not change the value, press **[Esc]** and return to step 3.
- c Type the new value.

**8** To change the displayed **cold rail temperature**:

The number after the words Cold Rail Temp (on the Alarm Settings menu) is an offset, in degrees Fahrenheit, above the ambient temperature. When no bearing on a given rail generates a delta temperature reading greater than or equal to this value, the system generates a Cold Rail alarm for the given rail. There is a different Cold Rail alarm for each rail. That is, there is a Cold North Rail alarm and a Cold South Rail alarm (or, depending on track direction, a Cold East Rail alarm and a Cold West Rail alarm).

```
      :
[D] - Hot Wheel ..... 698
[E] - Cold Rails ..... 9
[F] - Cold Rail Temp ..... 10
[G] - Cold Res Counter ..... 9
      :
      :
```

- a Select **Cold Rail Temp** from the Alarm Settings menu.

This prompt appears.

```
Cold Rails alarm setting (default = 10)
Enter a value between 1 and 30:
```

If the new value has less than three digits, type leading zeros to make it three digits long or press **[Enter]** after typing one or two digits.

- b To not change the value, press **[Esc]** and return to step 3.
- c Type the new value.

**9** To change the displayed **cold resistor counter**:

The number after the words Cold Res Counter is the maximum number (per railside) of consecutive trains, having Cold Resistor alarms, allowed before generating a Successive Cold Resistors Exceeded alarm. Under normal circumstances, cold resistor conditions represent System Alarms, not Integrity Failures. However, if the number of consecutive trains bearing identical Cold Resistor alarms equals or exceeds the Cold Resistor Counter option on the Alarm Settings menu, this condition becomes an Integrity Failure. If the number of consecutive trains bearing identical Cold Resistor alarms equals or exceeds the cold-resistor limit, the System Alarms section of the Train Detail and Exception Detail Reports displays the message "Successive Cold Resistors Exceeded."

```
      .  
      .  
      .  
[F] - Cold Rail Temp ..... 10  
[G] - Cold Res Counter ..... 9  
[H] - Differential Enabled ..... Yes  
[I] - Advanced  
[X] - Exit
```

**a** Select **Cold Res Counter**

This prompt appears.

```
Cold Res Counter alarm setting (default = 3)  
Enter a value between 1 and 9:
```

If the new value has less than three digits, type leading zeros to make it three digits long or press **[Enter]** after typing one or two digits.

- b** To not change the value, press **[Esc]** and return to step **3**.
- c** Type the new value.

**10** To change the displayed **carside-slope value**:

The number after the words Carside Slope on the Alarm Settings (Advanced) menu is the slope value used when doing carside-slope calculation/analysis. **Section 2.0 - Defect Detection** describes the Carside Slope alarm process. In order for Carside Slope alarms to be processed, they must be enabled using the Carside Slope option on the Equipment Settings menu. The detection of Carside Slope alarms stops if the speed of the train drops below 7 mph (11.3 kph).

```
Alarm Settings (Advanced)
-----
Alarm Settings (Advanced)
-----
[A] - Carside Slope ..... 1.31
[B] - Carside Minimum ..... 155
[C] - Res Test: Minimum Rail Avg .... 25
[D] - Res Test: Minimum Wheel Avg ... 28
[E] - Max Alarms ..... 13
[X] - Exit
```

**a** Select **Carside Alarm** from the Alarm Settings menu.

This prompt appears.

```
Carside Slope alarm setting (default = 1.31)
Enter a value between 0.01 and 2.55:
```

Slope value is in **n.nn** format. If the new value has less than three digits, type leading zeros, trailing zeros, or both. Thus, for .98, type **0.98**. For 1.2, type **1.20**.

**b** To not change the value, press **[Esc]** and return to step **3**.

**c** Type the new value.

11 To change the displayed **carside minimum heat value**:

The number after the words Carside Minimum (on the Alarm Settings Advanced menu) is a minimum offset (in degrees Fahrenheit) used when doing carside-slope calculation/analysis. If the Carside Slope option on the Equipment Settings menu is disabled during train passage, no carside-slope calculation/analysis is done and, thus, no Carside Slope alarms are generated. If the Carside Slope option on the Equipment Settings menu is disabled at the time a Train Detail report is requested, no carside-slope calculation is done, and thus, no carside-slope alarm-limit lines are generated. **Section 2.0 - Defect Detection** describes the Carside Slope alarm process.

```
Alarm Settings (Advanced)
-----
[A] - Carside Slope ..... 1.31
[B] - Carside Minimum ..... 155
[C] - Res Test: Minimum Rail Avg .... 25
[D] - Res Test: Minimum Wheel Avg ... 28
[E] - Max Alarms ..... 13
[X] - Exit
```

- a Select **Carside Minimum** from the Alarm Settings (Advanced) menu.

This prompt appears.

```
Carside Minimum alarm setting (default = 155)
Enter a value between 0 and 300:
```

If the new value has less than three digits, type leading zeros to make it three digits long or press **[Enter]** after typing one or two digits.

- b To not change the value, press **[Esc]** and return to step 3.
- c Type the new value.

**12** To change other Alarm setting options:

Select the desired setting. After the prompt, enter a new value.

```
Alarm Settings (Advanced)
-----
[A] - Carside Slope ..... 1.31
[B] - Carside Minimum ..... 155
[C] - Res Test: Minimum Rail Avg .... 25
[D] - Res Test: Minimum Wheel Avg ... 28
[E] - Max Alarms ..... 13
[X] - Exit
```

### 4.2.6 Equipment Settings

To set or change one or more of the equipment parameters:

- 1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
Setup Menu
-----
[A] - Date and Time
[B] - MP/KP
[C] - Track Designation ..... Single
[D] - Track Direction ..... N/S
[E] - Alarm Settings
[F] - Equipment Settings
      .
      .
      .
```

2 Select the Equipment Settings menu.

A menu and prompt like this appears.

```

Equipment Settings
-----
[A] - Dragger ..... No
[B] - High Load ..... No
[C] - Wide Load ..... No
[D] - Hot Wheel ..... Yes
[E] - AEI ..... Yes
[F] - Hot Bearing ..... Yes
[G] - Presence Hardware ..... Yes
[H] - Main AC Power ..... No
[I] - Advance Transducers ..... No
[J] - DC Power ..... No
[K] - Surge Protector ..... No
[L] - Scanner Heater AC Monitor .... Yes
[M] - Select scanner types
[N] - Advanced
[X] - Exit

```

The current setting for each menu option is displayed. For example, the screen above shows that Wide-Load alarm detection is inactive (NO). To change one of the settings, press the letter corresponding to the desired option. Except for the Gate Distance option, which requires a value entry, all the options toggle between two or three settings.

3 To leave the Equipment Settings menu and return to the Setup menu:

a Press **[Esc]** or type **X**.

The Setup menu reappears.

b Skip the remaining steps.

4 To change the current **dragger** (aka dragging-equipment) setting:

The Equipment Settings menu shows whether Dragging-Equipment alarm detection is enabled (YES) or disabled (NO). When disabled, Dragging-Equipment alarms won't be announced nor stored. Since they aren't stored, they can't be printed. When enabled, Dragging-Equipment alarms will be announced and stored. Since they are stored, they can be printed. In the presence of a continuous Dragger signal, the system alarms consecutive axles. When the system reaches the fifth consecutive Dragger alarmed axle, it flags the Stuck Dragger condition.

```

Equipment Settings
-----
[A] - Dragger ..... NO
[B] - High Load ..... NO
[C] - Wide Load ..... NO
      :
      :

```

a Select **Dragger** from the Equipment Settings menu.

The dragging-equipment setting toggles between active (YES) and inactive (NO). The Dragger option on the Equipment Settings menu changes. The Equipment Settings menu reappears.

If you want Dragging-Equipment alarm detection to occur, be sure that YES appears after the word Dragger on the Equipment Settings menu.

**b** Return to step 3.

**5** To change the current **high-load** setting:

The Equipment Settings menu shows whether High-Load alarm detection is active (YES) or inactive (NO). To announce High-Load alarms, YES must appear after the words High Load on the Equipment Settings menu, and Separate must appear after the words Clearance Mode on the Equipment Settings menu. To announce Shifted Load alarms, YES must appear after the words High Load on the Equipment Settings menu, and Multiplexed must appear after the words Clearance Mode on the Equipment Settings menu.

Equipment Settings	
-----	
[A] - Dragger .....	NO
[B] - High Load .....	NO
[C] - Wide Load .....	NO
:	
:	
:	

**a** Select **High Load** from the Equipment Settings menu.

The high-load setting toggles between active (YES) and inactive (NO). The High-Load option on the Equipment Settings menu changes. The Equipment Settings menu reappears.

If you want High-Load alarm detection to occur, be sure that YES appears after the word High-Load on the Equipment Settings menu.

**b** Return to Equipment Settings.

6 To change the other equipment settings:

```
Equipment Settings
-----
[A] - Dragger ..... No
[B] - High Load ..... No
[C] - Wide Load ..... No
[D] - Hot Wheel ..... Yes
[E] - AEI ..... Yes
[F] - Hot Bearing ..... Yes
[G] - Presence Hardware ..... Yes
[H] - Main AC Power ..... No
[I] - Advance Transducers ..... No
[J] - DC Power ..... No
[K] - Surge Protector ..... No
[L] - Scanner Heater AC Monitor .... Yes
[M] - Select scanner types
[N] - Advanced
[X] - Exit
```

- a Select the equipment option from the Equipment Settings menu.  
The setting toggles between active (YES) and inactive (NO). The Equipment Settings menu reappears.

- b Return to step 3.

7 Select Advanced option to view advanced equipment settings:

```
Equipment Settings (Advanced)
-----
[A] - Carside Slope ..... Yes
[B] - Clearance Type ..... Light Beam
[C] - Clearance Mode ..... Multiplexed
[D] - Winter Cycle ..... Oct - Mar
[E] - Transducer Gain ..... Normal
[F] - Resistor Test ..... Enabled
[G] - Gate Distance ..... 24.0 in
[H] - Dragger Debounce Time ..... 100 ms
[I] - Pre Train Dragger Dist ..... 6 ft
[J] - Pre Train High/Wide Dist .... 6 ft
[K] - Presence Timeout Period ... 10 sec
[L] - System Voltage ..... 12v
[M] - Sunshot Menu
[N] - Transducer / Scanner Offset Menu
[P] - Carrier Detect Active State .. Low
[X] - Exit
```

8 To change the current **carside-slope** setting:

The Equipment Settings (Advanced) menu shows whether Carside Slope alarm detection is enabled (YES) or disabled (NO). If disabled (NO) during train passage, no carside-slope calculation/analysis is done, and thus, no Carside Slope alarms are generated. If disabled (NO) at the time a Train Detail report is requested, no carside-slope calculation is done, and thus, no carside-slope alarm-limit lines are generated.



The table below lists the heater activation times for both normal and winter-cycle operation, grouped by ambient temperature.

Temperature Range in degrees Fahrenheit		Out of every ten seconds, the number of seconds the scanner heaters are active	
Low	High	Winter Cycle Disabled	Winter Cycle Enabled
--	16	4	8
17	35	3	7
36	51	2	2
52	80	1	1
80	--	Off	Off

The normal heater activation times aren't suitable for extremely cold climates, so the winter-cycle feature compensates for this. When this feature is disabled, the heater controls function normally. When enabled, the system increases the normal running time for the scanner heaters. The winter-cycle feature doesn't affect all the temperature ranges that the scanner heaters will activate on. It affects just the ones that are considered extremely cold.

**a** Select **Winter Cycle** from the Equipment Settings menu.

The winter-cycle setting toggles between enabled (YES) and disabled (NO). The Winter Cycle option on the Equipment Settings (Advanced) menu changes. The Equipment Settings (Advanced) menu reappears.

**b** Return to step 3.

**12** To change the current **transducer-gain** setting:

The Equipment Settings (Advanced) menu shows whether the transducer-gain setting is normal or high. Regardless of the setting, the SmartScanNG<sup>2</sup> system starts every train with the transducer input comparator set to high mode. Then, if the train is traveling 20 mph (32 kph) or more and if the transducer gain is set to normal mode, the transducer input comparator switches to normal mode. This means that it is rarely necessary to set this option to high.

When the comparator is in high mode, the comparator converts lower voltage pulses from the transducer into output pulses. This causes the system to be more sensitive to transducer output. When the comparator is in normal mode, the comparator has a better chance of filtering transducer pulses not caused by a wheel.

**a** Select **Transducer Gain** from the Equipment Settings (Advanced) menu.

The transducer-gain setting toggles between **normal** and **high**. The Transducer Gain option on the Equipment Settings (Advanced) menu changes. The Equipment Settings (Advanced) menu reappears.

**b** Return to step 3.

**13** To change the current **resistor-test** setting:

The Equipment Settings (Advanced) menu shows whether the resistor-test setting is enabled or disabled.

After a train clears a site, the system does an integrity test (when enabled) to verify that the scanners are operational and that the system can read alarm-level heat. This test consists of reading the temperature of power resistors, mounted to the back of the scanner shutters, after the shutters close. The recorded temperature of the shutter resistors is compared against expected values, which are calculated using a combination of the amount of time the shutters were open and the system battery voltage.

When the resistor integrity test is enabled, a system algorithm determines the minimum acceptable resistor temperature values for a given train. When disabled, the resistor integrity test is not performed.

The minimum required resistor temperatures for a given train are determined by the train's duration at the site and the resistor temperature baseline profile. This profile was established 20 minutes after the user calibrates the scanners with the autocalibration function. Twenty minutes is the cooling period required to allow the resistors to return to ambient temperature after autocalibration.

```

      .
      .
      .
[K] - Transducer Gain ..... Normal
[L] - AEI ..... NO
[M] - Resistor Test ..... Enabled
      .
      .
      .

```

**a** Select **Resistor Test** from the Equipment Settings (Advanced) menu.

The resistor-test setting toggles from enabled to disabled.

**b** Return to step 3.

**14** To change the current value for **gate distance** (gate width):

The Equipment Settings (Advanced) menu shows the number of inches between the centers of the gating transducers.

```

      .
      .
      .
[N] - Gate Distance ..... 24.0
[O] - Dragger Debounce Time ..... 200 ms
[P] - Pre Train Dragger Dist .... 200 ft
      .
      .
      .

```

**a** Select **Gate Distance** from the Equipment Settings (Advanced) menu.

This prompt appears.

```

Gate Distance equipment setting (default = 0.0)
Enter a value between 0.0 and 48.0:

```

The gate distance is in **nn.n** format. If the new value has less than three digits, type leading zeros, trailing zeros, or both. Thus, for 2, type **020**. The system inserts the decimal point for you. The gate distance (it is usually 24.0) can be recorded in 1/10-inch increments to reflect the actual transducer spacing. Accurate gating-transducer spacing results in accurate speed calculations.

- b** Type the three-digit number.

The Gate Distance option on the Equipment Settings menu changes. The Equipment Settings menu reappears.

- c** Return to step 3.

**15** To change the **Dragger Debounce Time**:

- a** Select **Dragger Debounce Time** from the Equipment Settings menu.

This prompt appears.

```
Dragger Debounce Time equipment setting (default = 100 ms)
Enter a value between 0 and 999:
```

If the new value has less than three digits, type leading zeros to make it three digits long or press [Enter] after typing one or two digits.

- b** Return to step 3.

**16** To change the Pre Train Dragger Distance:

- a** Select **Pre Train Dragger Dist** from the Equipment Settings menu.

This prompt appears.

```
Pre Train Dragger Dist equipment setting (default = 6 ft)
Enter a value between 0 and 999:
```

If the new value has less than three digits, type leading zeros to make it three digits long or press [Enter] after typing one or two digits.

- b** Return to step 3.

**17** To change the Pre Train High/Wide Distance:

- a** Select **Pre Train High/Wide Dist** from the Equipment Settings menu.

This prompt appears.

```
Pre Train High/Wide Dist equipment setting (default = 6 ft)
Enter a value between 0 and 999:
```

If the new value has less than three digits, type leading zeros to make it three digits long or press [Enter] after typing one or two digits.

- b** Return to step 3.

- 18** To change the **Presence Timeout Period** setting:
- a** Select **Presence Timeout Period** from the Equipment Settings (Advanced) menu.  
This prompt appears.

```
Presence Timeout Period equipment setting (default = 10 sec)
Enter a value from 5 to 30:
```

Enter the new value.

- b** Return to step **3**.
- 19** To change the **System Voltage** setting:
- a** Select **System Voltage** from the Equipment Settings (Advanced) menu.  
The setting toggles between 12v and 24v. The Equipment Settings menu reappears.
- b** Return to step **3**.

- 20** To view the **Sunshot Menu**:
- a** Select **Sunshot Menu** from the Equipment Settings (Advanced) menu.

```
Equipment Settings (Advanced)
-----
[A] - Carside Slope ..... Yes
[B] - Clearance Type ..... Light Beam
[C] - Clearance Mode ..... Multiplexed
[D] - Winter Cycle ..... Oct - Mar
[E] - Transducer Gain ..... Normal
[F] - Resistor Test ..... Enabled
[G] - Gate Distance ..... 24.0 in
[H] - Dragger Debounce Time ..... 100 ms
[I] - Pre Train Dragger Dist ..... 6 ft
[J] - Pre Train High/Wide Dist .... 6 ft
[K] - Presence Timeout Period ... 10 sec
[L] - System Voltage ..... 12v
[M] - Sunshot Menu
[N] - Transducer / Scanner Offset Menu
[P] - Carrier Detect Active State .. Low
[X] - Exit
```

21 To change the **Sunshot Menu** settings:

```
Sunshot Menu
-----
[A] - Sunshot Filter ..... Disabled
[B] - Bearing Scanner Orientation ..... 0 degrees
[C] - Latitude ..... 35.0456
[D] - Longitude ..... -85.3097
[E] - Print Sunshot Season
[X] - Exit
```

**NOTE:** The values for Bearing Scanner Orientation, Latitude, and Longitude should be entered **before** setting Sunshot Override to “Enabled”.

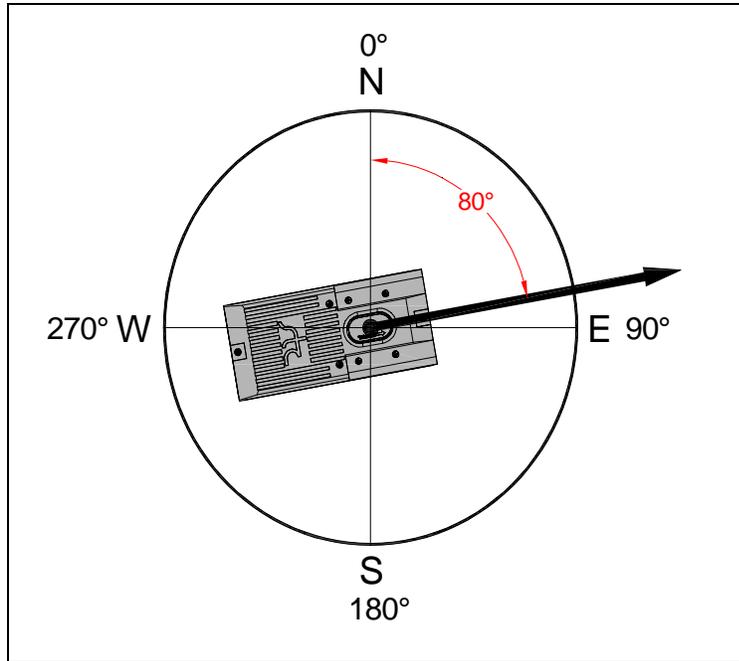
**a Sunshot Filter**

Set this option to “Enabled” to activate the Sun-Shot filtering functions. Once set to “Enabled,” exit the Sunshot Menu, Equipment Settings (Advanced), and Equipment Settings menus by pressing X three times. At this point, the detector will ask you to type the word “setup” to confirm the configuration changes made. After doing this, the NG2 stores the change(s) and starts calculating the site's sun-shot season(s) using the values stored for the Bearing Scanner Orientation, Latitude, and Longitude options.

Once the Sunshot Override option has been set to “Enabled,” the SmartscanNG<sup>2</sup> will start the calculations required to establish the sun-shot window(s) for the detector location. This process can take up to 13 hours to complete during which the SmartscanNG<sup>2</sup> functions normally (these calculations occur in the background). The sun-shot window for the current day is available approximately three minutes after the calculation process begins.

**b Bearing Scanner Orientation**

Set this parameter to the compass orientation, in degrees, at which the site's bearing scanners point. For instance, for the scanner represented in Figure 4 (below), the Bearing Scanner Orientation would be set to 80 degrees. Take care when determining the compass direction of your bearing scanners. This parameter is important and must be as accurate as possible. If you are using a compass at the site, be aware that the rails can influence the compass's accuracy. You can also use online mapping tools like Google Earth's ruler to measure the direction of the track.



**c Latitude**

For this parameter, enter the latitude of the detector location.

**d Longitude**

For this parameter, enter the longitude of the detector location.

The Dynamic Scan Window (DSW) parameters are new additions to the Sunshot menu. These options are hidden by default because they should only be modified by advanced users and only after careful consideration. They can be revealed by pressing Shift+1 (!) when the Sunshot menu is displayed. An example of the Sunshot Menu, with the DSW-related parameters (and others) displayed, is shown below.

```

Sunshot Menu
-----
[A] - Sunshot Filter ..... Disabled
[B] - Bearing Scanner Orientation ..... 0 degrees
[C] - Latitude ..... 35.0456
[D] - Longitude ..... -85.3097
[E] - Print Sunshot Season
[X] - Exit
  
```

The Dynamic Scan Window Start Sample and Dynamic Scan Window End Sample parameters narrow the window in which the detector looks for alarm-level temperature when the sunshot window is in effect. The standard/default window is from sample 0 to sample 48. This comprises the 24 inches between the two transducers (two samples are taken per inch of travel). In some applications, a tighter restriction is required (e.g., a nearly direct East/West track alignment and routine passage of open spline cars). In such cases, reducing the scan window by a few inches on either end of the scanning gate can filter most extraneous exposures of the scanner pyrometers to the sun – preventing false stops due to sunshots.

**e Print Sunshot Season**

This option displays the days and times during which a detector could experience sunshot events. The Bearing Scanner Orientation, Latitude, and Longitude values entered for the detector determine the time period(s) during which it could be susceptible to sunshots. For the NG<sup>2</sup> to return accurate results, the Sunshot Override option must previously have been enabled, and the NG<sup>2</sup> must have had time to perform its calculations.

**f Print Today's Window**

This option provides a snapshot, for the current day, of when a detector could experience sunshot events. The Bearing Scanner Orientation, Latitude, and Longitude values entered for the detector determine the time period(s) during which it could be susceptible to sunshots. For the NG<sup>2</sup> to return accurate results, the Sunshot Override option must previously have been enabled, and the NG<sup>2</sup> must have had time to perform its calculations.

**g Dynamic Scan Window Start Sample**

This option specifies the sample number on which the firmware begins evaluating bearing heat profiles for alarms. For instance, with the Window Start Sample set to 10, the firmware ignores the first ten samples when evaluating a heat profile for alarms (hot journal, differential, carside).

**h Dynamic Scan Window End Sample**

This option specifies the sample number on which the firmware stops evaluating bearing heat profiles for alarms. For instance, with the Window End Sample set to 38, the firmware ignores the last ten samples when evaluating a heat profile for alarms (hot journal, differential, carside).

**j Return to step 3.**

**22 To view the Transducer / Scanner Offset Menu:**

Select **Transducer / Scanner Offset Menu** from the Equipment Settings (Advanced) menu.

```
Equipment Settings (Advanced)
-----
[A] - Carside Slope ..... Yes
[B] - Clearance Type ..... Light Beam
[C] - Clearance Mode ..... Multiplexed
[D] - Winter Cycle ..... Oct - Mar
[E] - Transducer Gain ..... Normal
[F] - Resistor Test ..... Enabled
[G] - Gate Distance ..... 24.0 in
[H] - Dragger Debounce Time ..... 100 ms
[I] - Pre Train Dragger Dist ..... 6 ft
[J] - Pre Train High/Wide Dist .... 6 ft
[K] - Presence Timeout Period ... 10 sec
[L] - System Voltage ..... 12v
[M] - Sunshot Menu
[N] - Transducer / Scanner Offset Menu
[P] - Carrier Detect Active State .. Low
[X] - Exit
```

23 To change the **Transducer / Scanner Offset Menu** settings:

```

Transducer / Scanner Offset Menu
-----
[A] - Transducer Type ..... Frauscher (with WSC)
[B] - Rail Size ..... 136 (67.46)
[C] - Transducer Rail ..... Rail 1
[D] - East Rail Scanner Offset ..... 22 inches (T01)
[E] - West Rail Scanner Offset ..... 22 inches (T01)
[F] - East Wheel Scanner Offset ..... 0 inches (T01)
[G] - West Wheel Scanner Offset ..... 0 inches (T01)
[X] - Exit
    
```

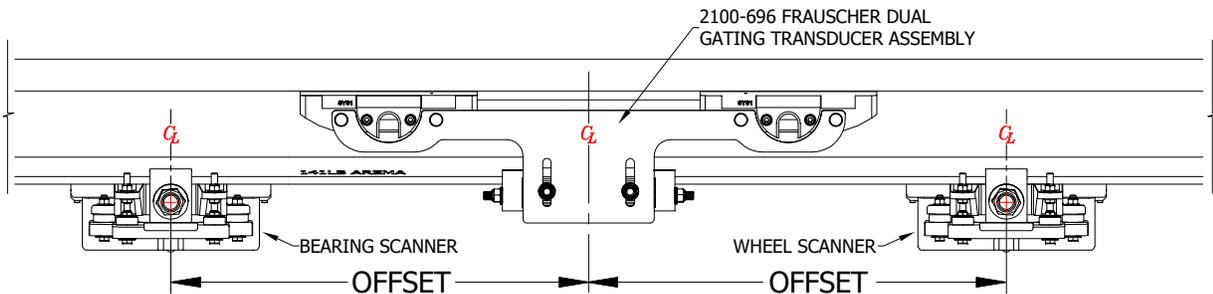
Note: If Magnetic is selected, the only option shown on the Transducer / Scanner Offset Menu is Transducer Type.

```

Transducer / Scanner Offset Menu
-----
[A] - Transducer Type ..... Magnetic
[X] - Exit
    
```

- a Select Transducer Type option to change the setting (toggles from Magnetic to Frauscher).

**NOTICE!**  
 When using Frauscher transducers, the settings for rail size and scanner offset **MUST** be entered in order for the system firmware to accurately calculate the “Virtual Gate” of each scanner. As depicted below, The scanner offset is measured from the center of the transducer bracket to the center of the scanner mounting bracket.



**b** To change the rail size, select the menu option. A prompt like this appears:

```
Select a Rail Size:
  lbs/yd (kg/m)
[A] - 100 (49.62)
[B] - 115 (57.05)
[C] - 122 (60.52)
[D] - 127 (63.00)
[E] - 132 (65.48)
[F] - 136 (67.46)
[G] - 141 (69.94)
```

Select the appropriate setting for your site.

**c** To set the scanner offset value for each scanner, select the menu option. A prompt like this appears.

```
East Rail Scanner Offset transducer setting (default = 22 inches)
Enter an OFFSET value from 0 to 100 inches:
```

Enter the appropriate offset setting for each scanner to the nearest inch.

Next, you will be prompted to select scanner orientation (this information is also necessary for “Virtual Gate” calculations).

```
Is the scanner closer to TO1 or TO2?
[1] - TO1
[2] - TO2
```

Enter the appropriate selection.

**d** Return to step 3.

## 4.2.7 Messages

To set or change any of the message parameters:

- 1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
Setup Menu
-----
[A] - Date and Time
[B] - MP/KP
[C] - Track Designation ..... Single
[D] - Track Direction ..... N/S
[E] - Alarm Settings
[F] - Equipment Settings
[G] - Messages Settings
[H] - AEI Settings
[I] - Load Default Setup Parameters
[J] - COM Port Settings
[K] - Network Settings
[L] - Talker Mode ..... Talk on Defect
[M] - N/E Integ Mode ..... 5B-Integ Fail
[N] - S/W Integ Mode ..... 5B-Integ Fail
[O] - Velocity ..... COM 3
[P] - Customer Initials ..... BNSF
[X] - Exit
```

- 2 Select the Messages menu.

A menu and prompt like this appears. The options on the Messages menu are used to affect the phrases broadcast to a passing train or are used to modify the parameters associated with the rebroadcast function.

```
Message Settings
-----
[A] - Axles ..... Yes
[B] - Speed ..... No
[C] - Temperature ..... No
[D] - Length ..... No
[E] - Slow ..... Yes
[F] - Power Off ..... No
[G] - Repeat No Defects ..... Yes
[H] - Cars Count ..... No
[I] - Customer Name ..... Yes
[J] - Arrival Message ..... No
[K] - Lft/Rt Alarm Ref ..... Yes
[L] - Car ID With Alarm ..... No
[M] - Include Details In Realtime ... No
[N] - Advanced
[X] - Exit
```

Enabling one or more of these options generates the ancillary messages: A (axle count), B (train speed), C (ambient temperature), D (train length), E (slow train), F (power off), and H (number of cars). The other options of the Messages menu aren't used to generate ancillary messages.

**3** To leave the Messages menu and return to the Setup menu:

- a** Press **[Esc]** or type **X**.  
The Setup menu reappears.
- b** Skip the remaining steps.

**4** To change the **announce-axles** setting:

The Messages menu shows whether the total axle count is to be part of (YES) or not part of (NO) post-train announcements. When the Highrange Transducer Miscounts alarm or Very Slow Train alarm occurs, the system won't announce the axle count, even when this option is enabled.

```

Messages Settings
-----
[A] - Axles ..... YES
[B] - Speed ..... NO
[C] - Temperature ..... YES
      :
      :
  
```

- a** Select **Axles** from the Messages menu.  
The announce-axles setting toggles between announce (YES) or not announce (NO). The Announce Axles option on the Messages menu changes. The Messages menu reappears.
- b** Return to step 3.

**5** To change the **announce-speed** setting:

The Messages menu shows whether the exit speed of the train is to be part of (YES) or not part of (NO) post-train announcements.

```

Messages Settings
-----
[A] - Axles ..... YES
[B] - Speed ..... NO
[C] - Temperature ..... YES
      :
      :
  
```

- a** Select **Speed** from the Messages menu.  
The announce-speed setting toggles between announce (YES) or not announce (NO). The Announce Speed option on the Messages menu changes. The Messages menu reappears.
- b** Return to step 3.

**6** To change the **announce-temperature** setting:

The Messages menu shows whether the ambient temperature (taken at the site by the shielded temperature probe as the train leaves the site) is to be part of (YES) or not part of (NO) post-train announcements.

```
Messages Settings
-----
[A] - Axles ..... YES
[B] - Speed ..... NO
[C] - Temperature ..... YES
[D] - Length ..... NO
      :
      :
```

- a** Select **Temperature** from the Messages menu.

The announce-temperature setting toggles between announce (YES) or not announce (NO). The Announce Temperature option on the Messages menu changes. The Messages menu reappears.

- b** Return to step 3.

**7** To change the **announce-train-length** setting:

The Messages menu shows whether the train length is to be part of (YES) or not part of (NO) post-train announcements. When the Highrange Transducer Miscounts alarm or Very Slow Train alarm occurs, the system won't announce length of train, even when this option is enabled.

```
Messages Settings
-----
[A] - Axles ..... YES
[B] - Speed ..... NO
[C] - Temperature ..... YES
[D] - Length ..... NO
[E] - Slow ..... YES
      :
      :
```

- a** Select **Length** from the Messages menu.

The announce-train-length setting toggles between announce (YES) or not announce (NO). The Announce Train Length option on the Messages menu changes. The Messages menu reappears.

- b** Return to step 3.

**8** To change the **announce-slow-train** setting:

The Messages menu shows whether a message indicating a slow train (one going 7 mph or slower) is to be part of (YES) or not part of (NO) post-train announcements.

- a** Select **Slow** from the Messages menu.

The announce-slow-train setting toggles between announce (YES) or not announce (NO). The Announce Slow Train option on the Messages menu changes. The Messages menu reappears.

**b** Return to step 3.

**9** To change the **announce-power-off** setting:

The Messages menu shows whether the power-off message is to be part of (YES) or not part of (NO) post-train announcements. The generation of this message depends on battery voltage, not AC power. It is generated whenever the voltage coming from the battery is less than 12.6 VDC. AC power need never have been off to cause this to happen. However, most times, it does indicate that AC power has been off, causing the battery to be drained.

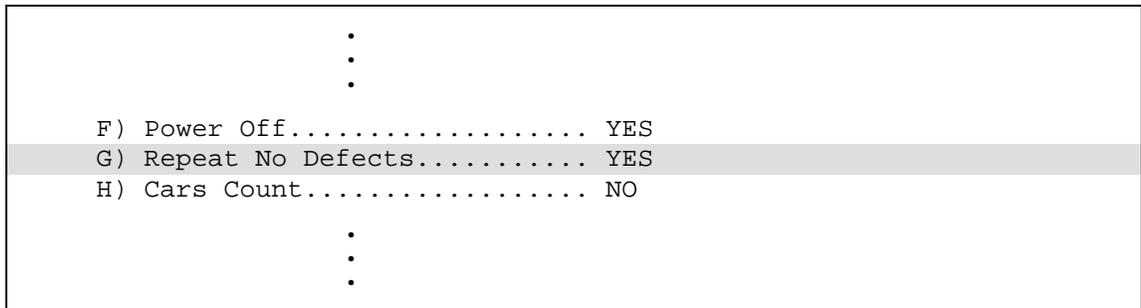
**a** Select **Power Off** from the Messages menu.

The announce-power-off setting toggles between announce (YES) or not announce (NO). The Announce Power Off option on the Messages menu changes. The Messages menu reappears.

**b** Return to step 3.

**10** To change the **repeat-no-defect-message** setting:

The Messages menu shows whether the no-defect message is to be repeated (YES) or not repeated (NO).



**a** Select **Repeat No Defects** from the Messages menu.

The repeat-no-defect-message setting toggles between enabled (YES) and disabled (NO). The Repeat No Defects option on the Messages menu changes. The Messages menu reappears.

**b** Return to step 3.

**11** To change the **announce-number-of-cars** setting:

The Messages menu shows whether the number of cars is to be part of (YES) or not part of (NO) post-train announcements.

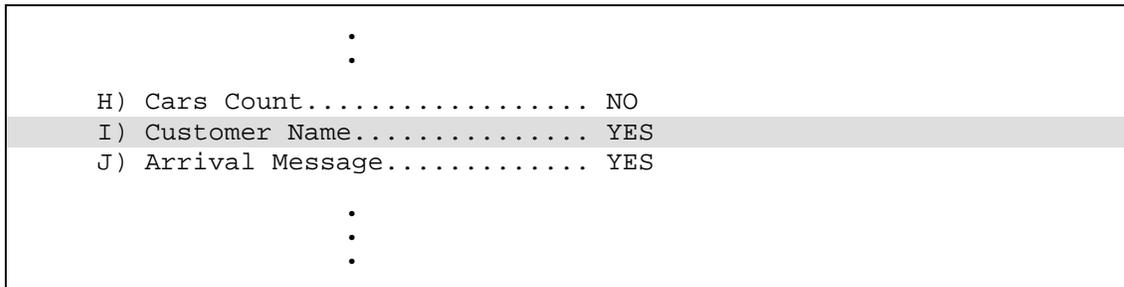
**a** Select **Cars Count** from the Messages menu.

The announce-number-of-cars setting toggles between announce (YES) or not announce (NO). The Announce Number of Cars option on the Messages menu changes. The Messages menu reappears.

**b** Return to step 3.

**12** To change the **announce-customer-name** setting:

The Messages menu shows whether the customer's railroad name is to be part of (YES) or not part of (NO) of all announcements.



- a** Select **Customer Name** from the Messages menu.

The announce-customer-name setting toggles between announce (YES) or not announce (NO). The Announce Customer Name option on the Messages menu changes. The Messages menu reappears.

- b** Return to step 3.

**13** To change the **announce-arrival-message** setting:

The Messages menu shows whether an arrival message announces (YES) or doesn't announce (NO) train arrival at the site.

- a** Select **Arrival Message** from the Messages menu.

The announce-arrival-message setting toggles between announce (YES) or not announce (NO). The Announce Train Arrival option on the Messages menu changes. The Messages menu reappears.

- b** Return to step 3.

**14** To change the **left-right-alarm-reference** setting:

The Messages menu shows whether the alarm reference is announced as left or right (YES) or as north, south, east, or west (NO).

- a** Select **Lft/Rt Alarm Ref** from the Messages menu.

The left-right-alarm-reference setting toggles between YES and NO. The Announce Left-Right Alarm Reference option on the Messages menu changes. The Messages menu reappears.

- b** Return to step 3.

**15** To change the **Car ID With Alarm** setting:

The Messages menu shows whether car-identification information is to be announced (YES) or not announced (NO). When this option is set to YES, and an Exception Alarm is found on a car, the car-identification information is included in the post-train announcement for the train having the Exception Alarm. This, of course, will only happen if the AEI option on the Equipment Settings menu is enabled (YES) and the AEI subsystem is functioning properly during train passage.

```
      .  
      .  
      .  
[L] - Car ID With Alarm ..... No  
[M] - Announce Differentials ..... No  
[O] - Advanced  
[X] - Exit
```

**a** Select **Car ID With Alarm** from the Messages menu.

The announce-car-identification setting toggles between enabled (YES) and disabled (NO). The Announce Car Identification option on the Messages menu changes. The Messages menu reappears.

**b** Return to step 3.

**16** To change the setting for **Differentials** announcements:

Select the menu option to toggle the current status of announcement from enabled (YES) to disabled (NO).

```
      .  
      .  
      .  
[L] - Car ID With Alarm ..... No  
[M] - Announce Differentials ..... No  
[O] - Advanced  
[X] - Exit
```

**17** To view Messages Settings (Advanced):

Select **Advanced** from the Messages Settings.

```
      .  
      .  
      .  
[L] - Car ID With Alarm ..... No  
[M] - Announce Differentials ..... No  
[O] - Advanced  
[X] - Exit
```

**18 To change Announce Hot Wheels or Announce High/Wide settings:**

```
Messages Settings (Advanced)
-----
[A] - Announce Hot Wheels ..... Yes
[B] - Announce High/Wide ..... Yes
[C] - Rebroadcast Time Limit ..... 5 min
[D] - Rebroadcast DTMF Code ..... 001
[E] - Num EOT Repeats ..... 1
[F] - EOT Repeat Delay ..... 5 sec
[X] - Exit
```

Select the menu item to step through options Yes, N/E Only, S/W Only, or No.

**19 To change the Rebroadcast Time Limit setting:**

- a** Select **Rebroadcast Time Limit** from the Messages menu.

This prompt appears.

```
Rebroadcast Time Limit message setting (default = 5 min)
Enter a value from 0 to 999:
```

If the new limit has less than three digits, type leading zeros.

- b** Type the three-digit value.
- c** Return to step 3.

**20 To change the rebroadcast-DTMF-code setting:**

The Messages menu shows the rebroadcast-DTMF-code setting. The stored DTMF code is the touchtone digits that trigger a rebroadcast. Up to three digits may be entered into this setup parameter. The SmartScanNG<sup>2</sup> system monitors radio traffic. When it receives the proper DTMF code, it will rebroadcast the last end-of-train message, provided the request EOT timer hasn't expired.

```
Messages Settings (Advanced)
-----
[A] - Announce Hot Wheels ..... Yes
[B] - Announce High/Wide ..... Yes
[C] - Rebroadcast Time Limit ..... 5 min
[D] - Rebroadcast DTMF Code ..... 001
[E] - Num EOT Repeats ..... 1
[F] - EOT Repeat Delay ..... 5 sec
[X] - Exit
```

- a Select **Rebroadcast DTMF Code** from the Messages menu.

This prompt appears.

```
Rebroadcast DTMF Code message setting (default = 001)
Enter a DTMF code (Esc to clear):
```

- b Type the new DTMF code or press **[Esc]**.
- c If you typed one or two digits, press **[Enter]**.

The Rebroadcast DTMF Code option on the Messages menu changes and the Messages menu reappears. If you typed only nondigits and then pressed **[Enter]**, the rebroadcast function would be turned off.

- d Return to step 3.

**21** To change the **number-of-repeats** setting:

The Messages menu shows a value for how many times the EOT announcement should be repeated. Valid values range from 0 through 5. When set to zero, the EOT announcement is spoken once with no repeats. When set to five, the EOT announcement is spoken once with five repeats for a total number of six times.

```
Messages Settings (Advanced)
-----
[A] - Announce Hot Wheels ..... Yes
[B] - Announce High/Wide ..... Yes
[C] - Rebroadcast Time Limit ..... 5 min
[D] - Rebroadcast DTMF Code ..... 001
[E] - Num EOT Repeats ..... 1
[F] - EOT Repeat Delay ..... 5 sec
[X] - Exit
```

- a Select **Num EOT Repeats** from the Messages menu.

This prompt appears.

```
Num EOT Repeats message setting (default = 1)
Enter a value between 0 and 5:
```

- b To not change the value, press **[Esc]** and return to step 3.
- c Type a digit less than 6.

All typed nondigits are ignored.

If you type a value greater than 5, this error message and prompt appear.

```
Invalid value specified
```

If you type an acceptable value, the Number of Repeats option on the Messages menu changes, and the Messages menu reappears.

- d If you get an error message, return to step **b**.
- e If you don't get an error message, return to step **3**.

**22** To change the time-between-repeats setting:

The Messages menu shows a value for how many seconds should elapse between EOT announcement repeats. Valid values range from 0 through 360.

```

      .
      .
      .
[E] - Num EOT Repeats ..... 1
[F] - EOT Repeat Delay ..... 5 sec
[X] - Exit

```

- a Select **EOT Repeat Delay** from the Messages menu.

This prompt appears.

```

EOT Repeat Delay message setting (default = 10)
Enter a value between 0 and 999:

```

If the new value has less than three digits, type leading zeros to make it three digits long or press **[Enter]** after typing one or two digits.

- b To not change the value, press **[Esc]** and return to step **3**.

### 4.2.8 AEI Reader Parameters

The AEI reader parameters directly affect how the AEI readers operate to acquire tags while a train is passing the site.

To set or change any of the AEI reader parameters:

- 1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```

      .
      .
[G] - Messages Settings
[H] - AEI Settings
[I] - Load Default Setup Parameters
      .
      .

```

## 2 Select **AEI Settings** to access menu options.

```
AEI Settings
-----
[A] - ID Separation ..... 2 IDs
[B] - Consecutive Reads ..... 2 Reads
[C] - MPRR Frequency ..... 915.000 MHz
[D] - MPRR Attenuation ..... 0
[E] - Multi-Track Tag Filter .. Disabled
[F] - AEI Reader Interface
[G] - Tag Reader Test
[X] - Exit
```

**ID Separation** specifies the number of intervening tags that must be read and reported before a given tag is reported again. Valid values are 1, 2, 3, and 4. The default is 2.

**Consecutive Reads** specifies the number of times that a tag must be read before it is considered a valid (reportable) tag. Valid values are 1, 2, 3, and 4. The default is 2.

**MPRR Frequency** specifies the transceiver frequency of the MPRR reader.

**MPRR Attenuation** sets the RF attenuation in 1 dB increments over a range of 10 dB from a maximum output of 2 W at 0-dB attenuation to a minimum of 200 mW output at 10-dB attenuation.

- The **Multi-Track Tag Filter**, when enabled, uses firmware algorithms to filter cross-track reads based on appended timestamps and tag data shared from adjacent readers.

The **AEI Reader Interface** allows for direct communication with the AEI reader and is used primarily for diagnostic purposes.

- The **Tag Reader Test** will allow you to wave a tag in front of the reader, and the detector will produce an audible beep and print out the tag information. The detector will simulate a track circuit signal and energize the antennas. Afterward, the log will show a Train Canceled event.

### 3 To change the **ID Separation** parameter:

Select the **ID Separation** option to toggle from 1 to 2, from 2 to 3, from 3 to 4, or from 4 to 1.

### 4 To change the **Consecutive Reads** parameter:

Select the **Consecutive Reads** option to toggle from 1 to 2, from 2 to 3, from 3 to 4, or from 4 to 1.

- 5 Select the **MPRR Frequency** setting to change the operating frequency.

This message appears.

