

Operator's Guide for CP Railway

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Because products evolve and system configurations change, this manual may not be an exact representation of the products and systems that you are using.

Software Version at the time of this publication CP_00-00 2023-04-13

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WARNING!

Contact with electrically active parts could result in sparks, burns, and electric shock. Because of this, you should avoid all electrical hazards when installing, wiring, operating, and maintaining the SmartScanNG² system. Failure to do so could result in damage to the equipment or severe injury to you.

NOTICE:

If equipped with an AEI subsystem, the user is required to obtain a Part 90 site license from the FCC to operate in the United States. See product label for the FCC ID number. Access the FCC Web site at www.fcc.gov/Forms/Form601/601.html for additional information concerning licensing requirements.

Users in all countries should check with the appropriate local authorities for licensing requirements.

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fax number: 423-499-0045 telephone number: 423-892-3029 This section lists the headings of this guide in sequential order with their page references.

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This section summarizes the purpose of this guide, describes the SmartScanNG² system, tells how to comment on this guide, and tells how to order more copies of this guide. It also covers the cautions and disclaimers of which the customer should be aware.

1.1 Purpose of This Guide

The technical staff at Southern Technologies Corporation (STC) created the SmartScanNG² system. This guide describes that system.

The SmartScanNG² system monitors moving trains and reports certain conditions detected on these trains. Parts of the system, like the bearing scanners, are installed on the tracks. Other parts of the system, like the controller module, are installed near the tracks. Most nontrackside components are factory-installed inside a wayside enclosure (aka bungalow). Therefore, the installation of these already installed components isn't covered in this guide.

The SmartScanNG² system is modular and firmware-driven. Hardware and firmware can be changed to meet the unique needs of a given railroad. Thus, some of the components that make up a SmartScanNG² system differ from railroad to railroad.

This guide is for those who purchase, install, maintain, troubleshoot, manage, or use the SmartScanNG² system.

1.2 SmartScanNG²

The SmartScanNG² system is a full-featured detection and reporting system. It monitors moving trains, providing real-time detection of:

- Overheated bearings
- Overheated wheels, when wheel scanners are installed and enabled
- Dragging equipment, when dragging-equipment detectors are installed and enabled
- Shifted loads, when wide-load detectors are installed and enabled
- Oversized loads, when high-load detectors are installed and enabled
- Automatic Equipment Identification (AEI) tags, when AEI hardware and firmware are installed and enabled
- Direction of the train
- Exit speed of the train

The SmartScanNG² system runs well in the harsh environments found along right of ways. It runs under the most adverse weather conditions, functioning over a temperature range of -40°F to +160°F (-40°C to +71°C). It runs in high-vibration situations. It runs unattended, carrying out all tasks without human intervention.

The SmartScanNG² system monitors trains traveling from 7 to 90 mph (11.3 to 145 kph). It monitors trains heading in either direction on the track.

When the SmartScanNG² system detects a defect, it informs the crew of the affected train via a voice transmission over an assigned radio channel. The voice is computer-generated from previously digitized human speech. It tells the crew the milepost of the reporting SmartScanNG² system, a warning that a defect has been detected, and other defect-related information. When no defect is detected, the voice tells the crew that the train was scanned and found free of defects.

There are three types of messages. Real-time messages are announced as the train passes over the site. Post-train messages are announced after the train has left the site, and all the recorded train data has been processed by the SmartScanNG² system. When enabled, there are also arrival messages. Arrival messages are announced as the train enters the site. The content and use of these three message types are railroad-specific.

The results of train scans are also stored for later use. With this stored data, the system can create formatted reports. To get them at the site, you need a computer. With a modem and a computer, you can retrieve them remotely.