```
Select a frequency:  
[A] - 903.750 MHz  
[B] - 911.500 MHz  
[C] - 915.000 MHz  
[D] - 918.500 MHz  
[E] - 921.500 MHz
```

Enter frequency selection. The AEI Reader Parameters menu reappears.

- 6 Select **MPRR Attenuation** to attenuate the RF output signal.

This message appears.

```
MPRR Attenuation AEI setting (default = 0)  
Enter a value between 0 and 10:
```

Enter a value "NN" (between 1 and 10), including leading zeros. This parameter sets the RF attenuation in 1 dB increments over a range of 10 dB from a maximum output of 2 W at 0-dB attenuation to a minimum of 200 mW output at 10-dB attenuation.

- 7 Select **Multi-Track Tag Filter** to toggle between **Enabled** and **Disable**.

When enabled, firmware algorithms are utilized to filter out cross-track reads.

- 8 To enter the **AEI reader interface**, select option.

This message appears.

```
Entering AEI Reader Interface  
<Type EXIT to quit>
```

- 9 To leave the AEI reader interface:

- a Type **EXIT**
- b Press **[Enter]**.

- 10 To leave the AEI Reader Parameters menu and return to the Setup menu, type **X**.

This prompt appears.

```
Initialize Reader now (Y/N)
```

- 11 To initialize the reader, type **Y**.

The Setup menu reappears.

- 12 To not initialize the reader, type **N**.

The Setup menu reappears.

- 13 Select **Tag Reader Test** to initiate test mode.

## 4.2.9 Load Default Setup Parameters

An option to load default setup parameters was included to assist installers in setting up a new system. When this menu item is selected, the parameters listed below are assigned the values listed below. A "yes" after a parameter means that it is "enabled." A "no" means that it is "disabled." The blanks after "Rebroadcast DTMF Code" mean that it is disabled.

Alarm Settings	
-----	-----
Absolute..... 170	Differential..... 150
Hot Wheel..... 900	Cold Rails..... 3
Cold Rail Temp..... 10	Cold Res Counter..... 3
Differential Enabled..... Yes	
Alarm Settings (Advanced)	
-----	-----
Carside Slope..... 1.31	Carside Minimum..... 155
Res Test: Minimum Rail Avg..... 25	Res Test: Minimum Wheel Avg..... 28
Bearing DSR Capture Temp..... 100	Wheel DSR Capture Temp..... 300
Max Alarms..... 13	
Equipment Settings	
-----	-----
Dragger..... Yes	Hot Wheel..... Yes
Hot Bearing..... Yes	High Load..... No
Wide Load..... No	AEI..... No
Presence Hardware..... Yes	Advance Transducers..... No
Scanner Heater AC Monitor..... Yes	Main AC Power Monitor..... No
DC Power Monitor..... No	Surge Protector Monitor..... No
Equipment Settings (Advanced)	
-----	-----
Carside Slope..... Yes	Winter Cycle..... Oct - Mar
Gate Distance..... 24.0 in	Dragger Debounce Time..... 100 ms
Pre Train Dragger Dist..... 6 ft	Pre Train High/Wide Dist..... 6 ft
Presence Timeout Period..... 10 sec	System Voltage..... 12 V
Resistor Test..... Enabled	Clearance Mode..... Multiplexed
Clearance Type..... Light Beam	Transducer Gain..... Normal
Transducer Type..... Magnetic	
Message Settings	
-----	-----
Arrival Message..... No	Customer Name..... Yes
Axles..... Yes	Speed..... No
Temperature..... No	Slow..... Yes
Power Off..... No	Repeat No Defects..... Yes
Length..... No	Cars Count..... No
Lft/Rt Alarm Ref..... Yes	Car ID With Alarm..... No
Announce Differentials..... No	Include Details In Realtime..... No
Message Settings (Advanced)	
-----	-----
Announce Hot Wheels..... No	Announce High/Wide..... Yes
Rebroadcast Time Limit..... 5 min	Rebroadcast DTMF Code..... 001
Num EOT Repeats..... 1	EOT Repeat Delay..... 5 sec
.	
.	
.	



To load the default setup parameters:

- 1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
      .  
      .  
      .  
[H] - AEI Settings  
[I] - Load Default Setup Parameters  
[J] - COM Port Settings  
[K] - Network Settings  
[L] - Talker Mode ..... Talk on Defect  
[M] - N/E Integ Mode ..... 5A-Maint Req  
[N] - S/W Integ Mode ..... 5A-Maint Req  
[O] - Velocity ..... COM 3  
[P] - Customer Initials ..... BNSF  
[X] - Exit
```

- 2 Select **Load Default Setup Parameters**.

This prompt appears.

```
This will save the settings.  
Are you sure? (y/n)
```

- 3 To not load default setup parameters:

Type **N**.

This message appears, followed by the Setup menu.

```
Settings will not be saved
```

- 4 To load default setup parameters:

Type **Y**.

This message appears, followed by the Setup menu.

```
Please type 'setup' to save settings.  
Press escape to abandon changes.
```

Type “setup” to save settings.

```
Saving settings  
Settings saved
```

Loading takes about a second. When finished, the Setup menu reappears.

## 4.2.10 COM1, COM2, COM3, COM4, & COM6

To change the parameters for serial port **COMx**:

- 1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
      .
      .
      .
[J] - COM Port Settings
[K] - Network Settings
[L] - Talker Mode ..... Talk on Defect
[M] - N/E Integ Mode ..... 5A-Maint Req
[N] - S/W Integ Mode ..... 5A-Maint Req
[O] - Velocity ..... COM 3
[P] - Customer Initials ..... BNSF
[X] - Exit
```

- 2 Select the **COM Port Settings** submenu to view options.

```
COM Port Settings
-----
[A] - COM1 19200
[B] - COM2 19200
[C] - COM3 19200
[D] - COM4 19200
[E] - COM6 19200
[F] - RS485 9600
[G] - Page Lines ..... 30
[X] - Exit
```

- 3 Select the **COMx** option to edit current settings.

```
Uart Settings
-----
[A] - Baud Rate ..... 19200
[B] - Flow control ..... None
[X] - Exit
```

- 4 To change the **Baud Rate**, type **A** to incrementally step through the selection options. Available settings are: 150, 300, 600, 1200, 2400, 4800, 9600, 19200, 38400, 57600, and 115200.
- 5 To change the **Parity** setting, type **B** to incrementally step through selection options. Available settings are None, Multi, Odd, and Even.
- 6 If you are done changing the parameters for **COMx**, type **X**.  
The Setup menu reappears.

## 4.2.11 Network Settings

To change the **Network Settings**:

- 1 Be sure that the Setup menu is displayed.

The Setup Menu looks like this.

```
      :
      :
[K] - Network Settings
[L] - Talker Mode ..... Talk on Defect
[M] - N/E Integ Mode ..... 5A-Maint Req
[N] - S/W Integ Mode ..... 5A-Maint Req
[O] - Velocity ..... COM 3
[P] - Customer Initials ..... BNSF
[X] - Exit
```

- 2 Select the **Network Settings** menu.

A menu and prompt like this appears. To access/change any of the menu options, type the letter that corresponds to the desired setting.

```
Network Settings
-----
[A] - IP Settings
[B] - Use Wifi ..... No
[C] - Wifi Inactivity Timeout ... 10 min
[D] - HTTP port ..... 80
[E] - HTTPS port ..... 8080
[F] - FTP port ..... 21
[G] - TELNET port ..... 23
[H] - Load default network settings
[X] - Exit
```

## 4.2.12 Talker Mode

The Talker Mode option lets you select whether announcements are made when a train with no alarms or integrity failures is scanned. The Talk Freely mode is the normal talker mode. In this mode, the system makes announcements even when defects are not detected. In Talk on Defect mode, the system makes announcements only when an alarm or integrity failure is detected. The default Talker Mode is Talk Freely.

To change the **Talker Mode** setting:

- 1 Be sure that the Setup menu is displayed.

The Setup Menu looks like this.

```
      .  
      .  
      .  
[L] - Talker Mode ..... Talk on Defect  
[M] - N/E Integ Mode ..... 5A-Maint Req  
[N] - S/W Integ Mode ..... 5A-Maint Req  
[O] - Velocity ..... COM 3  
[P] - Customer Initials ..... BNSF  
[X] - Exit
```

- 2 Select **Talker Mode** to toggle the setting. Available options are Talk on Defect or Talk Freely.

### 4.2.13 Integrity Mode

The N/E Integ Mode and S/W Integ Mode options let you select the integrity classification, 5A or 5B, for trains traveling in the N/E direction and the S/W direction.

With integrity classification mode 5A, any dragger or clearance-related integrity failure condition will result in an "Integrity Failure" announcement, and any other integrity failure condition will result in a "Maintenance Required" announcement.

With mode 5B, any detected integrity failure condition will result in an "Integrity Failure" announcement.

To change the **Integrity Mode** setting:

- 1 Be sure that the Setup menu is displayed.

The Setup Menu looks like this.

```
      .  
      .  
      .  
[L] - Talker Mode ..... Talk on Defect  
[M] - N/E Integ Mode ..... 5A-Maint Req  
[N] - S/W Integ Mode ..... 5A-Maint Req  
[O] - Velocity ..... COM 3  
[P] - Customer Initials ..... BNSF  
[X] - Exit
```

- 2 Select **N/E Integ Mode** or **S/W Integ Mode** to toggle between the 5A or 5B settings.

## 4.2.14 Velocity

The Velocity setting indicates to which of the NG<sup>2</sup>'s comm ports the installed Velocity module is connected. To change the **Velocity** setting:

- 1 Be sure that the Setup menu is displayed.

The Setup Menu looks like this.

```
      .  
      .  
      .  
[O] - Velocity ..... COM 3  
[P] - Customer Initials ..... BNSF  
[X] - Exit
```

- 2 Select **Velocity** to step through COM port settings. Available options are COM2, COM3, COM4, COM6, or Disabled.

## 4.2.15 Customer Initials

To change the **Customer Initials** setting:

- 2 Be sure that the Setup menu is displayed.

The Setup Menu looks like this.

```
      .  
      .  
      .  
[O] - Velocity ..... COM 3  
[P] - Customer Initials ..... BNSF  
[X] - Exit
```

- 3 Select **Customer Initials** to enter the new setting.

## 4.3 System Functions Menu

To execute one or more system functions:

- 1 Be sure that the Main menu is displayed.

The Main menu looks like this.

```
      .  
      .  
      .  
[J] - Event log  
[K] - System Functions Menu  
[L] - Replay train  
[M] - Security Menu  
[X] - Exit
```

## 2 Select the System Functions menu.

A menu and prompt like this appears. To access any of the System Functions menu options, type the letter that corresponds to the desired menu option.

```
System Functions Menu
-----
[A] - Radio Test
[B] - Vocabulary Test
[C] - Radio Inhibit
[D] - Start Manual Train
[E] - 1KHz Test Tone
[F] - Auto-Calibration
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[J] - Update Menu
[K] - Maintenance Menu
[L] - Volume up (3)
[M] - Volume down (3)
[N] - Resistor Baseline Data
[O] - Radio Programming Menu
[P] - Scanner test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual gate test
[X] - Exit
```

If a train is at the site when the System Functions menu is generated, "\*\*\*\* **Train Is Present** \*\*\*\*" is displayed just above the menu header for the System Functions menu. During that time, if you select any item on the System Functions menu, you will be prompted with "**Train Is Present. Continue?**" You must type **Y** to continue. Note that most items on the Systems Functions menu should not be performed while a train is present at the site.

## 3 To leave the System Functions menu and return to the Main menu:

- a Type **X**. The Main menu reappears.
- b Skip the remaining steps.

## 4 To execute the **radio test**:

The **Radio Test option** on the System Functions menu is used to broadcast a short message through the speaker and through the radio. Using this option lets you verify that the speaker and radio are working properly.

At single-track sites, the text of the message is usually "Testing, BNSF, milepost (*milepost number*), testing, one, two, three, four, five, four, three, two, one, testing." At multitrack sites, the text of the message is usually "Testing, BNSF, milepost (*milepost number*), track (*track designation*), testing, one, two, three, four, five, four, three, two, one, testing."

```
System Functions Menu
-----
[A] - Radio Test
[B] - Vocabulary Test
      .
      .
      .
```

- a Select **Radio Test** from the System Functions menu.

If the system isn't currently making any other voice announcements, it begins the Radio Test announcement. After the announcement finishes, the System Functions menu reappears.

If the system is currently making a voice announcement, the firmware displays the message "System Is Currently Making Voice Announcements! Try Again Later" and redisplay the System Functions menu.

- b While listening to the message, look at the PTT LED on the display panel.

The **PTT LED** should be lit.

If this LED isn't lit, the system's ability to send a message to the radio might be inhibited by the Radio Inhibit option on the System Functions menu. If the radio is inhibited, the results of this check are invalid.

- c Return to step 3.

5 To execute the **vocabulary test**:

The **Vocabulary Test option** on the System Functions menu is used to enunciate all of the stored speech phrases. This announcement is broadcast through the speaker, but not through the radio. Therefore, it isn't affected by the **Radio Inhibit option** being enabled.

The text of the message is "zero, one, two, three, four, five, six, **beep**, seven, eight, nine, not-working, **beep**, BNSF, milepost, main-3, system-working, no-defects, main-1, main-2, rebroadcast, hotwheel, defect, axle, dragging-equipment-near, north, south, third, fourth, rail, east, west, track, through, hot Journal, Shifted Load-near, you-have-a-defect, testing, inspect-from, train-too-slow, total-axles, speed, temperature, length, minus, point, first, second, inspect-remainder-of- train, left, right, side, load, middle, high-load, wide-load, power-off, excess-alarms, repeat, X, Y, Z, total-cars, detector-out, detector-alarm, scanner-resistor-test, beginning-in, minutes, A, B, C, D, E, F, G, H, I, J, K, L, M, N, O, P, Q, R, S, T, U, V, W, X, Y, Z, car-ID, no, alarm."

```
System Functions Menu
-----
[A] - Radio Test
[B] - Vocabulary Test
[C] - Radio Inhibit
      .
      .
      .
```

- a Select **Vocabulary Test** from the System Functions menu.

If the system isn't currently making any other voice announcements, it begins the Vocabulary Test announcement. After the announcement finishes, the System Functions menu reappears.

If the system is currently making a voice announcement, the firmware displays the "System Is Currently Making Voice Announcements! Try Again Later" message and the System Functions menu reappears.

- b Return to step 3.

**6 To execute the radio inhibit:**

The Radio Inhibit option is used to prevent radio activation for three minutes. During this time, any announcements generated by the system are broadcast through the speaker, but not through the radio. This feature may be overridden by recalling this submenu and then typing **N**.

```
System Functions Menu
-----
[A] - Radio Test
[B] - Vocabulary Test
[C] - Radio Inhibit
      .
      .
      .
```

- a Select **Radio Inhibit** from the System Functions menu.

This prompt appears.

```
PTT disabled for 3 minutes
```

- b Select Re-enable radio PTT to disable Radio Inhibit.

```
System Functions Menu
-----
[A] - Radio Test
[B] - Vocabulary Test
[C] - Re-enable radio PTT
      .
      .
      .
```

- c Return to step 3.

**7 To initiate the Start Manual Train function:**

In Manual Train Mode, the system opens all the shutters and simulates transducer pulses for about one minute. During this time, a person can check various aspects of the installed components. In this mode, the system runs the ramp function without generating heats. The train is marked as a test train. There won't be any voltage applied to the scanner inputs.

This is a timed test that should gate approximately 164 simulated axles. You can stop this test by selecting the Stop Manual Train option.

The data generated for this test train is stored in the Test Train directory, which contains data on the last test train only. The Last Test Train report gets its data from this directory.

```
System Functions Menu
-----
[A] - Radio Test
[B] - Vocabulary Test
[C] - Radio Inhibit
[D] - Start Manual Train
[E] - 1KHz Test Tone
      .
      .
      .
```

- a Select **Start Manual Train** from the System Functions menu.

This prompt appears.

```
Train Arrival
```

There will be an arrival message broadcast through the speaker only. During the test train, the TO1 & TO2 LEDs on the Display Panel will flash with each simulated axle.

After about a minute, this prompt appears and the post train announcements will be broadcast over the speaker.

```
Train Departure
```

- b Return to step 3.

**8** To generate the **1KHz test tone**:

The 1KHz Test Tone option is used to generate a continuous 1KHz tone for about 5 seconds. This test tone is to broadcast through the speaker and the radio.

- a Select **1KHz Test Tone** from the System Functions menu.

If the system isn't currently making any other voice announcements, it begins the tone.

If the system is currently making a voice announcement, the firmware displays the message "System Is Currently Making Voice Announcements! Try Again Later" and redisplay the System Functions menu.

- b While listening to the tone, look at the PTT LEDs on the display panel.

The **PTT LED** should be lit.

If this LED isn't lit, the system's ability to send a tone to the radio might be inhibited by the Radio Inhibit option on the System Functions menu. If the radio is inhibited, the results of this check are invalid.

- c Return to step 3.

## 9 To start **Auto-Calibration**:

The SmartScanNG<sup>2</sup> system self-calibrates its pyrometer interface circuitry. You need only put a preheated calibrated heat source on a scanner and place the system in autocalibration mode by using the Auto-Calibration option. The system then scans all pyrometer inputs until the signal from the calibrated heat source is located. The necessary adjustments to the related interface circuitry are automatically made while the system monitors its own progress by analyzing changes in the heat signals. Once the procedure has been completed, autocalibration mode is disengaged, and the calibration results are displayed on your computer. For more details, see **Appendix D - Calibration of Type III Scanners**.

- a Place a preheated calibrated heat source on the scanner to be calibrated.
- b Select **Auto-Calibration** from the System Functions menu.

The SmartScanNG<sup>2</sup> system will now calibrate the channel associated with the scanner on which the heat source has been placed. Follow along on your interface screen until you see "Auto-Calibration Disengaged." This message is an indication that the system is done with the calibration procedure. To abort the process, press **[Esc]** (on your computer) or remove the heat source (from the scanner).

- c When "Auto-Calibration Disengaged" is displayed on your computer, remove the calibrated heat source.

Upon completion of autocalibration, the system acquires the scanner resistor temperature baseline values. The process begins with a 20-minute wait period in which the resistors are allowed to cool down. The system counts down during this period, sounding a tone each minute. After the 20-minute cooldown period, the system opens and closes the shutters for a period of 8 minutes.

- d Return to step 3.

## 10 To force a **system reset**:

The Remote System Reset option allows you to force a system reset through a remote connection. It can also be used locally.

- a Select **Remote System RESET** from the System Functions menu.

This prompt appears.

```
Remote System RESET
Are you sure? (y/n)
```

- b To not reset the system:

- Type **N**.

The System Functions menu reappears.

- Return to step 3.

- c To reset the system, type **Y**.

This message appears.

```
Restarting in 2 seconds
Waiting 2sec to start 'A' to abort
Configured IP = 0.0.0.0
Configured Mask = 0.0.0.0
MAC Address= 00:03:f4:08:8c:fe

Comm is booting...
Starting telnet task on port 23... running.

The system has finished booting.
```

If connected locally, after a few seconds, the prompt “Press ESC for the Main Menu” appears.

- d Return to step 3.

### 11 To delete all stored train data:

The Delete All Stored Train Data option allows you to erase all stored train data. This encompasses all data on the trains in the Trains directory, Exceptions directory, and Test Train directory. After deleting all the train data, there isn't any way of regenerating it. The data is gone forever.

```
      .
      .
      .
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[K] - Update Menu
      .
      .
      .
```

- a Select **Delete All Stored Train Data** from the System Functions menu.

This prompt appears.

```
Are you sure? (y/n)
```

- b To not delete all stored train data:

- Type **N**.

The System Functions menu reappears.

- Return to step 3.

- c To delete all stored train data, type **Y**.

This message appears.

```
Train data cleared.
```

d Return to step 3.

## 12 To delete all events stored in the Event Log:

The Clear Event Log option is used to erase all events stored in the Event Log and displayed on the Event Log report. After deleting the log, there isn't any way of regenerating it. The data is gone forever.

```
      .
      .
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[J] - Update Menu
      .
      .
```

a Select **Clear Event Log** from the System Functions menu.

This prompt appears.

```
Are you sure? (y/n)
```

b To not delete all events stored in the Event Log:

- Type **N**.

The System Functions menu reappears.

- Return to step 3.

c To delete all events stored in the Event Log, type **Y**.

The System Functions menu reappears.

d Return to step 3.

## 13 Update Menu (software update):

```
      .
      .
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[J] - Update Menu
[K] - Maintenance Menu
      .
      .
```

a Select **Update Menu** from the System Functions menu.

This prompt appears.

```
Update Menu
-----
[A] - Select Update File
[X] - Exit
```

- b** Choose the **Select Update File** from the Update Functions menu.

This prompt appears.

```
Select update file:
[A] - NS_00-69.ng
[B] - NS_00-70.ng
```

- d** Select the appropriate file from the menu options and follow the prompts to update the NG<sup>2</sup>'s software.

**14** To view **the** maintenance menu:

```
      :
      :
[K] - Maintenance Menu
[L] - Volume up (3)
[M] - Volume down (3)
      :
      :
```

Select the **Maintenance Menu** from the System Functions menu.

A prompt like this appears.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
06/10/2020 08:42:03, 13.9V, 69°F
Maintenance Menu
-----
[A] - View maintenance statistics
[B] - Reset System Health
[C] - Re-evaluate last 40 trains.
[D] - Maintenance email list
[X] - Exit
```

**15** To view maintenance statistics:

Select the **View Maintenance Statistics** option from the maintenance menu.

Information like this is displayed.

```
Calculating statistics ...

-----
STATISTICS                               Trains Evaluated: 40   Days Spanned: 3
-----
Scanner      Max Avg      Resistor Avg  Cold  Cold  Resistor  Amb
              Max Avg      Max Avg  Scanner Resistor  Batt  Temp
              Max Avg      Max Avg  cnt  %  cnt  %
-----
East Brng    63  11  282  242  0  1  2  0  0  Avg  13.8  +67
West Brng    57  12  300  281  0  1  2  0  0  Max  13.9  +74
East Whl    144  1  299  276  0  0  0  0  0  Min  13.7  +65
West Whl    268  24  298  257  0  0  0  0  0
-----
Transducer Data
-----
Total Axles Scanned..... 13283
Total Txd. Miscounts..... 5
Percent Miscounts..... 0.04%
Trains With Miscounts..... 3
Trains In Sample..... 40
Percent Trains W/ Miscounts.. 7.5%
-----

Hardware Status
-----
East Bearing Scanner.....Pass
West Bearing Scanner.....Pass
East Wheel Scanner.....Pass
West Wheel Scanner.....Pass
Gating Transducers.....Needs Attention
Possible Cause: Slow train movements, improper loading of transducers,
transducer connections intermittent, transducer not adjusted correctly
on rail, or defective transducer
5% had Reverse Direction Detected

Ambient Temperature Probe.....Pass
Power.....Pass
Presence Hardware.....Pass
Dragger.....Disabled
High Load Detector.....Disabled
Wide Load Detector.....Disabled
AEI Subsystem.....Pass
```

**16** To reset system health:

```
Maintenance Menu
-----
[A] - View maintenance statistics
[B] - Reset System Health
[C] - Re-evaluate last 40 trains.
[D] - Maintenance email list
[X] - Exit
```

**a** Select **Reset System Health** from the Maintenance menu.

A prompt like this appears.

```
Are you sure? (y/n)
```

**b** To not reset system health:

- Type **N**.

The Maintenance Menu reappears.

**c** To reset system health, type **Y**. This prompt appears.

```
System health cleared
```

The Maintenance Menu reappears.

**17** To re-evaluate the last 40 trains:

**a** Select **Re-evaluate last 40 trains** from the Maintenance menu.

A prompt like this appears.

```
Are you sure? (y/n)
```

This option allows you to reload the statistics from the last 40 trains after system health has been reset.

**b** Type **X** to return to the System Functions menu.

**18** To access **Maintenance email list**:

```
Maintenance Menu
-----
[A] - View maintenance statistics
[B] - Reset System Health
[C] - Re-evaluate last 40 trains.
[D] - Maintenance email list
[X] - Exit
```

**a** Select **Maintenance email list** from the Maintenance menu.

A prompt like this appears.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
06/10/2020 09:07:51, 13.9V, 69°F
Maintenance email list
-----
[A] - southern.technologies.corp@gmail.com
[B] - bwalls@southern-tech.com
[P] - New email address
[Q] - Email subject: Tyner Track 2
[X] - Exit
```

**b** Select **New email address** to add a new address or select existing address to edit or delete from the list.

- c Type Q to edit email subject.
- d Type X to return to the System Functions menu.

**19** To adjust speaker volume:

```

      .
      .
[L] - Volume up (3)
[M] - Volume down (3)
[N] - Resistor Baseline Data
      .
      .

```

There are 10 selectable volume levels (0-9). Level-0 is minimum volume and Level-9 is the maximum volume. The current volume setting is indicated in parenthesis.

- a From the System Functions menu, select **Volume up** to increment current volume level or **Volume down** to decrement level.
- b Return to step 3.

**20** To view **Resistor Baseline Data**:

```

      .
      .
[N] - Resistor Baseline Data
[O] - Radio Programming Menu
[P] - Scanner test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual gate test
[X] - Exit

```

- a Select **Resistor Baseline Data** from the System Functions menu.

A prompt like this appears.

Resistor Data																						
VOLTS	AMB	DATE	TIME	STATUS	30	40	50	60	70	80	90	100	110	120	130	Offset						
140	160	180	200	220	240	260	280	300	320	340	360	380	400	420	440	460	480					
Rail 1 (Type III)																						
14.3	68	08/24/18	10:12	VALID	202	203	208	208	205	208	209	211	215	217	220							
					221	227	232	235	239	240	240	240	240	240	240	240	60					
Rail 2 (Type III)																						
14.3	68	08/24/18	10:12	VALID	218	225	225	225	225	225	225	225	225	225	225	225	75					
					225	225	225	225	225	225	225	225	225	225	225	225						
Wheel 1 (Type III)																						
14.3	68	08/24/18	10:12	VALID	178	190	196	191	193	194	197	201	199	205	201							
					207	209	214	217	218	221	222	224	231	227	233	236	238	241	244	246	249	252
Wheel 2 (Type III)																						
14.3	68	08/24/18	10:12	VALID	172	180	183	175	178	182	179	180	184	182	187							
					191	193	198	201	202	209	209	212	214	216	220	223	226	229	232	235	238	241

- b Type X to return to the System Functions menu.
- c Return to step 3.

**21 To change or view Radio Programming Menu :**

```
      :  
      :  
[O] - Radio Programming Menu  
[P] - Scanner test  
[Q] - Calibrate Frauscher Transducers  
[R] - Virtual gate test  
[X] - Exit
```

**a** Select **Radio Programming Menu** from the System Functions menu.

A prompt like this appears.

```
Identifying radio type...  
Reading radio data...  
  
SmartSCAN NG2, MP/KP:1234.5, Track:Single  
07/01/2020 07:00:58, 13.7V, 79°F  
DTX-160                               Firmware version: 1.05  
Radio Programming Menu                 Transmit  Receive  
-----  
[A] - Channel 1..... 160.920    160.920  
[B] - Channel 2..... 160.480    160.480  
[C] - Channel 3..... 161.565    160.395  
[D] - Channel 4..... 160.455    160.455  
[E] - Channel 5..... 160.440    160.440  
[F] - Channel 6..... 160.440    160.440  
[G] - Channel 7..... 160.440    160.440  
[H] - Channel 8..... 160.440    160.440  
[I] - Carrier Detect On/Off (-dBm) ..... 80.0 / 90.0  
[J] - Current channel ..... HW control  
[X] - Exit
```

**b** Select channel to edit frequencies.

**c** Select Carrier Detect to edit settings.

```
The default value for Carrier Detect On is 110.0 (-dBm)  
Enter new Carrier Detect On (-dBm) value between 060.0 and 127.0 (###.#):
```

**d** Type X to return to the System Functions menu.

**e** Return to step 3.

**22 To perform a Scanner test (for diagnostic purposes):**

```
      :  
      :  
[P] - Scanner test  
[Q] - Calibrate Frauscher Transducers  
[R] - Virtual gate test  
[X] - Exit
```

**a** Select **Scanner test** from the System Functions menu.

A prompt like this appears.

```
East rail bearing scanner pot: 63
West rail bearing scanner pot: 70
East rail wheel scanner pot: 63
West rail wheel scanner pot: 60

The test will time out after 10 minutes
You can end the test early by pressing any key.

Beginning test...

East bearing      West bearing      East wheel      West wheel
      0              1              0              24
```

All scanners will open shutters and begin scanning for heat. Results are displayed on the prompt.

- b Type any key to return to the System Functions menu.
- c Return to step 3.

**23 To perform a Calibrate Frauscher Transducers:**

```
      .
      .
      .
[P] - Scanner test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual gate test
[X] - Exit
```

- a Select **Calibrate Frauscher Transducers** from the System Functions menu.

A prompt like this appears.

```
Which transducer?
[A] - Transducer 1
[B] - Transducer 2
[C] - Both
```

Select a transducer (or both) to initiate calibration.

```
Are you sure? (y/n)

Sending calibration signal...
Calibration started, please wait up to 60 seconds...
Calibration complete
Transducer 1: Success
```

- b Type any key to return to the System Functions menu.
- c Return to step 3.

## 24 To perform a **Virtual gate test**:

```
      .  
      .  
      .  
[P] - Scanner test  
[Q] - Calibrate Frauscher Transducers  
[R] - Virtual gate test  
[X] - Exit
```

- a** Select **Virtual gate test** from the System Functions menu.

A prompt like this appears.

```
Select a scanner:  
[1] - East Rail  
[2] - West Rail  
[3] - East Wheel  
[4] - West Wheel
```

Select a scanner to initiate test.

```
Are you sure? (y/n)  
You have 2 minutes to test.  
Test running, press any key to abort the test...
```

While in Virtual Gate Test Mode, the goal is to simulate a wheel that passes over the gating transducers and then continues moving to the scanner under test. The system notifies you when the simulated wheel is in the virtual gate area by cycling the shutters. The following steps describe how to use the Virtual Gate Test Mode.

- From the Virtual Gate Test Mode menu, select a scanner in which you want to see its Virtual Gate position.
- Swipe across the Gating Transducers with a metal object in the direction of the scanner under test. Maintain a speed faster than 1.6 seconds between sensors.
- Swipe across the sensors again. However, this time continue moving the metal object to the scanner under test while maintaining a constant speed.
- The shutters rapidly cycle one time to indicate when the system is looking for heat in the virtual window located at the scanner, which should be at the time that the metal object (simulated axle) passes the scanner. *If the shutters do not cycle, the entry for closest transducer (TO1 or TO2) may be incorrect.*
- Simulating various axle speeds, repeat as needed to confirm settings.

The test mode runs for two minutes before timing out. Otherwise, any keypress ends the session. Rapid shutter flutter is an indication that two minutes have expired and the test has ended automatically. The event log records a canceled train at the end of the testing session.

- b** Type any key to return to the System Functions menu.
- c** Return to step **3**.

## 4.4 Replay EOT Announcement

The EOT message for every train that is stored in longterm memory can be replayed through the local speaker. The replaying of the EOT message does not activate the PTT, so it isn't broadcast over the radio.

To replay the train announcement for a given train:

- 1 Be sure that the Main menu is displayed.

The Main menu looks like this.

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event log
[K] - System Functions Menu
[L] - Replay train
[M] - Security Menu
[X] - Exit
```

- 2 Select **Replay train**.

These prompts appear.

```
Enter train number:
Exception train? (y/n)
Text only? (y/n)
```

3 Type the train number and responses to prompts.

If you typed a three-digit valid train number, you'll hear the EOT announcement through the speaker.

4 If you typed one or two digits, press **[Enter]**.

If the typed train number is valid, pressing **[Enter]** produces the announcement.

## 4.5 System Security

This menu is only available during initial setup or when logged in with an administrative password.

To view or change system security settings:

Be sure that the Main menu is displayed.

The Main menu looks like this.

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event log
[K] - System Functions Menu
[L] - Replay train
[M] - Security Menu
[X] - Exit
```

Select the **Security Menu**. This menu/prompt appears.

```
Security Menu
-----
[A] - Admin password not set
[B] - User password not set
[C] - Change wifi password
[X] - Exit
```

System login with an administrative password allows all access to system menus.

System login with user password allows access to report menus and system functions menu but restricts access to the setup menu and security menu.

Select an option to set or change the password.

```
Enter a new password (20 character maximum):
```



## 5.0 Web/Secure Wireless User Interface

---

The web/secure wireless interface allows **on-site** and **off-site** access with the system. This interface allows the user to view reports and to modify system parameters.

To use the secure wireless interface locally, you need:

- A phone, tablet, or computer with WiFi capability
- Communications browser, which is installed on the device

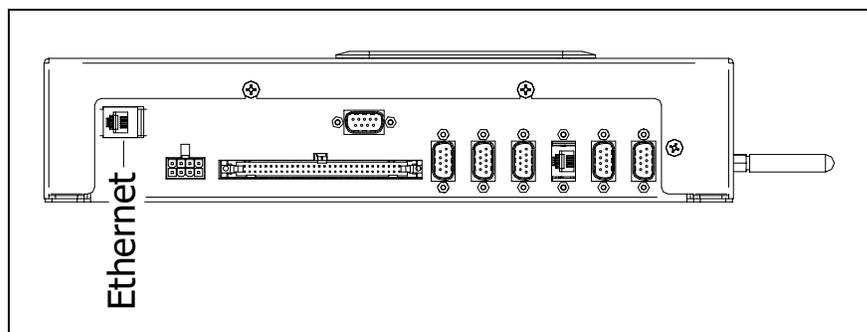
For remote access via a web browser:

- A computer with internet connectivity
- A SmartScanNG<sup>2</sup> with Ethernet connectivity

The SmartScanNG<sup>2</sup> web interface provides:

- Train Summary report
- Train Detail reports
- System Status report
- System configuration
- Event Log report
- Software update

To connect to the SmartScanNG<sup>2</sup> remotely with a web browser, the controller module must have an Ethernet connectivity routed to the RJ45 connector as shown below.



To make a wireless local connection, the WiFi setting must be enabled on the SmartScanNG<sup>2</sup>. Search for and select the NG network on your wireless device. Enter the correct WiFi password to make a successful network connection.

To view the web page for your SmartScanNG<sup>2</sup>, open a web browser on your computer. Enter the unit's IP address to the address bar of your browser. Login with a security password.

See the example below. The contents of your web page will be different.

The screenshot displays the SmartScanNG<sup>2</sup> web interface. At the top, it shows the site's name and status: Milepost: 1234.5, Track: North, 05/29/2024, 13:15, Battery: 13.5V, Temp: 25F. A notification bar indicates "A Train Is Present". Below this are navigation tabs: Train Data, System Status, Configuration, Logs, Maintenance Info, System Functions, Software Update, and Calibration. The "Train Summary Data" tab is selected, showing a dropdown menu with "Train Summary Data" and "Exception Train Summary" options. A "Refresh" button is present. The main content is a table of train data with columns: Trn#, Date, Time, Cars, Axles, TO1, TO2, Dir, Speed (Min, Max, Exit), Bearing Avg (East, West), Wheel Max (East, West), Temp, Bat, and Alarms. The table lists 20 train entries from 949 to 973. At the bottom of the table are "More" and "All" buttons. A red arrow points from the "More" button to the text below.

Trn#	Date	Time	Cars	Axles	TO1	TO2	Dir	Speed			Bearing Avg		Wheel Max		Temp	Bat	Alarms
								Min	Max	Exit	East	West	East	West			
973	05/29/24	12:59	44	180	180	180	S	45	47	47	1	0	55	29	+28F	13.7v	
972	05/29/24	12:37	106	430	430	430	S	40	43	40	3	2	84	40	+27F	13.7v	
971	05/29/24	11:53	28	164	164	164	N	37	41	37	3	2	159	82	+25F	13.7v	
970	05/29/24	11:31	29	330	330	330	S	20	33	21	2	1	124	88	+25F	13.7v	
969	05/29/24	11:00	15	168	168	168	N	38	45	38	1	1	58	30	+24F	13.7v	
968	05/29/24	10:42	24	100	100	100	N	45	47	45	0	0	58	40	+20F	13.8v	
967	05/29/24	10:16	27	162	162	162	S	27	30	28	3	2	189	165	+17F	13.8v	
966	05/29/24	09:34	72	296	296	296	S	19	26	20	1	2	199	173	+15F	13.8v	
965	05/29/24	08:51	98	400	400	400	S	31	34	31	1	1	108	103	-50F	13.9v	
964	05/29/24	07:55	2	8	8	8	N	35	35	35	2	3	40	24	+22F	13.9v	
963	05/29/24	06:30	139	564	564	564	S	35	38	35	0	0	70	42	+23F	13.9v	
962	05/29/24	06:02	182	740	740	740	N	29	38	29	1	0	49	29	+26F	13.9v	
961	05/29/24	03:56	58	358	358	358	N	37	41	37	2	2	108	124	+23F	13.9v	
960	05/29/24	03:26	70	284	284	284	N	31	37	31	1	1	351	310	+25F	13.9v	
959	05/29/24	03:10	18	106	106	106	N	36	37	36	2	3	97	78	+25F	13.9v	
958	05/29/24	02:12	122	494	494	494	N	31	42	31	1	1	46	24	+30F	13.8v	
957	05/28/24	22:23	89	362	362	362	N	35	43	35	5	5	52	34	+30F	13.7v	
956	05/28/24	21:21	55	248	248	248	N	42	48	42	1	1	64	38	+30F	13.7v	
955	05/28/24	20:04	156	630	630	630	N	22	36	22	2	1	58	30	+27F	13.7v	
954	05/28/24	19:39	89	362	362	362	N	34	41	34	3	2	78	62	+26F	13.7v	
953	05/28/24	18:15	46	200	200	200	N	42	46	42	2	0	94	58	+30F	13.6v	
952	05/28/24	17:32	93	386	386	386	S	31	36	34	1	1	66	34	+28F	13.6v	
951	05/28/24	16:35	120	488	488	488	N	39	46	39	0	1	52	29	+29F	13.6v	
950	05/28/24	15:51	58	358	358	358	N	35	40	35	2	1	86	161	+31F	13.6v	
949	05/28/24	15:06	178	720	720	720	N	16	31	16	1	1	55	36	+32F	13.6v	

Click the "More" button at the bottom to load more train data.

The web page header includes the site's Kilometerpost or Milepost, Track Designator, Site ID, Date, Time, Battery voltage, Temperature, and Login status. The main page includes eight tabs. Train Summary Data (or Exception Train Summary), System Status, Configuration, Logs, Maintenance Info, System Functions, Software Update, and Auto Cal. Clicking on the tabs will change the display in the main body of the page.

A pop-up indicator will appear above the tabs whenever a train is present.

On the Train Data tab between the Train Summary Data label and the header for the report columns is a key showing the various indicators present on the report (axle alarms, Integrity Failures, System Alarms, and DSR Records). Certain colors and characters at certain locations around a train's train number indicate the presence of these items. Hovering the mouse pointer over a train number also produces a pop-up window showing any axle alarms, Integrity Failures, and/or System Alarms present on the train.

## 5.1 Train Data

To view the train data, left-click the **Train Data** tab. The Train Summary Data will be displayed as depicted in the example above.

To view a train detail report, slide the mouse pointer to highlight the row for the desired train in the Train Summary Data Table. Left-click to select the train. A new window appears for each **Train Detail** report. This report also has the Show Announcements and Show DSR Charts buttons that display additional windows and information and provide replay and download of the spoken announcements. See the example below.

Train Details - Train #973
Milepost: 1234.5 / North

Date: 05/29/24	Axles: 180	Speed	Train Length: 2601	Amb. temp.: +28F
Time: 12:59	T01: 180	Min: 45	Shutters Open: 49 sec	Battery: 13.7v
Dir: South	T02: 180	Max: 47		
	Cars: 44	Avg: 45		
		Exit: 47		

Software Version: CSX\_01-77 2024-04-23

Scanner Performance							Alarm Limits		
Scanner	Max	Avg	Resistor Read	Req	CF		Alarm	Limit	
East Bearing	25	1	241	163	B	0	Absolute	170	
West Bearing	43	0	274	181	B	0	Differential	255	
East Wheel	55	39	270	141	B	0	Hot Wheel	652	
West Wheel	29	17	276	171	B	0	Carside Slope	1.31	
Resistor Test Mode: Enabled								Carside Min	90
								Cold Rail Temp	10
								Announce Hot Wheels	Yes
								Announce High Load	Yes
								Announce Wide Load	Yes
								Announce Differential	Yes

**System Alarms**  
None.

**Integrity Failures**  
None.

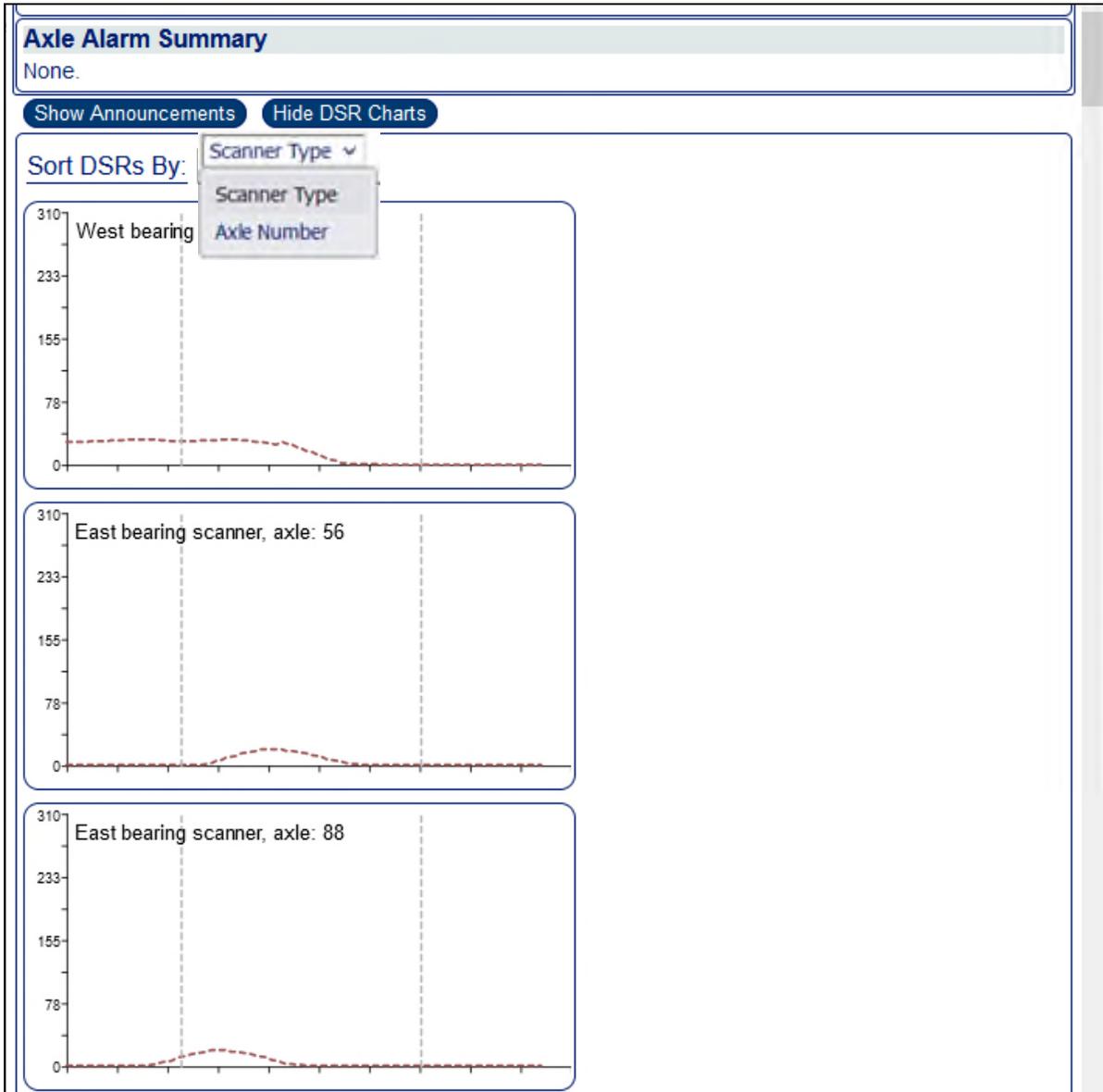
**Axle Alarm Summary**  
None.

Show Announcements
Show DSR Charts

Car	Axle	Bearing		Wheel		ON	OFF	PW1	PW2	Alarms
		East	West	East	West					
1	1	0	43	49	18	30	1120	15	16	
	2	1	0	40	18	31	70	16	16	
3	0	0	38	18	30	70	15	16		
4	0	0	46	29	30	476	15	15		
5	0	0	49	24	30	70	15	16		
6	0	0	49	21	30	70	15	15		

See Section 6.0 Producing Reports for a detailed explanation of the various report headers.

In the DSR display section of the Train Detail Report, a drop-down list provides two options for sorting the DSR charts. The default option is, by “Scanner Type”, and, when selected, the DSR charts are displayed with all the bearing scanner-related DSRs first followed by all the wheel scanner-related DSRs. The other option is by “Axle Number”, which sorts all of the DSR records (both bearing and wheel scanner DSRs) by axle number and presents them in order, starting from the lowest axle number represented.



DSR Sort Options Example

## 5.2 System Status

To view the system status, left-click the **System Status** tab. Grab and drag the slider bar to view the full range of system settings. See the example depicted below.

**SMARTSCAN NG<sup>2</sup>**

Milepost: 1234.5 Track: Single 07/03/2024, 12:56 Battery: 13.3V Temp: 58F  
Logged in as admin. [Logout](#)

[Train Data](#) [System Status](#) [Configuration](#) [Logs](#) [Maintenance Info](#) [System Functions](#) [Software Update](#) [Calibration](#)

### System Status

Site Information ▲	
Milepost	1234.5
Track Designator	Single
Track Direction	North/South
Time Zone	Central
Daylight Savings Time	Disabled
Software Version	BNSF_01-01 2022-04-26
Speech Version	BNSF English Ryan 1.0
Talker Mode	Talk Freely
N/E Integ Mode	5B-Integ Fail
S/W Integ Mode	5B-Integ Fail
Velocity	Enabled
SICM Board Rev	1.2 or lower

Alarm Settings ▲	
Absolute	170
Differential	150
Hot Wheel	900
Cold Rails	3
Cold Rail Temp	10
Cold Res Counter	3
Differential Enabled	Yes

Alarm Settings (Advanced) ▲	
Carside Slope	1.31
Carside Minimum	155
Res Test: Minimum Rail Avg	25
Res Test: Minimum Wheel Avg	28
Bearing DSR Capture Temp	100
Wheel DSR Capture Temp	300
Max Alarms	13

Equipment Settings ▲	
Dragger	Yes
Hot Wheel	Yes
Hot Bearing	Yes
High Load	No

•  
•  
•

By clicking on the header of a section, you can contract/expand the details for that section.

## 5.3 Configuration

To view the system configuration settings, left-click the **Configuration** tab. Then left-click the category tabs to view or edit the various parameters. If necessary, grab and drag the slider bar to view the full range of system settings. See the samples depicted below.

To modify the current setting, click on the parameter field and type the new value. The **Apply Changes** button will be outlined in red when changes have been entered. Left-click the **Apply Changes** button to save changes. An “Update Successful” message will appear.

The screenshot displays the SMARTSCAN NG² web interface. At the top, the header shows the device name and status: Milepost: 1234.5, Track: Single, 07/03/2024, 13:17, Battery: 13.4V, Temp: 57F, and Logged in as admin. Below the header is a navigation menu with tabs for Train Data, System Status, Configuration (selected), Logs, Maintenance Info, System Functions, Software Update, and Calibration. The main content area is titled 'Configuration' and includes a 'Load Default Setup Parameters' button. A sidebar on the left lists various configuration categories: Date/Time (selected), Site Parameters, Alarm Settings, Alarm Settings (Advanced), Equipment Settings, Equipment Settings (Advanced), Messages, Messages Settings (Advanced), Network Settings, COM Port Settings, AEI Settings, and Import/Export. The 'Date/Time' settings are displayed in a table:

Date/Time	
Date	07/03/2024
Time	13:18
Time Zone	Central ▾
Daylight Savings Time	Disabled ▾

An 'Apply Changes' button is located below the settings table.

**Date/Time Tab**

### Configuration [System Functions](#) [Parameters](#)

Date/Time	
<b>Site Parameters</b>	<b>Site Parameters</b>
Alarm Settings	Milepost <input type="text" value="1234.5"/>
Alarm Settings (Advanced)	Track Designation <input type="text" value="Single"/>
Equipment Settings	Track Direction <input type="text" value="Single"/>
Equipment Settings (Advanced)	Velocity <input type="text" value="North"/>
Messages	Talker Mode <input type="text" value="South"/>
Messages Settings (Advanced)	N/E Integ Mode <input type="text" value="East"/>
Network Settings	S/W Integ Mode <input type="text" value="West"/>
COM Port Settings	<input type="text" value="Middle"/>
AEI Settings	<input type="text" value="Main 1"/>
Import/Export	<input type="text" value="Main 2"/>
	<input type="text" value="Main 3"/>
	<input type="button" value="Apply Changes"/>

**Site Parameters Tab**

## Configuration

[Load Default Setup Parameters](#)

- Date/Time
- Site Parameters
- Alarm Settings**
- Alarm Settings (Advanced)
- Equipment Settings
- Equipment Settings (Advanced)
- Messages
- Messages Settings (Advanced)
- Network Settings
- COM Port Settings
- AEI Settings
- Import/Export

### Alarm Settings

Absolute	<input type="text" value="170"/>	min = 1, max = 300
Differential	<input type="text" value="150"/>	min = 1, max = 300
Hot Wheel	<input type="text" value="900"/>	min = 1, max = 900
Cold Rails	<input type="text" value="3"/>	min = 1, max = 9
Cold Rail Temp	<input type="text" value="10"/>	min = 1, max = 30
Cold Res Counter	<input type="text" value="3"/>	min = 1, max = 9
Differential Enabled	<input type="text" value="yes"/>	

[Apply Changes](#)

### Alarm Settings Tab

- Train Data
- System Status
- Configuration
- Logs
- Maintenance Info
- System Functions
- Software Update
- Calibration

## Configuration

[Load Default Setup Parameters](#)

Date/Time	<b>Alarm Settings (Advanced)</b>	
Site Parameters	Carside Slope	<input type="text" value="1.31"/> min = 0.01, max = 2.55
Alarm Settings	Carside Minimum	<input type="text" value="155"/> min = 0, max = 300
<b>Alarm Settings (Advanced)</b>	Res Test: Minimum Rail Avg	<input type="text" value="25"/> min = 0, max = 300
Equipment Settings	Res Test: Minimum Wheel Avg	<input type="text" value="28"/> min = 0, max = 900
Equipment Settings (Advanced)	Bearing DSR Capture Temp	<input type="text" value="100"/> min = 0, max = 300
Messages	Wheel DSR Capture Temp	<input type="text" value="300"/> min = 0, max = 900
Messages Settings (Advanced)	Max Alarms	<input type="text" value="13"/> min = 1, max = 13
Network Settings	<a href="#">Apply Changes</a>	
COM Port Settings		
AEI Settings		
Import/Export		

**Alarm Settings (Advanced) Tab**

## Configuration

[System Functions](#)

[Load Default Setup Parameters](#)

<a href="#">Date/Time</a>	<b>Equipment Settings</b>
<a href="#">Site Parameters</a>	Dragger <input type="checkbox"/>
<a href="#">Alarm Settings</a>	Hot Wheel <input type="checkbox"/>
<a href="#">Alarm Settings (Advanced)</a>	Hot Bearing <input type="checkbox"/>
<b>Equipment Settings</b>	High Load <input type="checkbox"/>
<a href="#">Equipment Settings (Advanced)</a>	Wide Load <input type="checkbox"/>
<a href="#">Messages</a>	AEI <input type="checkbox"/>
<a href="#">Messages Settings (Advanced)</a>	East Rail Scanner Type <input type="text" value="Type III"/>
<a href="#">Network Settings</a>	West Rail Scanner Type <input type="text" value="Type III"/>
<a href="#">COM Port Settings</a>	East Wheel Scanner Type <input type="text" value="Type III"/>
<a href="#">AEI Settings</a>	West Wheel Scanner Type <input type="text" value="Type III"/>
<a href="#">Import/Export</a>	Presence Hardware <input type="checkbox"/>
	Advance Transducers <input type="checkbox"/>
	Scanner Heater AC Monitor <input type="checkbox"/>
	Main AC Power Monitor <input type="checkbox"/>
	DC Power Monitor <input type="checkbox"/>
	Surge Protector Monitor <input type="checkbox"/>
	<a href="#">Apply Changes</a>

**Equipment Settings Tab**

## Configuration

[Load Default Setup Parameters](#)

Date/Time

Site Parameters

Alarm Settings

Alarm Settings (Advanced)

Equipment Settings

**Equipment Settings (Advanced)**

Messages

Messages Settings (Advanced)

Network Settings

COM Port Settings

AEI Settings

Import/Export

### Equipment Settings (Advanced)

Clearance Mode	<input type="text" value="Multiplexed"/>	
Clearance Type	<input type="text" value="Light Beam"/>	
Carside Slope	<input type="text" value="yes"/>	
Winter Cycle	<input type="text" value="yes"/>	
Winter Cycle Start Month	<input type="text" value="October"/>	
Winter Cycle End Month	<input type="text" value="March"/>	
Transducer Gain	<input type="text" value="Normal"/>	
Resistor Test	<input type="text" value="Enabled"/>	
Gate Distance (inches)	<input type="text" value="24.0"/>	
Dragger Debounce Time (mS)	<input type="text" value="100"/>	min = 0, max = 999
Pre Train Dragger Dist (feet)	<input type="text" value="6"/>	min = 0, max = 999
Pre Train High/Wide Dist (feet)	<input type="text" value="6"/>	min = 0, max = 999
Presence Timeout Period (seconds)	<input type="text" value="10"/>	min = 5, max = 30
System Voltage	<input type="text" value="12"/>	
Transducer Type	<input type="text" value="Magnetic"/>	

[Apply Changes](#)

### Equipment Settings (Advanced) Tab

- Train Data
- System Status
- Configuration**
- Logs
- Maintenance Info
- System Functions
- Software Update
- Calibration

## Configuration

[Load Default Setup Parameters](#)

- Date/Time
- Site Parameters
- Alarm Settings
- Alarm Settings (Advanced)
- Equipment Settings
- Equipment Settings (Advanced)**
- Messages
- Messages Settings (Advanced)
- Network Settings
- COM Port Settings
- AEI Settings
- Import/Export

### Equipment Settings (Advanced)

Clearance Mode	<input type="text" value="Multiplexed"/>	
Clearance Type	<input type="text" value="Light Beam"/>	
Carside Slope	<input type="text" value="yes"/>	
Winter Cycle	<input type="text" value="yes"/>	
Winter Cycle Start Month	<input type="text" value="October"/>	
Winter Cycle End Month	<input type="text" value="March"/>	
Transducer Gain	<input type="text" value="Normal"/>	
Resistor Test	<input type="text" value="Enabled"/>	
Gate Distance (inches)	<input type="text" value="24.0"/>	
Dragger Debounce Time (mS)	<input type="text" value="100"/>	min = 0, max = 999
Pre Train Dragger Dist (feet)	<input type="text" value="6"/>	min = 0, max = 999
Pre Train High/Wide Dist (feet)	<input type="text" value="6"/>	min = 0, max = 999
Presence Timeout Period (seconds)	<input type="text" value="10"/>	min = 5, max = 30
System Voltage	<input type="text" value="12"/>	
Transducer Type	<input type="text" value="Magnetic"/>	

[Apply Changes](#)

## Messages Tab

## Configuration

[Load Default Setup Parameters](#)

- Date/Time
- Site Parameters
- Alarm Settings
- Alarm Settings (Advanced)
- Equipment Settings
- Equipment Settings (Advanced)
- Messages
- Messages Settings (Advanced)**
- Network Settings
- COM Port Settings
- AEI Settings
- Import/Export

### Messages Settings (Advanced)

Announce Hot Wheels	No	▼
Announce High/Wide	Yes	▼
Rebroadcast Time Limit (minutes)	5	min = 0, max = 999
Rebroadcast DTMF Code	001	
Num EOT Repeats	1	min = 0, max = 5
EOT Repeat Delay (seconds)	5	min = 0, max = 999

[Apply Changes](#)

**Messages Settings (Advanced) Tab**

[Train Data](#) [System Status](#) [Configuration](#) [Logs](#) [Maintenance Info](#) [System Functions](#) [Software Update](#) [Calibration](#)

## Configuration

[Load Default Setup Parameters](#)

- Date/Time
- Site Parameters
- Alarm Settings
- Alarm Settings (Advanced)
- Equipment Settings
- Equipment Settings (Advanced)
- Messages
- Messages Settings (Advanced)
- Network Settings**
- COM Port Settings
- AEI Settings
- Import/Export

### Network Settings

Use Static Address	<input type="text" value="no"/>	
Static IP	<input type="text" value="192.168.1.101"/>	
Static Mask	<input type="text" value="255.255.255.0"/>	
Default Gateway	<input type="text" value="192.168.1.1"/>	
DNS Server	<input type="text" value="192.168.1.1"/>	
TELNET Port	<input type="text" value="23"/>	min = 0, max = 65535
FTP Port	<input type="text" value="21"/>	min = 0, max = 65535
HTTP Port	<input type="text" value="80"/>	min = 0, max = 65535
HTTPS Port	<input type="text" value="8080"/>	min = 0, max = 65535
Use Wifi	<input type="text" value="no"/>	
Wifi Inactivity Timeout (min)	<input type="text" value="10"/>	min = 0, max = 30

[Apply Changes](#)

### Network Settings Tab

## Configuration

[Load Default Setup Parameters](#)

- Date/Time
- Site Parameters
- Alarm Settings
- Alarm Settings (Advanced)
- Equipment Settings
- Equipment Settings (Advanced)
- Messages
- Messages Settings (Advanced)
- Network Settings
- COM Port Settings**
- AEI Settings
- Import/Export

### COM Port Settings

COM1 (Serial Interface)	19200	▼
COM2 (Not Used)	19200	▼
COM4 (MeteorComm)	19200	▼
COM6 (FlashHost)	57600	▼
RS485 (Not Used)	9600	▼
Page Lines	30	min = 0, max = 9999

[Apply Changes](#)

**Comm Port Settings Tab**

- Train Data
- System Status
- Configuration**
- Logs
- Maintenance Info
- System Functions
- Software Update
- Calibration

## Configuration

[Load Default Setup Parameters](#)

- Date/Time
- Site Parameters
- Alarm Settings
- Alarm Settings (Advanced)
- Equipment Settings
- Equipment Settings (Advanced)
- Messages
- Messages Settings (Advanced)
- Network Settings
- COM Port Settings
- AEI Settings**
- Import/Export

### AEI Settings

ID Separation	<input type="text" value="2"/>	min = 1, max = 4
Consecutive Reads	<input type="text" value="2"/>	min = 1, max = 4
RF Frequency (MHz)	<input type="text" value="915.000"/>	
RF Attenuation (dB)	<input type="text" value="0"/>	min = 0, max = 10
Multi-Track Tag Filter	<input type="text" value="no"/>	

[Apply Changes](#)

**AEI Settings Tab**

## Configuration

[Load Default Setup Parameters](#)

- Date/Time
- Site Parameters
- Alarm Settings
- Alarm Settings (Advanced)
- Equipment Settings
- Equipment Settings (Advanced)
- Messages
- Messages Settings (Advanced)
- Network Settings
- COM Port Settings
- AEI Settings
- Import/Export**

### Import/Export

- General Settings
- Network Settings
- Security Settings
- Calibration Settings

[Export](#) | [Import](#)

Import/Export Tab

## 5.4 System Event Log

The Log report is used for diagnostics. As certain system events occur, entries are posted into a log. Each time an entry is made into this log, it receives an event number, the date and time that the event was recorded, and an event description. Events are listed in chronological order, beginning with the most recent event.

To view the log report, left-click the **Logs** tab. Use the dropdown menu to select the Log Type, either **Event Log** or **Security Log**. See the Event Log sample depicted below.

SMARTSCAN NG<sup>2</sup>

Milepost: 1234.5 Track: North 29/05/2024, 14:30 Battery: 13.4V Temp: 13C  
Logged in as admin. Logout

Train Data System Status Configuration **Logs** Maintenance Info System Functions Software Update Calibration

Event Log Refresh Log Type Event Log

0001: [29/05/2024 13:26:15] (54) - Serial Connection timed out: id-3  
0002: [29/05/2024 13:06:21] (47) - Analyzer: Tag Reader Type None detected  
0003: [29/05/2024 13:06:09] (54) - Admin logged in: id-3, serial interface  
0004: [29/05/2024 13:05:51] (47) - Analyzer: Analyzer booted up  
0005: [29/05/2024 13:05:31] (53) - Searching for Velocity  
0006: [29/05/2024 13:05:24] (58) - Comm Startup  
0007: [29/05/2024 13:05:24] (58) - Reset cause: Software  
0008: [05/29/2024 13:04:58] (53) - Rebooting for update  
0009: [05/29/2024 13:04:57] (53) - System Update successful  
0010: [05/29/2024 13:04:36] (62) - Processor update complete  
0011: [05/28/2024 09:45:25] (54) - Serial Connection timed out: id-3  
0012: [05/28/2024 09:25:21] (54) - Admin logged in: id-3, serial interface  
0013: [05/23/2024 13:16:11] (54) - Serial Connection timed out: id-3  
0014: [05/23/2024 12:53:04] (54) - Admin logged in: id-3, serial interface  
0015: [05/23/2024 12:52:58] (54) - Admin logged out: id-3  
0016: [05/23/2024 12:52:53] (54) - Admin logged in: id-3, serial interface  
0017: [05/22/2024 07:12:31] (47) - Analyzer: Analyzer booted up  
0018: [05/22/2024 06:10:44] (47) - Analyzer: Analyzer booted up  
0019: [05/22/2024 06:10:23] (53) - Searching for Velocity  
0020: [05/22/2024 06:10:22] (58) - Comm Startup  
0021: [05/22/2024 06:10:22] (58) - Reset cause: Software  
0022: [05/22/2024 06:09:37] (47) - Analyzer: Analyzer booted up

More All

Click the “**More**” button at the bottom to load more events.

## 5.5 Maintenance Information

Left-click the **Maintenance Info** tab to view maintenance data. Left-click Change Train Range to change the range of trains used for maintenance calculations. The default range is the last forty trains.

SMARTSCAN NG<sup>2</sup>

Milepost: 1234.5 Track: North 05/30/2024, 08:10
Battery: 13.8V Temp: 21F

[Logged in as admin. Logout](#)

Train Data
System Status
Configuration
Logs
Maintenance Info
System Functions
Software Update
Calibration

### Maintenance Information

Statistics accumulated for the last 40 trains. [Change Train Range](#) [Refresh](#)  
 Includes data from the last 3 days.

#### Scanner Statistics

Scanner	Max	Avg	Resistor		Avg CF	Cold Scanner		Cold Resistor	
			Max	Avg		Cnt	%	Cnt	%
East Bearing	68	1	300	258	0	2	5	0	0
West Bearing	97	2	300	287	0	1	2	0	0
East Wheel	351	39	314	292	0	0	0	0	0
West Wheel	310	18	354	313	0	0	0	0	0

#### Transducer Statistics

Total Axles Scanned	15056
Total Txd. Miscounts	0
Percent Miscounts	0.00%
Trains With Miscounts	0
Trains In Sample	40
Percent Trains W/ Miscounts	0.00%

#### System Statistics

	Battery	Ambient Temp
Avg	13.7	21
Max	14.0	32
Min	13.6	-50

#### Hardware Status

East Bearing Scanner	Pass
West Bearing Scanner	Pass
East Wheel Scanner	Pass
West Wheel Scanner	Pass
Gating Transducers	Pass
Ambient Temperature Probe	<span style="background-color: red; color: white; padding: 2px;">Failure</span>
- 2% had Ambient Temperature Probe Unreliable Possible Cause: Ambient temperature probe damaged, temperature probe cable damaged	
Power Subsystem	Pass
Presence Hardware	Pass
Dragger	Pass
High Load Detector	Disabled
Wide Load Detector	Disabled
AEI Subsystem	Disabled

## 5.6 System Functions

Some but not all system functions can be accessed remotely. Left-click the **Systems Functions** tab to view available options. Left-click the corresponding button to initiate the desired function.

The screenshot displays the SMARTSCAN NG² web interface. At the top, a dark blue header contains the logo and system status information: Milepost: 1234.5, Track: North, 30/05/2024, 06:35, Battery: 13.3V, Temp: 18C, and a user login status of 'Logged in as admin' with a 'Logout' button. Below the header is a navigation menu with tabs for Train Data, System Status, Configuration, Logs, Maintenance Info, System Functions (which is highlighted), Software Update, and Calibration. The main content area is titled 'System Functions' and is divided into several sections:

- System Test Functions:** Contains five rows, each with a text label and a button: 'Broadcast A Test Message Over The Radio' (Radio Test), 'Run Vocabulary Test' (Vocabulary Test), 'Temporarily Inhibit Radio Broadcast' (Timed Radio Inhibit), 'Generate 1kHz Test Tone' (Test Tone), and 'Start Manual Train' (Test Train).
- Stored Data Resets:** Contains four rows, each with a text label and a button: 'Clear Train Data' (Clear Data), 'Clear Event Log Contents' (Clear Log), 'Reset System Health Statistics' (Reset Stats), and 'Load Default Setup Parameters' (Load Defaults).
- Speaker Volume Adjust:** Features a dropdown menu for 'Select Speaker Volume Setting' (currently set to 3) and an 'Apply Setting' button.
- Maintenance Alert Email List:** Includes a text input field for 'Add An Address:' with an 'Add' button, and a dark grey bar at the bottom with 'Apply Email List Changes' and an 'Apply' button.

Below the 'Maintenance Alert Email List' section, there are three vertically aligned dots indicating a scrollable list of items.

System Functions (cont.)

•  
•  
•

**System Reboot**

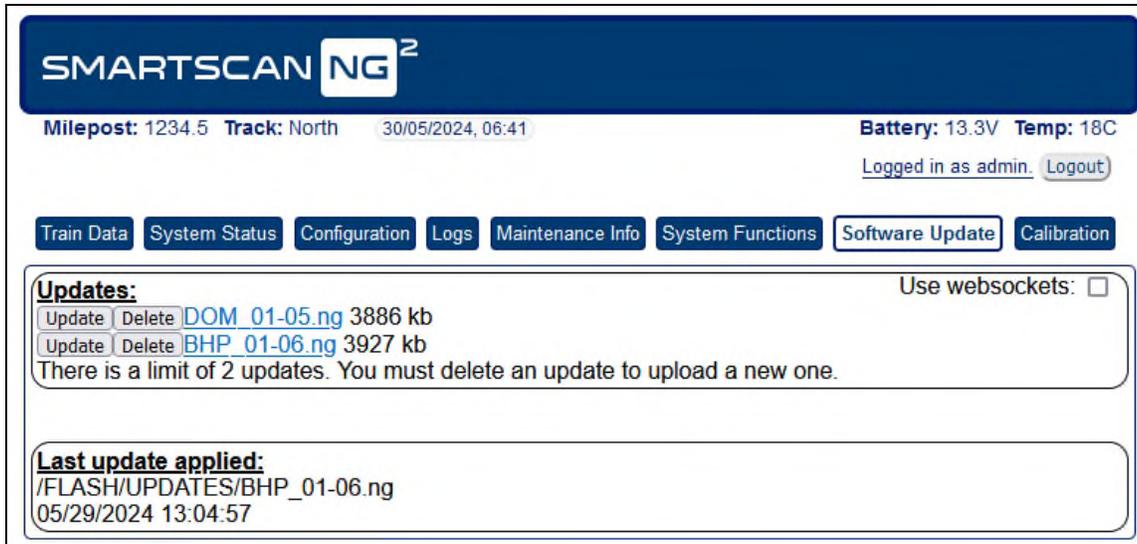
Reboot System Processors Reboot Now

**Resistor Baseline Data**

Scanner	Type	Date	Time	Battery Voltage	Ambient Temp	Status	30	40	50	60	70	80	90	100
Rail 1	Type III	16/05/22	10:49	13.4V	56F	VALID	172	174	178	178	180	182	183	186
Rail 2	Type III	28/04/22	08:26	13.0V	56F	VALID	205	208	209	212	214	215	217	220
Wheel 1	Type III	28/04/22	08:26	13.0V	56F	VALID	316	317	318	318	324	322	326	331
Wheel 2	Type III	28/04/22	08:26	13.0V	56F	VALID	328	330	332	334	335	337	343	345

## 5.7 Software Update

To perform a remote software update, left-click the **Software Update** tab. This tab is the only way to upload software packages onto the detector. Once a package is on the detector, the user can install it either by using this tab or by using the Serial Interface.



The screenshot shows the SMARTSCAN NG<sup>2</sup> web interface. At the top, the header displays the device name and status: Milepost: 1234.5, Track: North, 30/05/2024, 06:41, Battery: 13.3V, Temp: 18C. Below the header, there are navigation tabs: Train Data, System Status, Configuration, Logs, Maintenance Info, System Functions, Software Update (highlighted), and Calibration. The main content area is titled "Updates:" and contains a table of updates. The table has two columns: "Update" and "Delete". The first row shows "DOM\_01-05.ng" (3886 kb) with an "Update" button and a "Delete" button. The second row shows "BHP\_01-06.ng" (3927 kb) with an "Update" button and a "Delete" button. Below the table, there is a message: "There is a limit of 2 updates. You must delete an update to upload a new one." To the right of the "Updates:" section, there is a checkbox labeled "Use websockets:". Below the updates section, there is a section titled "Last update applied:" which shows the file path "/FLASH/UPDATES/BHP\_01-06.ng" and the timestamp "05/29/2024 13:04:57".

The **Upload** button is used to load a new software package onto the detector for subsequent installation. To upload a new file, left-click on the Upload button. Search for and select a software file on your computer. Only two files can be stored at a time. If there are already two files, you must delete one before uploading another.

When the upload is complete, left-click the **Update** button and follow the instructions to update the software. The **Update** button is used to install a previously uploaded software packet so that it becomes the detector's operating software.

## 5.8 Calibration

To perform the automatic scanner calibration function, in the Scanner Auto Calibration section of the Calibration page, left-click the **Start** button.

Note that the Frauscher Transducer Calibration section of the Calibration page will be displayed only if the system has been configured to use Frauscher transducers. The Transducer Type option under the Setup/Equipment menu must be set to Frauscher.

To perform Frauscher calibration, select TO1, TO2, or both – then left-click the **Start Calibration** button.

**SMARTSCAN NG<sup>2</sup>**

Milepost: 1234.5 Track: North 30/05/2024, 06:44 Battery: 13.3V Temp: 19C  
Logged in as admin. Logout

Train Data System Status Configuration Logs Maintenance Info System Functions Software Update Calibration

### Scanner Auto Calibration

**Calibration Status**

Scanner	Scanner Type	Potentiometer Setting Prev.	Setting Current	Last Calibration Date	Last Calibration Time
East Bearing	III		41	16/05/2022	10:22
West Bearing	III		40	28/04/2022	08:07
East Wheel	III		41	28/04/2022	08:09
West Wheel	III		42	28/04/2022	08:11

Click 'Start' button to begin calibration. \*\*\*INSTALL BLACK FILTER BEFORE CALIBRATING TYPE III WHEEL SCANNER\*\*\*

Start Stop

History

### Frauscher Transducer Calibration

Select the transducer to be calibrated:

T01  
 T02  
 Both

Start Calibration



## 6.0 Producing Reports

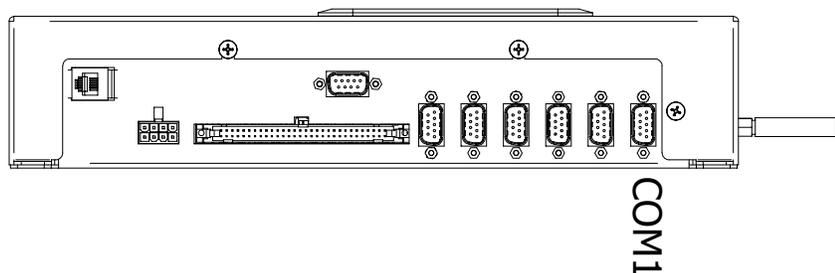
---

The SmartScanNG<sup>2</sup> system provides:

- Train Summary report
- Train Detail report
- Exception Summary report
- extended Exception Detail report
- abbreviated Exception Detail report
- System Status report
- AEI Diagnostic Detail report
- Event Log report
- Maintenance report

This section shows a sample of each report with a description of each field. It also lists step-by-step instructions on producing each report both **on-site** and **off-site**. The instructions for each report start with you being at the Main menu, which is described below.

- 1 If **on-site**, plug your computer into the SmartScanNG<sup>2</sup> serial port COM1.



- 2 Turn on your computer.
- 3 Be sure that your computer has installed communications software, that it is set to use full-duplex, and that the baud rate is set to 19,200.  
Use your communications software to open a LOG file and capture the whole session to the file. When your session is complete, you may then view what you have done with an editor, print it with a printer, or store it for later retrieval.
- 4 On your computer, open a LOG file.
- 5 If **off-site**, establish communications with the SmartScanNG<sup>2</sup> via Ethernet or modem as appropriate.

**6** Press **[Esc]**.

If a password has previously been assigned, this prompt appears.

```
Enter password:
```

**7** Type assigned password.

**8** To get the serial interface to come up, press **[Esc]**.

The Main menu appears.

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event log
[K] - System Functions Menu
[L] - Replay train
[M] - Security Menu
[X] - Exit
```

At the above prompt, you can produce one of the listed reports selecting the appropriate option.

If a train is at the site when the Main menu is generated, "\*\*\* Train Is Present \*\*\*" is displayed just above the menu header for the Main menu.

**9** When done, close the LOG file.

**10** To exit the serial interface and return the system to normal operation, type **X**.

When a session ends, if a modem was used, the system sends various commands to the modem to prepare it for future use. If at any time during the disconnect procedure, lines such as "+++ATH0" appear on your screen, these are merely commands preparing the modem for further use. They shouldn't be construed as anything that is meant for the user.

## 6.1 Train Summary Report

The Train Summary report lists all trains currently stored in the Trains directory. A train number is shown for each train entry so that a Train Detail report may easily be produced for any train listed on the summary.

The report is divided into a header section and a detail section. The header section contains general information about the site. The detail section contains summary information on each train that passed the site.

The SmartScanNG<sup>2</sup> system calculates a checksum for each train. This checksum is stored with the train data. Later, when the system retrieves this data, it recalculates the checksum. If the two checksums don't match, the Train Summary report so states in the detail section. So, instead of getting a train record, you'll get a checksum-error line.

Below is a sample of part of a Train Summary report. The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

```

=====
                        Southern Technologies Corporation
                        Next Generation Detector System
                        TRAIN SUMMARY
=====
Software Version: BNSF0001 2020-07-10                               MP/KP: 1234.5
                                                                    Track: Single

Current Alarm Settings
Critical..... 170   Carside Slope... 1.31
Differential.. 150   Cold Rail Temp.. 10
Hot Wheel..... 900

Total Trains: 100
=====

```

Train#	Date	Time	Cars	Axles	TxD Counts			D i	Speed			Bearing Average		Wheel Maximum		Amb Temp Bat	
					TO1	TO2	r		Min	Max	Xit	East	West	East	West	Temp	Bat
W117A	05/11/24	04:21	16	70	70	70	N	40	40	40	18	18	827	21	-2F	14.6v	
W116	05/11/24	04:17	16	70	70	70	N	40	40	40	18	18	826	21	-2F	14.6v	
B115A	05/11/24	01:01	203	832	832	832	N	60	60	60	188	19	18	21	-2F	14.6v	
114	05/10/24	09:48	203	832	832	832	N	60	60	60	18	19	18	21	-2F	14.6v	
113	05/10/24	09:44	203	832	832	832	N	60	60	60	18	19	18	21	-2F	14.6v	
B112S	05/10/24	09:10	16	70	70	70	N	40	40	40	5	4	18	21	-2F	14.6v	
B111A	05/10/24	09:55	16	70	70	70	N	40	40	40	21	17	18	21	-2F	14.6v	
B110A	05/10/24	09:49	16	70	70	70	N	40	40	40	21	18	18	21	-2F	14.6v	
109S	05/10/24	09:47	16	70	70	70	N	40	40	40	1	1	21	21	-2F	14.6v	
108S	05/10/24	09:45	16	70	70	70	N	40	40	40	1	1	21	21	-2F	14.6v	
B107A*	05/10/24	09:11	21	86	86	86	S	39	39	39	30	30	205	207	-2F	14.6v	
B106A*	05/10/24	09:09	21	86	86	86	S	39	39	39	30	30	205	207	-2F	14.6v	
B105BC	07/12/24	13:43	16	70	70	70	S	19	19	19	23	21	21	24	-2F	14.6v	
B104AC	07/12/24	13:40	16	70	70	70	N	20	20	20	21	24	21	24	-2F	14.6v	
B103AC	07/12/24	13:09	16	70	70	70	S	19	19	19	23	21	21	24	-2F	14.6v	
102S*	07/12/24	11:33	26	118	118	118	N	40	40	40	26	26	60	64	-2F	14.6v	
101S*	07/12/24	11:28	26	118	118	118	N	40	40	40	26	26	60	64	-2F	14.6v	
.																	
.																	
.																	

```

=====
END OF REPORT - Press any key...
=====

```

The table below lists the fields from the header section and the contents of each field.

Heading	Contents of Field
Software Version	The version number and its release date, which is in yyyy/mm/dd format. This firmware resides on the processor modules.
MP/KP	The five-digit milepost/kilometer post of the site. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the MP/KP submenu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. <b>Section 4.0 - Serial Interface</b> tells how to set this value using the Track Number submenu of the Setup menu.
Current Alarm Settings	<p>The alarm parameters currently defined in the system setup. These values were in place at the time this report was run.</p> <ul style="list-style-type: none"> <li>• The value after Absolute is set by the Absolute option on the Alarm Settings menu.</li> <li>• The value after Differential is set by the Differential option on the Alarm Settings menu.</li> <li>• The heading Hot Wheel only appears when the Hotwheel option on the Equipment Settings menu is <u>enabled</u>. The value after Hot Wheel is set by the Hotwheel option on the Alarm Settings menu.</li> <li>• The value after Carside Slope is set by the Carside Slope option on the Alarm Settings menu.</li> <li>• The value after Minimum is set by the Carside Minimum option on the Alarm Settings menu.</li> <li>• The value after Cold Rail Temp is set by the Cold Rail Temperature option on the Alarm Settings menu.</li> </ul> <p><b>Section 4.0 - Serial Interface</b> tells how to set these values.</p>
Total Trains	The total number of trains with data currently stored in the NG <sup>2</sup> .

The table below lists the fields from the detail section and the contents of each field.

Heading	Contents of Field
Train#	The number that identifies the train in the Trains directory.
	There is one unlabeled column between those labeled "Train#" and "Date." This column can contain <b>A, B, I, S</b> , or nothing. If "A," an Exception Alarm was detected on the train. If "I," an Integrity Failure was detected. If "B," both an Exception Alarm and an Integrity Failure were detected. If "S," a System Alarm was detected, but Exception Alarms and Integrity Failures weren't. If blank, no Exception Alarm, Integrity Failure, or System Alarm was detected.
Date	The date the train arrived at the site. Date is in mm/dd/yy format. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time the train arrived at the site. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Cars	The total number of cars counted by the SmartScanNG <sup>2</sup> system.
Axles	The total number of axles counted by the SmartScanNG <sup>2</sup> system.
TO1	The total number of hits counted by gating transducer TO1. TO1 is the first gating transducer going north or east from the bearing scanner. It is the gating transducer <u>closest</u> to the bearing scanner.
TO2	The total number of hits counted by gating transducer TO2. TO2 is the second gating transducer going north or east from the bearing scanner. It is the gating transducer <u>farthest</u> from the bearing scanner.
Dir	The direction the train was traveling. Valid values are N, S, E, and W.
Speed (mph)	The train's minimum, maximum, and exit speed in miles per hour.
Bearing Average	Under this heading are two columns, one for each bearing scanner, containing the average temperature read by the bearing scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west.
Wheel Maximum	Under this heading are two columns, one for each wheel scanner, containing the maximum temperature read by the wheel scanners. If the track orientation is east and west, the wheel scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. This field appears only when the Hotwheel option on the Equipment Settings menu is enabled.
AEI Tags	The total number of AEI tags stored. The number of tag pairs found plus those single tags that lack a match. The AEI subsystem is enabled using the AEI option on the Equipment Settings menu.
Amb Temp	The ambient temperature, in degrees Fahrenheit, at the time the train arrived at the site.
Bat	The system battery voltage at the time the train passed the site.

To produce a Train Summary report:

- 1 Using the serial interface, display the Main menu.

**Section 4.0 - Serial Interface** tells how to display the Main menu. The Main menu looks like this.

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
      .
      .
```

- 2 Select **Train Summary**.

At any time you can interrupt the printing of the report by pressing ESC

- 3 The Main menu reappears upon completion of the report.

At this time, you can produce another report by selecting the appropriate option.

- 4 When done, close the LOG file.

- 5 To exit the serial interface and return the SmartScanNG<sup>2</sup> system to normal operation, type **X**.

## 6.2 Train Detail Report

The Train Detail report provides detailed information on a single train. When choosing this report, you'll be prompted for a train number. When prompted, enter a train number from the Train Summary report. The train number appears under the column titled "Train#" in the detail section of the Train Summary report.

Carside Slope alarm detection is enabled/disabled using the Carside Slope option on the Equipment Settings menu. Hotwheel alarm reporting is enabled/disabled using the Hotwheel option on the Equipment Settings menu. The AEI subsystem is enabled/disabled using the AEI option on the Equipment Settings menu.

Where wheel scanners are properly installed, wheel temperatures are always recorded, even if the Hotwheel option is disabled. On the other hand, if the AEI option is disabled during train passage, no AEI information is recorded. If the Carside Slope option is disabled during train passage, no Carside Slope alarms are generated. But, if it is enabled at the time a report is requested, a carside-slope alarm-limit line is generated for each car of the train.

Below is a sample of part of a Train Detail report when both the AEI option and the Hotwheel option on the Equipment Settings menu were enabled at the time the report was requested. The Carside Slope option on the Equipment Settings menu was disabled. Also, both the AEI and Hotwheel options were enabled while the specified train was passing the site. The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

```

=====
                        Southern Technologies Corporation
                        Next Generation Detector System
                        TRAIN DETAIL
=====
Train#: 117                Axles: 70                Speed                MP/KP: 1234.5
Date: 05/11/24            Cars: 16                Min: 40                Track: Single
Time: 04:21                Direction: North        Max: 40                Temperature: -2F
                        Shutters Open: 26            Avg: 40                Battery: 14.6v
                        Length: 971                Exit: 40
=====
Scanner      Resistor      Txdr
Max Avg Read Req CF  Counts  Alarm      Limit  Carside Parm
-----
East Brng  18  18    1  0T  0  TO1  70  Critical    170  Slope:  1.31
West Brng  18  18    1  0T  0  TO2  70  Minimum: 155
East Whl   827 29    0  0T  0  Differential 150
West Whl   21  21    0  0T  0  Hot Wheel    600
                        Cold Rail Temp 10

Resistor Test Mode: Enabled
Shutter close times: 0, 0, 0, 0
=====
Software Version: BNSF0001 2020-07-10

-----
System Alarms

None

-----
Integrity Failures

None

-----
Axle Alarm Summary

Axle  39 East Hot Wheel (suppressed)

-----
Announcements made

" "
" b n s f milepost 1 2 3 4 point 5 "
" "
" b n s f milepost 1 2 3 4 point 5 no defects repeat no defects total axles 7 0 "
.
.
.

(continued on next page)

```

Train Detail

### Train Detail (continued)

•  
•  
•

Car	Axle	Rail		Wheel		ON	OFF	PW1	PW2	Alarms
		East	West	East	West					
1	1	18	18	18	21	33	82	21	20	
	2	18	18	18	21	33	62	21	20	
	3	18	18	18	21	33	62	21	20	
	4	18	18	18	21	33	528	20	20	
	5	18	18	18	21	33	62	20	20	
	6	18	18	18	21	33	62	20	20	
Carside Ave:		East	18	West	18		Carside	Alarms:	East 178	West 178
2	7	18	18	18	21	33	141	21	20	
	8	18	18	18	21	33	62	20	20	
	9	18	18	18	21	33	528	21	20	
	10	18	18	18	21	33	62	21	20	
Carside Ave:		East	18	West	18		Carside	Alarms:	East 178	West 178
3	11	18	18	18	21	33	140	20	20	
	12	18	18	18	21	33	62	20	20	
	13	18	18	18	21	33	528	21	20	
	14	18	18	18	21	33	62	20	20	
Carside Ave:		East	18	West	18		Carside	Alarms:	East 178	West 178
4	15	18	18	18	21	33	140	20	20	
	16	18	18	18	21	33	62	21	20	
	17	18	18	18	21	33	528	21	20	
	18	18	18	18	21	33	62	20	20	
Carside Ave:		East	18	West	18		Carside	Alarms:	East 178	West 178
5	19	18	18	18	21	33	140	21	20	
	20	18	18	18	21	33	62	20	20	
	21	18	18	18	21	33	528	21	20	
	22	18	18	18	21	33	62	21	20	
Carside Ave:		East	18	West	18		Carside	Alarms:	East 178	West 178
6	23	18	18	18	21	33	140	20	20	
	24	18	18	18	21	33	62	21	20	
	25	18	18	18	21	33	528	21	20	
	26	18	18	18	21	33	62	21	20	
Carside Ave:		East	18	West	18		Carside	Alarms:	East 178	West 178
7	27	18	18	18	21	33	140	20	20	
	28	18	18	18	21	33	62	21	20	
	29	18	18	18	21	33	528	21	20	
	30	18	18	18	21	33	62	20	20	
Carside Ave:		East	18	West	18		Carside	Alarms:	East 178	West 178
8	31	18	18	18	21	33	140	21	20	
	32	18	18	18	21	33	62	20	20	
	33	18	18	18	21	33	528	20	20	
	34	18	18	18	21	33	62	21	20	
Carside Ave:		East	18	West	18		Carside	Alarms:	East 178	West 178

•  
•  
•

The Train Detail report is divided into three sections. The header section contains general information about the site (like the MP/KP) and some detail information about the specific train (like the train's exit speed) that passed the site. The detail section contains more detailed information (like the car number) about the specific train. In between these two sections is the system-events section, which contains all System Alarms and Exception Alarms associated with the train.

The SmartScanNG<sup>2</sup> system calculates a checksum for each train. This checksum is stored with the train data. Later, when the system retrieves this data, it recalculates the checksum. If the two checksums don't match, the Train Detail report so states (as shown below).