1.3 General Specifications - SmartScanNG²

Maximum Train Length	Successfully scanned computer-simulated trains with axle counts greater than 4000 axles.
Input Voltage - DC	Controller Module and Chassis: 10 to 30 VDC. Maximum system current, including two bearing scanners and two wheel scanners, with train present and radio transmitting approximately 11.7 amps. Idle current 900mA.
Input Voltage - AC	100 – 130 Volts @ 15 Amps, 50-60Hz
Input Voltage Protection	Circuit Breaker, Self-Restoring Fuses, Metal Oxide Varistors, Reverse Polarity Protected
Processors	Two Embedded Processor Modules, each with the following features: Motorola ColdFire® Processor, 32-bit, 250MHz clock (125MHz bus), 64MB DDR2 RAM, 32MB non-volatile Flash, 16GB Micro SD. Non-volatile time/date, system configuration, and train storage.
Serial Communications Ports	Up to six RS-232 ports are available, depending on internal options, and one RS-485 port — all with standard male D-Sub 9 connectors.
User Accessible Inputs	2 Bearing Scanner, 2 Wheel Scanner, 2 Wheel Gating Transducer, 2 Wheel Advanced Transducer, 8 Opto-Isolated Digital, 1 Precision Ambient Temperature Probe, 1 Train Presence Detection - Internal 2-Wire Audio Overlay Track Circuit
Network	One 10/100 Mbps Ethernet port with a standard RJ45 connector for networking capabilities. One RJ45 connector for access to the optional internal Velocity Module.
Voice Communications	Internal VHF Radio Transceiver: Ritron DTX-160 - 8 channels, 6 watts, narrowband, 134MHz to 176MHz. Additionally equipped with a radio interface for customer-specified analog or NXDN™ digital mobile radio
Dual-tone Multi-frequency Decoder	DTMF decoder recognizes all standard digits — 0 through 9, #, *, A, B, C, D. (Reception of a customer-specified sequence of digits triggers a rebroadcast of the last voice announcement.)
Secure Wireless Access	The NGX supports wireless standards IEEE 802.11 b/g/n with 2.4GHz RF band power amplifier. Secure data communications with 128-bit WEP, WPA- PSK (TKIP), WPA2-PSK Authentication. This feature can be enabled/disabled from the keypad.
Operating Temperature	-40°C to +71°C, Fanless Operation, Industrial Temperature Range
Size	15.5"W x 22.0"H x 4.5"D
Weight	31 lbs.
Finish	White powder coat over stainless steel.
Manufacturer	Southern Technologies Corporation, Chattanooga, Tennessee

1.4 Cautions

Contact with electrically active parts could result in sparks, burns, and electric shock. Because of this, you should avoid all electrical hazards when installing, wiring, operating, and maintaining the SmartScanNG² system. Failure to do so could result in damage to the equipment or serious injury to you.

In operation, batteries generate and release flammable hydrogen gas, which, if ignited by a burning cigarette, naked flame, or spark, may cause a battery explosion with a dispersion of casing fragments and corrosive liquid electrolytes. So, carefully follow the manufacturer's instructions. Keep all sources of gas ignition away from the batteries and do <u>not</u> allow metallic articles to contact the negative and positive terminals of a battery at the same time.

1.5 Disclaimers

The correct use of this guide, the environmental conditions at the time of installation, the method of the installation itself, and the installation of customer-supplied components are beyond the control of STC. So too, are the correct use and maintenance of all or part of the SmartScan system. Therefore, the installer, user, and maintenance of all or part of the smartScan system. STC assumes no risk, liability, or responsibility for errors and omissions on the part of the installer, user, or maintainer.

1.6 How to Comment on This Guide

We want to hear from you. Tell us what you like or don't like about this guide. Send your comments to:

Southern Technologies Corporation Technical Publications Department 6145 Preservation Drive Chattanooga, Tennessee 37416-3638 USA

All comments become the sole property of STC, and none will be returned.

1.7 How to Order More Copies of This Guide

When placing an order for more copies of this guide, refer to the order number shown on the cover of this guide. To request pricing and delivery, call 423-892-3029, fax 423-499-0045, or send an email to email@southern-tech.com. Electronic copies of this guide are also available.

1.8 Standard Warranty

Systems manufactured by Southern Technologies Corporation carry a 14-month warranty from the date of shipment. Warranty is limited to repair or replacement, at the sole discretion of STC, of any goods found to be defective in either materials or workmanship during the 14-month period following shipment. Warranty does not apply to a product with signs of obvious abuse or a product that has been improperly installed.

STC warrants that goods represented by this warranty statement have been designed and manufactured with all reasonable care and attention to appropriate regulatory documents. STC makes no representation that the goods covered by this warranty are suitable for the application they are used for. The application of the goods is at the sole discretion of the purchaser.

The purchaser is responsible for the shipment of the defective product to STC. STC will pay the return shipping charges.

Products purchased from others but included in STC systems carry the original manufacturer's warranty, typically 12 months. Warranty claims for these products must be made directly to the original equipment manufacturer.

This section describes the Exception Alarms (aka defect alarms, aka train alarms) and how they are detected. Also covered are miscellaneous train scanning features.

2.1 System Activation

System activation is the process used to detect train presence and to prepare for train scanning. It is during the scanning process that the system checks for defects.

The SmartScanNG² system is equipped with one of two primary means of train arrival detection, which are the track circuit or advance transducers. In case of a failure in the primary detection method, the gating transducers act as a backup to detect train arrival. Once the system senses a train's presence, it enters scanning mode. In other words, the system has been activated. It then opens the scanner's shutters and disables their heaters. It then waits for further evidence of a train at the site in the form of gating transducer activity.