```

Southern Technologies Corporation
Next Generation Detector System
TRAIN DETAIL
=====
CHECKSUM ERROR: StartAddr 134879 EndAddr 134930

```

In addition, each axle has a checksum associated with it. If an axle is determined to have an invalid checksum, the Train Detail report so states in the associated axle's row (as shown below).

```

Southern Technologies Corporation
Next Generation Detector System
TRAIN DETAIL
=====
.
.
.
-----
Car  Axle  Trk  North  South  ON  OFF  PW1  PW2  Alarms
-----
  1    1    0   56    21   25   0    6    6
    2    0   57    21   25   59    6    6
    3    0   56    21   25   59    8    8
    4    CHECKSUM ERROR: StartAddr 136416 EndAddr 136427
    5    1   56    21   25   59    6    6
    6    1   56    21   25   59    6    6

  2    7    2   56    20   25  162    6    6
    8    2   56    21   25   59    6    6

.
.
.

```

The table below lists the fields from the header section and the contents of each field.

Heading	Contents of Field
Train#	The number that identifies the train in the Trains directory.
Date	The date the train arrived at the site. The date is in mm/dd/yy format. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time the train arrived at the site. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Axles	The total number of axles counted by the SmartScanNG <sup>2</sup> system.
Cars	The total number of cars counted by the SmartScanNG <sup>2</sup> system.
Direction	The direction the train was traveling. Valid values are North, South, East, and West.
Shutters Open	The number of seconds it took the train to pass over the site.
Length	The length of the train in feet.
Speed	The train's minimum, maximum, average, and exit speeds in miles per hour.
MP/KP	The five-digit milepost/kilometer post of the site. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the MP/KP submenu of the Setup menu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. <b>Section 4.0- Serial Interface</b> tells how to set this value using the Track Number submenu of the Setup menu.
Temperature	The ambient temperature at the time the train arrived at the site. Temperature is in degrees Fahrenheit.
Battery	The system battery voltage at the time the train passed the site.
Scanner	Location of the bearing and wheel scanners. If the track orientation is east and west, the scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. The wheel scanner field only appears when Hotwheel alarm reporting is enabled using the Hotwheel option on the Equipment Settings menu.
Max	The maximum temperature, above the ambient temperature in degrees Fahrenheit, recorded by the bearing scanner on a given railside. For example, if the ambient temperature (at the time the train arrived at the site) is 77°F (25°C), and the value in this field is 112, the maximum temperature would be 189°F (87.2°C).
Avg	The average temperature, above the ambient temperature in degrees Fahrenheit, calculated from all recorded temperatures from the bearing scanner on a given railside. For example, if the ambient temperature (at the time the train arrived at the site) is 86°F (30°C) and the value in this field is 55, the average temperature would be 141°F (60.6°C).

Heading	Contents of Field
Resistor Read	The scanner resistor temperature (read after train passage), in degrees Fahrenheit, recorded by the bearing scanner on a given railside.
Resistor Req	The resistor temperature, in degrees Fahrenheit, required by the scanner on a given railside to avoid a Cold Resistor alarm. This value was calculated using the amount of time the shutters were open and the Resistor Test Mode option in effect at the time the train exits the site. If the Resistor Test Mode option is <u>disabled</u> , a zero appears in this field.
	<p>One of five uppercase letters follows the Resistor Req temperature.</p> <ul style="list-style-type: none"> <li><b>B</b> The baseline resistor integrity test method was used for this train.</li> <li><b>D</b> The resistor integrity test (that is, the Resistor Test Mode option) was disabled by the user.</li> <li><b>I</b> The interim resistor integrity test method was used for this train.</li> <li><b>T</b> For this train, the shutters were open for less than 30 seconds.</li> <li><b>V</b> For this train, the battery voltage (measured with the shutters open) was less than 12.5 volts.</li> </ul> <p>For <b>D</b>, <b>T</b>, and <b>V</b>, the required resistor heat is set to zero (that is, a zero appears in the Resistor Read field). A <b>T</b> or <b>V</b> indicates that the integrity test was not performed due to low voltage or insufficient shutter open time, which could result in an invalid resistor integrity test if it was performed.</p>
CF	The percentage difference between the required resistor value and the value that was actually read. For example, if the required resistor temperature is 180 and the actual resistor temperature is 135 the correction factor would be 25% ( $1 - (135 / 180) = .25$ ), and 25 would appear in this field.
Txdr Counts	The gating transducer designator (either TO1 or TO2) followed by the total number of hits on that transducer.
Alarm Limit	<p>The Hotwheel alarm level; the Hot Journal alarm levels for Absolute and Differential; and the Cold Rail Temperature offset. These values were in place at the time the train arrived at the site.</p> <ul style="list-style-type: none"> <li>• The value after Absolute is set by the Absolute option on the Alarm Settings menu.</li> <li>• The value after Differential is set by the Differential option on the Alarm Settings menu.</li> <li>• The value after Hot Wheel is set by the Hotwheel option on the Alarm Settings menu.</li> <li>• The value after Cold Rail Temp is set by the Cold Rail Temperature option on the Alarm Settings menu.</li> </ul> <p><b>Section 4.0 - Serial Interface</b> tells how to set these values.</p>

Heading	Contents of Field
Carside Parm	<p>The Carside Slope alarm parameter values that were in place at the time the train arrived at the site.</p> <ul style="list-style-type: none"> <li>• The value after Carside Slope is set by the Carside Slope option on the Alarm Settings menu.</li> <li>• The value after Minimum is set by the Carside Minimum option on the Alarm Settings menu.</li> </ul> <p><b>Section 4.0 - Serial Interface</b> tells how to set these values.</p>
Resistor Test Mode	<p>The status of the post-train resistor integrity test at the time the train arrived at the site. Valid values (aka modes) are Enabled, Reduced, and Disabled. <b>Section 4.0 - Serial Interface</b> tells how to set this value using the Resistor Test Mode option on the Equipment Settings menu.</p>
Software Version	<p>The version numbers of the firmware and their release dates, which are in yyy/mm/dd format. This firmware resides on the processor modules.</p>
AEI System Data	<p>The number of AEI tags read (by antenna0 and antenna1) and the total number of tags stored for the train. Where both tags of a tag pair are operational, each antenna will read one tag of the pair. The total number of tags stored represents the number of tag pairs found plus those single tags that lack a match. This heading and the columns under it appear only when the AEI subsystem is <u>enabled</u> using the AEI option on the Equipment Settings menu.</p>

The table below lists the fields from the system-events section and the contents of each field.

Heading	Contents of Field
System Alarms	<p>Lists any System Alarms detected at the time the train passed the site. If none were detected, this header is followed by the word "none."</p> <p><b>Appendix A - System Alarms</b> describes the conditions and events that the system flags as System Alarms.</p>
Integrity Failures	<p>Lists any Integrity Failures detected at the time the train passed the site. If none were detected, this header is followed by the word "none."</p> <p><b>Appendix B - Integrity Failures</b> describes the conditions and events that the system flags as Integrity Failures.</p>
Axle Alarm Summary	<p>Lists each Exception Alarm found on the train and the axle on which it was found. If none were found, this header is followed by the word "none."</p>
Announcements Made	<p>Lists the announcements transmitted on the designated radio frequency.</p>

The table below lists the fields from the detail section and the contents of each field.

Heading	Contents of Field
Car	The car number as determined by the firmware.
Axle	The axle number.
Rail	Under this heading are two columns, one for each bearing scanner, containing the temperature read by the bearing scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. If the Hotwheel option on the Equipment Settings menu is <u>disabled</u> , the word "Rail" doesn't appear, but the two columns do.
Wheel	Under this heading are two columns, one for each wheel scanner, containing the temperature read by the wheel scanners. If the track orientation is east and west, the wheel scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. This heading and the two columns under it appear only when the Hotwheel option on the Equipment Settings menu is <u>enabled</u> .
ON	The number of milliseconds a bearing was scanned.
OFF	The number of milliseconds between axles (when no axle was between the gating transducers).
PW1	The recorded width of the pulse generated by gating transducer TO1. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.
PW2	The recorded width of the pulse generated by gating transducer TO2. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.
Alarms	Any Exception Alarm found on the given axle.

To produce a Train Detail report:

- 1 Using the serial interface, display the Main menu.

**Section 4.0 - Serial Interface** tells how to display the Main menu. The Main menu looks like this.

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
      .
      .
      .
```

- 2 Select **Train Detail**.

This prompt appears.

```
Enter Train Number:
```

- 3 Type the train number.

If you typed a three-digit invalid train number, the Main menu reappears. If you typed a three-digit valid train number, a report for that train is produced. The last line of the report reads: "END OF REPORT - Press any key..."

- 4 If you typed one or two digits, press **[Enter]**.

If you typed an invalid train number, pressing **[Enter]** causes the Main menu to reappear. If the typed train number is valid, pressing **[Enter]** produces a report for it. The last line of the report reads: "END OF REPORT - Press any key..."

- 5 To return to the Main menu after a report is produced, press any key.

At this time, you can produce another report by selecting the appropriate option.

- 6 When done, close the LOG file.

- 7 To exit the serial interface and return the SmartScanNG<sup>2</sup> system to normal operation, type **X**.

### 6.3 Exception Summary Report

The Exception Summary report lists all trains currently stored in the Exceptions directory. (A train is stored in the Exceptions directory if either an Exception Alarm or an Integrity Failure was detected on it as it passed the site.) A train number is shown for each train entry so that an Exception Detail report may easily be produced for any train listed on the summary.

The report is divided into a header section and a detail section. The header section contains general information about the site. The detail section contains summary information on each exception train (that is, on each train having an Exception Alarm, an Integrity Failure, or both) that passed the site.

The SmartScanNG<sup>2</sup> system calculates a checksum for each train. This checksum is stored with the train data. Later, when the system retrieves this data, it recalculates the checksum. If the two checksums don't match, the Exception Summary report so states in the detail section. So, instead of getting a train record, you'll get a checksum-error line.

Below is a sample of part of an Exception Summary report when Hotwheel alarm detection was disabled during report processing and when the AEI subsystem was enabled during train passage. (When the report is run, if the Hotwheel option on the Equipment Settings menu is disabled, the hotwheel information is hidden. When the report is run, if the AEI option is disabled, the tag information is hidden.) The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

```

Southern Technologies Corporation
Next Generation Detector System
EXCEPTION SUMMARY
=====
Software Version: BNSF0001 2020-07-10                MP/KP: 1234.5
                                                    Track: Single

Current Alarm Settings
Absolute..... 200   Carside Slope... 1.60
Differential.. 130   Minimum..... 300
Hot Wheel..... 652   Cold Rail Temp.. 10

Total Trains: 2
=====
Train# Ref#   Date   Time Cars Axles TO1  TO2  r Min Max Xit  Bearing Bearing AEI  Amb  Bat
            Date   Time Cars Axles TO1  TO2  r Min Max Xit  Average Maximum Tags Temp
            Date   Time Cars Axles TO1  TO2  r Min Max Xit  East  West  East  West  Tags Temp
-----
  2 A   78  12/20/23 13:23  79  336  336  336 N  27  38  37   5   5   39  279  159  +61F 15.1v
  1 A   64  12/20/23 14:21  94  382  382  382 S  34  40  40  19  13  55  282  184  +66F 15.2v

```

Below is a sample of part of an Exception Summary report when the Hotwheel option on the Equipment Settings menu is enabled. The contents of your report will be different.

```

      .
      .
      .
Current Alarm Settings
Absolute..... 200   Carside Slope... 1.60
Differential.. 130   Minimum..... 300
Hot Wheel..... 652   Cold Rail Temp.. 10

Total Trains: 2
-----
Train# Ref#   Date   Time Cars Axles TO1   D   Bearing   Wheel
              i   Speed   Average   Maximum   AEI  Amb
              r Min Max Xit East  West  East  West  Tags Temp  Bat
-----
      .
      .
      .

```

The table below lists the fields from the header section and the contents of each field.

Heading	Contents of Field
Software Version	The version numbers of the firmware and their release dates, which are in yyyy/mm/dd format. This firmware resides on the processor modules.
MP/KP	The five-digit milepost/kilometer post of the site. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the MP/KP submenu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. <b>Section 4.0 - Serial Interface</b> tells how to set this value using the Track Number submenu of the Setup menu.
Current Alarm Settings	<p>The alarm parameters currently defined in the system setup. These values were in place at the time this report was run.</p> <ul style="list-style-type: none"> <li>• The value after Absolute is set by the Absolute option on the Alarm Settings menu.</li> <li>• The value after Differential is set by the Differential option on the Alarm Settings menu.</li> <li>• The heading Hot Wheel only appears when the Hotwheel option on the Equipment Settings menu is enabled. The value after Hot Wheel is set by the Hotwheel option on the Alarm Settings menu.</li> <li>• The value after Carside Slope is set by the Carside Slope option on the Alarm Settings menu.</li> <li>• The value after Minimum is set by the Carside Minimum option on the Alarm Settings menu.</li> <li>• The value after Cold Rail Temp is set by the Cold Rail Temperature option on the Alarm Settings menu.</li> </ul> <p><b>Section 4.0 - Serial Interface</b> tells how to set these values.</p>
Total Trains	The total number of trains with data currently stored in the Exceptions directory of the NG <sup>2</sup> .

The table below lists the fields from the detail section and the contents of each field.

Heading	Contents of Field
Train#	The number that identifies the train in the Exceptions directory.
	There is one unlabeled column between those labeled "Train#" and "Ref#." This column can contain <b>A, B, I, S</b> , or nothing. If "A," an Exception Alarm was detected on the train. If "I," an Integrity Failure was detected. If "B," both an Exception Alarm and an Integrity Failure were detected. If "S," a System Alarm was detected, but Exception Alarms and Integrity Failures weren't. If blank, no Exception Alarm, Integrity Failure, or System Alarm was detected.
Ref#	Represents the Train Sequence Number in the Train Summary.
Date	The date the train arrived at the site. Date is in mm/dd/yy format. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time the train arrived at the site. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Cars	The total number of cars counted by the SmartScanNG <sup>2</sup> system.
Axles	The total number of axles counted by the SmartScanNG <sup>2</sup> system.
TO1	The total number of hits counted by gating transducer TO1. TO1 is the first gating transducer going north or east from the bearing scanner. It is the gating transducer <u>closest</u> to the bearing scanner.
TO2	The total number of hits counted by gating transducer TO2. TO2 is the second gating transducer going north or east from the bearing scanner. It is the gating transducer <u>farthest</u> from the bearing scanner.
Dir	The direction the train was traveling. Valid values are N, S, E, and W.
Speed (mph)	The train's Min, Max, and exit speed in miles per hour.
Bearing Average	Under this heading are two columns, one for each bearing scanner, containing the average temperature read by the bearing scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west.
Wheel Maximum	Under this heading are two columns, one for each wheel scanner, containing the maximum temperature read by the wheel scanners. If the track orientation is east and west, the wheel scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. This field appears only when the Hotwheel option on the Equipment Settings menu is enabled.
AEI Tags	The total number of AEI tags stored. The number of tag pairs found plus those single tags that lack a match. This heading only appears if the AEI subsystem is enabled using the AEI option on the Equipment Settings menu.
Amb Temp	The ambient temperature, in degrees Fahrenheit, at the time the train arrived at the site.
Bat	The system battery voltage at the time the train passed the site.

To produce an Exception Summary report:

- 1 Using the serial interface, display the Main menu.

**Section 4.0 - Serial Interface** tells how to display the Main menu. The Main menu looks like this.

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
      :
      :
```

- 2 Select the **Exception Summary** report.

The last line of the report reads: "END OF REPORT - Press any key..."

- 3 To return to the Main menu, press any key.

At this time, you can produce another report by selecting the appropriate option.

- 4 When done, close the LOG file.

- 5 To exit the serial interface and return the SmartScanNG<sup>2</sup> system to normal operation, type **X**.

## 6.4 Exception Detail Report

The Exception Detail report provides detailed information on a single train. When choosing this report, you'll be prompted for a train number. When prompted, enter a train number from the Exception Summary report. The train number appears under the column titled "Train#" in the detail section of the Exception Summary report.

Carside Slope alarm detection is enabled/disabled using the Carside Slope option on the Equipment Settings menu. Hotwheel alarm reporting is enabled/disabled using the Hotwheel option on the Equipment Settings menu. The AEI subsystem is enabled/disabled using the AEI option on the Equipment Settings menu.

Where wheel scanners are properly installed, wheel temperatures are always recorded, even if the Hotwheel option is disabled. On the other hand, if the AEI option is disabled during train passage, no AEI information is recorded. If the Carside Slope option is disabled during train passage, no Carside Slope alarms are generated. But, if it is enabled at the time a report is requested, a carside-slope alarm-limit line is generated for each car of the train.

Below is a sample of part of an Exception Detail report when both the AEI option and Hotwheel option were enabled at the time the report was requested. The Carside Slope option was disabled. The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

```

Southern Technologies Corporation
Next Generation Detector System
EXCEPTION DETAIL
=====
Train#: 78                Axles: 336                Speed                    MP/KP: 1234.5
Date: 06/05/24           Cars: 79                  Min: 27                  Track: North
Time: 13:23              Direction: North          Max: 38                  Temperature: +61F
                        Shutters Open: 158       Avg: 32                  Battery: 15.1v
                        Length: 7205              Exit: 37
=====
Scanner      Max Avg Read Req CF      Txdr      Alarm      Limit  Carside Parm
-----
East Brng 39 5 241 232B 0  T01 336  Absolute  200  Slope: 1.60
West Brng 279 5 261 246B 0  T02 336  Differential 130  Minimum: 300
East Whl 41 1 42 18B 0      Hot Wheel 652
West Whl 6 0 49 27B 0      Cold Rail Temp 10
Resistor Test Mode: Disabled      High/Wide Alarm Direction: BOTH
=====
Software Version: BNSF_00-06 2020-02-11
=====
AEI System Data

Tags Read          Tags Stored: 159
-----
Antenna 0: 79
Antenna 1: 80

-----
System Alarms

None

-----
Axle Alarm Summary

113 West Rail Absolute

-----
.
.
.

(continued on next page)

```

•  
•  
•

-----  
Announcements made

" BNSF milepost 1 2 3 4 point 5 north track "  
" BNSF milepost 1 2 3 4 point 5 north track you have a defect "  
" BNSF milepost 1 2 3 4 point 5 north track hot box left side axle 1 1 3  
total axles 3 3 6 temperature 6 1 "  
" BNSF milepost 1 2 3 4 point 5 north track hot box left side axle 1 1 3  
total axles 3 3 6 temperature 6 1 "  
" BNSF milepost 1 2 3 4 point 5 north track hot box left side axle 1 1 3  
total axles 3 3 6 temperature 6 1 detector out "

-----

Car	Rail				Wheel				ON	OFF	PW1	PW2	Alarms
	Axle	East	West	East	West	East	West						
1	1	0	0	3	0	49	0	20	20	UP	8638		
	2	1	3	2	3	49	116	20	19				
	3	1	0	3	3	49	125	19	19				
	4	0	0	1	0	49	781	18	17				
	5	0	0	7	4	49	125	18	18				
	6	0	0	3	2	49	116	18	17				
	Carside Ave: East		0	West		0	Carside Alarms: East 255 West 255						
2	7	0	0	1	0	49	293	20	19	BNSF 5377			
	8	0	0	1	0	49	113	20	20				
	9	0	0	2	1	49	113	20	19				
	10	0	0	0	0	49	768	20	19				
	11	0	0	1	0	49	113	19	18				
	12	2	0	6	3	48	113	18	17				
	Carside Ave: East		0	West		0	Carside Alarms: East 255 West 255						
3	13	5	2	5	2	49	402	18	18	TTGX 254642			
	14	10	0	1	0	49	90	18	18				
	15	5	1	0	0	49	1435	18	18				
	16	3	1	0	0	49	90	18	18				
	Carside Ave: East		10	West		1	Carside Alarms: East 255 West 255						
4	17	7	5	1	0	48	505	18	17	TTGX 965878			
	18	8	5	5	2	48	90	18	17				
	19	1	2	2	0	48	1428	17	17				
	20	1	0	2	0	48	90	20	20				
	Carside Ave: East		8	West		6	Carside Alarms: East 255 West 255						
5	21	6	2	4	0	48	496	20	19	TTGX 977074			
	22	8	1	0	0	48	90	19	18				
	23	6	6	3	1	48	1417	19	18				
	24	3	1	1	0	48	89	18	18				
	Carside Ave: East		10	West		4	Carside Alarms: East 255 West 255						
6	25	3	1	1	0	48	495	19	19	TTGX 979693			
	26	6	2	0	0	48	89	18	18				
	27	0	2	2	0	48	1413	19	19				
	28	1	0	1	0	48	88	19	18				
	Carside Ave: East		4	West		2	Carside Alarms: East 255 West 255						

-----

•  
•  
•

The extended Exception Detail report is divided into three sections. The header section contains general information about the site (like the MP/KP) and some detail information about the specific train (like the train's exit speed) that passed the site. The detail section contains more detailed information (like the car number) about the specific train. In between these two sections is the system-events section, which contains all System Alarms and Exception Alarms associated with the train.

The SmartScanNG<sup>2</sup> system calculates a checksum for each train. This checksum is stored with the train data. Later, when the system retrieves this data, it recalculates the checksum. If the two checksums don't match, the extended Exception Detail report so states (as shown below).

```

Southern Technologies Corporation
Next Generation Detector System
EXCEPTION DETAIL
=====
CHECKSUM ERROR: StartAddr 134879 EndAddr 134930

```

In addition, each axle has a checksum associated with it. If an axle is determined to have an invalid checksum, the extended Exception Detail report so states in the associated axle's row (as shown below).

```

Southern Technologies Corporation
Next Generation Detector System
EXCEPTION DETAIL
=====
      .
      .
      .
-----
Car  Axle  Trk  North  South  ON  OFF  PW1  PW2  Alarms
-----
  1    1    0   56    21   25   0    6    6
    2    0   57    21   25   59    6    6
    3    0   56    21   25   59    8    8
    4      CHECKSUM ERROR: StartAddr 136416 EndAddr 136427
    5    1   56    21   25   59    6    6
    6    1   56    21   25   59    6    6

  2    7    2   56    20   25  162    6    6
    8    2   56    21   25   59    6    6

      .
      .
      .

```

The table below lists the fields from the header section and the contents of each field.

Heading	Contents of Field
Train#	The number that identifies the train in the Exceptions directory.
Date	The date the train arrived at the site. Date is in mm/dd/yy format. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time the train arrived at the site. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Axles	The total number of axles counted by the SmartScanNG <sup>2</sup> system.
Cars	The total number of cars counted by the SmartScanNG <sup>2</sup> system.
Direction	The direction the train was traveling. Valid values are North, South, East, and West.
Shutters Open	The number of seconds it took the train to pass over the site.
Length	The length of the train in feet.
Speed	The train's Min, Max, Avg, and exit speed in miles per hour.
MP/KP	The five-digit milepost/kilometer post of the site. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the MP/KP submenu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. <b>Section 4.0 - Serial Interface</b> tells how to set this value using the Track Number submenu of the Setup menu.
Temperature	The ambient temperature at the time the train arrived at the site. Temperature is in degrees Fahrenheit.
Battery	The system battery voltage at the time the train passed the site.
Scanner	Location of the scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west
Max	The maximum temperature, above the ambient temperature in degrees Fahrenheit, recorded by the scanner on a given railside. For example, if the ambient temperature (at the time the train arrived at the site) is 77°F (25°C) and the value in this field is 112, the maximum temperature would be 189°F (87.2°C).
Avg	The average temperature, above the ambient temperature in degrees Fahrenheit, calculated from all recorded temperatures from the scanner on a given railside. For example, if the ambient temperature (at the time the train arrived at the site) is 86°F (30°C) and the value in this field is 55, the average temperature would be 141°F (60.6°C).

Heading	Contents of Field
Resistor Read	The scanner resistor temperature (read after train passage), in degrees Fahrenheit, recorded by the scanner on a given rai1side.
Resistor Req	The resistor temperature, in degrees Fahrenheit, required by the scanner on a given rai1side to avoid a Cold Resistor alarm. This value was calculated using the amount of time the shutters were open and the Resistor Test Mode option in effect at the time the train exits the site. If the Resistor Test Mode option is <u>disabled</u> , a zero appears in this field.
	<p>One of five uppercase letters follows the Resistor Req temperature.</p> <ul style="list-style-type: none"> <li><b>B</b> The baseline resistor integrity test method was used for this train.</li> <li><b>D</b> The resistor integrity test (that is, the Resistor Test Mode option) was disabled by the user.</li> <li><b>I</b> The interim resistor integrity test method was used for this train.</li> <li><b>T</b> For this train, the shutters were open for less than 30 seconds.</li> <li><b>V</b> For this train, the battery voltage (measured with the shutters open) was less than 12.5 volts.</li> </ul> <p>For <b>D</b>, <b>T</b>, and <b>V</b>, the required resistor heat is set to zero (that is, a zero appears in the Resistor Read field). A <b>T</b> or <b>V</b> indicates that the integrity test was not performed due to low voltage or insufficient shutter open time, which could result in an invalid resistor integrity test if it was performed.</p>
CF	The percentage difference between the required resistor value and the value that was actually read. For example, if the required resistor temperature is 180 and the actual resistor temperature is 135 the correction factor would be 25% ( $1 - (135 / 180) = .25$ ), and 25 would appear in this field.
Txdr Counts	The gating transducer designator (either TO1 or TO2) followed by the total number of hits on that transducer.
Alarm Limit	<p>The Hotwheel alarm level; the Hot Journal alarm levels for Absolute and Differential; and the Cold Rail Temperature offset. These values were in place at the time the train arrived at the site.</p> <ul style="list-style-type: none"> <li>• The value after Absolute is set by the Absolute option on the Alarm Settings menu.</li> <li>• The value after Differential is set by the Differential option on the Alarm Settings menu.</li> <li>• The value after Hot Wheel is set by the Hotwheel option on the Alarm Settings menu.</li> <li>• The value after Cold Rail Temp is set by the Cold Rail Temperature option on the Alarm Settings menu.</li> </ul> <p><b>Section 4.0 - Serial Interface</b> tells how to set these values.</p>

Heading	Contents of Field
Carside Parm	<p>The Carside Slope alarm parameter values that were in place at the time the train arrived at the site.</p> <ul style="list-style-type: none"> <li>• The value after Carside Slope is set by the Carside Slope option on the Alarm Settings menu.</li> <li>• The value after Minimum is set by the Carside Minimum option on the Alarm Settings menu.</li> </ul> <p><b>Section 4.0 - Serial Interface</b> tells how to set these values.</p>
Resistor Test Mode	<p>The status of the post-train resistor integrity test at the time the train arrived at the site. Valid values (aka modes) are Enabled, Reduced, and Disabled. <b>Section 4.0 - Serial Interface</b> tells how to set this value using the Resistor Test Mode option on the Equipment Settings menu.</p>
High/Wide Alarm Direction	Displays selected option from the Configuration Options menu.
Software Version	The version numbers of the firmware and their release dates, which are in yyyy/mm/dd format. This firmware resides on the processor modules.
AEI System Data	The number of AEI tags read (by antenna0 and antenna1) and the total number of tags stored for the train. Where both tags of a tag pair are operational, each antenna will read one tag of the pair. The total number of tags stored represents the number of tag pairs found plus those single tags that lack a match. This heading and the columns under it appear only when the AEI subsystem is <u>enabled</u> using the AEI option on the Equipment Settings menu.

The table below lists the fields from the system-events section and the contents of each field.

Heading	Contents of Field
System Alarms	<p>Lists any System Alarms detected at the time the train passed the site. If none were detected, this header is followed by the word "none."</p> <p><b>Appendix A - System Alarms</b> describes the conditions and events that the system flags as System Alarms.</p>
Integrity Failures	<p>Lists any Integrity Failures detected at the time the train passed the site. If none were detected, this header is followed by the word "none."</p> <p><b>Appendix B - Integrity Failures</b> describes the conditions and events that the system flags as Integrity Failures.</p>
Axle Alarm Summary	Lists each Exception Alarm found on the train and the axle on which it was found. If none were found, this header is followed by the word "none."
Announcements Made	Lists the announcements transmitted on the designated radio frequency.

The table below lists the fields from the detail section and the contents of each field.

Heading	Contents of Field
Car	The car number as determined by the firmware.
Axle	The axle number.
Rail	Under this heading are two columns, one for each bearing scanner, containing the temperature read by the bearing scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. If Hotwheel alarm detection is <u>disabled</u> , the word "Rail" doesn't appear, but the two columns do.
Wheel	Under this heading are two columns, one for each wheel scanner, containing the temperature read by the wheel scanners. If the track orientation is east and west, the wheel scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. This heading and the two columns under it appear only when Hotwheel alarm detection is <u>enabled</u> .
ON	The number of milliseconds a bearing was scanned.
OFF	The number of milliseconds between axles (when no axle was between the gating transducers).
PW1	The recorded width of the pulse generated by gating transducer TO1. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.
PW2	The recorded width of the pulse generated by gating transducer TO2. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.
Alarms	Any Exception Alarm found on the given axle.

To produce the extended Exception Detail report:

- 1 Using the serial interface, display the Main menu.

**Section 4.0 - Serial Interface** tells how to display the Main menu. The Main menu looks like this.

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
      .
      .
      .
```

- 2 Select **Exception Detail**.

This prompt appears.

```
Enter Train Number:
```

- 3 Type the train number.

If you typed a three-digit invalid train number, the Main menu reappears. If you typed a three-digit valid train number, the prompt below appears.

- 4 If you typed one or two digits, press **[Enter]**.

If you typed a three-digit invalid train number, the Main menu reappears. If you typed a three-digit valid train number, this prompt appears.

```
Abbreviated? (y/n)
```

- 5 To produce the extended Exception Detail report, type **N**.

If you typed an invalid train number, the Main menu reappears. If the typed train number is valid, a report for that train is produced.

- 6 To return to the Main menu after a report is produced, press any key.

At this time, you can produce another report by selecting the appropriate option.

- 7 When done, close the LOG file.

- 8 To exit the serial interface and return the SmartScanNG<sup>2</sup> system to normal operation, type **X**.

## 6.5 Abbreviated Exception Detail Report

The abbreviated Exception Detail report is like the extended Exception Detail report. However, the abbreviated report doesn't display all the recorded axle data. It only displays axle data for:

- The car immediately preceding a car with an alarmed axle.
- The car containing the alarmed axle.
- The car immediately following the car with the alarmed axle.

For example, assume that a train consisted of 3 locomotives and 20 cars, and Exception Alarms were found on cars 3, 10, 15, and 17. The Abbreviated Exception Detail report for this train would only list axle data for cars 2, 3, 4, 9, 10, 11, 14, 15, 16, 17, and 18. These car numbers comprise the alarmed cars themselves and all cars immediately before and immediately after them.

Like the extended Exception Detail report, the abbreviated Exception Detail report is divided into three sections. The header section contains general information about the site (like the MP/KP) and some detail information about the specific train (like the train's exit speed) that passed the site. The detail section contains more detailed information (like the car number) about the specific train. In between these two sections is the system-events section, which contains all System Alarms and Exception Alarms associated with the train.

Below is a sample of part of an abbreviated Exception Detail report when the AEI option was enabled and the Carside Slope option, and the Hotwheel option were disabled at the time the report was requested. The contents of your report will be different.

Southern Technologies Corporation  
 Next Generation Detector System  
 EXCEPTION DETAIL  
 ABBREVIATED

```

=====
Train#: 30           Axles: 572           Speed           MP/KP: 1234.5
Date: 06/05/24     Cars: 141           Min: 28         Track: North
Time: 11:30        Direction: South    Max: 30         Temperature: +66F
                   Shutters Open: 202 Avg: 29          Battery: 13.4v
                   Length: 8362        Exit: 29
=====
  
```

•  
•  
•

Axle Alarm Summary

```

-----
327 East Hot Wheel
328 West Hot Wheel
  
```

```

-----
Car  Axle  Trk  North  South  ON  OFF  PW1 PW2  Alarms
-----
 79  321   7   21    0    16  45  125  18  17  CLBX  60921
     322  24   29    0     0  45   87  19  19
     323   2    1    0     0  45  975  17  17
     324   1    3    0    58  45   87  19  18
     Carside Ave: East 16 West 25  Carside Alarms: East 110 West 122

 80  325  15   29   339  328  45  130  18  18  RCRX  2419
W   326  22   38   408  246  45   88  18  17
W   327  22   33   528  415  45  629  17  16  East Hot Wheel
W   328  16   34   442  532  45   88  18  18  West Hot Wheel
     Carside Ave: East 29 West 50  Carside Alarms: East 127 West 155

 81  329   6   20   113   36  45  128  15  15  OFOX  7808
     330  22    7    0    28  45   88  17  16
     331  15   24    0     0  45  991  17  16
     332  12   21    0     0  45   87  17  16
     Carside Ave: East 21 West 25  Carside Alarms: East 117 West 122
  
```

To produce the abbreviated Exception Detail report:

- 1 Using the serial interface, display the Main menu.

**Section 4.0 - Serial Interface** tells how to display the Main menu. The Main menu looks like this.

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
      .
      .
      .
```

- 2 Select **Exception Detail**.

This prompt appears.

```
Enter Train Number:
```

- 3 Type the train number.

If you typed a three-digit invalid train number, the Main menu reappears. If you typed a three-digit valid train number, the prompt below appears.

- 4 If you typed one or two digits, press **[Enter]**.

If you typed a three-digit invalid train number, the Main menu reappears. If you typed a three-digit valid train number, this prompt appears.

```
Abbreviated? (y/n)
```

- 5 To produce the abbreviated Exception Detail report, type **Y**.

If you typed an invalid train number, the Main menu reappears. If the typed train number is valid, a report for that train is produced. The last line of the report reads: "END OF REPORT - Press any key..."

- 6 To return to the Main menu after a report is produced, press any key.

At this time, you can produce another report by selecting the appropriate option.

- 7 When done, close the LOG file.

- 8 To exit the serial interface and return the SmartScanNG<sup>2</sup> system to normal operation, type **X**.

## 6.6 System Status Report

The System Status report contains the system's current setup configuration. Once a SmartScanNG<sup>2</sup> system is set up properly, print this report. Then, keep it in the wayside enclosure for future reference. Should you ever need to set up the system again, you'll have most of the information you'll need on this report. Below is a sample of the top half of a System Status report. The contents of your report will be different.

```

=====
                        Southern Technologies Corporation
                        Next Generation Detector System
                        SYSTEM STATUS REPORT
=====
                        Date:07/20/24   Time:09:36   Battery: 14.6v   Ambient Temp.: -2F
=====
SICM Board Rev..... 1.3           MP/KP..... 1234.5
Time Zone..... Eastern           Track..... Single
Daylight Savings Time..... Disabled   Track Dir..... N/S
AC Power..... On                 Talker Mode..... Talk Freely
N/E Integ Mode..... 5B-Integ Fail   S/W Integ Mode..... 5B-Integ Fail
Velocity..... COM3

Software Version
-----
BNSF0001 2020-07-10

Speech Version
-----
BNSF English Ryan 1.0

Alarm Settings
-----
Absolute..... 170           Differential..... 150
Hot Wheel..... 900         Cold Rails..... 3
Cold Rail Temp..... 10     Cold Res Counter..... 3
Differential Enabled..... Yes

Alarm Settings (Advanced)
-----
Carside Slope..... 1.31       Carside Minimum..... 155
Res Test: Minimum Rail Avg..... 25   Res Test: Minimum Wheel Avg..... 28
Bearing DSR Capture Temp..... 100    Wheel DSR Capture Temp..... 300
Max Alarms..... 13

Equipment Settings
-----
Dragger..... Yes           Hot Wheel..... Yes
Hot Bearing..... Yes       High Load..... No
Wide Load..... No         AEI..... No
Presence Hardware..... Yes   Advance Transducers..... No
Scanner Heater AC Monitor..... Yes   Main AC Power Monitor..... No
DC Power Monitor..... No     Surge Protector Monitor..... No

Equipment Settings (Advanced)
-----
Carside Slope..... Yes       Winter Cycle..... Oct - Mar
Gate Distance..... 24.0 in   Dragger Debounce Time..... 100 ms
Pre Train Dragger Dist..... 6 ft   Pre Train High/Wide Dist..... 6 ft
Presence Timeout Period..... 10 sec  System Voltage..... 12 V
Resistor Test..... Enabled     Clearance Mode..... Multiplexed
Clearance Type..... Light Beam   Transducer Gain..... Normal
Transducer Type..... Magnetic
.
.
.

```

Below is a sample of the bottom half of a System Status report. The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

```

      .
      .
      .
Message Settings
-----
Arrival Message..... No      Customer Name..... Yes
Axles..... Yes             Speed..... No
Temperature..... No        Slow..... Yes
Power Off..... No          Repeat No Defects..... Yes
Length..... No             Cars Count..... No
Lft/Rt Alarm Ref..... Yes   Car ID With Alarm..... No
Announce Differentials..... No Include Details In Realtime..... No

Message Settings (Advanced)
-----
Announce Hot Wheels..... No      Announce High/Wide..... Yes
Rebroadcast Time Limit..... 5 min Rebroadcast DTMF Code..... 001
Num EOT Repeats..... 1          EOT Repeat Delay..... 5 sec

Network Settings
-----
Use Static Address..... Yes      Static IP..... 10.14.22.56
Static Mask..... 255.255.255.0   Default Gateway..... 192.168.1.1
DNS Server..... 192.168.1.1      TELNET Port..... 23
FTP Port..... 21                HTTP Port..... 80
HTTPS Port..... 8080            Use Wifi..... No
Wifi Inactivity Timeout..... 10 min

Sunshots
-----
Sunshot Override..... No        Scanner Orientation..... 0
Latitude..... 35.0456           Longitude..... -85.3097
Dynamic Scan Window Start..... 10 Dynamic Scan Window End..... 38

Port Settings
-----
COM1..... Baud 19200 NA/NA      COM2..... Baud 19200 NA/NA
COM3..... Baud 19200 NA/NA      COM4..... Baud 19200 NA/NA
COM5..... Baud 19200 NA/NA      COM6..... Baud 19200 NA/NA
RS485..... Baud 9600 NA/NA      Page Lines..... 30

AEI Settings
-----
Tag Reader Type..... None        ID Separation..... 2
Consecutive Reads..... 2         RF Frequency (MHz)..... 915.000
RF Attenuation (dB)..... 0       Multi-Track Tag Filter..... Disabled

Scanner Calibration Date / Digital Potentiometer Settings
-----
Rail 1 Type III..... 07/12/2020 14:45 / 55   Rail 2 Type III..... 07/12/2020 14:52 / 69
Wheel 1 Type III..... 07/12/2020 14:49 / 41   Wheel 2 Type III..... 07/12/2020 14:54 / 63

Resistor Baseline
-----
Rail 1 Type III..... Valid       Rail 2 Type III..... Valid
Wheel 1 Type III..... Valid       Wheel 2 Type III..... Valid

```

The table below lists the fields on the System Status report and the contents of each field.

Heading	Contents of Field
Date	The date at the time this report was generated. Date is in mm/dd/yy format. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time at the time this report was generated. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Battery	The system battery voltage at the time this report was generated.
Ambient Temp	The ambient temperature at the time this report was generated. Temperature is in degrees Fahrenheit.
SICM Bd Rev	The board revision of the installed system interconnect module.
MP/KP	The five-digit milepost/kilometer post of the site. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the MP/KP submenu.
Time Zone	The time zone that is currently defined in the system setup. Valid values are Eastern, Central, Mountain, and Pacific. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Track Number submenu of the Setup menu.
Daylight Savings Time	Whether daylight-saving time is to be observed or not. If disabled, all times throughout the year are in standard time. If enabled, all times between the second Sunday in March and the first Sunday in November are in daylight-saving time. All other times are in standard time. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Track Dir	The track direction of the site. Valid values are N/S (for north/south) and E/W (for east/west). <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Track Number submenu of the Setup menu.
AC Power	Indicates if AC power is currently present.
Velocity	Indicates which Comm port is connected to the Velocity.
Multitech	Indicates which Comm port is connected to the Multitech or if it is disabled.
Software Versions	The version numbers of the firmware and their release dates, which are in yyyy/mm/dd format. This firmware resides on the processor modules.
Speech Version	The version numbers of the Speech files.

Heading	Contents of Field
Alarm Settings	The alarm parameters and limits as they are currently defined in the system setup. <b>Section 4.0 - Serial Interface</b> tells how to change these parameters and limits using the Alarm Settings menu of the Setup menu.
Equipment Settings	Equipment configuration as currently defined in the system setup. <b>Section 4.0 - Serial Interface</b> tells how to change this configuration using the Equipment Settings menu of the Setup menu.
Message Settings	Message configuration as currently defined in the system setup. <b>Section 4.0 - Serial Interface</b> tells how to change this configuration using the Messages menu of the Setup menu.
Network Settings	The network parameters and limits as they are currently configured in the system setup.
Sunshots	The sunshot parameters as they are currently configured in the system setup.
Port Settings	Communications port parameter settings as currently defined in system setup. These parameters reflect the baud rate and parity settings for each communications port. <b>Section 4.0 - Serial Interface</b> tells how to change these parameter settings using the Setup menu.
AEI Settings	This heading appears when the AEI subsystem is enabled using the AEI option on the Equipment Settings menu. <b>Section 4.0 - Serial Interface</b> tells how to set these values using the AEI Reader Parameters menu of the Setup menu.
Scanner Cal. Date	Date and time each scanner was last calibrated. The autocalibration function maintains these fields.
Resistor Baseline	<b>See the explanation below.</b>

For the resistor integrity test that is performed after train passage, there are two methods used to calculate the expected resistor temperature. The baseline resistor integrity test method requires the prerequisite of valid resistor baseline data to be stored in nonvolatile memory. Until the system acquires this data, it applies the interim resistor integrity test method to each train. The resistor data used in the baseline resistor integrity test method appears at the bottom of the System Status report, as shown below.

Resistor Data																						
-----																						
VOLTS	AMB	DATE	TIME	STATUS	30	40	50	60	70	80	90	100	110	120	130							
140	160	180	200	220	240	260	280	300	320	340	360	380	400	420	440	460	480					
-----																						
RAIL 1 (TypeII)																						
13.2	043	12/02/09	15:57	VALID	56,	71,	82,	91,	100,	105,	111,	116,	118,	122,	124							
					127,	130,	134,	136,	137,	140,	141,	142,	144,	145,	147,	148,	149,	150,	151,	152,	154,	154
RAIL 2 (TypeII)																						
13.2	043	12/02/09	15:57	VALID	58,	71,	81,	89,	96,	101,	105,	109,	110,	112,	115							
					117,	118,	122,	123,	125,	125,	128,	129,	130,	131,	132,	134,	134,	135,	137,	137,	138,	138

Included in the data above is a resistor heat profile of each scanner resistor, which covers a period of 30 to 480 seconds, in 10 and 20-second intervals. The differences in resistor heat between the two scanners are due to the cable lengths used in this example. A 65-foot (19.8-meter) cable for the rail1 bearing scanner and a 100-foot (30.5-meter) cable for the rail2 bearing scanner. Additional items in the data are the battery voltage measured with the shutters open, the date and time of the data acquisition, and the status of the heat profile data.

In this example, the status of both sets of resistor data is **VALID**, meaning they are being used in the baseline integrity test for each train. There are two other possibilities for status, pending and invalid. If the word **PENDING** appears in the status column, the system is waiting for the resistors to cool before acquiring resistor data or for the battery to charge to 12.5 volts. **INVALID** indicates that the system has tried twice and could not acquire valid resistor data. In either case, the system applies the interim integrity test to passing trains, which doesn't require resistor baseline data.

The system acquires the resistor data 20 minutes after the user calibrates the scanners with the autocalibration function. The resistor data acquisition runs unattended. Twenty minutes is the cooling period required to allow the resistors to return to ambient temperature after autocalibration. If a train should interrupt the cooling period, the resistor data acquisition runs 20 minutes after the shutters close following the passage of the train.

During the resistor-cooling period, the system announces through the speaker the following. These announcements aren't broadcast over the radio.

- A beep sounds once per minute until two minutes before the resistor test.
- At two minutes until the test, "Scanner resistor test beginning in 2 minutes" is voiced.
- At one minute until the test, "Scanner resistor test beginning in 1 minute" is voiced.

After the resistor cooling period:

- As the test begins, "Testing" is voiced. During this time, the word **PENDING** appears in the status column of the Resistor Data section.
- If the test was successful, "System working" is voiced. The word **VALID** appears in the status column of the Resistor Data section, signifying that the baseline test applies to each passing train.
- If the test wasn't successful, "Scanner resistor test beginning in two-zero minutes" is voiced, meaning that the system will try once more after 20 minutes to acquire an accurate resistor heat profile. During this time, the word **PENDING** appears in the status column of the Resistor Data section. If the test fails a second time, the word **INVALID** appears in the same column. The system applies the interim integrity test to each passing train while either **PENDING** or **INVALID** appears.

To produce a System Status report:

- 1 Using the serial interface, display the Main menu.

**Section 4.0 - Serial Interface** tells how to display the Main menu. The Main menu looks like this.

```
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
      .
      .
      .
```

- 2 Select **System Status**.
- 3 After producing the report, you are returned to the Main menu. At this time, you can produce another report by selecting the appropriate option.
- 4 When done, close the LOG file.
- 5 To exit the serial interface and return the SmartScanNG<sup>2</sup> system to normal operation, type **X**.

## 6.7 AEI Diagnostic Detail Report

The AEI Diagnostic Detail report provides detailed information on a single train. It contains information that can be useful in troubleshooting AEI-related problems. When choosing this report, you'll be prompted for a train number. When prompted, type a train number from the Train Summary report. The train number appears under the column titled "Train#" in the detail section of that report.

The AEI subsystem is enabled/disabled using the AEI option on the Equipment Settings menu. If the AEI option is disabled during train passage, no AEI information is recorded.

Below is a sample of part of an AEI Diagnostic Detail report when both the AEI option and the Hotwheel option on the Equipment Settings menu were enabled at the time the report was requested. The Carside Slope option on the Equipment Settings menu was disabled. Also, both the AEI and Hotwheel options were enabled while the specified train was passing the site. The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

Like the Train Detail report, the AEI Diagnostic Detail report is divided into three sections. The header section contains general information about the site (like the MP/KP) and some detail information about the specific train (like the train's exit speed) that passed the site. The detail section contains more detailed information (like the car number) about the specific train. In between these two sections is the system-events section, which contains all System Alarms and Exception Alarms associated with the train.

Southern Technologies Corporation  
 Next Generation Detector System  
 AEI Diagnostic

```

=====
Train#: 1215           Speed: 30MPH           MP/KP: 1234.5
Date: 06/10/24       Axles: 340           Track: Single
Time: 06:47          Direction: South      Temperature: +67F
Length: 5064         Shutters Open: 113   Battery: 13.9v
=====
  
```

```

=====
AEI System Data:
Tags Read: 147           Length: 5076
Antenna 0: 81           Axles: 337
Antenna 1: 66
=====
  
```

```

=====
T94 Report Data:
Locomotives - Tagged: 2   Untagged: 0   Conversion Status: A
Railcars    - Tagged: 76  Untagged: 6   Conversion Status: A
Status Codes- Equip : A   Movement: A   Termination: N
Speed       -   Min: 30   Max: 38       Avg: 34
Errors     - Length: 0   Platform: 3
=====
  
```

```

=====
Software Version   Package: xNS_00-73 2020-04-15 09-48-27
=====
  
```

```

-----
TMSTMP Axle Truck On Off PW1 PW2
00000 Car=1, Axles=6, Trks=2, Tags=2, Spd=38, Len=72, Ant1Window=00000|02174
01763 1 1 35 1748 20 20
01874 2 1 34 79 20 19

01994 3 1 35 85 22 20
02000 *BNSF 1804 side=R trk=1 len=76 axls=6 S|L|0|4 hs0= 9 hs1= 3 flags=211 rcvdTS=02116|02118|04365 QCnt=0

02436 BNSF 1804 side=L trk=2 len=76 axls=6 S|L|0|4 hs0= 9 hs1= 3 flags=124 rcvdTS=02566|02569|04365 QCnt=0
02543 4 2 34 513 20 20
02663 5 2 34 85 20 19
02777 6 2 35 80 22 20
02892 CarEnd= 1, flags=6, Ant0Window=02423|02892

02893 Car=2, Axles=6, Trks=2, Tags=2, Spd=38, Len=72, Ant1Window=02893|03420
03007 7 3 34 193 20 20
03120 8 3 34 80 20 20
03123 *BNSF 1015 side=L trk=3 len=74 axls=6 S|L|0|4 hs0= 0 hs1= 7 flags=201 rcvdTS=03215|03415|05113 QCnt=0
03240 9 3 35 85 22 20

03770 trk= 4 hs0=02 hs1=00 flags=10C rcvdTS=03915|03965|05113 QCnt=0
03814 10 4 35 537 20 19
03933 11 4 35 84 20 19
04049 12 4 36 79 20 18
04141 CarEnd= 2, flags=2, Ant0Window=03695|04141

04142 Car=3, Axles=4, Trks=2, Tags=2, Spd=38, Len=44, Ant1Window=04142|04485
04200 *EDFX201593 side=R trk=5 len=43 axls=4 S|R|0|4 hs0=19 hs1= 5 flags=211 rcvdTS=04365|04515|06114 QCnt=0
04233 13 5 35 148 20 19
04334 14 5 35 64 20 19

04731 EDFX201593 side=L trk=6 len=43 axls=4 S|R|0|4 hs0=19 hs1= 5 flags=124 rcvdTS=04766|04769|06114 QCnt=0
04739 15 6 35 370 19 18
04840 16 6 35 64 19 18
04907 CarEnd= 3, flags=5, Ant0Window=04638|04907
  
```

•  
•  
•

The table below lists the fields from the header section and the contents of each field.

Heading	Contents of Field
Train#	The number that identifies the train in the Trains directory.
Date	The date the train arrived at the site. Date is in mm/dd/yy format. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time the train arrived at the site. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the Date and Time submenu of the Setup menu.
Length	The length of train in feet.
Speed	The train's exit speed in miles per hour.
Axles	The total number of axles counted by the SmartScanNG <sup>2</sup> system.
Direction	The direction the train was traveling. Valid values are North, South, East, and West.
Shutters Open	The number of seconds it took the train to pass over the site.
MP/KP	The five-digit milepost/kilometer post of the site. <b>Section 4.0 - Serial Interface</b> tells how to change this value using the MP/KP submenu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. <b>Section 4.0 - Serial Interface</b> tells how to set this value using the Track Number submenu of the Setup menu.
Temperature	The ambient temperature at the time the train arrived at the site. Temperature is in degrees Fahrenheit.
Battery	The system battery voltage at the time the train passed the site.
AEI System Data	The number of AEI tags read (by antenna0 and antenna1) and the total number of tags stored for the train. Where both tags of a tag pair are operational, each antenna will read one tag of the pair. The total number of tags stored represents the number of tag pairs found plus those single tags that lack a match. This heading and the columns under it appear only when the AEI subsystem is enabled using the AEI option on the Equipment Settings menu.
T94 Report Data	Locomotives & railcars (tagged/untagged), status codes, movement codes, platform codes, etc.
Software Version	The version numbers of the firmware and their release dates, which are in yyyy/mm/dd format. This firmware resides on the processor modules.

The following excerpt is from the detail section of the AEI Diagnostic report

```

      .
      .
      .
TMSTMP Axle Truck On Off PW1 PW2
00000 CarStart=1, Axles=4, Trucks=2, Tags=1, Speed=23, Len=59
00026      1      1      58      0      19      19
00285      2      1      59      203      12      10

00945      BNSF 6113 side=L trk=2 len=59 axls=4 51|5|0|2 hs0= 0 hs1=13 flags=181
01030      3      2      58      685      20      20
01294      4      2      58      205      15      14
01535 CarEnd= 1
      .
      .
      .

```

The table below lists the fields from the detail section and the contents of each field.

Heading	Contents of Field
TMSTMP	The timestamp of a recorded event in milliseconds after train detection.
Axle	The axle number.
Truck	The truck number. Each railroad vehicle has two or more trucks (that is, wheel assemblies). The trucks are numbered, starting with 0, and increasing from the beginning of the train to the end. Each axle record is associated with one of these trucks. The axles are assigned the number of the truck with which they've been associated. These assigned truck numbers appear in this field. If the Hotwheel option on the Equipment Settings menu is <u>enabled</u> , this field doesn't appear.
ON	The number of milliseconds a bearing was scanned.
OFF	The number of milliseconds between axles (when no axle was between the gating transducers).
PW1	The recorded width of the pulse generated by gating transducer TO1. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.
PW2	The recorded width of the pulse generated by gating transducer TO2. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.

The AEI Diagnostic report has one line of data for every AEI tag associated with each car. See highlighted data line in the example below.

```

      •
      •
      •

TMSTMP Axle Truck On Off PW1 PW2
00000 CarStart=1, Axles=4, Trucks=2, Tags=1, Speed=23, Len=59
00026      1      1      58      0      19      19
00285      2      1      59      203      12      10

00945      BNSF 6113 side=L trk=2 len=59 axls=4 51|5|0|2 hs0= 0 hs1=13 flags=181
01030      3      2      58      685      20      20
01294      4      2      58      205      15      14
01535 CarEnd= 1
      •
      •
      •

```

The table below defines the relevant fields in the AEI tag portion of car data.

Field Value	Field Definition
00945	Timestamp of tag read.
BNSF 6113	AEI vehicle identification
side=L	Left side of car
trk=2	Truck two of car.
len=59	Car length of 59 feet.
axls=4	Four-axle car.
51 5 0 2	<b>51</b> is the Data Format Code. <b>5</b> is the Equipment Group Code (5 = locomotive). <b>0</b> is the Platform Code. <b>2</b> is the Tag Type.
hs0= 0	Handshakes on antenna-0 equal zero.
hs1=13	Handshakes on antenna-1 equal thirteen.
flags=181	Diagnostic code (for STC use)

To produce an AEI Diagnostic report:

- 1 Using the serial interface, display the Main menu.

**Section 4.0 - Serial Interface** tells how to display the Main menu. The Main menu looks like this.

```
      .
      .
      .
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event log
      .
      .
      .
```

- 2 Select **AEI Diagnostic**.

This prompt appears.

```
Enter Train Number:
```

- 3 Type the train number.

If you typed a three-digit invalid train number, the Main menu reappears. If you typed a three-digit valid train number, a report for that train is produced. The last line of the report reads: "END OF REPORT - Press any key..."

- 4 If you typed one or two digits, press **[Enter]**.

If you typed an invalid train number, pressing **[Enter]** causes the Main menu to reappear. If the typed train number is valid, pressing **[Enter]** produces a report for it. The last line of the report reads: "END OF REPORT - Press any key..."

- 5 To return to the Main menu after a report is produced, press any key.

At this time, you can produce another report by selecting the appropriate option.

- 6 When done, close the LOG file.

- 7 To exit the serial interface and return the SmartScanNG<sup>2</sup> system to normal operation, type **X**.

## 6.8 Event Log Report

The Event Log report is used for diagnostics. As certain system events occur, entries are posted into the event log. Each time an entry is made into this log, it receives an event number, the date and time that the event was recorded, and event description.

The entries are stored in a section of SRAM that can hold up to 300 separate entries. Each time an event is recorded which exceeds this maximum, the new one overwrites the oldest recorded event. The entries are saved during a power outage but can be deleted with the Clear Event Log option on the System Functions menu. Producing the report at this time produces a "No Events" message. If events have been recorded and not cleared, they're listed in chronological order, beginning with the most recently recorded event.

Below is a sample of part of an Event Log report. The contents of your report will be different. The date/time at the top of the report is the system date/time at the time the report was generated. Each line of text (that is, each event) contains these fields.

- The date at which the event was recorded (date is in mm/dd/yyyy format)
- The time at which the event was recorded (time is in 24-hour hh:mm:ss format, where 8 a.m. is 08:00:00, noon is 12:00:00, 8 p.m. is 20:00:00, and midnight is 00:00:00)
- The task priority (number in parenthesis –used for diagnostic purposes)
- The event description

```
Log: /FLASH/SYSTEM/logs/EVENTLOG.txt
-----
[06/05/2024 13:05:57] (55) - Admin logged in: id-26, telnet ip-184.174.165.45
[06/05/2024 12:52:42] (48) - Stored train #1113
[06/05/2024 12:52:42] (48) - Train Departure
[06/05/2024 12:52:09] (48) - Train Arrival
[06/05/2024 11:51:36] (55) - Admin logged out: id-26
[06/05/2024 11:48:57] (55) - Admin logged in: id-26, telnet ip-184.174.165.45
[06/05/2024 11:48:39] (55) - Telnet Connection timed out: id-26
[06/05/2024 11:38:08] (55) - Admin logged in: id-26, telnet ip-184.174.165.45
[06/05/2024 11:27:33] (48) - Stored train #1112
[06/05/2024 11:27:24] (48) - Train Departure
[06/05/2024 11:25:08] (48) - Train Arrival
[06/05/2024 10:43:55] (48) - Stored train #1111
[06/05/2024 10:43:44] (48) - Train Departure
[06/05/2024 10:40:27] (48) - Train Arrival
[06/05/2024 10:03:53] (48) - Stored train #1110
[06/05/2024 10:03:43] (48) - Train Departure
[06/05/2024 10:01:12] (48) - Train Arrival
[06/05/2024 09:00:04] (48) - Stored train #1109
[06/05/2024 08:59:55] (48) - Train Departure
[06/05/2024 08:57:50] (48) - Train Arrival
[06/05/2024 08:50:46] (55) - Admin logged out: id-27
[06/05/2024 08:43:45] (55) - Admin logged in: id-27, telnet ip-184.174.165.45
[06/05/2024 08:42:46] (55) - Telnet Connection timed out: id-27
[06/05/2024 08:16:26] (55) - Admin logged in: id-27, telnet ip-184.174.165.45
[06/05/2024 08:12:09] (55) - Telnet Connection timed out: id-27
[06/05/2024 08:00:51] (55) - Admin logged in: id-27, telnet ip-184.174.165.45
      •
      •
      •
```

To produce an Event Log report:

- 1 Using the serial interface, display the Main menu.

**Section 4.0 - Serial Interface** tells how to display the Main menu. The Main menu looks like this.

```
      .  
      .  
      .  
[F] - Train DSRs  
[G] - AEI Diagnostic  
[I] - Setup  
[J] - Event log  
      .  
      .  
      .
```

- 2 Select **Event Log**.

The last line of the report reads: "END OF REPORT - Press any key..."

- 3 To return to the Main menu, press any key.

At this time, you can produce another report by selecting the appropriate option.

- 4 When done, close the LOG file.

- 5 To exit the serial interface and return the SmartScanNG<sup>2</sup> system to normal operation, type **X**.

## 7.0 Radio Announcements

---

The NG<sup>2</sup> reports defects in two ways:

- Announcements made via the road channel
- Reports, which may be printed to provide detailed defect information

This section describes radio announcements. The prior section described reports.

Radio announcements consist of a set of predefined spoken messages with each message triggered by a particular event or set of events. The message formats and announcement criteria are covered below.

In the examples that follow, the message "BNSF" is announced because it was enabled using the **Announce Customer Name option** on the Messages menu. **Section 4.0 - Serial Interface** tells how to enable and disable this message.

Anytime a message needs to be announced, the expanded holdoff logic kicks in, and the process is as follows:

- 1 Check the Holdoff line.  
The Holdoff line is enabled when the road channel is busy.
- 2 If the Holdoff line is free, announce your messages and skip the remaining steps.
- 3 If the Holdoff line is currently in use, start the Holdoff timer and begin monitoring the Holdoff line.
- 4 If the Holdoff line frees up before the Holdoff timer expires, return to step 1.
- 5 If the Holdoff timer expires without the Holdoff line ever becoming free, announce your messages.

### 7.1 Arrival Messages

The arrival message is used to announce train arrival at the site. Its use is optional. You can enable or disable it using the **Announce Arrival Message option** on the Messages menu. The format of this announcement is:

```
[customer name] Milepost (mile) [track indicator]
```

At a multitrack site, "track indicator" represents the position in the message text that the track designator (such as "East Track") is inserted into the announcements. At a single-track site, no message text is inserted for track indicator.

For example, at a single-track site, the announcement is like this. In this example, milepost 359.4 was used.

```
BNSF
Milepost 3-5-9 point 4
```

At a multitrack site, the announcement is like this. In this example, milepost 297.1 was used.

```
BNSF
Milepost 2-9-7 Point 1
South Track
```

The arrival message is only announced once per train.

## 7.2 Real-Time Messages

Real-time messages consist of announcements that occur as the train is passing over the site. These messages have two possible formats. The format used is determined by whether the Message Setting option "Include Details in Real-Time" is set to "Yes" or "No."

When the option is set to "No," the general format of the real-time message is:

```
[customer name] Milepost (mile) [track indicator] You Have a Defect
```

When the option is set to "Yes," the general format of the real-time message is:

```
[customer name] Milepost [mile] [track indicator] You Have a Defect
[Alarm Type][Side Indication][Axle Number]
```

For example, at a single-track site, where an alarm has been detected and "Include Details in Real-Time" is enabled, the general format of the announcement is like this. In this example, milepost 321.4 was used.

```
BNSF
Milepost 3-2-1 Point 4
You Have a Defect
[alarm announcement]
(5-second pause)
BNSF
Milepost 3-2-1 Point 4
You Have a Defect
[alarm announcement]
```

At a multitrack site, when the “Include Details in Real-Time” option is set to “No,” the announcement is like this.

```
BNSF
Milepost 2-9-7 Point 1
South Track
You Have a Defect
```

At a single-track site, when the “Include Details in Real-Time” option is set to “Yes,” the announcement is like this.

```
BNSF
Milepost 3-2-1 Point 4
You Have a Defect
Hot Journal
East Rail
Axle 9-0
(5-second pause then repeated)
```

At a multitrack site, when the “Include Details in Real-Time” option is set to “Yes,” the announcement is like this.

```
BNSF
Milepost 3-2-1 Point 4
Main 1
You Have a Defect
Dragging Equipment
South Track
Near Axle 9-0
(5-second pause then repeated)
```

### 7.3 Post-Train Messages

Post-train (end-of-train) announcements are given after the train has left the site and all the recorded train data has been processed by the SmartScanNG<sup>2</sup> system.

These messages consist of four distinct scenarios, each with its own spoken message. The scenarios are:

- Exception Alarms not detected and Integrity Failures not detected
- Exception Alarms not detected and Integrity Failures detected
- Exception Alarms detected and Integrity Failures not detected
- Exception Alarms detected and Integrity Failures detected

**Exception Alarms** are associated with axles. When the **Clearance Mode option** on the Messages menu is set to separate, there are eight Exception Alarms. They are the Carside Slope, Absolute, Differential, Dragging-Equipment, High-Load, Hotwheel, Pyrometer Saturation, and Wide-Load alarms. When the **Clearance Mode option** is set to multiplexed, there are seven Exception Alarms. They are the Carside Slope, Absolute, Differential, Dragging-Equipment, Hi-Wide, Hotwheel, and Pyrometer Saturation alarms.

The four types of Hot Journal alarms are Absolute, Differential alarms, Pyrometer Saturation alarms, and Carside Slope alarms. When one of these four alarms occurs, a Hot Journal alarm is announced. The system only announces Dragging-Equipment, High-Load, Shifted Load, Hot Journal, Hotwheel, and Wide-Load.

**Integrity Failures** are the Dead Battery, Dead Resistor, Dead Wheel Scanner Resistor, Stuck Dragger During Train Passage, Stuck Dragger Pretrain, Stuck High-Load Detector Pretrain, Stuck Wide-Load Detector Pretrain, Successive Cold Rails Exceeded, Successive Cold Resistors Exceeded, Successive Cold Wheel Resistors Exceeded, Successive Cold Wheels Exceeded, Train Present on Restart, and sometimes Cold Resistor alarms, Cold Wheel Scanner Resistor alarms, and Highrange Transducer Miscounts alarms.

The Highrange Transducer Miscounts alarm can be either a System Alarm or an Integrity Failure, depending on the presence of a Very Slow Train alarm. If a highrange transducer miscount occurs on a train that also contains a Very Slow Train alarm, the firmware treats the miscount condition as a System Alarm. If a highrange transducer miscount occurs on a train traveling faster than 7 mph (11.3 kph), the firmware treats the miscount condition as an Integrity Failure.

The Cold Resistor alarm and the Cold Wheel Scanner Resistor alarm can be either a System Alarm or an Integrity Failure, depending on post-train calculated correction factor. After a train has passed the site, a more accurate resistor value is calculated. This *new* value is then used to calculate a correction factor. The factor is the percentage difference between the *new* value and the value that was actually read. If the correction factor is less than 24%, no Cold Resistor alarm and no Cold Wheel Scanner Resistor alarm is generated. If the correction factor is in the range of 24% to 40%, the Cold Resistor alarm and the Cold Wheel Scanner Resistor alarm is considered a **system alarm**. If the correction factor for a given rail on any train is greater than 40%, the Cold Resistor alarm and the Cold Wheel Scanner Resistor alarm is considered an **integrity failure**.

Below is the Messages menu. The options on this submenu affect the phrases broadcast to a passing train or are used to modify the parameters associated with the rebroadcast function.

Messages Settings		
-----		
[A]	- Axles .....	Yes
[B]	- Speed .....	No
[C]	- Temperature .....	No
[D]	- Length .....	No
[E]	- Slow .....	Yes
[F]	- Power Off .....	No
[G]	- Repeat No Defects .....	Yes
[H]	- Cars Count .....	No
[I]	- Customer Name .....	Yes
[J]	- Arrival Message .....	Yes
[K]	- Lft/Rt Alarm Ref .....	Yes
[L]	- Car ID With Alarm .....	No
[M]	- Include Details In Realtime ...	No
[N]	- Announce Differentials .....	No
[O]	- Advanced	
[X]	- Exit	

Enabling one or more of these highlighted options generates the ancillary messages. The other options of the Messages menu aren't used to generate ancillary messages.

In the examples that follow, not all ancillary messages are shown. This is because only axle count and train speed were enabled. That is, only the **Announce Axles option** on the Messages menu and the **Announce Speed option** on the Messages menu were enabled. Site ambient temperature, train length, number of cars, power off, and slow train were disabled. **Section 4.0 - Serial Interface** tells how to enable and disable these messages using the Messages menu.

When the Highrange Transducer Miscounts alarm or Very Slow Train alarm occurs, the system won't announce axle count, train speed, train length, or number of cars (even if these messages are enabled).

### 7.3.1 Nothing Detected

When neither an Exception Alarm nor an Integrity Failure is detected, the no-defect message is announced in the post train message. If the **Repeat No Defects option** on the Messages menu is disabled, the format of this announcement is:

```
[customer name] Milepost (mile) [track indicator] [speed indicator]
No Defects [other ancillary messages]
```

*(5-second pause)*

```
[customer name] Milepost (mile) [track indicator] [speed indicator]
No Defects [other ancillary messages]
```

If the **Repeat No Defects option** is enabled, the format of this announcement is:

```
[customer name] Milepost (mile) [track indicator] [speed indicator]
No Defects
Repeat No Defects [other ancillary messages]
```

*(5-second pause)*

```
[customer name] Milepost (mile) [track indicator] [speed indicator]
No Defects
Repeat No Defects [other ancillary messages]
Detector Out
```

For example, at a single-track site, if the **Repeat No Defects option** is disabled the format of this announcement is:

```
BNSF
Milepost 3-2-1 Point 4
Speed 4-5
No Defects
Total Axles 9-8
```

*(5-second pause)*

```
BNSF
Milepost 3-2-1 Point 4
Speed 4-5
No Defects
Total Axles 9-8
Detector Out
```

For example, at a multitrack site, if the **Repeat No Defects option** is disabled the format of this announcement is:

```
BNSF
Milepost 2-9-7 Point 1
South Track
Speed 5-3
No Defects
Total Axles 1-6-2
    (5-second pause)
```

```
BNSF
Milepost 2-9-7 Point 1
South Track
Speed 5-3
No Defects
Total Axles 1-6-2
Detector Out
```

### 7.3.2 Only an Integrity Failure Detected

Integrity failures are caused when the system determines that a condition exists that could prevent proper scanning of a train. They indicate an unusual operating condition that may require train stoppage, later maintenance, or both. Integrity failures appear in the header of Train Detail reports and Exception Detail reports. **Section 6.0 - Producing Reports** tells how to produce these reports. **Appendix B - Integrity Failures** describes the conditions and events that the SmartScanNG<sup>2</sup> system flags as Integrity Failures.

When no Exception Alarms are detected but an Integrity Failure is detected, "Integrity Failure" is announced. The format of this announcement is:

```
[customer name] Milepost (mile) [track indicator] [ancillary
messages]
Integrity Failure
    (5-second pause)

[customer name] Milepost (mile) [track indicator] [ancillary
messages]
Integrity Failure
Detector Out
```

For example, at a double-track site, the announcement is like this.

```
BNSF  
Milepost 3-9-9 Point 1  
South Track  
Integrity Failure
```

*(5-second pause)*

```
BNSF  
Milepost 3-9-9 Point 1  
South Track  
Integrity Failure  
Detector Out
```

### 7.3.3 Only Exception Alarms Detected

When one or more Exception Alarms are detected and an Integrity Failure is not detected, the alarms are announced.

The format of this announcement is:

```
[customer name] Milepost (mile) [track indicator] [speed indicator]  
[alarm announcements] [other ancillary messages] [excessive-alarms  
indicator]
```

*(5-second pause)*

```
[customer name] Milepost (mile) [track indicator] [speed indicator]  
[alarm announcements] [other ancillary messages] [excessive-alarms  
indicator]
```

Per train, a maximum of thirteen alarms will be announced regardless of the total number of alarms detected. This includes a maximum of four Hot Journal alarms, four Hotwheel alarms, two Dragging Equipment alarms, one Shifted Loadalarm, one High-Load alarm, one Wide-1 alarm, and one Wide-2 alarm. For example, if you had five Hotwheel alarms followed by six Hot Journal alarms, only four Hotwheel alarms followed by four Hot Journal alarms would be announced. This, however, doesn't affect what is reported. For example, if a train contains seven Hot Journal alarms, the Train Detail report will show all seven, even though only the first four are announced.

Hotwheel alarms use the same general format as Hot Journal alarms. High-Load, Shifted Load, and Wide-Load alarms use the same general format as Dragging-Equipment alarms.

The **Clearance Type option** on the Equipment menu can be set to either tripwire or light beam. This option is only used where high-load detectors and wide-load detectors are installed with the NG<sup>2</sup>. Both high-load detectors and wide-load detectors must be either tripwire detectors or light-beam detectors.

When a wide-load detector is configured for tripwire operation, the system only records one Wide-Load alarm, regardless of the wide-load signal status. This is because you can only break a wire once.

When it is configured for light-beam operation, the system records every Wide-Load alarm that occurs. However, the system won't flag Wide-Load alarms on consecutive axles. At least one unalarmed axle must separate the alarmed axles. Regardless of the number of detected Wide-Load alarms, the system only announces a maximum of three.

When a high-load detector is configured for tripwire operation, the system only records one High-Load alarm, regardless of the high-load signal status. This is because you can only break a wire once.

When it is configured for light-beam operation, the system records every High-Load alarm that occurs. However, the system won't flag High-Load alarms on consecutive axles. At least one unalarmed axle must separate the alarmed axles. Regardless of the number of detected High-Load alarms, the system only announces a maximum of three.

The **Clearance Mode option** on the Equipment menu can be set to either separate or multiplexed. This option is only used where high-load detectors and wide-load detectors are installed with an NG<sup>2</sup>. When this option is set to separate, the alarms coming from the high-load detectors are announced as High-Load alarms and the alarms coming from the wide-load detectors are announced as Wide-Load alarms. When this option is set to multiplexed, the alarms coming from the high-load detectors and wide-load detectors are announced as Shifted Load alarms. For example, at a single-track site having one Hot Journal alarm and no Integrity Failure, the announcement is like this. This example assumes that the **Left-Right Alarm Reference option** on the Messages menu was enabled.

```
BNSF
Milepost 3-2-1 Point 4
Hot Journal Left-Side Axle-7-5
Total Axles 9-8
    (5-second pause)
```

```
BNSF
Milepost 3-2-1 Point 4
Hot Journal Left-Side Axle-7-5
Total Axles 9-8
Detector Out
```

At a multitrack site having one Hot Journal alarm and no Integrity Failure, the announcement is like this. This example assumes that the **Left-Right Alarm Reference option** on the Messages menu was enabled.

BNSF  
Milepost 3-2-1 Point 4  
North Track  
Hot Journal Left-Side Axle-1-5-3  
  
(5-second pause)

BNSF  
Milepost 3-2-1 Point 4  
North Track  
Hot Journal Left-Side Axle-1-5-3  
Detector Out

At a double-track site having one Dragging-Equipment alarm and no Integrity Failure, the announcement is like this. This example makes no assumption as to whether the **Left-Right Alarm Reference option** was disabled or enabled. Either will result in the following.

BNSF  
Milepost 2-9-7 Point 1  
South Track  
Speed 4-5  
Dragging-Equipment Near-Axle-8-4  
Total Axles 8-8  
  
(5-second pause)

BNSF  
Milepost 2-9-7 Point 1  
South Track  
Speed 4-5  
Dragging-Equipment Near-Axle-8-4  
Total Axles 8-8  
Detector Out

At a single-track site having two Hot Journal alarms and no Integrity Failure, the announcement is like this. This example assumes that the **Left-Right Alarm Reference option** was disabled.

```
BNSF
Milepost 3-2-1 Point 4
Speed 4-5
First-Hot Journal North-Side Axle-7-5
Second-Hot Journal North-Side Axle-8-0
Total Axles 9-0

(5-second pause)
```

```
BNSF
Milepost 3-2-1 Point 4
Speed 4-5
First-Hot Journal North-Side Axle-7-5
Second-Hot Journal North-Side Axle-8-0
Total Axles 9-0
```

At a double-track site having two Hotwheel alarms, one Shifted Load alarm, and no Integrity Failure, the announcement is like this. This example assumes that the **Left-Right Alarm Reference option** was disabled.

```
BNSF
Milepost 2-9-7 Point 1
Speed 4-5
South Track
First-Hotwheel North-Side Axle-6-5
Second-Hotwheel North-Side Axle-7-0
Shifted Load From-Axle-8-4 To Axle-9-2
Total Axles 1-4-4

(5-second pause)
```

```
BNSF
Milepost 2-9-7 Point 1
Speed 4-5
South Track
First-Hotwheel North-Side Axle-6-5
Second-Hotwheel North-Side Axle-7-0
Shifted Load From-Axle-8-4 To Axle-9-2
Total Axles 1-4-4
Deetector Out
```

In the above example, there was a condition generating a Shifted Load alarm from axle 84 to axle 92. The "from" parameter is only used with High-Load, Shifted Load, and Wide-Load alarms. It isn't used with Dragging-Equipment alarms. However, all four alarms can use the "near" parameter, as in "Shifted Load Near-Axle-3-3."

At a single-track site having one Hot journal alarm, one Dragging-Equipment alarm, and no Integrity Failure, the announcement is like this. This example assumes that the **Left-Right Alarm Reference option** was enabled.

BNSF  
Milepost 3-2-1 Point 4  
Speed 4-5  
Hot Journal Left-Side Axle-7-5  
Dragging-Equipment Near-Axle-8-4  
Total Axles 9-8  
  
(15-second pause)

BNSF  
Milepost 3-2-1 Point 4  
Speed 4-5  
Hot Journal Left-Side Axle-7-5  
Dragging-Equipment Near-Axle-8-4  
Total Axles 9-8

At a single-track site having four or more Dragging-Equipment alarms and no Integrity Failure, the announcement is like this.

BNSF  
Milepost 3-2-1 Point 4  
Speed 4-5  
First-Dragging-Equipment Near-Axle-1-2  
Second-Dragging-Equipment Near-Axle-1-4  
Third-Dragging-Equipment Near-Axle-2-0  
Total Axles 9-8  
Excessive Alarms  
  
(5-second pause)

BNSF  
Milepost 3-2-1 Point 4  
Speed 4-5  
First-Dragging-Equipment Near-Axle-1-2  
Second-Dragging-Equipment Near-Axle-1-4  
Third-Dragging-Equipment Near-Axle-2-0  
Total Axles 9-8  
Excessive Alarms  
Detector Out

### 7.3.4 Both Exception Alarms and an Integrity Failure Detected

Integrity failures are caused when the system determines that a condition exists that could prevent proper scanning of a train. They indicate an unusual operating condition that may require train stoppage, later maintenance, or both. Integrity failures appear in the header of Train Detail reports and Exception Detail reports. **Section 6.0 - Producing Reports** tells how to produce these reports. **Appendix B - Integrity Failures** describes the conditions and events that the SmartScanNG<sup>2</sup> system flags as Integrity Failures.

When one or more alarm conditions and an Integrity Failure are detected, both the alarm announcements and the "Integrity Failure" is announced. The format of this announcement is:

```
[customer name] Milepost (mile) [track indicator] [speed indicator]
[alarm announcement] [ancillary messages]
Integrity Failure
```

*(5-second pause)*

```
[customer name] Milepost (mile) [track indicator] [speed indicator]
[alarm announcement] [ancillary messages]
Integrity Failure
Detector Out
```

For example, at a single-track site having a Hot Journal alarm and an Integrity Failure, the announcement is like this.

```
BNSF
Milepost 3-2-1 Point 4
Speed 4-5
Hot Journal Left-Side Axle-6-2
Total Axles 9-8
Integrity Failure
```

*(5-second pause)*

```
BNSF
Milepost 3-2-1 Point 4
Speed 4-5
Hot Journal Left-Side Axle-6-2
Total Axles 9-8
Integrity Failure
Detector Out
```



## 8.0 Scheduled Maintenance

---

This section lists the items that STC recommends be done during scheduled maintenance.

An up-and-running SmartScanNG<sup>2</sup> system needs to be visited from time to time to do scheduled maintenance. The frequency of these visits is up to the customer. STC recommends visits every 30 to 90 days. Maintenance requirements change with environmental conditions. For example, if the system is installed in a damp or a dusty environment, it may be necessary to visit the location more frequently to clean the optics. The optical system is the item most likely to need periodic maintenance. If moisture or dust isn't a problem, you may not need to do scheduled maintenance more often than every 90 days.

What is done during a maintenance visit is up to the customer. However, STC does have some recommendations. For normal scheduled maintenance, STC recommends these steps.

- 1 Be sure that you have on hand a 50-foot (15-meter) or longer tape measure, a #2 Phillips head screwdriver, a small slotted screwdriver, a 9/16-inch torque wrench, a laptop computer, a multimeter, and the alignment fixture.
- 2 At trackside, check track conditions on all tracks.
- 3 If any track is pumping (vertical displacement of the rails) or running (lateral displacement of the rails) more than 2 inches (5 centimeters), have it repaired before proceeding.
- 4 At trackside, check for damaged transducers, damaged transducer cables, and other damaged components.
- 5 If you find any damaged components, repair or replace them before proceeding.  
STC transducers don't require a lot of care and attention. Once installed correctly, you don't need to remove them from the rail for cleaning or readjustment.
- 6 At trackside, check that all transducers on all tracks are properly aligned and calibrated (refer to Section 9.2 of Track Hardware Manual for details) Verify that all mounting hardware on all transducers has been secured to manufacturer's recommended torque settings.
- 7 At the trackside, check all scanner-mounting bolts on all tracks.
- 8 If all scanner mounts aren't snug against the gauge side of the rail, fix this problem before proceeding.
- 9 From under all scanners, remove ballast that could damage the scanner during train passage.
- 10 Remove all obstructions to the scan path of each scanner.
- 11 If the wayside enclosure isn't attached to a properly installed outside grounding system, fix this problem before proceeding.
- 12 At all outlets inside the wayside enclosure, check if the AC power is stable and at least 110 volts at 20 amperes.

- 13 If the AC power isn't stable or if it isn't at least 110 volts at 20 amperes, fix this problem before proceeding.
- 14 If not all outlets inside the wayside enclosure are grounded properly, fix this problem before proceeding.
- 15 If the battery is dead, damaged, or emitting a strong sulfurous odor, replace it before proceeding.

**WARNING**

In operation, batteries generate and release flammable hydrogen gas, which, if ignited by a burning cigarette, naked flame, or spark, may cause battery explosion with a dispersion of casing fragments and corrosive liquid electrolyte. So, carefully follow the manufacturer's instructions for installation and service. Keep all sources of gas ignition away from the batteries and do not allow metallic articles to contact the negative and positive terminals of a battery at the same time

**WARNING**

A damaged or aged battery, in combination with the connected battery charger, can pose a serious health threat. The battery can produce hydrogen sulfide gas, which is characterized by its unique "rotten egg" smell. So, when a strong sulfurous odor is detected, remove power to the battery charger and check the battery for excessive heating. Do not inhale the fumes.

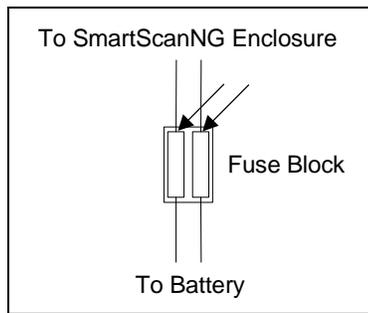
- 16 If the battery charger hasn't been properly grounded, fix this problem before proceeding.
- 17 If the SmartScanNG<sup>2</sup> enclosure hasn't been properly grounded, fix this problem before proceeding.  

There are vents on the top, bottom, and sides of the charger. Blocking any of these vents could result in damage to the charger or battery.
- 18 Remove anything that is blocking the vents on the battery charger.  

One end of the battery temperature probe cable has a three-pin plug, which plugs into a receptacle on the front of the battery charger. The other end, which has a temperature sensor sealed in it, should be attached to the negative battery post. If the battery temperature probe is defective or not installed, the red defective LED is lit.
- 19 On the front of the battery charger, if the red defective-temperature-probe LED is lit, fix the underlying problem before proceeding.
- 20 Switch the multimeter to the DC volts scale.  

The **equipment side** of the fuse block is directly wired to the SmartScanNG<sup>2</sup> enclosure. The **battery side** of the fuse block is wired to the battery via the distribution block.

- 21** Touch the leads from the multimeter to the terminals on the equipment side of the fuse block.



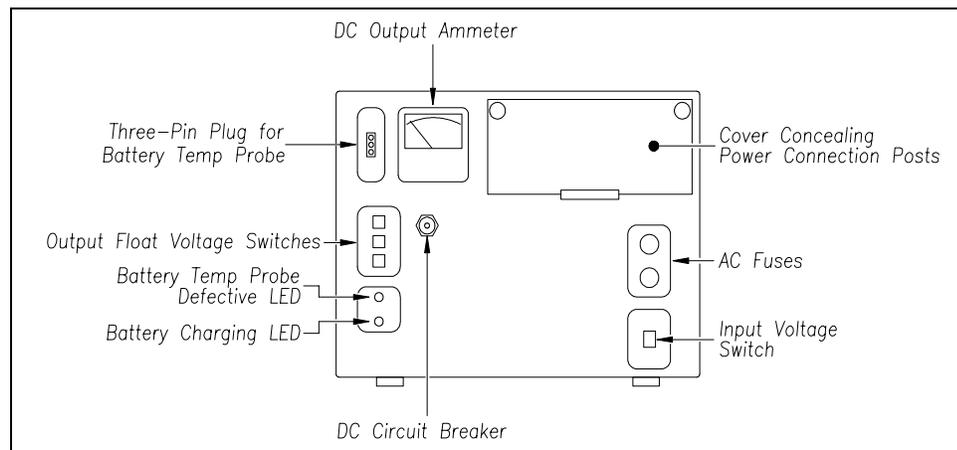
- 22** If the voltage (on the equipment side of the fuse block) is 12.3 through 14 VDC, go to step **26**.

- 23** If the voltage (on the equipment side of the fuse block) is 0 VDC:

- a** Touch the leads to the terminals on the battery side of the fuse block.
- b** If the voltage (on the battery side of the fuse block) is greater than 0 VDC, replace each fuse in the fuse block with a BAF-25 (25-amp 250-volt) fast-acting fuse and return to step **25**.
- c** If the voltage (on the battery side of the fuse block) is 0 VDC, fix any wiring problems between the fuse block, the distribution block, the battery, and the charger.
- d** Return to step **25**.

- 24** If the voltage is less than 12.3 VDC:

- a** On the battery charger, check the input voltage switch for proper setting.



The input voltage switch can be set to 115 VAC or 230 VAC. Use 115 for input voltages between 108 and 128. Use 230 for input voltages between 216 and 256.

- b** On the battery charger, check the output float voltage switches.

- c If the switches are set lower than 12.30 VDC, reset them to 14.00 VDC.

To reset the switches, use a small slotted screwdriver to turn each switch to the desired number. The ten's digit is always 1 and can't be changed. The top switch controls the unit's digit. The middle switch controls the tenth's digit. The bottom switch controls the hundredth's digit. The factory default is **14.00 VDC**, which is the **recommended setting**. To select 14.00 VDC, turn the top switch to 4, the middle switch to 0, and the bottom switch to 0.

- d Open the small door cover on the top-right corner of the front of the charger.

**Do not touch the uninsulated parts of the wires or the charger's binding posts. Doing so could result in sparks, burns, or electric shock.**

- e Check that all binding posts nuts are tight and that all wiring is correct.

- f On the battery charger, check the AC fuses to see if either is blown.

- g If blown, replace with 4-amp 250-volt fast-acting fuses.

- h On the battery charger, check the DC circuit breaker to see if it is open (tripped).

When closed, about 0.09 inch (0.23 centimeters) of the breaker's button is seen. When open, the button is popped out, showing about 0.25 inch (0.64 centimeters).

- i If open (tripped), push the breaker's button in to reset the DC circuit breaker.

- j Check to see if the battery charger is plugged in.

- k If the battery charger isn't plugged in, plug it in.

- l Check the battery-charging LED.

If the battery is charging properly, the yellow battery-charging LED is lit solid. If one or more of the output float voltage switches are set between numbers, the yellow battery-charging LED flashes.

- m If the yellow battery-charging LED is not lit, call STC for help in fixing this problem.

- n If the yellow battery-charging LED is lit solid, monitor the voltage for ten minutes.

If the voltage is gradually increasing, the battery is probably charging. After the battery has charged for five hours, the battery voltage should be very near the float voltage setting. If the voltage isn't gradually increasing, the battery is probably not charging. This may indicate that the battery is defective and should be replaced.

**25** If the voltage is greater than 14 VDC:

- a Check the output float voltage switches on the center-left edge of the battery charger.

- b Be sure that each switch is set on a number and not between numbers.

- c If the switches are set to 14.00 VDC or less, cut all power to the SmartScanNG<sup>2</sup> system and call STC for help in fixing this problem.

- d If the switches are set higher than 14.00 VDC, reset them to 14.00 VDC and return to step **25**.

To reset the switches, use a small slotted screwdriver to turn each switch to the desired number. The ten's digit is always 1 and can't be changed. The top switch controls the unit's digit. The middle switch controls the tenth's digit. The bottom switch controls the hundredth's digit. The factory default is **14.00 VDC**, which is the **recommended setting**. To select 14.00 VDC, turn the top switch to 4, the middle switch to 0, and the bottom switch to 0.

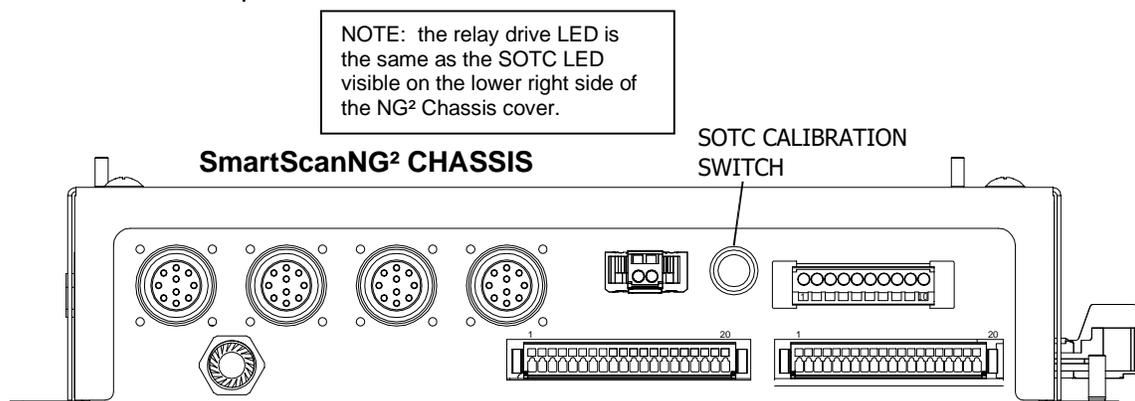
- 26** On the display panel, look at the COP-A and COP-B LEDs.



The COP LEDs indicate the condition of the CPUs. If both CPUs are running their programs correctly, their LEDs blink on and off. If a program isn't operating as expected, the LED for the affected CPU is lit solid or isn't lit at all.

- 27** If either or both of the **COP LEDs** is lit solid or isn't lit at all, call STC for help in fixing this problem.
- 28** On the display panel, look at the **SYS WARN** LED. If a system warning has been flagged, the SYS WARN LED will be lit and the Check System Health message will be displayed on the bottom text line of the home screen. The Sys. Health Menu provides a status indicator for the various system health checks.
- 29** To see if the system is being activated by the gating transducers:
- Produce a Train Detail Report for the last train.  
**Section 6.0 - Producing Reports** tells how to produce this report.
  - On the Train Detail report, check under the System Alarms section of the report for the words "No Approach Track."  
  
The No Approach Track alarm indicates that the track circuit (or the advance transducers) failed to signal the presence of a train and that the SmartScanNG<sup>2</sup> system started from the train passing over the gating transducers.
  - If the words "No Approach Track" don't appear, go to step **32**.

- 30** If your system uses advance transducers, go to step **32**.
- 31** If your system uses a track circuit:
- From the center of the gating transducers, measure the distance you want the track circuit to pick up the presence of a train.
  - The distance must be at least 25' (7.62 m) and no more than 150' (45.7 m).
  - At the point just measured, place a 0.06Ω shunt across both rails. The track must be shunted before the calibration switch is pressed.
  - Press and HOLD the Calibration Switch until the relay drive LED starts blinking. Release the switch and the LED will stop blinking. The ZEPIC III will automatically begin the calibration process. NOTE: The track shunt MUST remain in place during the calibration process.



- The relay drive will pick up (LED on) when the unit has successfully calibrated. This process can take up to 45 seconds to complete.

## Verification

- Lift the shunt, and the relay drive should drop.
- Move the shunt 20' farther out from the calibration point and verify the relay drive does not pick up.
- Go to step 33.

**IMPORTANT:** To ensure accurate activation point, always place the shunt BEFORE pressing the Calibration Switch.

If the ZEPIC cannot achieve calibration, it will blink the relay drive LED three (3) times in rapid succession, indicating a calibration error. The unit will continuously repeat the calibration procedure (there is no need to press the Calibration Switch), allowing you to troubleshoot the track circuit, wiring, and battery. Once the issue has been corrected, repeat the calibration procedure outlined in steps 2 - 5.

Both the ZEPIC III and Z3 Plus have a two-wire track circuit and will activate an equal distance on both sides of the track feed point.

**32** If your system uses advance transducers:

You will next verify that each advance transducer is functional.

- a** Using a metal wrench, stroke the top of one of the advance transducers.  
The scanner shutters should open completely for 10 seconds.
- b** On one of the bearing scanners, check to see if the shutter opens.
- c** If the shutter didn't open, fix this problem before proceeding.
- d** Using a metal wrench, stroke the top of the other advance transducer.  
The scanner shutters should open completely for 10 seconds.
- e** On one of the bearing scanners, check to see if the shutter opens.
- f** If the shutter didn't open, fix this problem before proceeding.

**33** Produce a Train Summary report.

**Section 6.0 - Producing Reports** tells how to produce this report.

The Train Summary report lists all trains currently stored in the Trains directory. A line of information is shown for each train entry. The report is divided into a header section and a detail section. The header section contains general information about the site. The detail section contains summary information on each train that passed the site.

**34** On the Train Summary report, check the Axles column.

Axle count should be an even number. Odd-numbered axle counts are possible indications of gating transducer problems.

**35** If there is an odd axle count and if train speed was always above 7 mph, go to step **37**.

If at any time during train passage the train speed was less than or equal to 7 mph (11.3 kph), gating transducer problems probably don't exist. If the train speed was always above 7 mph, gating transducer problems probably do exist.

The Very Slow Train alarm indicates that, at some point during train passage, four consecutive axles crossed the gating transducers at a speed of 7 mph (11.3 kph) or less. This alarm appears on a Train Detail report.

If there are many slow trains (that is, many trains traveling less than 7 mph) at this site, it may be necessary to relocate the scanners and other track hardware to a better location. Deciding to do this should be made in consultation with STC. Relocating a site is beyond the scope of this document.

**36** If there is an even axle count and the values under "Axles," "T01," and "TO2" are the same, go to step **41**.

If things are working correctly, all three values for a given train should be equal. You'll do the next step only if things aren't working correctly.

**37** Determine which gating transducer is recording incorrect information.

Determine which gating transducer is recording incorrect axle counts and whether it is not counting all axles or counting extra ones. You may not be able to do this by just looking at the values under the Axles, T01, and T02 columns of the Train Summary report. Sometimes, a transducer problem causes the number in the Axles column to be incorrect. Therefore, the true axle count may have to be determined from an alternate source such as the next detector system that encounters the train with the transducer-count imbalance.

After you determine which gating transducer is miscounting, you'll need to change a jumper setting on the Interface board. If T01 is the problem, you'll change the setting for J201. If T02 is the problem, you'll change the setting for J202. If both T01 and T02 have a problem, both jumpers will need to be changed.

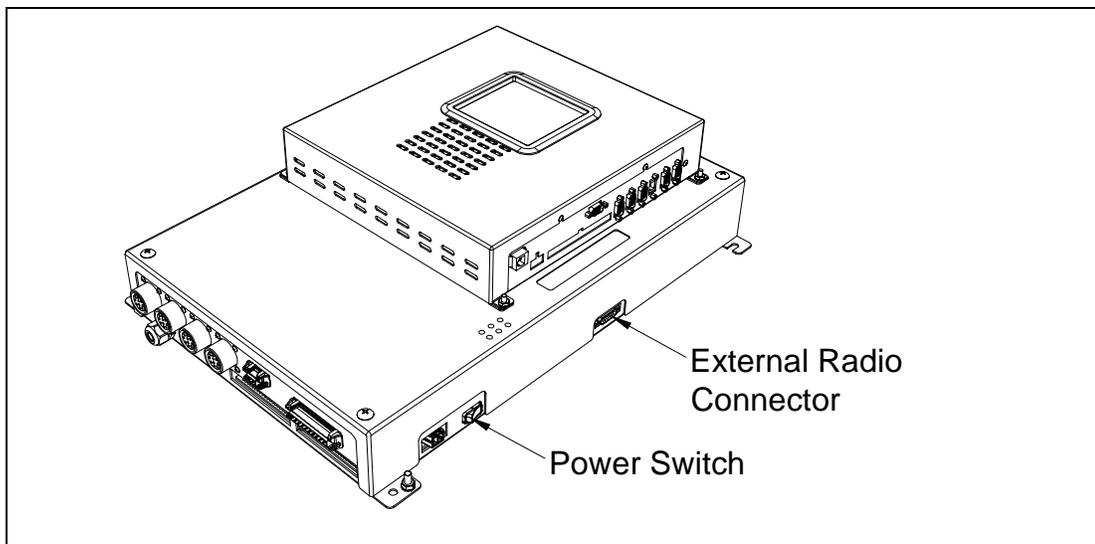
**Changes to the jumpers should be made only after all external conditions that cause transducer miscounts have been corrected.** Some of these external conditions are improperly installed transducers, loose transducer bolts, incorrect transducer heights, damaged transducers, damaged transducer cables, and loose wiring connections. You should have already checked and corrected for these external conditions in steps **4** through **10** above. If you think the corrections you made in those steps fixes gating transducer miscounting, you can skip some of the steps below.

The process of adjusting the transducer loading is trial and error. Generally, if you are having too many transducer counts, lower the loading resistance to make the transducer less sensitive. Likewise, too few counts suggest that the transducer is not sensitive enough, so you would select a loading value with more resistance.

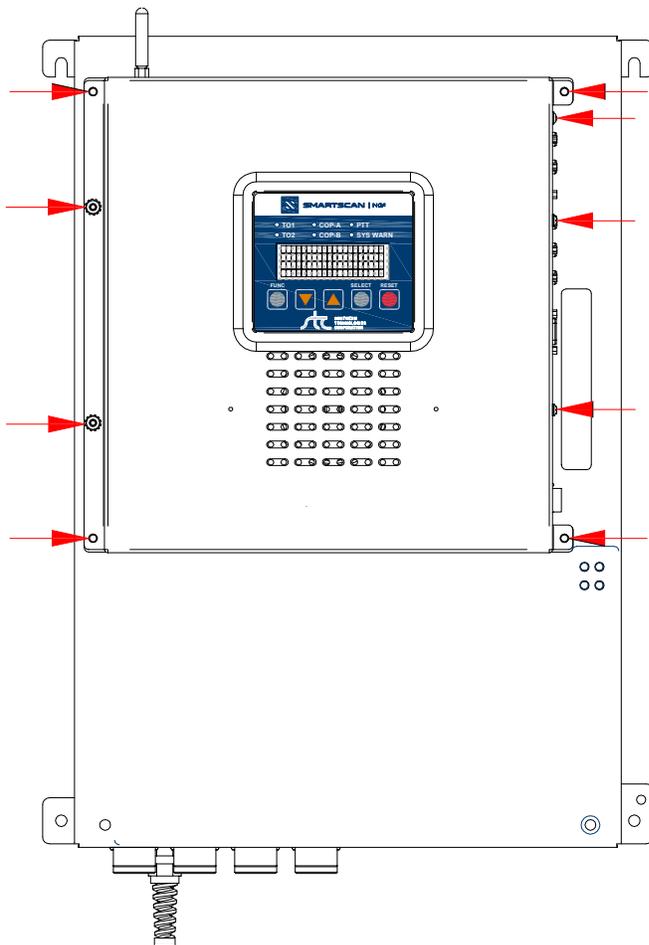
**38** If you corrected all external conditions that negatively affect gating transducers and you think this fixes gating transducer miscounting, go to step **41**.

**39** If the selected gating transducer appears to be missing axles (that is, the transducer that is showing a number of hits less than the true axle count):

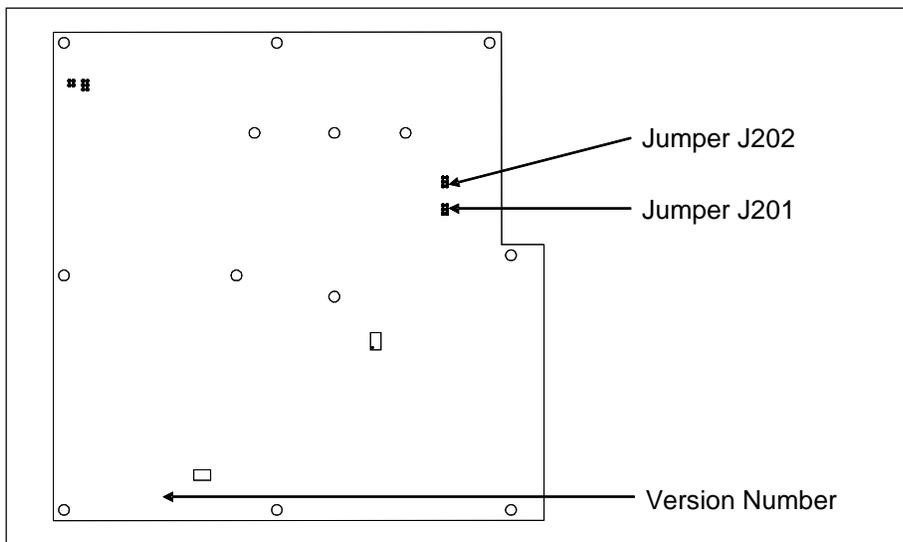
- a** Toggle off the DC power switch on the right edge of the SmartScanNG<sup>2</sup> enclosure.



- b** Remove the six nuts and three screws holding the cover over the Interface board.



The Interface board is now visible.



- c** To prevent the base assembly from falling, replace two of the just removed nuts onto the top two mounting studs on the SmartScanNG<sup>2</sup> enclosure.

- d Store the removed cover, three screws, and remaining four nuts in a safe place until you replace them.

The available loading sensitivities vary depending on which version of Interface board you have and whether resistors are attached to the jumpers or not. The version number is printed on the lower-left edge of the board.

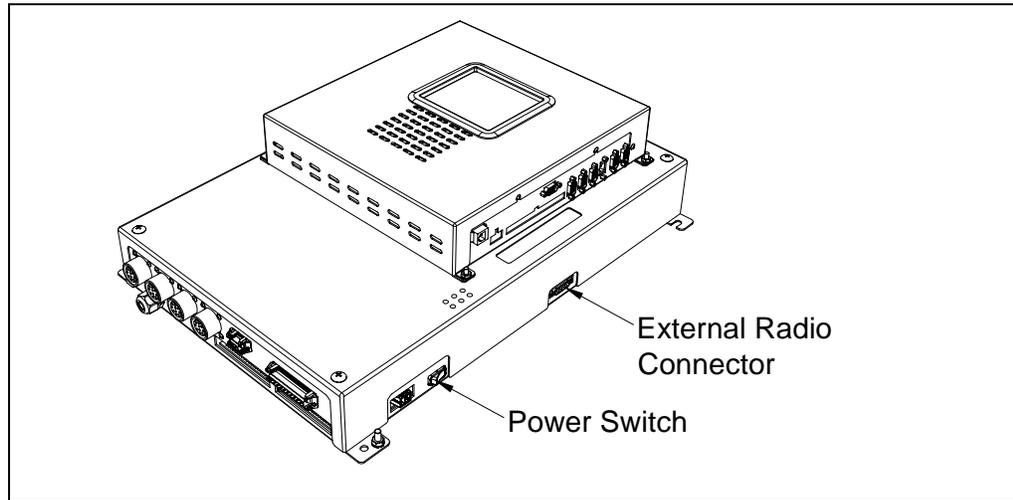
- e The table below lists the highest, middle, and lowest sensitivity for transducer loading. Highest is the most sensitive. The jumper's top position is the one closest to the external speaker.

J201 or J202 Jumper Position	Sensitivity Level
Top	Lowest Sensitivity
Center	Middle Sensitivity
Bottom	Highest Sensitivity

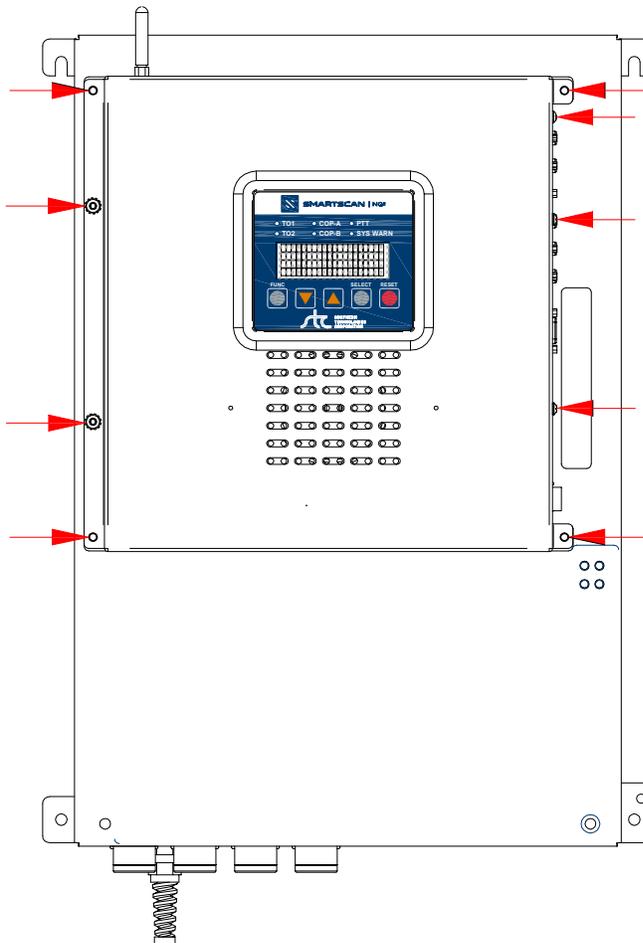
- f If TO1 is the selected gating transducer and the J201 jumper is currently on the lowest sensitivity position, move it to the middle sensitivity position.
- g If TO1 is the selected gating transducer and the J201 jumper is currently on the middle sensitivity position, move it to the highest sensitivity position.
- h If TO1 is the selected gating transducer and the J201 jumper is currently on the highest sensitivity position, call STC for help in fixing this problem.
- i If TO2 is the selected gating transducer and the J202 jumper is currently on the lowest sensitivity position, move it to the middle sensitivity position.
- j If TO2 is the selected gating transducer and the J202 jumper is currently on the middle sensitivity position, move it to the highest sensitivity position.
- k If TO2 is the selected gating transducer and the J202 jumper is currently on the highest sensitivity position, call STC for help in fixing this problem.
- l Remove the two nuts holding the base assembly to the SmartScanNG<sup>2</sup> enclosure.
- m Using the saved six nuts and three screws, reattach the cover over the Interface board.
- n Toggle on the DC power switch on the right edge of the SmartScanNG<sup>2</sup> enclosure.

**40** If the selected gating transducer appears to be counting extra axes (that is, the transducer that is showing a number of hits more than the true axle count):

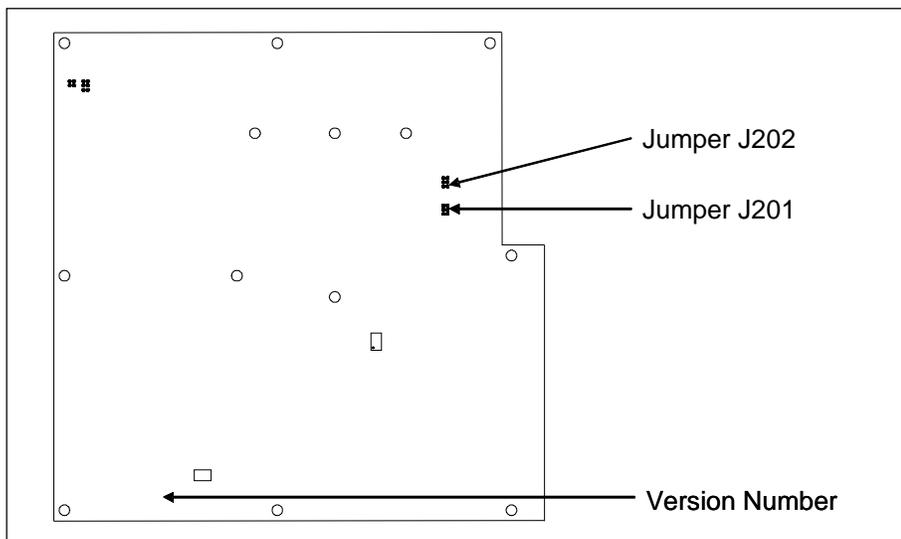
**a** Toggle off the DC power switch on the right edge of the SmartScanNG<sup>2</sup> enclosure.



**b** Remove the six nuts and three screws holding the cover over the Interface board.



The Interface board is now visible.



- c To prevent the base assembly from falling, replace two of the just removed nuts onto the top two mounting studs on the SmartScanNG<sup>2</sup> enclosure.
- d Store the removed cover, three screws, and remaining four nuts in a safe place until you replace them.

The available loading sensitivities vary depending on which version of Interface board you have and whether resistors are attached to the jumpers or not. The version number is printed on the lower-left edge of the board.

- e The table below lists the highest, middle, and lowest sensitivity for transducer loading. Highest is the most sensitive. The jumper's top position is the one closest to the external speaker.

J201 or J202 Jumper Position	Sensitivity Level
Top	Lowest Sensitivity
Center	Middle Sensitivity
Bottom	Highest Sensitivity

- f If TO1 is the selected gating transducer and the J201 jumper is currently on the highest sensitivity position, move it to the middle sensitivity position.
- g If TO1 is the selected gating transducer and the J201 jumper is currently on the middle sensitivity position, move it to the lowest sensitivity position.
- h If TO1 is the selected gating transducer and the J201 jumper is currently on the lowest sensitivity position, call STC for help in fixing this problem.
- i If TO2 is the selected gating transducer and the J202 jumper is currently on the highest sensitivity position, move it to the middle sensitivity position.
- j If TO2 is the selected gating transducer and the J202 jumper is currently on the middle sensitivity position, move it to the lowest sensitivity position.
- k If TO2 is the selected gating transducer and the J202 jumper is currently on the lowest sensitivity position, call STC for help in fixing this problem.

- l Remove the two nuts holding the base assembly to the SmartScanNG<sup>2</sup> enclosure.
  - m Using the saved six nuts and three screws, reattach the cover over the Interface board.
  - n Toggle on the DC power switch on the right edge of the SmartScanNG<sup>2</sup> enclosure.
- 41 To use the serial interface to open the scanner shutters:
- a Using the serial interface, display the Main menu.  
**Section 4.0 - Serial Interface** tells how to display the Main menu
  - b Select the System Functions Menu

```

System Functions Menu
-----
[A] - Radio Test
[B] - Vocabulary Test
[C] - Radio Inhibit [D] - Start Manual Train
[E] - 1KHz Test Tone
[F] - Auto-Calibration
[G] - Remote System RESET
[H] - Delete All Stored Train Data
[I] - Clear Event Log
      .
      .
      .

```

- c To open the shutters, select the Auto-Calibration option.  
The protective shutters in all scanners should open and stay open for three minutes. This might not be enough time to check and clean the shutters and optics. If that isn't enough time, select this option again.
- 42 In each scanner, check if its shutter opened.
- 43 If any shutter didn't open, fix this problem before proceeding.
- 44 In each scanner, check for dirty optics.
- 45 If dirty, clean the scanner optics with the supplied lens cleaning kit.  
**Do not use solvents, ammonia-based cleaning solutions, or isopropyl alcohol on the optics. Use clean water or a mild solution of dishwashing liquid. After the liquid on the optics dries, lightly wipe the optics with a clean, dry chamois patch.**
- 46 If the date and time displayed on the top of the System Functions menu are incorrect, fix them before proceeding.  
**Section 4.0 - Serial Interface** tells how to change the date and time.
- 47 To check the operation of the radio:
- a From the System Functions menu, select Radio Test.  
During a radio test, the SmartScanNG<sup>2</sup> system outputs phrases through the speaker and the radio. Alternatively, you can output a 1kHz test tone instead of phrases. To do this, you would select the 1KHz Test Tone option.

- b While listening to the message or tone, look at the display panel.

The PTT LED should be lit.

If this LED isn't lit, the system's ability to send a message or tone to the radio might be inhibited. This can happen when one uses the Radio Inhibit option on the System Functions menu. If the radio is inhibited, the results of this check are invalid.

- c If the PTT LED isn't lit and the radio isn't inhibited, call STC for help in fixing this problem.

**48** To check the integrity of the speech data:

- a Be sure that the speaker has its volume set to an audible level.

- b Using the serial interface, display the Main menu.

**Section 4.0 - Serial Interface** tells how to display the Main menu.

```
      .  
      .  
      .  
[J] - Event log  
[K] - System Functions Menu  
[L] - Replay train  
[M] - Security Menu  
[X] - Exit
```

- c Select the System Functions menu.

```
System Functions Menu  
-----  
[A] - Radio Test  
[B] - Vocabulary Test  
[C] - Radio Inhibit  
[D] - Start Manual Train  
      .  
      .  
      .
```

- d From the System Functions menu, select Vocabulary Test

This message appears.

```
Starting Vocabulary Test
```

If the system isn't currently making any other voice announcements, it begins the Vocabulary Test announcement. The SmartScanNG<sup>2</sup> system outputs phrases through the speaker, but not through the radio. After the announcement finishes, the System Functions menu reappears.

If the system is currently making a voice announcement, the firmware displays the "System Is Currently Making Voice Announcements! Try Again Later" message and the System Functions menu reappears.

- e If you hear nothing or speech that is too garbled to understand, call STC for help in fixing this problem.

**49** To generate a test train to check number of axles:

- a** Quickly stroke the top of each gating transducer with a metal wrench, alternating between TO1 and TO2.
- b** Repeat step **a** nine more times, for a total of **ten** simulated axles.
- c** Wait for the system to time out and the shutters to close.
- d** Produce a Train Detail report for the last train.

**Section 4.0 - Producing Reports** tells how to produce this report.

- e** On the report, check that the number of axles agrees with the number of times that you stroked the gating transducers.
- f** On the report, if the number of axles doesn't agree with the number of times that you stroked the gating transducers, call STC for help in fixing this problem.

**50** To generate a test train to check hot bearings:

STC recommends that you use the calibrated heat source (2100-810NG) only when the outside (ambient) temperature is above 0°F (-18°C) and below 90°F (32°C). If you must use it at other times, do so only when the needle is centered on the front of the temperature meter. If the needle isn't stabilized within ± 2 degrees of set point, the heat source isn't operating properly.

- a** Ready the calibrated heat source.

The heat source has reached operating temperature and stabilized when the temperature meter needle remains centered.

- b** With the power cord to the front of the scanner, place the calibrated heat source on the bearing scanner that is on the rail with the gating transducers.
- c** Quickly stroke the top of each gating transducer with a metal wrench, alternating between TO1 and TO2 for a total of **six** simulated axles.

You should hear the real-time defect message. No matter how many defects are found, the real-time defect message is only announced once.

- d** Wait for the system to time out, which normally takes about 10 seconds.

You should hear an end-of-train message with three Hot Journal alarms. Per train, only the first three Hot Journal alarms are ever announced.

- e** Listen to be sure that the Hot Journal alarms are announced and that they are announced for the correct side.

If you do not hear anything, no alarm-level heat was recorded. No measurable heat from a bearing scanner may be due to loose connections, a scanner not being connected to the bottom of the SmartScanNG<sup>2</sup> enclosure, a defective shutter motor in the scanner, or a damaged scanner.

- f** If you do not hear any Hot Journal alarms being announced, fix this problem before proceeding.
- g** If the Hot Journal alarms are announced for the wrong side, switch the bearing scanner connections on the bottom of the SmartScanNG<sup>2</sup> enclosure.
- h** Repeat the test, this time placing the calibrated heat source on the bearing scanner on the opposite rail

i Verify the results as before.

If the results are correct, your system should function properly when scanning the bearings of real trains.

j Remove the calibrated heat source.

k Store the calibrated heat source and its cable in the wayside enclosure.

**51** On the Train Summary report, check the column marked "Average."

For each train, the values in the two columns under this heading should be within four degrees of each other.

**52** If the columns aren't within four degrees and if the scanner optics are clean, recalibrate and realign the scanner.

**Appendix D - Calibration of /Type III Scanners** tells how to calibrate the scanners.

**53** On the Train Summary report, check the last column of the report.

The last column shows the battery voltage at the time each train passed the site. It should show values between 13.0 and 14.5 volts. Values outside this range may be caused by:

- No AC power for an extended period
- Improperly adjusted float voltage
- Defective battery
- Blown fuses
- Defective battery charger

**54** If the most recent value isn't between 13.0 and 14.5 volts, investigate and fix any problems before proceeding.

**55** If this is a double-track site, repeat steps **18** through **59** for the other track (that is, for the other SmartScanNG<sup>2</sup> system).

## 9.0 Customer Service

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At STC, the customer is number one. STC is committed to products that work and customers that are satisfied. Nothing less is acceptable. This section tells how to get answers for questions, fixes for problems, and parts for spares.

### 9.1 Reaching STC

You can reach STC by mail, telephone, fax, and email. By mail, you can reach STC at:

Southern Technologies Corporation  
6145 Preservation Drive  
Chattanooga, Tennessee 37416-3638  
USA

Mail and shipments are replied to as soon as possible, normally within one working day. Equipment repair usually takes longer.

By telephone, you can reach STC at 423-892-3029, Monday through Friday, from 8:00 a.m. until 5:00 p.m. Eastern time. After business hours, a machine answers the calls. These calls are returned promptly the next business day. By fax, you can reach STC at 423-499-0045. The fax machine can receive faxes at all times. Faxes are replied to as soon as possible, normally within one working day. By email, you can reach STC at [email@southern-tech.com](mailto:email@southern-tech.com). Email is replied to as soon as possible, normally within one working day.

### 9.2 Returning Equipment for Repair

Return any defective or malfunctioning equipment to STC for repair or replacement. You don't need a return authorization number. You don't even need to make a telephone call first. Just ship it directly to the **Repair Department** at the address above.

With the returned equipment, include:

- Complete address of where the equipment is to be returned.
- Name and telephone number of the person who should be contacted to answer questions about the equipment.
- A written explanation of the equipment defect or malfunction.
- Any reports or other data that would be helpful in diagnosing the problem.
- If out of warranty, credit card number (to be charged) with its expiration date.

### 9.3 Reporting Problems or Suggestions

If you have any problems, suggestions, or questions related to STC equipment, telephone the **Engineering Department** at the telephone number above. When calling, state the equipment you're calling about. Your call will then be directed to the right person.

### 9.4 Ordering Spare Parts

If you need any spare parts to support STC equipment, telephone or fax the **Sales Department** at the telephone numbers above.

When calling, state that you're calling to order parts. Your call will then be directed to the right person. When placing the order, reference the STC part numbers listed in this guide. However, if you don't have the part numbers, the sales staff can obtain them for you and provide you with current pricing and availability.

When emailing or faxing, include:

- Purchase Order Number for the order or credit card number (to be charged) with its expiration date.
- Complete address where the parts are to be shipped.
- Complete address where the invoice is to be mailed.
- Name and telephone number of the person who should be contacted to answer questions about the order.
- For each item ordered, part number, complete description, and quantity needed.

### 9.5 Checking on Shipments and Orders

If you need to check on the status of any shipment or order, telephone or fax the **Sales Department** at the telephone numbers above.

When calling, state that you're checking the status of a shipment or order. Your call will then be directed to the right person. Have your Purchase Order Number ready when you call. However, if you don't have the order number, the sales staff can locate your order number and provide you with the status of the shipment or order.

When emailing or faxing, include:

- Purchase Order Number for the shipment or order being checked.
- Name and telephone number of the person who should be contacted after the order status is checked.
- Your fax number, if available.

# Appendix A

## System Alarms

---

This appendix describes the conditions and events that the SmartScanNG<sup>2</sup> system flags as System Alarms. These alarms provide data about passing trains and system status. These alarms are listed under the System Alarms section of the Train Detail and Exception Detail reports. **Section 6.0 - Producing Reports** tells how to produce these reports.

### A.1 Ambient Temperature Probe Unreliable Alarm

The Ambient Temperature Probe Unreliable alarm indicates that the temperature probe is giving unreliable readings.

### A.2 Cold Rail Alarm

The Cold Rail alarm indicates that the temperatures of all bearings (of the train) on the designated rail were below a given temperature. When no bearing on a given rail generates a delta temperature reading greater than or equal to the temperature set by the **Cold Rail Temperature option** on the Alarm Settings menu, the system generates a Cold Rail alarm. **Section 4.0 - Serial Interface** tells how to view or change the **Cold Rail Temperature option**.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
07/20/2020 10:49:42, 14.6V, -2°F
Alarm Settings
-----
[A] - Absolute ..... 170
[B] - Differential ..... 150
[C] - Hot Wheel ..... 900
[D] - Cold Rails ..... 3
[E] - Cold Rail Temp ..... 10
[F] - Cold Res Counter ..... 3
[G] - Differential Enabled ..... Yes
[H] - Advanced
[X] - Exit
```

There is a different Cold Rail alarm for each rail. That is, there is a Cold North Rail alarm and a Cold South Rail alarm (or, depending on track direction, a Cold East Rail alarm and a Cold West Rail alarm).

The **maximum number** (per rai1side) of consecutive trains, having Cold Rail alarms, allowed before generating a Successive Cold Rails Exceeded alarm is set by the **Cold Rails option** on the Alarm Settings menu. If the number of consecutive trains bearing Cold Rail alarms equals or exceeds the cold-rail-alarm limit, the message "Successive Cold Rails Exceeded" is displayed on the Train Detail and Exception Detail report. Successive Cold Rails Exceeded alarms are covered in the next appendix. **Section 4.0 - Serial Interface** tells how to view or change the **Cold Rails option**.

### A.3 Cold Resistor Alarm

A resistor is mounted to the inside of the bearing scanner's shutter. A voltage is applied to this resistor while the shutter is open, causing it to heat up. After a train has left a site and the shutters have closed, the temperature of the resistor is read by the scanner pyrometer. In this way, a check of the system's ability to read heat correctly is made. The Cold Resistor alarm indicates that the **minimum value** expected for the temperature of the resistor wasn't met. This minimum value is determined by the firmware and is dependent upon the time it takes a train to pass a site.

If the **minimum value** wasn't met, a second check compares the recorded resistor temperature against the limit that was established using the **Absolute option** on the Alarm Settings menu. (This alarm limit is an offset, in degrees Fahrenheit, above the ambient temperature.) If the recorded resistor temperature meets or exceeds the absolute-alarm limit, the firmware cancels any previously flagged Cold Resistor alarms. **Section 4.0 - Serial Interface** tells how to view or change the **Absolute option**.

Alarm Settings	
-----	
[A] - Absolute .....	170
[B] - Differential .....	150
[C] - Hot Wheel .....	900
	•
	•
	•

There is a different Cold Resistor alarm for each rail. That is, there is a Cold North Resistor alarm and a Cold South Resistor alarm (or, depending on track direction, a Cold East Resistor alarm and a Cold West Resistor alarm).

The **maximum number** (per raiiside) of consecutive trains, having Cold Resistor alarms, allowed before generating a Successive Cold Resistors Exceeded alarm is set by the **Cold Resistor Counter option** on the Alarm Settings menu. Successive Cold Resistors Exceeded alarms are covered in the next appendix. **Section 4.0 - Serial Interface** tells how to view or change the **Cold Resistor Counter option**.

	:	
	:	
[C]	- Differential .....	115
[D]	- Hot Wheel .....	698
[E]	- Cold Rails .....	9
[F]	- Cold Rail Temp .....	10
[G]	- Cold Res Counter .....	9
	:	
	:	

After a train has passed the site, a more accurate *required* resistor value will be calculated, taking into account the ambient temperature. This new value is then used to calculate a correction factor. The factor is the percentage difference between the *required* resistor value and the value that was actually read. For example, if the *required* resistor temperature is 180 and the actual resistor temperature is 135 the correction factor would be 25% ( $1 - (135 / 180) = 0.25$ ).

If the correction factor is less than 24%, no Cold Resistor alarm is generated. If the correction factor is in the range of 24% to 40%, the Cold Resistor alarm is considered a **system alarm**. If the correction factor for a given rail on any train is greater than 40%, the Cold Resistor alarm is considered an **integrity failure**.

During the post-train resistor test, if a read resistor value isn't greater than 76% of the *required* resistor value, two additional checks will be performed. Either of these checks can generate a Cold Resistor alarm. For more information on these checks, see **A.13 Rail Resistor Test Overridden Alarm**.

## A.4 Cold Wheel Scanner Alarm

The Cold Wheel Scanner alarm represents the wheel scanner's equivalent of the bearing scanner's Cold Rail alarm. When no wheel on a given rail generates a delta temperature reading greater than or equal to a preset minimum, the system generates a Cold Wheel Scanner alarm. The preset minimum temperature is determined by the firmware and is currently 9°F above ambient (5°C above ambient). The customer can't change this value. Just like Cold Rail alarms, separate Cold Wheel Scanner alarms exist for each raiiside.

The **maximum number** (per rai1side) of consecutive trains, having Cold Wheel Scanner alarms, allowed before generating a Successive Cold Wheels Exceeded alarm is set by the **Cold Rails option** on the Alarm Settings menu. Successive Cold Wheels Exceeded alarms are covered in the next appendix. **Section 4.0 - Serial Interface** tells how to view or change the **Cold Rails option**.

	:	
	:	
[C] - Differential .....		115
[D] - Hot Wheel .....		698
[E] - Cold Rails .....		9
[F] - Cold Rail Temp .....		10
[G] - Cold Res Counter .....		9
	:	
	:	

### A.5 Cold Wheel Scanner Resistor Alarm

The Cold Wheel Scanner Resistor alarm represents the wheel scanner's equivalent of the bearing scanner's Cold Resistor alarm. Evaluation of Cold Wheel Scanner Resistor alarm mimics the same logic used in the evaluation of Cold Resistor alarms. In this way, the system confirms the scanner's ability to read alarm-level heat. Just like Cold Resistor alarms, separate Cold Wheel Scanner Resistor alarms exist for each rai1side.

The **maximum number** (per rai1side) of consecutive trains, having Cold Wheel Scanner Resistor alarms, allowed before generating a Successive Cold Wheel Resistors Exceeded alarm is set by the **Cold Resistor Counter option** on the Alarm Settings menu. Successive Cold Wheel Resistors Exceeded alarms are covered in the next appendix. **Section 4.0 - Serial Interface** tells how to view or change the **Cold Resistor Counter option**.

	:	
	:	
[C] - Differential .....		115
[D] - Hot Wheel .....		698
[E] - Cold Rails .....		9
[F] - Cold Rail Temp .....		10
[G] - Cold Res Counter .....		9
	:	
	:	

After a train has passed the site, a more accurate *required* resistor value will be calculated, taking into account the ambient temperature. This new value is then used to calculate a correction factor. The factor is the percentage difference between the *required* resistor value and the value that was actually read. For example, if the *required* resistor temperature is 180 and the actual resistor temperature is 135 the correction factor would be 25% ( $1 - (135 / 180) = 0.25$ ).

If the correction factor is less than 24%, no Cold Wheel Scanner Resistor alarm is generated. If the correction factor is in the range of 24% to 40%, the Cold Wheel Scanner Resistor alarm is considered a **system alarm**. If the correction factor for a given rail on any train is greater than 40%, the Cold Wheel Scanner Resistor alarm is considered an **integrity failure**.

During the post-train resistor test, if a read resistor value isn't greater than 76% of the required resistor value, two additional checks will be performed. Either of these checks can generate a Cold Wheel Scanner Resistor alarm. For more information on these checks, see **A.20 Wheel Resistor Test Overridden Alarm**.

## A.6 Highrange Transducer Miscounts Alarm

The Highrange Transducer Miscounts alarm indicates that the transducer counts for TO1 and TO2 differ by seven or more. This calculation is made after each axle crosses both gating transducers. When this alarm occurs, the system won't announce axle count, exit speed, length of train, or total number of cars (even if these messages are enabled).

The Highrange Transducer Miscounts alarm can be either a System Alarm or an Integrity Failure, depending on the presence of a Very Slow Train alarm. If a highrange transducer miscount occurs on a train that also contains a Very Slow Train alarm, the firmware treats the miscount condition as a System Alarm. This logic assumes that the train's slow rate of travel likely caused the transducer miscount condition. If a highrange transducer miscount occurs on a train traveling faster than 7 mph (11.3 kph), the firmware treats the miscount condition as an Integrity Failure.

## A.7 Integrity Failure Alarm

The Integrity Failure alarm indicates that the SmartScanNG<sup>2</sup> system determined that a condition exists that could prevent proper scanning of a train. In other words, this alarm indicates the existence of one or more conditions in which the integrity of the system, and its ability to accurately record train data, may be compromised. These unusual conditions, called Integrity Failures, may require train stoppage, later maintenance, or both. They are covered in the next appendix.

## A.8 Low Battery Alarm

The **Low Battery alarm** indicates a float voltage of at least 11.8 volts, but less than 12.6 volts, on the standby battery. (The **Dead Battery alarm** indicates a float voltage of less than 11.8 volts on the standby battery.)

## A.9 Midrange Transducer Miscounts Alarm

The Midrange Transducer Miscounts alarm indicates that the transducer counts for TO1 and TO2 differ by five or six. This calculation is made after each axle crosses both gating transducers.

## A.10 No Approach Track Alarm

The No Approach Track alarm indicates that the system presence detection system (that is, the track circuit or the advance transducers) didn't detect the arrival of the train at the site. Instead, the system started the train scanning process when a gating transducer sensed the train.

**NOTE:** This alarm is suppressed if the Presence Hardware is set to “No” in Equipment Setup Menu.

## A.11 Pyrometer Noise Filtered Rail Alarm

The Pyrometer Noise Filtered Rail alarm indicates that a pyrometer in a bearing scanner might be becoming unreliable. This alarm isn't considered an Integrity Failure and therefore won't result in “Integrity Failure” being part of the post-train announcement.

There is a different Pyrometer Noise Filtered Rail alarm for each rail. That is, there is a Pyrometer Noise Filtered North Rail alarm and a Pyrometer Noise Filtered South Rail alarm (or, depending on track direction, a Pyrometer Noise Filtered East Rail alarm and a Pyrometer Noise Filtered West Rail alarm).

## A.12 Pyrometer Noise Filtered Wheel Alarm

The Pyrometer Noise Filtered Wheel alarm indicates that a pyrometer in a wheel scanner might be becoming unreliable. This alarm isn't considered an Integrity Failure and therefore won't result in “Integrity Failure” being part of the post-train announcement.

There is a different Pyrometer Noise Filtered Wheel alarm for each rail. That is, there is a Pyrometer Noise Filtered North Wheel alarm and a Pyrometer Noise Filtered South Wheel alarm (or, depending on track direction, a Pyrometer Noise Filtered East Wheel alarm and a Pyrometer Noise Filtered West Wheel alarm).

## A.13 Rail Resistor Test Overridden Alarm

During the post-train resistor test, if a read resistor value isn't greater than 76% of the required resistor value, two additional checks will be performed. The average heats for both bearings are tested against the value set by the **Resistor Test Minimum Rail Average option** on the Alarm Settings (Advanced) menu.

```
      :  
      :  
[A] - Carside Slope ..... 1.31  
[B] - Carside Minimum ..... 155  
[C] - Res Test: Minimum Rail Avg .... 25  
      :  
      :
```

If the average heats are less than the value set by the **Resistor Test Minimum Rail Average option**, the system generates a Cold Resistor alarm.

If the average heats are greater than or equal to this value, bearing temperatures are compared on an axle-by-axle basis. This second check determines if more than half of the temperatures read by the bearing scanner with the low-read resistor value are 70% or less than the temperatures read by the other bearing scanner on the same axle. If 50% or more of the axles are low, a Cold Resistor alarm is flagged. If not, a Cold Resistor alarm isn't flagged, but a Rail Resistor Test Overridden alarm is.

There is a different Rail Resistor Test Overridden alarm for each rail. That is, there is a North Rail Resistor Test Overridden alarm and a South Rail Resistor Test Overridden alarm (or, depending on track direction, an East Rail Resistor Test Overridden alarm and a West Rail Resistor Test Overridden alarm).

## **A.14 Reverse Direction Detected Alarm**

Trains that are being scanned correctly will have axles whose on times (axles between the gating transducers) are less than their off times (axles not between the gating transducers). When processing axles two and three, the system checks for an on-time that is greater than the off-time. If the axle's on time is greater than its off time, the system reverses the direction locked-in by the first gating pulse, reverses the opening and closing gate assignment for TO1 and TO2, and generates a false transducer pulse. The system considers the gate active for the next axle at the time it determines the current axle's opening gate pulse was missed.

The Reverse Direction Detected alarm indicates that the system entered a state where it is scanning for bearing temperatures when the axles are outside the scanning gate. In this state, the transducer that should be opening the scanning gate is considered by the system to be the transducer that is closing the gate. Likewise, the transducer that should be closing the scanning gate is considered the transducer that is opening the gate.

## **A.15 Short Train Alarm**

The Short Train alarm indicates that a train had fewer than 50 axles.

## **A.16 Stuck Dragger Recovered Alarm**

The Stuck Dragger Recovered alarm indicates that a stuck dragger was detected during train passage and, at some point later, the dragging-equipment detector returned to its neutral position. After returning to its neutral position, the firmware must scan at least eight consecutive Dragger free axles before flagging this condition again.

## **A.17 Stuck SOTC Alarm**

The Stuck SOTC alarm indicates that the track circuit remained activate after train passage.

## A.18 Test Train Alarm

The Test Train alarm indicates that a given train was generated by the SmartScanNG<sup>2</sup> system. These trains are used for testing purposes and do not represent actual trains passing the site.

## A.19 Very Slow Train Alarm

The Very Slow Train alarm indicates that, at some point during train passage, four consecutive axles crossed the gating transducers at a speed of 7 mph (11.3 kph) or less. When this alarm occurs, the system won't announce axle count, exit speed, length of train, and total number of cars (even if these messages are enabled).

## A.20 Wheel Resistor Test Overridden Alarm

During the post-train resistor test, if a read resistor value isn't greater than 76% of the required resistor value, two additional checks will be performed. The average heats for both wheels are tested against the value set by the **Resistor Test Minimum Wheel Average option** on the Alarm Settings menu.

If the average heats are less than the value set by the **Resistor Test Minimum Wheel Average option**, the system generates a Cold Wheel Scanner Resistor alarm.

If the average heats are greater than or equal to this value, wheel temperatures are compared on an axle-by-axle basis. This second check determines if more than half of the temperatures read by the wheel scanner with the low-read resistor value are 70% or less than the temperatures read by the other wheel scanner on the same axle. If 50% or more of the axles are different, a Cold Wheel Scanner Resistor alarm is flagged. If not, a Cold Wheel Scanner Resistor alarm isn't flagged, but a Wheel Resistor Test Overridden alarm is.

There is a different Wheel Resistor Test Overridden alarm for each rail. That is, there is a North Wheel Resistor Test Overridden alarm and a South Wheel Resistor Test Overridden alarm (or, depending on track direction, an East Wheel Resistor Test Overridden alarm and a West Wheel Resistor Test Overridden alarm).

# Appendix B

## Integrity Failures

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This appendix describes the conditions and events that the SmartScanNG<sup>2</sup> system flags as Integrity Failures. These alarms indicate conditions in which the integrity of the system, and its ability to record train data accurately, may be compromised. These alarms are listed under the Integrity Failure section of the Train Detail and Exception Detail reports. **Section 6.0 - Producing Reports** tells how to produce these reports.

### B.1 Cold Resistor Alarm

A resistor is mounted to the inside of the bearing scanner's shutter. A voltage is applied to this resistor while the shutter is open, causing it to heat up. After a train has left a site and the shutters have closed, the temperature of the resistor is read by the scanner pyrometer. In this way, a check of the system's ability to read heat correctly is made. The Cold Resistor alarm indicates that the minimum value expected for the temperature of the resistor wasn't met. This minimum value is determined by the firmware and is dependent upon the time it takes a train to pass a site. Separate Cold Resistor alarms exist for each railside.

After a train has passed the site, a more accurate *required* resistor value will be calculated, taking into account the ambient temperature. This new value is then used to calculate a correction factor. The factor is the percentage difference between the *required* resistor value and the value that was actually read. For example, if the *required* resistor temperature is 180 and the actual resistor temperature is 135 the correction factor would be 25% ( $1 - (135 / 180) = 0.25$ ).

If the correction factor is less than 24%, no Cold Resistor alarm is generated. If the correction factor is in the range of 24% to 40%, the Cold Resistor alarm is considered a **system alarm**. If the correction factor for a given rail on any train is greater than 40%, the Cold Resistor alarm is considered an **integrity failure**.

During the post-train resistor test, if a read resistor value isn't greater than 76% of the *required* resistor value, two additional checks will be performed. Either of these checks can generate a Cold Resistor alarm. For more information on these checks, see **A.13 Rail Resistor Test Overridden Alarm**.

### B.2 Cold Wheel Scanner Resistor Alarm

The Cold Wheel Scanner Resistor alarm represents the wheel scanner's equivalent of the bearing scanner's Cold Resistor alarm. Evaluation of Cold Wheel Scanner Resistor alarm mimics the same logic used in the evaluation of Cold Resistor alarms. In this way, the system confirms the scanner's ability to read alarm-level heat. Just like Cold Resistor alarms, separate Cold Wheel Scanner Resistor alarms exist for each railside.

After a train has passed the site, a more accurate *required* resistor value will be calculated, taking into account the ambient temperature. This new value is then used to calculate a correction factor. The factor is the percentage difference between the *required* resistor value and the value that was actually read. For example, if the *required* resistor temperature is 180 and the actual resistor temperature is 135 the correction factor would be 25% ( $1 - (135 / 180) = 0.25$ ).

If the correction factor is less than 24%, no Cold Wheel Scanner Resistor alarm is generated. If the correction factor is in the range of 24% to 40%, the Cold Wheel Scanner Resistor alarm is considered a **system alarm**. If the correction factor for a given rail on any train is greater than 40%, the Cold Wheel Scanner Resistor alarm is considered an **integrity failure**.

During the post-train resistor test, if a read resistor value isn't greater than 76% of the required resistor value, two additional checks will be performed. Either of these checks can generate a Cold Wheel Scanner Resistor alarm. For more information on these checks, see **A.20 Wheel Resistor Test Overridden Alarm**.

### B.3 Dead Battery Alarm

The **Dead Battery alarm** indicates a float voltage of less than 11.8 volts on the standby battery. (The **Low Battery alarm** indicates a float voltage of at least 11.8 volts, but less than 12.6 volts, on the standby battery.)

### B.4 Dead Resistor Alarm

The bearing scanner's Dead Resistor alarm indicates the presence of two separate conditions. First, the train must contain a Cold Rail alarm on a given rail. Second, the recorded temperature for the bearing scanner's resistor on that rail must fall below the value set by the **Cold Rail Temperature option** on the Alarm Settings menu. **Section 4.0 - Serial Interface** tells how to view or change this value.

Alarm Settings	
-----	
[A] - Absolute .....	170
[B] - Differential .....	150
[C] - Hot Wheel .....	900
[D] - Cold Rails .....	3
[E] - Cold Rail Temp .....	10
[F] - Cold Res Counter .....	3
[G] - Differential Enabled .....	Yes
[H] - Advanced	
[X] - Exit	

There is a different Dead Resistor alarm for each rail. That is, there are a Dead North Resistor alarm and a Dead South Resistor alarm (or, depending on track direction, a Dead East Resistor alarm and a Dead West Resistor alarm).

## B.5 Dead Wheel Scanner Resistor Alarm

The wheel scanner's Dead Wheel Scanner Resistor alarm indicates the presence of two separate conditions. First, the train must contain a Cold Wheel Scanner alarm on a given rail. Second, the recorded temperature for the wheel scanner's resistor on that rail must fall below the value set by the **Cold Rail Temperature option** on the Alarm Settings menu. **Section 4.0 - Serial Interface** tells how to view or change this value.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
07/20/2020 10:55:48, 14.6V, -2°F
Alarm Settings
-----
[A] - Absolute ..... 170
[B] - Differential ..... 150
[C] - Hot Wheel ..... 900
[D] - Cold Rails ..... 3
[E] - Cold Rail Temp ..... 10
[F] - Cold Res Counter ..... 3
[G] - Differential Enabled ..... Yes
[H] - Advanced
[X] - Exit
```

There is a different Dead Wheel Scanner Resistor alarm for each rail. That is, there is a Dead North Wheel Scanner Resistor alarm and a Dead South Wheel Scanner Resistor alarm (or, depending on track direction, a Dead East Wheel Scanner Resistor alarm and a Dead West Wheel Scanner Resistor alarm).

## B.6 Highrange Transducer Miscounts Alarm

The Highrange Transducer Miscounts alarm indicates that the transducer counts for TO1 and TO2 differ by seven or more. This calculation is made after each axle crosses both gating transducers. When this alarm occurs, the system won't announce axle count, exit speed, length of train, or total number of cars (even if these messages are enabled).

The Highrange Transducer Miscounts alarm can be either a System Alarm or an Integrity Failure, depending on the presence of a Very Slow Train alarm. If a highrange transducer miscount occurs on a train that also contains a Very Slow Train alarm, the firmware treats the miscount condition as a System Alarm. This logic assumes that the train's slow rate of travel likely caused the transducer miscount condition. If a highrange transducer miscount occurs on a train traveling faster than 7 mph (11.3 kph), the firmware treats the miscount condition as an Integrity Failure.

## **B.7 Stuck Dragger During Train Passage Alarm**

The Stuck Dragger During Train Passage alarm indicates that the preset maximum number of consecutive axles have had Dragging-Equipment alarms during train passage. The maximum number is determined by the firmware and is currently five.

## **B.8 Stuck Dragger Pretrain Alarm**

The Stuck Dragger Pretrain alarm indicates that the dragging-equipment detector was stuck before the scanners started scanning. That is, between the time of first receiving a pulse from the track circuit (or the advance transducers) and the time of first receiving a pulse from either gating transducer, the SmartScanNG<sup>2</sup> system detected an open circuit from the dragging-equipment detector.

## **B.9 Stuck High-Load Detector Pretrain Alarm**

The Stuck High-Load Detector Pretrain alarm indicates that, before the scanners started scanning, the high-load detector was stuck. That is, between the time of first receiving a pulse from the track circuit (or the advance transducers) and the time of first receiving a pulse from either gating transducer, the SmartScanNG<sup>2</sup> system detected an open circuit from the high-load detector.

## **B.10 Stuck Wide-Load Detector Pretrain Alarm**

The Stuck Wide-Load Detector Pretrain alarm indicates that, before the scanners started scanning, the wide-load detector was stuck. That is, between the time of first receiving a pulse from the track circuit (or the advance transducers) and the time of first receiving a pulse from either gating transducer, the SmartScanNG<sup>2</sup> system detected an open circuit from the wide-load detector.

There is a different Stuck Wide-Load Detector Pretrain alarm for each rail. That is, there is a Stuck Wide-Load Detector Pretrain North Side alarm and a Stuck Wide-Load Detector Pretrain South Side alarm (or, depending on track direction, a Stuck Wide-Load Detector Pretrain East Side alarm and a Stuck Wide-Load Detector Pretrain West Side alarm).

## B.11 Successive Cold Rails Exceeded Alarm

The Successive Cold Rails Exceeded alarm indicates that at least a preset maximum number of consecutive trains, all having Cold Rail alarms on the same rai1side, have passed a site. The maximum number (per rai1side) of consecutive trains having Cold Rail alarms allowed before generating an Integrity Failure alarm is set by the **Cold Rails option** on the Alarm Settings menu. **Section 4.0 - Serial Interface** tells how to view or change this value.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
07/20/2020 10:55:48, 14.6V, -2°F
Alarm Settings
-----
[A] - Absolute ..... 170
[B] - Differential ..... 150
[C] - Hot Wheel ..... 900
[D] - Cold Rails ..... 3
[E] - Cold Rail Temp ..... 10
[F] - Cold Res Counter ..... 3
[G] - Differential Enabled ..... Yes
[H] - Advanced
[X] - Exit
```

Under normal circumstances, Cold Rail conditions represent System Alarms, not Integrity Failures. However, if the number of consecutive trains bearing the same Cold Rail alarm equals or exceeds the **Cold Rails option** on the Alarm Settings menu, this condition becomes an Integrity Failure. When this happens, the System Alarms section of the Train Detail and Exception Detail reports displays the message "Successive Cold Rails Exceeded."

## B.12 Successive Cold Resistors Exceeded Alarm

The Successive Cold Resistors Exceeded alarm indicates that at least a preset maximum number of consecutive trains, all having Cold Resistor alarms on the same rai1side, have passed a site. The maximum number (per rai1side) of consecutive trains having Cold Resistor alarms allowed before generating an Integrity Failure alarm is set by the **Cold Resistor Counter option** on the Alarm Settings menu. **Section 4.0 - Serial Interface** tells how to view or change this value.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
07/20/2020 10:55:48, 14.6V, -2°F
Alarm Settings
-----
[A] - Absolute ..... 170
[B] - Differential ..... 150
[C] - Hot Wheel ..... 900
[D] - Cold Rails ..... 3
[E] - Cold Rail Temp ..... 10
[F] - Cold Res Counter ..... 3
[G] - Differential Enabled ..... Yes
[H] - Advanced
[X] - Exit
```

Under normal circumstances, Cold Resistor conditions represent System Alarms, not Integrity Failures. However, if the number of consecutive trains bearing the same Cold Resistor alarm equals or exceeds the **Cold Resistor Counter option** on the Alarm Settings menu, this condition becomes an Integrity Failure. When this happens, the Integrity Failures section of the Train Detail and Exception Detail reports displays the message "Successive Cold Resistors Exceeded."

### B.13 Successive Cold Wheels Exceeded Alarm

The Successive Cold Wheels Exceeded alarm indicates that at least a preset maximum number of consecutive trains, all having Cold Wheel Scanner alarms on the same railside, have passed a site. The user determines the number of consecutive trains used in the comparison through the **Cold Rails option** on the Alarm Settings menu. **Section 4.0 - Serial Interface** tells how to view or change this value.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
07/20/2020 10:55:48, 14.6V, -2°F
Alarm Settings
-----
[A] - Absolute ..... 170
[B] - Differential ..... 150
[C] - Hot Wheel ..... 900
[D] - Cold Rails ..... 3
[E] - Cold Rail Temp ..... 10
[F] - Cold Res Counter ..... 3
[G] - Differential Enabled ..... Yes
[H] - Advanced
[X] - Exit
```

Under normal circumstances, cold-wheel conditions represent System Alarms, not Integrity Failures. However, if the number of consecutive trains bearing the same Cold Wheel Scanner alarm equals or exceeds the **Cold Rails option** on the Alarm Settings menu, this condition becomes an Integrity Failure. When this happens, the Integrity Failures section of the Train Detail and Exception Detail reports displays the message "Successive Cold Wheels Exceeded."

## B.14 Successive Cold Wheel Resistors Exceeded Alarm

The Successive Cold Wheel Resistors Exceeded alarm indicates that at least a preset maximum number of consecutive trains, all having Cold Wheel Scanner Resistor alarms on the same raiiside, have passed a site. The user determines the number of consecutive trains used in the comparison through the **Cold Resistor Counter option** on the Alarm Settings menu. **Section 4.0 - Serial Interface** tells how to view or change this value.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
07/20/2020 10:55:48, 14.6V, -2°F
Alarm Settings
-----
[A] - Absolute ..... 170
[B] - Differential ..... 150
[C] - Hot Wheel ..... 900
[D] - Cold Rails ..... 3
[E] - Cold Rail Temp ..... 10
[F] - Cold Res Counter ..... 3
[G] - Differential Enabled ..... Yes
[H] - Advanced
[X] - Exit
```

Under normal circumstances, cold-wheel-resistor conditions represent System Alarms, not Integrity Failures. However, if the number of consecutive trains bearing the same Cold Wheel Scanner Resistor alarm equals or exceeds the **Cold Resistor Counter option** on the Alarm Settings menu, this condition becomes an Integrity Failure. When this happens, the Integrity Failure section of the Train Detail and Exception Detail reports displays the message "Successive Cold Wheel Resistors Exceeded."

## B.15 Train Present on Restart Alarm

The Train Present on Restart alarm indicates that a train was present at the site when the system was starting up.



## Appendix C

# Replacement of Type III Scanners

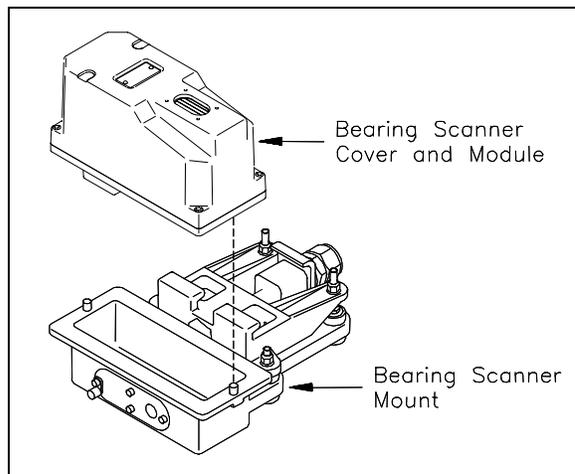
---

There are bearing scanners and wheel scanners. Both contain two major parts. The top part is the cover-and-module assembly. The module and its protective cover are tightly integrated and rarely should be taken apart. Except for the change of **filter frames** in the wheel scanner module, both types of cover-and-module assemblies are identical and can be used interchangeably. The bottom part is the mount. Bearing scanner mounts and wheel scanner mounts are different in design. They can't be interchanged.

This appendix tells how to replace scanner cover-and-module assemblies. Replacement of scanner mounts isn't covered in this guide.

### C.1 Bearing Scanners

*The figure below shows the major parts of a bearing scanner.*



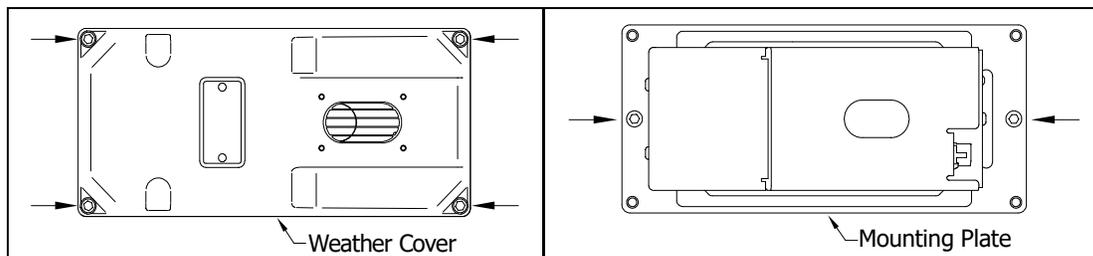
To replace a bearing scanner cover-and-module assembly:

- 1 Be sure that you have on hand a new scanner cover-and-module assembly.
- 2 Be sure that you have on hand a T-handle 1/4-inch hex-wrench.
- 3 Turn off all power to the scanners.

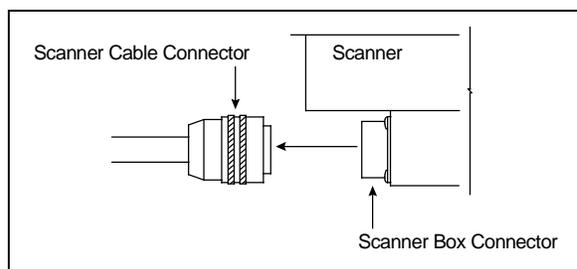
This requires turning off the DC power switch on the SmartScanNG<sup>2</sup> enclosure and unplugging the AC power cord on the bottom of the SmartScanNG<sup>2</sup> enclosure.

- Using a T-handle 1/4-inch hex-wrench, loosen the six socket-head-cap screws on the cover of the bearing scanner.

Four screws attach the weather cover to the mounting plate and two screws attach the mounting plate to the mount.

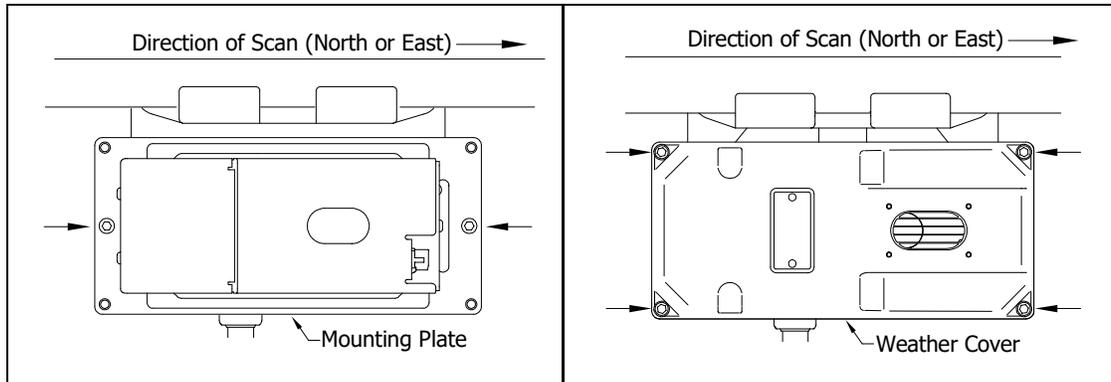


- Separate the bearing scanner cover-and-module assembly from its mount.
- Disconnect the heater wiring plug.
- Disconnect the scanner cable connector from the scanner box connector.



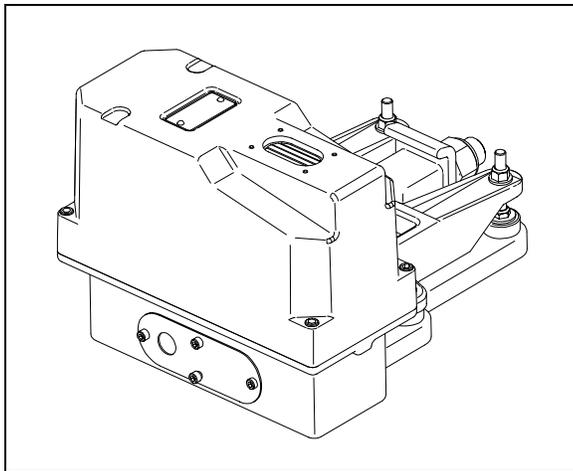
- Store the removed scanner cover-and-module assembly in a safe place until you return it to STC for repair.
- Attach the scanner cable connector to the scanner box connector of the new scanner cover-and-module assembly.
- With the hole on top of the bearing scanner cover facing north or east, set the mounting plate back onto its scanner mount.
- Using the T-handle 1/4-inch hex-wrench, uniformly tighten the two socket-head-cap screws.
- Reconnect the heater wiring plug.
- With the hole on top of the bearing scanner cover facing north or east, set the weather cover back onto its mounting plate.
- Using the T-handle 1/4-inch hex-wrench, uniformly tighten the four socket-head-cap screws.

The top view of the bearing scanner mounting plate and weather cover is shown below.



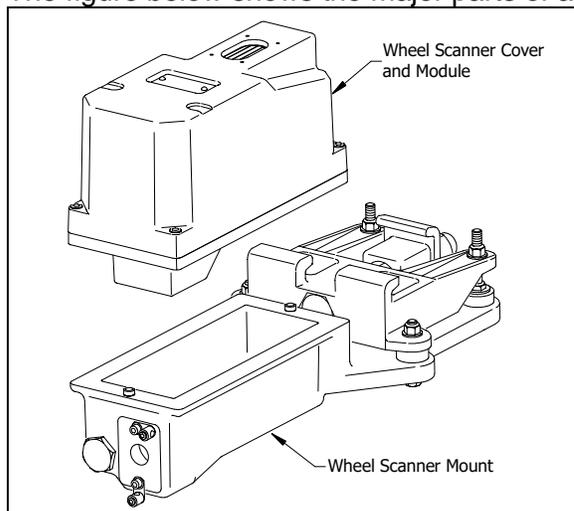
**15** Turn on power to the scanners.

An assembled bearing scanner looks like this.



## C.2 Wheel Scanners

The figure below shows the major parts of a wheel scanner.



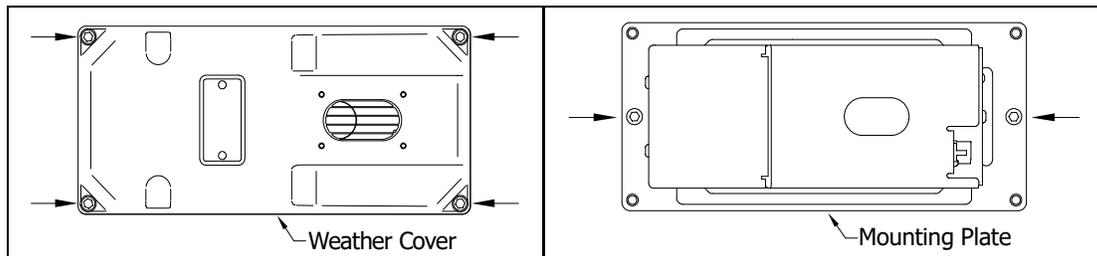
To replace a wheel scanner cover-and-module assembly:

- 1 Be sure that you have on hand a new scanner cover-and-module assembly.
- 2 Be sure that you have on hand a T-handle 1/4-inch hex-wrench.
- 3 Turn off all power to the scanners.

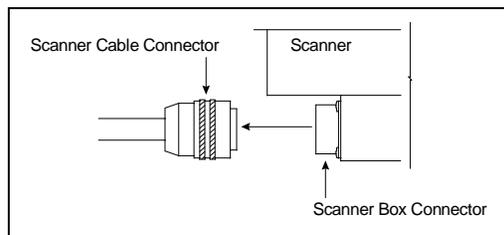
This requires turning off the DC power switch on the SmartScanNG<sup>2</sup> enclosure and unplugging the AC power cord on the bottom of the SmartScanNG<sup>2</sup> enclosure.

- 4 Using a T-handle 1/4-inch hex-wrench, loosen the six socket-head-cap screws on the cover of the wheel scanner.

Four screws attach the weather cover to the mounting plate and two screws attach the mounting plate to the mount.



- 5 Separate the wheel scanner cover-and-module assembly from its mount.
- 6 Disconnect the heater wiring plug.
- 7 Disconnect the scanner cable connector from the scanner box connector.



- 8 Store the removed scanner cover-and-module assembly in a safe place until you return it to STC for repair.
- 9 Attach the scanner cable connector to the scanner box connector of the new scanner cover-and-module assembly.
- 10 With the hole on top of the wheel scanner cover facing the center of the track, set the mounting plate back onto its scanner mount.
- 11 Using the T-handle 1/4-inch hex-wrench, uniformly tighten the two socket-head-cap screws.
- 12 Reconnect the heater wiring plug.
- 13 With the hole on top of the wheel scanner cover facing the center of the track, set the weather cover back onto its mounting plate.
- 14 Using the T-handle 1/4-inch hex-wrench, uniformly tighten the four socket-head-cap screws.
- 15 Turn on power to the scanners.

# Appendix D

## Calibration of Type III Scanners

---

The SmartScanNG<sup>2</sup> system self-calibrates its pyrometer interface circuitry. You need only put a preheated calibrated heat source on a scanner and place the system in autocalibration mode. The system then scans all pyrometer inputs until the signal from the calibrated heat source is located. The necessary adjustments to the related interface circuitry are automatically made while the system monitors its own progress by analyzing changes in the heat signals. Once the procedure has been completed, autocalibration mode is disengaged and the calibration results are displayed on your computer.

This appendix tells how to use the calibrated heat source to calibrate the scanners.

### D.1 Bearing Scanners

**STC recommends that you use the calibrated heat source (2100-810NG) only when the outside (ambient) temperature is above -18°C (0°F) and below 32°C (90°F).** If you must use it at other times, do so only when the needle is centered on the front of the temperature meter. If the needle isn't stabilized within  $\pm 2$  degrees of set point, the heat source isn't operating properly.

To calibrate a bearing scanner:

- 1 Be sure that you have on hand an STC calibrated heat source (2100-810NG) and a laptop computer.
- 2 On the control panel of the calibrated heat source, toggle the **Gating** switch off.
- 3 Plug the proper end of the supplied 50-foot (15-meter) power cord into the **six**-contact circular connector on the front of the calibrated heat source.

**Sixty Hz is critical for proper operation.** For a site that doesn't have a 120-volt 60-Hz power source, the heat source should be powered from a true sine wave inverter capable of 250 watts with an output of at least 110 volts at 60 Hz. The inverter should operate from an input voltage of 10.5 VDC to 15 VDC. A 120-volt USA socket should be provided to match the heat source power cord. The inverter should be grounded according to the manufacturer's recommendations.

#### **WARNING**

Once plugged in, both function connectors will have live AC present.

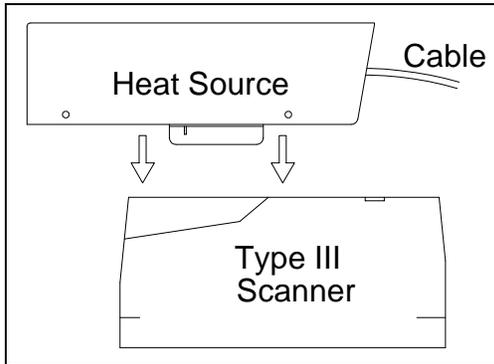
- 4 Using the supplied dust cap, cover the function connector that isn't being used.
- 5 Plug the other end of the power cord into the 120-volt USA socket.
- 6 On the control panel of the calibrated heat source, turn the temperature knob to **180°**.

- 7 Put the heat source in a shady area, out of direct sunlight and out of the wind.
- 8 Wait about 8 minutes for the heat source to reach operating temperature and stabilize.

The heat source has reached operating temperature and stabilized when the temperature meter needle remains centered.

Once the temperature stabilizes, calibration may begin. Once stabilized, the temperature will change less than plus-or-minus one degree Fahrenheit.

- 9 With the power cord to the front of the scanner, place the calibrated heat source on the bearing scanner.



- 10 To prepare your computer:
  - a Plug your computer into COM1 using a crossover (null-modem) cable.
  - b Turn on your computer.
  - c Be sure that your computer has installed communications software, that it is set to use full-duplex, and that the baud rate is set to 19,200.
- 11 Using the serial interface, display the Main menu.

The Main menu looks like this.

```

SmartSCAN NG2, MP/KP:1234.5, Track:Single
06/05/2020 16:31:08, 13.9V, 69°F
Main Menu - Comm
-----
          .
          .
          .
[K] - System Functions Menu
[L] - Replay train
[M] - Security Menu
[X] - Exit
  
```

**12** Select **Auto-calibration** to calibrate the system's pyrometer interface circuitry.

The SmartScanNG<sup>2</sup> system will now calibrate itself. **Follow along on your computer screen until you see "Auto-Calibration Disengaged."** This message is an indication that the system is done with the calibration procedure. To abort the process, press **[Esc]** on your computer or remove the heat source from the bearing scanner.

```
      .  
      .  
      .  
[F] - Auto-Calibration  
[G] - Reboot System  
[H] - Delete All Stored Train Data  
[I] - Clear Event Log  
[J] - Update Menu  
[K] - Maintenance Menu  
[L] - Volume up (3)  
[M] - Volume down (3)  
[N] - Resistor Baseline Data  
[O] - Radio Programming Menu  
[P] - Scanner test  
[Q] - Calibrate Frauscher Transducers  
[R] - Virtual gate test  
[X] - Exit
```

On your computer screen, an acceptable calibration looks like this. Your values will be different.

```

Auto Calibration Selected
Scanner Types
-----
Rail-1..... Type-II   Rail-2..... Type-III
Wheel-1..... Type-III  Wheel-2..... Type-II

Is this correct ?

Signal levels in millivolts with closed shutters
      Rail1           Rail2           Wheel1           Wheel2
Min/Max/Average  Min/Max/Average  Min/Max/Average  Min/Max/Average
0  80  20    0  60  20    0  60  20    20  80  40

Opening the shutters.
Scanning for heat source. Press the 'Esc' key to abort.
Located 187F heat source at Rail1. Auto-calibration beginning in 0 secs.

.....Auto-Calibration Engaged.....

Testing Digital-Pot U-306. Stand by.
Digital-pot checks OK.
Previous calibrated digital-pot. setting was 38.
Adjusting digital-pot.
Temp = 225F  Pot = 59  Sec = 1  Pot. decremented by 1 step.
Temp = 224F  Pot = 58  Sec = 1  Pot. decremented by 1 step.
Temp = 221F  Pot = 57  Sec = 2  Pot. decremented by 1 step.
Temp = 219F  Pot = 56  Sec = 3  Pot. decremented by 1 step.

      .
      .

Temp = 183F  Pot = 35  Sec = 15  Pot. decremented by 1 step.
Temp = 182F  Pot = 34  Sec = 18  Pot. decremented by 1 step.
Temp = 181F  Pot = 33  Sec = 29  Pot. decremented by 1 step.
Temp = 179F  Pot = 33  Sec = 93  Monitoring heat source temperature.
Rail1 digital-pot setting of 33 was stored in EEPROM.
East Rail Scanner Calibration complete.
The setpoint is 180F. The calibrated temp. is 179F.
Closing the shutters.
Resistor test pending.

.....Auto-Calibration Disengaged.....

```

Before the shutters are opened, if you get a signal level greater than 200 millivolts, it usually means that there is noise on the scanner inputs, which most times is caused by an electrical problem with the scanner. If you cannot isolate and fix the cause of this problem, call STC for help.

```

Auto Calibration Selected

Signal levels in millivolts with closed shutters
      Rail1           Rail2           Wheel1           Wheel2
Min/Max/Average  Min/Max/Average  Min/Max/Average  Min/Max/Average
210 250 210    0  60  20    0  60  20    20  80  40

      .
      .
      .

```

Before the shutters are closed, if you don't get a calibrated temperature in the range 178°F to 182°F, it means that the scanner wasn't calibrated. If cleaning the optics doesn't solve your problem, replace the scanner cover-and-module assembly. If this doesn't solve your problem, call STC for help in fixing the problem.

- 13 When "Auto-Calibration Disengaged" is displayed on your computer, remove the calibrated heat source.
- 14 To return to the Main menu, type **X**.
- 15 To exit the serial interface and return the system to normal operation, type **X**.
- 16 Store the calibrated heat source and its power cord in the wayside enclosure.

**NOTE:**

Upon completion of autocalibration, the system acquires the scanner resistor temperature baseline values. The process begins with a 20 minute wait period in which the resistors are allowed to cool down. The system counts down during this period, sounding a tone each minute. After the 20-minute cooldown period, the system opens and closes the shutters for a period of 8 minutes.

Covering the apertures of all four scanners during the baseline acquisition routine should result in a more accurate baseline measurement because the reference for the scanner is stable when covered. See **Appendix H** for a detailed explanation and instructions.

## D.2 Wheel Scanners

STC recommends that you use the calibrated heat source (2100-810NG) only when the outside (ambient) temperature is above  $-18^{\circ}\text{C}$  ( $0^{\circ}\text{F}$ ) and below  $32^{\circ}\text{C}$  ( $90^{\circ}\text{F}$ ). If you must use it at other times, do so only when the needle is centered on the front of the temperature meter. If the needle isn't stabilized within  $\pm 2$  degrees of set point, the heat source isn't operating properly.

To calibrate a wheel scanner:

- 1 Be sure that you have on hand an STC calibrated heat source (2100-810NG) and a laptop computer.
- 2 On the control panel of the calibrated heat source, toggle the **Gating** switch off.
- 3 Plug the proper end of the supplied 50-foot (15-meter) power cord into the six-contact circular connector on the front of the calibrated heat source.

**Sixty Hz is critical for proper operation.** For a site that doesn't have a 120-volt 60-Hz power source, the heat source should be powered from a true sine wave inverter capable of 250 watts with an output of at least 110 volts at 60 Hz. The inverter should operate from an input voltage of 10.5 VDC to 15 VDC. A 120-volt USA socket should be provided to match the heat source power cord. The inverter should be grounded according to the manufacturer's recommendations.

### WARNING

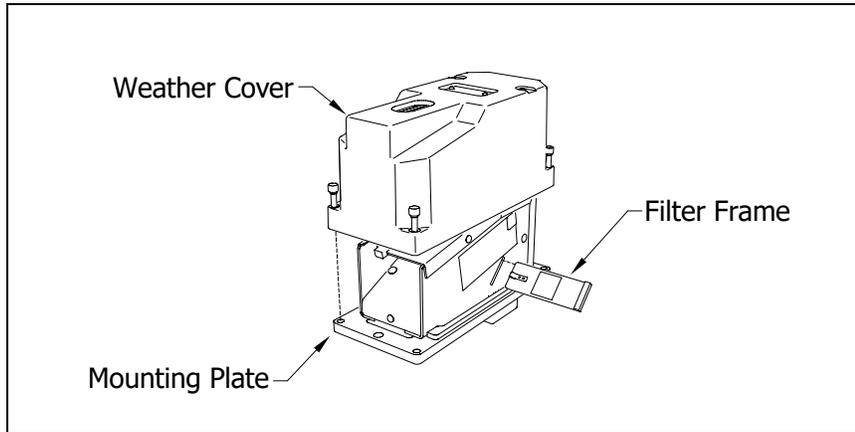
Once plugged in, both function connectors will have live AC present.

- 4 Using the supplied dust cap, cover the function connector that isn't being used.
- 5 Plug the other end of the power cord into the 120-volt USA socket.
- 6 On the control panel of the calibrated heat source, turn the temperature knob to **180°**.
- 7 Put the heat source in a shady area, out of direct sunlight and out of the wind.
- 8 Wait about 8 minutes for the heat source to reach operating temperature and stabilize.

The heat source has reached operating temperature and stabilized when the temperature meter needle remains centered.

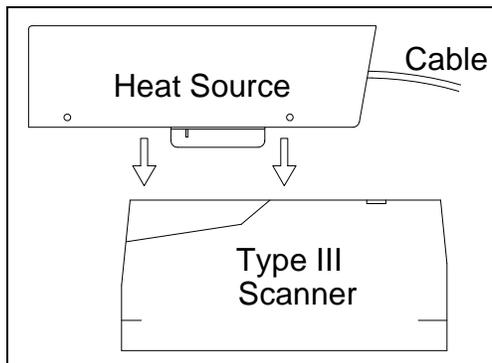
Once the temperature stabilizes, calibration may begin. Once stabilized, the temperature will change less than plus-or-minus one degree Fahrenheit.

- 9 Replace the red filter frame with the black one during calibration.



You'll need to remove the weather cover before you can replace the filter frame. Four socket head cap screws attach the weather cover to the mounting plate. Before continuing, be sure that the black filter frame is securely in place and that the four socket-head-cap screws on the weather cover are completely tight.

- 10** With the power cord to the front of the scanner, place the calibrated heat source on the wheel scanner.



- 11** To prepare your computer:
  - a** Plug your computer into COM1 using a crossover (null-modem) cable.
  - b** Turn on your computer.
  - c** Be sure that your computer has installed communications software, that it is set to use full-duplex, and that the baud rate is set to 19,200.

**12** Using the serial interface, display the Main menu.

The Main menu looks like this.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
06/05/2020 16:31:08, 13.9V, 69°F
Main Menu - Comm
-----
                .
                .
                .
[K] - System Functions Menu
[L] - Replay train
[M] - Security Menu
[X] - Exit
```

**13** Select the **Auto-Calibration option** to calibrate the system's pyrometer interface circuitry.

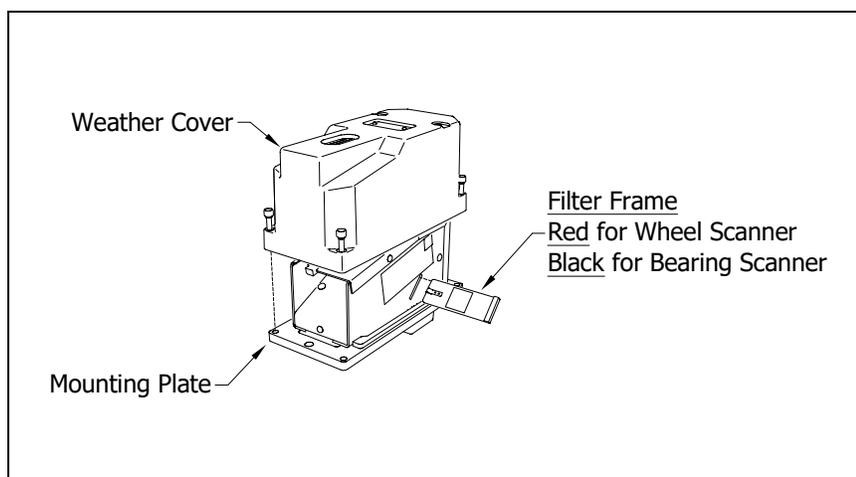
The SmartScanNG<sup>2</sup> system will now calibrate itself. **Follow along on your computer screen until you see "Auto-Calibration Disengaged."** This message is an indication that the system is done with the calibration procedure. To abort the process, press **[Esc]** on your computer or remove the heat source from the wheel scanner.

Before the shutters are opened, if you get a signal level greater than 200 millivolts, it usually means that there is noise on the scanner inputs, which most times is caused by an electrical problem with the scanner. If you cannot isolate and fix the cause of this problem, call STC for help.

```
                .
                .
                .
[F] - Auto-Calibration
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[J] - Update Menu
[K] - Maintenance Menu
[L] - Volume up (3)
[M] - Volume down (3)
[N] - Resistor Baseline Data
[O] - Radio Programming Menu
[P] - Scanner test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual gate test
[X] - Exit
```

Before the shutters are closed, if you don't get a calibrated temperature in the range 178°F to 182°F, it means that the scanner wasn't calibrated. If cleaning the optics doesn't solve your problem, replace the scanner cover-and-module assembly. If this doesn't solve your problem, call STC for help in fixing the problem.

- 14 When "Auto-Calibration Disengaged" is displayed on your computer, remove the calibrated heat source.
- 15 To return to the Main menu, type **X**.
- 16 To exit the serial interface and return the system to normal operation, type **X**.
- 17 Replace the black filter frame with the red one immediately following the successful completion of the auto-calibration function.



**\*\* Before continuing, be sure that the red filter frame is securely in place and that the four socket-head-cap screws on the weather cover are completely tight. \*\***

- 18 Store the calibrated heat source and its power cord in the wayside enclosure.

#### **NOTE:**

Upon completion of autocalibration, the system acquires the scanner resistor temperature baseline values. The process begins with a 20 minute wait period in which the resistors are allowed to cool down. The system counts down during this period, sounding a tone each minute. After the 20-minute cooldown period, the system opens and closes the shutters for a period of 8 minutes.

Covering the apertures of all four scanners during the baseline acquisition routine should result in a more accurate baseline measurement because the reference for the scanner is stable when covered. See **Appendix K** for a detailed explanation and instructions.



## Appendix E

### Lens Cleaning of Type III Scanners

---

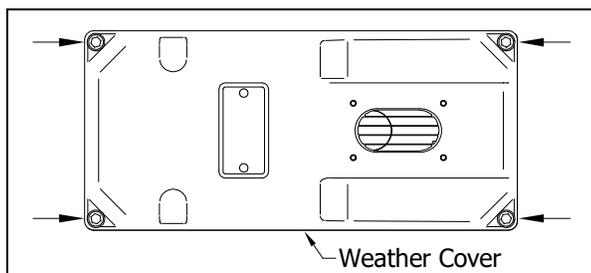
This appendix tells how to clean the optics in the scanners.

To clean the optics in the scanners:

- 1 Be sure that you have on hand a T-handle 1/4-inch hex-wrench.
- 2 Turn off all power to the scanners.

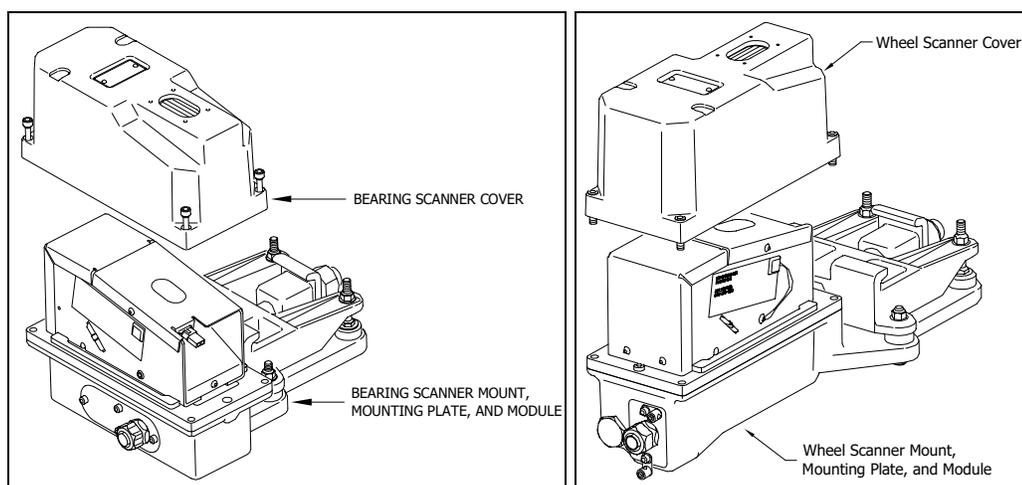
This requires turning off the DC power switch on the SmartScanNG<sup>2</sup> enclosure and unplugging the AC power cord on the bottom of the SmartScanNG<sup>2</sup> enclosure.

- 3 Using the T-handle 1/4-inch hex-wrench, loosen the four socket-head-cap screws that attach the weather cover to the mounting plate.



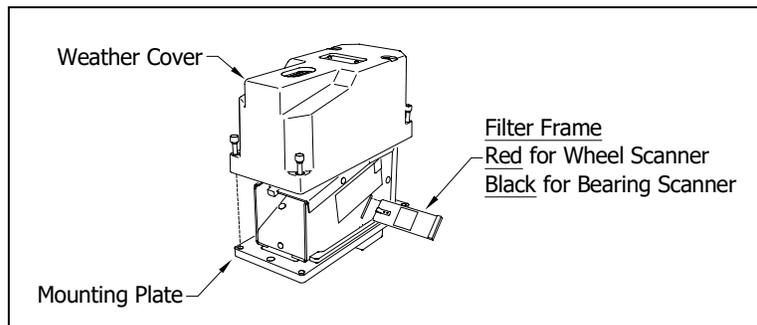
- 4 Remove the weather cover from its mounting plate.

Be careful not to damage the electrical connection for the cover heaters.



- 5 Disconnect the heater wiring plug.

On the side of the scanner module, you'll find a metal tab that protrudes about 1/4 inch outside the module.



- 6 Grasp the tab and pull the filter frame out of the scanner module.
- 7 Using the brush supplied with the tool kit, lightly dust any excess material from the filter frame glass.  
Be careful not to abrade or scratch the surface of the lens.
- 8 Apply a small amount of Vallen V8L cleaning solution (included in the tool kit) directly to the glass filter to loosen any remaining contamination.
- 9 Gently polish the reflective glass surface of the filter to remove any remaining contamination.  
Pay close attention to the area around the perimeter of the lens. It is important that the entire surface of the lens is clean.
- 10 Open the shutter by stroking one of the gating transducers with a piece of ferrous metal.
- 11 If the lens surface appears to have any dust on it, insert the brush from the tool kit through the baffle plates until it contacts the lens surface and apply a twisting motion to dislodge any accumulated dust.
- 12 Remove the brush and visually inspect the lens for cleanliness.
- 13 Reinstall the filter frame assembly properly - (The reflective surface will be facing the viewport opening of the scanner) Reconnect the heater wiring plug.
- 14 Re-connect the scanner cover heater.
- 15 If this is a **bearing scanner**:  
With the hole on top of the bearing scanner cover facing north or east, set the weather cover back onto its mounting plate. Using the T-handle 1/4-inch hex-wrench, uniformly tighten the four socket-head-cap screws.
- 16 If this is a **wheel scanner**:  
With the hole on top of the wheel scanner cover facing the center of the track, set the weather cover back onto its mounting plate. Using the T-handle 1/4-inch hex-wrench, uniformly tighten the four socket-head-cap screws.
- 17 Turn on power to the scanners.

# Appendix F

## Predictive Gate Scanning

---

This appendix describes predictive gate scanning of bearings.

### F.1 Overview

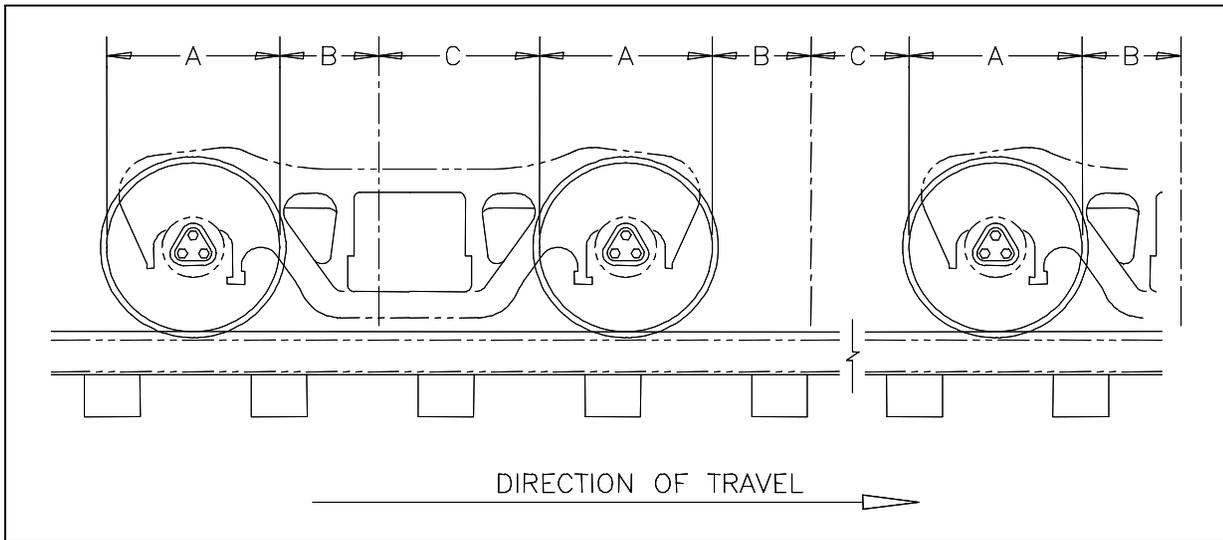
If a pyrometer is exposed to extreme infrared energy emission, the device itself can be driven into a saturated state. When this happens, it is blinded to subsequent changes in infrared energy emission. This blinded state can last up to 1-1/2 seconds.

Under certain circumstances, a pyrometer may be driven into saturation before the opening of the gate for a given axle. If the open-gate period was the only time during which pyrometer readings were sampled and processed, the system might miss an overheated bearing due to a device that was blinded before the opening of the gate. This can happen when a bearing is so overheated that it gives off infrared energy that can be seen by the pyrometer long before the bearing enters the pyrometer's field of view.

To compensate for this, the SmartScanNG<sup>2</sup> system includes special logic for processing heat seen by the pyrometers as they scan between the axle gates. The interval between axles has been divided into two parts.

The first part of this interval is the 16 inches (40.6 centimeters) that immediately precede the axle as it approaches the bearing scanners. This interval is treated as a "predictive gate" region in which the actual gate period (the time a bearing is physically in the pyrometer's field of view) is extended by 16 inches (40.6 centimeters). The remainder of the "between gate" interval forms the second part. Heat values read during this second interval are ignored.

The figure below depicts the three distinct scanning intervals (the in-gate period plus the two between-gate intervals).



The table below defines the intervals.

Interval	Description
A	The normal bearing scanning interval of about 24 inches (61 centimeters), depending on the transducer spacing.
B	A distance of about 16 inches (40.6 centimeters) before a given wheel.
C	The distance between wheels that doesn't fall within interval-B.

## F.2 Scanning Process

Interval-A is the normal bearing scanning interval. Interval-B is an extension of interval-A. The greatest value read in either of these two intervals is recorded as the temperature for the axle. This value is checked for alarm levels in the same manner that scanned bearing temperatures are normally handled.

For interval-A: Heat values read during interval-A are processed normally.

For interval-B: Heat values read during interval-B that do not meet or exceed the Absolute alarm threshold are ignored. Values that meet or exceed the Absolute alarm threshold are handled as follows:

- If the interval-A heat value meets or exceeds the Absolute alarm threshold, it is processed normally and the interval-B heat reading is ignored.
- If the interval-A heat value does not meet or exceed the Absolute alarm threshold, but interval-B heat value does, a Pyrometer Saturation alarm is flagged and the interval-B heat value is stored and reported for the alarmed axle.

For interval-C: Heat values read during interval-C are ignored.

The Very Slow Train alarm indicates that, at some point during train passage, four consecutive axles crossed the gating transducers at a speed of 7 mph (11.3 kph) or less. The firmware doesn't check for Pyrometer Saturation alarms if the train has been flagged with a Very Slow Train alarm.

### F.3 Reporting the Pyrometer Saturation Alarm

If a Pyrometer Saturation alarm is detected and assigned to an axle, a printed message will appear on Detail reports.

The figure below shows part of a Train Detail report with a Pyrometer Saturation alarm. The contents of your report will be different.

```

Southern Technologies Corporation
Next Generation Detector System
TRAIN DETAIL
=====
      .
      .
      .

      Rail      Wheel
Car Axle East  West East  West  ON  OFF PW1 PW2 Alarms
  1   1   58   30  98   102  35   0  16  17
      2   58   30  98   102  35   82 13 13
      3  219   30  98   102  35   85 13 13  East Rail Pyro Saturation Alarm
      4   58   30  98   102  35   839 13 13
      5   58   30  98   102  35   85 13 13
      6   58   30  98   102  35   85 13 13

  2   7   58   30  98   102  35   238 13 13
      8   58   30  98   102  34   85 13 13

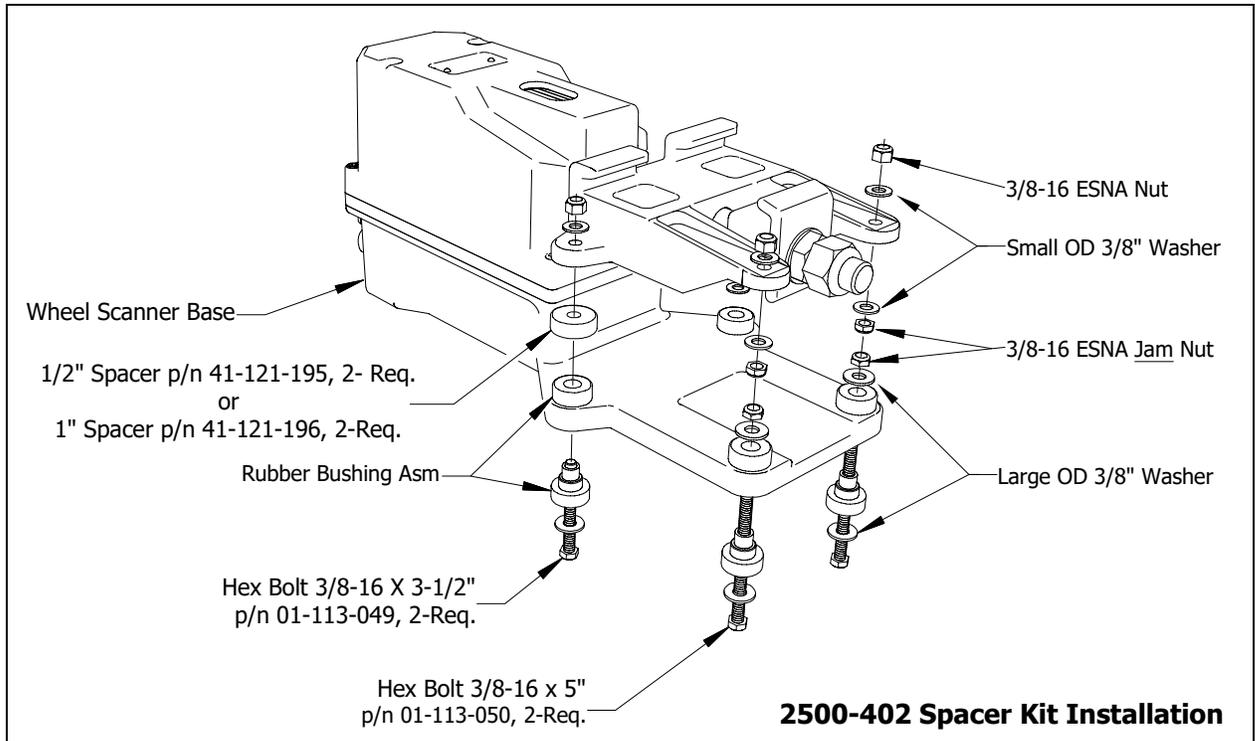
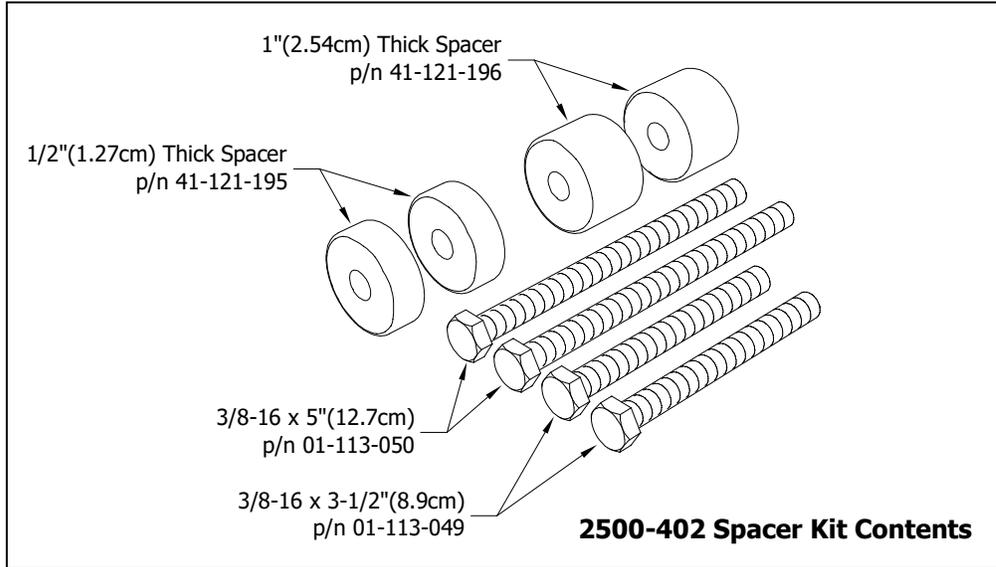
      .
      .
      .
  
```



# Appendix G

## 2500-402 Spacer Kit Installation

The 2500-402 Spacer Kit provides hardware necessary to lower the Type III Hotwheel Scanner assembly by either 1/2" or 1" for those applications that require additional rail clearance.





# Appendix H

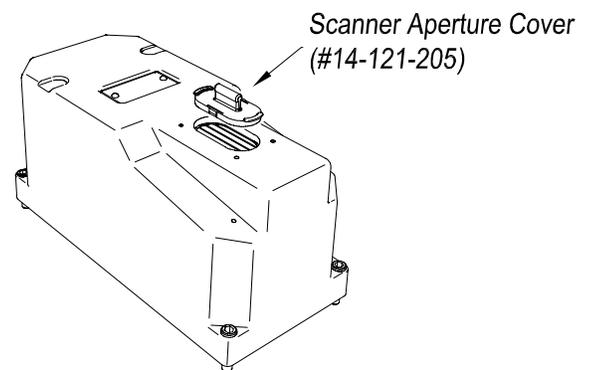
## Scanner Resistor Baseline Acquisition

---

Upon completion of autocalibration, the system will acquire the scanner resistor temperature baseline values. The process begins with a 20-minute wait period in which the resistors are allowed to cool down. The system counts down during this period, sounding a tone each minute. After the 20-minute cool-down period, the system opens and closes the shutters for a period of 8 minutes.

**NOTE:** For wheel scanners, it is imperative that the red filter frame is replaced immediately after autocalibration has disengaged and before resistor baseline acquisition begins.

The reason for establishing the baseline tables at the end of the Auto-Cal cycle is the assumption that the system is then at its peak operating efficiency. The system is freshly calibrated and the lenses are clean. With the baselines established, the system can then recognize and compensate for slight degradations of the lens caused by moisture or dirt accumulation on the lens surface.



### H.1 Cover the Scanners

Covering the openings of all four scanners during the baseline establishment routine should result in a more accurate baseline measurement because the reference for the scanner is stable when covered. If you initiate a baseline measurement on a partly sunny day or partly cloudy night, the odds are that for one part of the test you will see clear sky, and for another part of the test you may well be looking at a cloud. Clouds are warmer than clear sky. When clear sky is the reference for the scanner, the recorded heat values tend to be higher than when the scanner references off of a cloud. STC has observed as much as 40 degrees difference. This condition can result in an unusable baseline. If you block the scanner's view of the sky completely, you wind up with a very stable reference and a resulting stable baseline.

Depicted above, the Scanner Aperture Cover (#14-121-205) is designed specifically to use during the baseline resistor test. If these covers are unavailable, a piece of corrugated cardboard or a small piece of 1/4 inch plywood about 6 inches square placed over the scanner openings does a pretty good job of providing a stable reference and it will simply blow away if a train slips up on you. A 6 inch 2x4 block laid on the opening will work on windy days, and will probably vibrate off if a train catches you. This is a helpful hint for improving the performance of the baseline acquisition process, not a requirement.

**WARNING:** Extreme caution must be taken to avoid a situation where field personnel are trying to quickly clear 4 scanners in front of a train.

## H.2 Bungalow Speaker Announcements

During the resistor-cooling period, the system announces through the speaker the following. These announcements aren't broadcast over the radio.

- A beep sounds once per minute until two minutes before the resistor test.
- At two minutes until the test, "Scanner resistor test beginning in 2 minutes" is voiced.
- At one minute until the test, "Scanner resistor test beginning in 1 minute" is voiced.

After the resistor cooling period:

- As the test begins, "Testing" is voiced. During this time, the word PENDING appears in the Status column of the Resistor Data section.
- If the test was successful, "System working" is voiced. The word VALID appears in the Status column of the Resistor Data section, signifying that the baseline test applies to each passing train.
- If the test wasn't successful, "Scanner resistor test beginning in two-zero minutes" is voiced, meaning that the system will try once more after 20 minutes to acquire an accurate resistor heat profile. During this time, the word PENDING appears in the Status column of the Resistor Data section of the System Status Report. If the test fails a second time, the word INVALID appears in the same column. The system applies the interim integrity test to each passing train while either PENDING or INVALID appears.

## H.3 Processing Resistor Baseline Results

Here are two rules the system uses:

- If any of the temperatures in the baseline table are less than or equal to 40°F, we consider the baseline to be invalid.
- The next sequential temperature has to increase or be no less than 6°F cooler than the last temperature. That is, if a temperature is 100°F, for example, the next temperature has to be greater than 100, equal to 100, but not less than 94.

If the system gets an invalid baseline, it will automatically try a second time. If it gets interrupted, it will also try a second time. The 300° F temperatures that show up in the baselines occasionally are more a reflection of the duty cycle controller for the shutter resistor. Some controllers cause the shutter resistors to heat up more quickly and sometimes overshoot the desired set point, whereas a controller that is operating at its optimum efficiency will ramp up to a value slightly below 300° F. Temperatures above 300° F do not result in an invalid baseline.

Look at the Resistor Data section of the System Status Report. INVALID indicates that the system has tried twice and could not acquire valid resistor data. If any of the baseline results for a scanner show INVALID, the only way to capture a new baseline is to run the Auto Cal process again. If the word PENDING appears in the Status column, the system is waiting for the resistors to cool before acquiring resistor data or for the battery to charge to 13 volts. INVALID indicates that the system has tried twice and could not acquire valid resistor data. In either case, the system will apply the interim integrity test to passing trains, which doesn't require resistor baseline data.

## Examples: Resistor Baseline Results

Resistor Data																		
VOLTS	AMB	DATE	TIME	STATUS	30	40	50	60	70	80	90	100	110	120	130			
140	160	180	200	220	240	260	280	300	320	340	360	380	400	420	440	460	480	
RAIL 1																		
15.3	-008	01/11/12	12:53	INVALID	300	300	300	300	300	300	300	300	300	300	300	300	300	
					300	300	300	300	300	300	300	300	300	300	300	300	300	
RAIL 2																		
15.3	-008	01/11/12	12:53	INVALID	300	300	300	300	300	300	300	300	300	300	300	300	300	
					300	300	300	300	300	300	300	300	300	300	300	300	300	
WHEEL 1																		
15.3	-009	01/11/12	12:26	VALID	155	152	155	152	150	150	149	149	148	147	147			
					148	149	150	149	150	151	150	151	151	151	151	150	151	152
WHEEL 2																		
15.3	-009	01/11/12	12:26	VALID	160	156	157	162	157	157	155	155	156	155	156			
					154	156	157	158	157	158	158	160	160	158	158	160	160	158

Resistor Data																		
VOLTS	AMB	DATE	TIME	STATUS	30	40	50	60	70	80	90	100	110	120	130			
140	160	180	200	220	240	260	280	300	320	340	360	380	400	420	440	460	480	
RAIL 1																		
13.4	057	09/30/11	11:59	INVALID	285	285	289	294	289	288	289	288	287	287	288			
					287	289	290	290	272	270	277	294	297	297	297	298	300	300
RAIL 2																		
13.4	055	09/30/11	10:50	VALID	272	271	274	280	277	275	270	264	262	264	271			
					277	278	282	284	285	287	283	280	272	271	270	269	268	269
WHEEL 1																		
13.4	055	09/30/11	10:50	VALID	145	148	154	155	156	157	156	156	157	160	158			
					160	160	162	161	164	162	164	168	163	158	163	160	167	168
WHEEL 2																		
13.4	055	09/30/11	10:50	VALID	128	132	137	137	138	137	141	138	138	141	140			
					141	142	142	144	144	145	148	147	147	148	147	148	149	150

Resistor Data																		
VOLTS	AMB	DATE	TIME	STATUS	30	40	50	60	70	80	90	100	110	120	130			
140	160	180	200	220	240	260	280	300	320	340	360	380	400	420	440	460	480	
RAIL 1																		
13.5	061	05/25/11	15:25	VALID	242	251	258	263	264	265	267	268	268	270	271			
					272	275	277	278	280	281	283	284	284	285	287	287	288	287
RAIL 2																		
13.5	061	05/25/11	15:25	VALID	262	268	274	282	282	282	282	283	284	285	285			
					288	289	291	294	296	297	297	298	300	300	300	300	300	300
WHEEL 1																		
13.7	063	06/27/11	14:09	INVALID	112	116	117	117	116	116	114	114	112	112	111			
					110	112	111	112	114	110	104	100	96	94	85	87	76	69
WHEEL 2																		
13.7	063	06/27/11	14:09	INVALID	135	2	2	2	2	2	148	2	2	2	2			
					2	2	2	2	2	2	2	2	2	2	2	2	2	2



# Appendix I Communications Ports

COM1  
COM2  
COM3/Velocity  
COM4  
COM5  
COM6  
RS485  
Molex Conn  
Ethernet

**NOTE:** The factory default setting for serial ports COM1-COM6 is 19,200 baud. The default setting for the RS485 port is 9,600 baud.

**COM1** – To use the serial interface, connect a local computer (DTE) using a null-modem cable and set the communications software to use full-duplex. **This is the standard local access port.**

**COM2** - Currently unused.

**COM3** – Used to communicate with the Velocity Modem board's instruction set and database. COM3 is connected to Port 2 on the Velocity Modem board.

**COM4** - This port is allocated specifically for communications with a MeteorComm radio for the purpose of transmitting train data to a central office server.

**COM5** – At systems with AEI, attach a null-modem cable from the AEI (DTE) Interface Module to COM5 (DTE) of the Controller module.

**COM6** - Used to load a software update package onto the NG2.

**RS485** – Used to communicate with auxiliary equipment such as wind monitor.

**ETHERNET** – To establish an Ethernet connection, you need a network interface card (NIC) in your computer and a Category 5 (CAT5) 8-wire network cable for basic 10/100 functionality.

DCE (Data Circuit-Terminating Equipment) Modem				Connecting Cable	DTE (Data Terminal Equipment) Computer			Connecting Cable	DTE (Data Terminal Equipment) Computer		
Pins on the Modem		Name and Abbreviation		Inside the Straight-Through Connecting Cable	Abbr.	Pins on the Computer		*Inside the Null-Modem Connecting Cable	Abbr	Pins on the Computer	
Female DB25	DB9					Male DB25	DB9			Male DB25	DB9
1	-	Frame Ground (Chassis)	FG	————	FG	1	-	————	FG	1	-
2	3	Transmitted Data (TD)	TxD	←————	TxD	2	3	↔	TxD	2	3
3	2	Received Data (RD)	RxD	————→	RxD	3	2	↔	RxD	3	2
4	7	Request to Send	RTS	←————	RTS	4	7	↔	RTS	4	7
5	8	Clear to Send	CTS	————→	CTS	5	8	↔	CTS	5	8
6	6	Data Set Ready	DSR	————→	DSR	6	6	↔	DSR	6	6
7	5	Signal Ground	SG	————	SG	7	5	····	SG	7	5
8	1	Data Carrier Detect	DCD or CD	————→	DCD or CD	8	1	····	DCD or CD	8	1
20	4	Data Terminal Ready	DTR	←————	DTR	20	4	↔	DTR	20	4
22	9	Ring Indicator	RI	————	RI	22	9	————	RI	22	9



## Appendix J SunShot Mediation Approaches

The SmartscanNG<sup>2</sup> provides a three-tiered approach to reducing false stops caused by sunshots. These tiers are:

- The Sunshot Window Calculation
- The Pre-Gate Heat Evaluation
- The Dynamic Scan Window (DSW)

### **Sunshot Window Calculation**

Site-specific calculation of the days and times when a site could be vulnerable to sunshots.

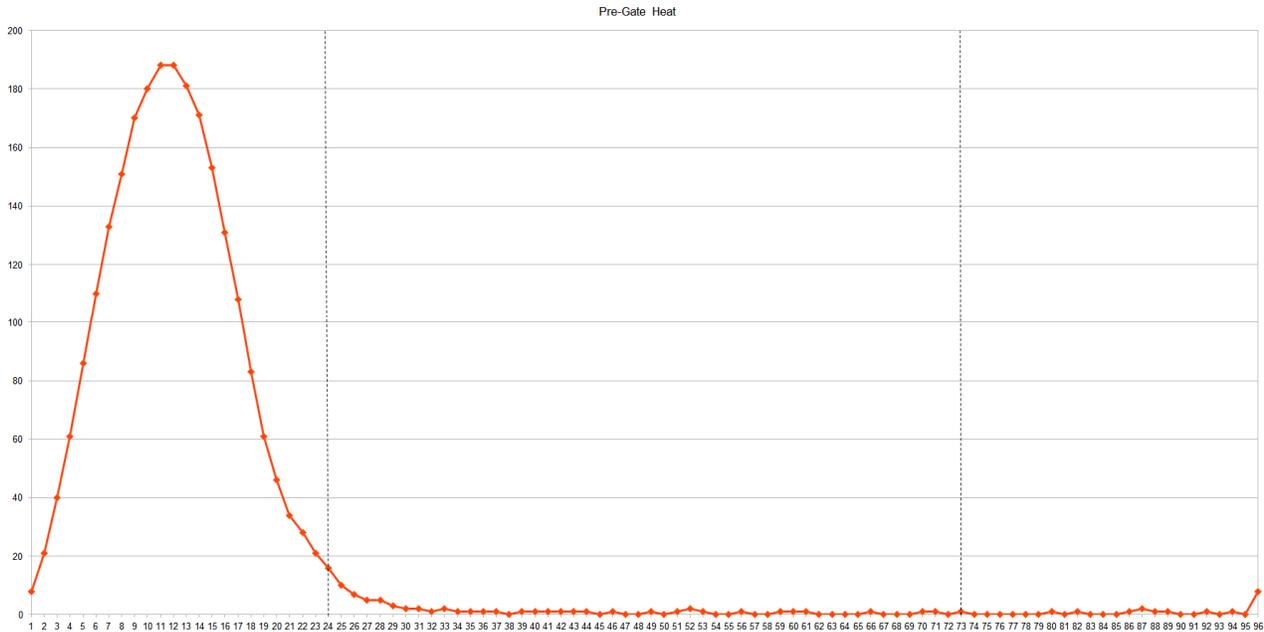
The SmartscanNG<sup>2</sup> can calculate the days and times during which a detector is vulnerable to sunshots. This requires entering a detector's GPS coordinates and the compass orientation of its bearing scanners as setup parameters in the detector. When the Sunshot Override option is then enabled, the detector calculates the specific days and time(s) of day during which the bearing scanners could be exposed directly to the sun. With this done, the detector's sunshot filtering functions will activate only during the calculated sunshot windows – the specific, calculated, days and time(s) of day.

When a train crosses the detector site during the calculated sunshot window, the SmartScanNG<sup>2</sup> evaluates bearing heat profiles differently. It anticipates that high heat seen very early, or very late, in the profile of a given bearing indicates exposure of a scanner pyrometer to the sun rather than an elevated bearing temperature.

### **Pre-Gate Heat Evaluation Process** (Pyrometer Saturation vs. Sunshot)

Excessive pre-gate heat is handled differently during a detector's active sunshot window.

In rare instances, it is possible to blind a scanner's pyrometer by exposing it to excessive heat immediately before the bearing enters the scanning gate. This happens only in cases of super-heated bearings (e.g. hot enough to heat up the side frame of a truck). When this occurs, the detector flags the bearing with a Pyro Saturation alarm. A sun-shot can replicate the characteristics of such an event. Figure 1 illustrates this with an actual sunshot event.



**Figure 1: Example Pre-Gate Sunshot Event**

The chart in Figure 1 shows the full 96 samples recorded by the NG<sup>2</sup> for a bearing. In this depiction, sample #24 represents the point at which the bearing entered the scan gate, and sample #72 represents the point at which the bearing exited the scan gate. Samples #1 through #23 represent the pre-gate region of the scan. In this example:

- 1) Alarm level heat was detected in the pre-gate region and,
- 2) No heat (above ambient) was recorded while the bearing was in the scan gate.

As such, this bearing would have been flagged with a Pyro Saturation Hot Journal alarm.

However, where the Sunshot Override option is enabled AND a train passes during the site's calculated sunshot window, the detector interprets this event as a sunshot, **not** as a Pyro Saturation alarm, and flags the bearing with a sunshot-detected warning. This information is available for processing by back-office applications and is displayed in reports retrieved from the detector.

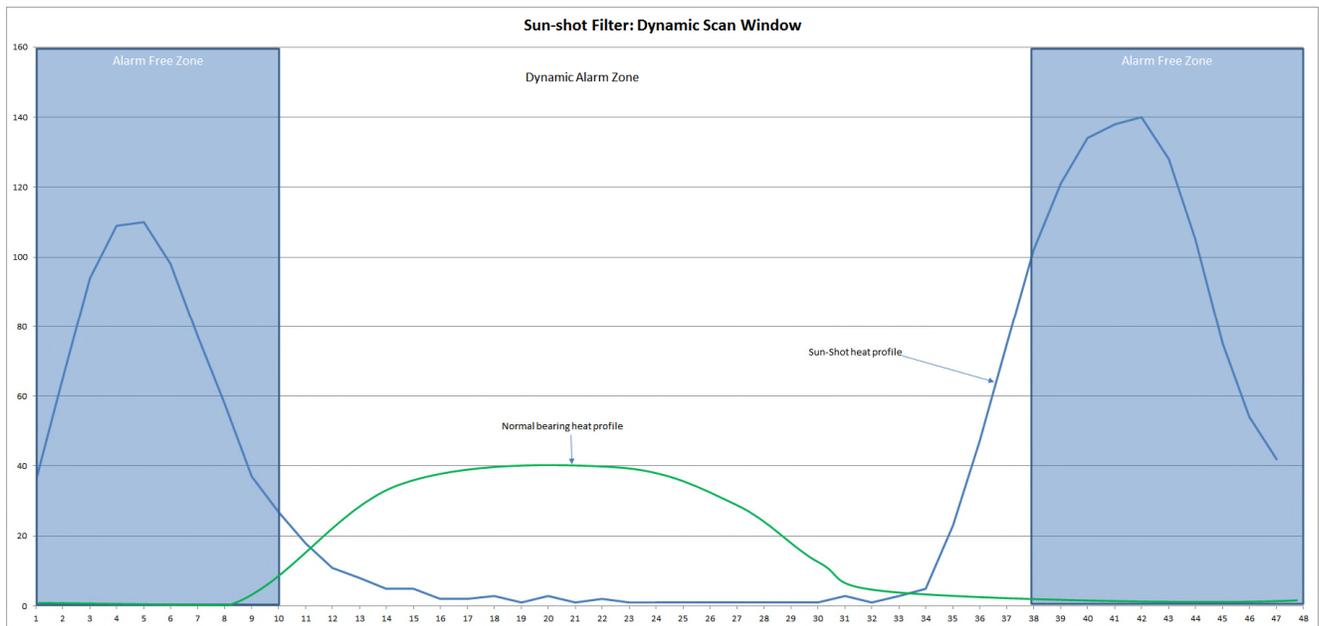
### **Dynamic Scan Window (DSW)**

Provides for filtering of the leading and trailing heat profile samples to prevent flagging sun-shot events as hot-bearing alarms.

When sun-shot events occur, the scanner's pyrometer receives direct exposure to the sun as a bearing either enters or exits the scan gate. The Dynamic Scan Window feature provides for filtering of a bearing's first few and/or last few recorded heat samples during the process of evaluating it for alarms. In this way, only the heat emitted by the bearing will be considered when assessing its profile. The curve of a typical heat profile shows a peak within the center third of the recorded samples. Thus, filtering the first and last few samples presents little risk for mislabeling an actual overheated bearing as a sunshot.

The SmartscanNG<sup>2</sup> allows the user to choose the number of heat profile samples to filter at the beginning and end of the gate period independently. The Dynamic Scan Window function is active only when 1) the Sunshot Override option is enabled, and 2) a train is scanned during a detector's active sunshot window. When the Dynamic Scan Window function is active, it flags bearings having alarm-level heat detected in the filtered regions with a sunshot-detected warning. This information is available for processing by back-office applications and displayed in reports retrieved from the detector.

Figure 2 illustrates the Dynamic Scan Window. The blue regions represent a detector filtering the first ten and last ten samples for alarm processing purposes. The blue line represents heats detected during an actual sunshot event. For reference, the superimposed green line depicts a heat profile recorded for a typical bearing (it is an actual profile).



**Figure 2: Depiction of Dynamic Scan Window with normal bearing heat profile superimposed**

## Configuring The Sunshot Filter Options

The options used to configure the sunshot functions are on the Sunshot Menu.

Main Menu > Setup Menu > Equipment Settings > Equipment Settings (Advanced) > Sunshot Menu

```
Sunshot Menu
-----
[A] - Sunshot Override ..... Disabled
[B] - Bearing Scanner Orientation ..... 0 degrees
[C] - Latitude ..... 35.0456
[D] - Longitude ..... -85.3097
[E] - Print Sunshot Season
[X] - Exit
```

Figure 3: Sunshot options configuration menu

**NOTE:** The values for Bearing Scanner Orientation, Latitude and Longitude should be entered **before** setting Sunshot Override to “Enabled”.

### Sunshot Override

Set this option to “Enabled” to activate the Sunshot filtering functions. Once set to “Enabled”, exit the Sunshot Menu and the Equipment Settings (Advanced) menu and the Equipment Settings (by pressing X three times). At this point the detector will ask you to confirm the configuration changes made by typing the word, “setup”. At this point, the NG<sup>2</sup> stores the change and starts calculating the site's sunshot season(s) using the values stored for the Bearing Scanner Orientation, Latitude, and Longitude options.

### Bearing Scanner Orientation

Set this parameter to the compass orientation, in degrees, at which the site's bearing scanners point. For instance, for the scanner represented in Figure 4 (below), the Bearing Scanner Orientation would be set to 80 degrees. Take care when determining the compass direction of your bearing scanners. This parameter is important and must be as accurate as possible. If you are using a compass at the site, be aware that the rails can influence the compass's accuracy. You can also use online mapping tools like Google Earth's ruler to measure the direction of the track.

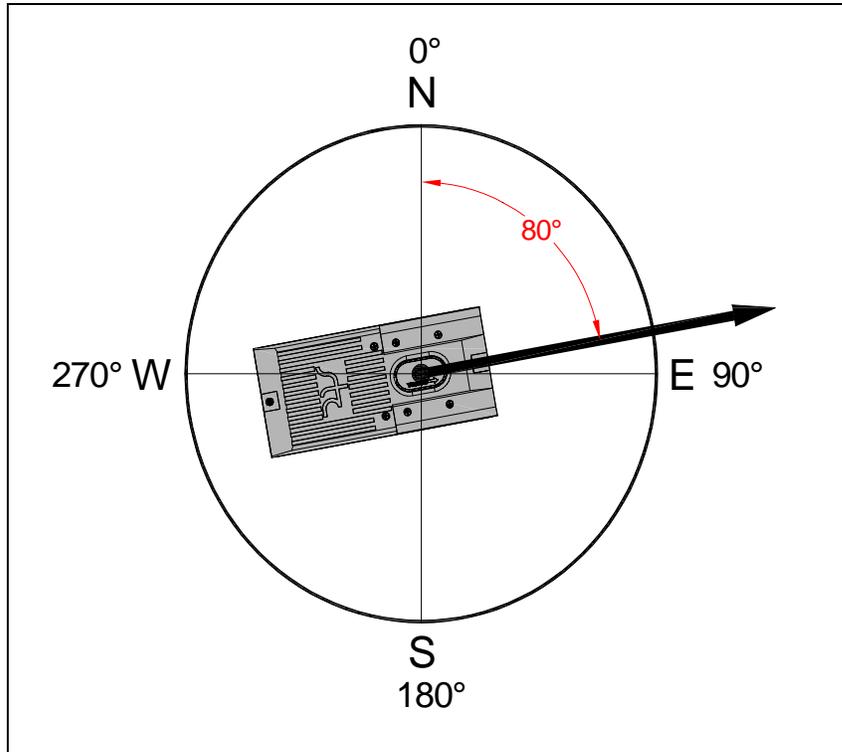


Figure 4: Scanner orientation example

### Latitude

For this parameter, enter the latitude of the detector location.

### Longitude

For this parameter, enter the longitude of the detector location.

The Dynamic Scan Window (DSW) parameters are new additions to the Sunshot menu. These options are hidden by default because they should be modified by advanced users only and only after careful consideration. They can be revealed by pressing Shift+1 (!) when the Sunshot menu is displayed. An example of the Sunshot Menu, with the DSW related parameters (and others) displayed, is shown below.

```
Sunshot Menu
-----
[A] - Sunshot Override ..... Disabled
[B] - Bearing Scanner Orientation ..... 0 degrees
[C] - Latitude ..... 35.0456
[D] - Longitude ..... -85.3097
[E] - Print Sunshot Season
[F] - Print Today's Window
[G] - Dynamic Scan Window Start Sample ..... 10
[H] - Dynamic Scan Window End Sample ..... 38
[X] - Exit
```

**Figure 5: Sunshot options configuration menu – with Dynamic Scan Window options displayed.**

The Dynamic Scan Window Start Sample and Dynamic Scan Window End Sample parameters narrow the window in which the detector looks for alarm-level temperature when the sunshot window is in effect. The standard/default window is from sample 0 to sample 48. This comprises the 24 inches between the two transducers (two samples are taken per inch of travel). In some applications, a tighter restriction is required (e.g. a nearly direct East/West track alignment and routine passage of open spline cars). In such cases, reducing the scan window by a few inches on either end of the scanning gate can filter most extraneous exposures of the scanner pyrometers to the sun – preventing false stops due to sunshots.

**Dynamic Scan Window Start Sample**

This option specifies the sample number on which the firmware begins evaluating bearing heat profiles for alarms. For instance, with the Window Start Sample set to 10, the firmware ignores the first ten samples when evaluating a heat profile for alarms (hot journal, differential, carside).

**Dynamic Scan Window End Sample**

This option specifies the sample number on which the firmware stops evaluating bearing heat profiles for alarms. For instance, with the Window End Sample set to 38, the firmware ignores the last ten samples when evaluating a heat profile for alarms (hot journal, differential, carside).

**Print Sunshot Season**

This option displays the days and times during which a detector could experience sunshot events. The Bearing Scanner Orientation, Latitude, and Longitude values entered for the detector determine the time period(s) during which it could be susceptible to sunshots. For the NG<sup>2</sup> to return accurate results, the Sunshot Override option must previously have been enabled and the NG<sup>2</sup> must have had time to perform its calculations.

**Print Today's Window**

This option provides a snapshot, for the current day, of when a detector could experience sunshot events. The Bearing Scanner Orientation, Latitude, and Longitude values entered for the detector determine the time period(s) during which it could be susceptible to sunshots. For the NG<sup>2</sup> to return accurate results, the Sunshot Override option must previously have been enabled and the NG<sup>2</sup> must have had time to perform its calculations.



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