Once the system is active, it reads pulses from the two rail-mounted gating transducers, which are designated TO1 and TO2. On the rail nearest the wayside enclosure, these transducers are mounted near and to the north or east of the bearing scanners. **TO1** is the gating transducer closest to the bearing scanner. **TO2** is the one farthest from the bearing scanner.



The signals from these gating transducers indicate to the system that passing wheels are in view of the scanners. Furthermore, the speed of the train is determined by using the known distance between TO1 and TO2 versus the time required for a given wheel to pass over them.

Four axles must pass over the gating transducers for the system to consider the event a valid train. This prevents maintenance equipment from generating alarms and causing unwanted voice messages on the road channel.

2.2 System Deactivation

System deactivation is the process used to detect the moment that the train exits the site. This happens in one of two ways, which is dependent upon whether the track circuit or one of the transducers has activated the system.

If the track circuit activates the system, the system waits for the track-circuit signal to be absent for ten seconds before deactivating. Likewise, if a transducer activates the system, the system waits for ten seconds of inactivity from the gating transducers before deactivating.

2.3 Speed Calculation

The train's minimum, maximum, average, and exit speeds in miles per hour are shown on the reports. The system calculates the speed by knowing the distance between the two transducers versus the time that it takes a given wheel to pass over them. Calculated speeds over 99 mph (159 kph) are reported as 99 mph. If a train has fewer than eight axles, its speed is reported as 0 mph.

Trains traveling at less than 7 mph (11.3 kph) are considered "very slow." If a passing train drops below this speed threshold, the detection of Differential alarms, Pyrometer Saturation alarms, and Carside Slope alarms isn't performed. After the passage of these trains, the phrase "train too slow" is appended to the post-train message (when the Announce Slow Train option is enabled), and a diagnostic message is noted on the Train Detail and Exception Detail reports. Also, after the passage of these trains, axle count, exit speed, length of train, and the total number of cars aren't announced. This is true even when the Announce Axles option, Announce Speed option, Announce Train Length option, and Announce Number of Cars option are enabled.

The report fragment below, from the <u>header</u> section of a Train Detail report, shows the location of this message.

2.4 Train Direction

Train direction is based on whether TO1 or TO2 generated the first gating transducer pulse.

2.5 Transducer Pulse Processing

As a wheel enters the sensing range of a transducer, the transducer should respond with a positive-going pulse. The polarization of the two wires from the transducer determines if this pulse is positive or negative.

Here is a simple test that you can use to verify the correct polarization of the gating transducers. While watching the TO1 and TO2 LEDs on the display panel, have someone lay a metal wrench on one of the gating transducers. The corresponding LED should briefly light as the wrench touches the transducer. Then lift the wrench up. The LED shouldn't light as the wrench is lifted away. Repeat the test for the other transducer.



On the Interface board (in the Controller module), the transducer signals undergo RF filtering and amplification with a gain of 30. For validation, the amplified signals are fed into comparators, which create 5 VDC pulses lasting the period of time that the amplified signals remain above 620 millivolts. Processor-A receives these 5 VDC pulses through ports PA0 (TO1) and PA1 (TO2).



A firmware-controlled feature of the comparator circuit allows adjustment of the threshold voltage based on the speed of the train. Trains traveling less than 20 mph (32 kph) use the 620-millivolt threshold setting for maximum sensitivity. However, faster trains cause the transducers to generate a higher signal voltage, which allows the system to increase the threshold voltage. This improves the signal-to-noise ratio resulting in better signal validation.

Processor-A internally generates interrupts on the positive-going and negative-going edges of each transducer pulse coming from the comparator. The positive edge of each comparator pulse starts a timer. The timer stops with the detection of a negative-going edge. The width of each pulse is a determining factor of signal validity. Three milliseconds or greater is considered to be a valid signal. The firmware rejects any pulse width shorter than 3 milliseconds. Rejected pulses don't increment the transducer counters.

In normal operation, the gating transducers fire in sequence, first one, then the other. With 24-inch (61-centimeter) gating-transducer spacing, a wheel passes over both gating transducers before the next wheel passes over a gating transducer. Therefore, two consecutive pulses on the same gating transducer are not physically possible. However, in the unlikely event that a gating transducer is ever caused to fire by another source, such as electrical interference from a locomotive's traction motor, a spike counter for the gating transducer that misfired will be incremented by one. To increment the axle counter, one pulse from each gating transducer must occur in sequence.

2.6 Axle Scanning

The SmartScanNG² system begins sampling bearing and wheel (where wheel scanners are installed) temperatures upon detection of train arrival – when presence goes active or when the first wheel of the first vehicle crosses the leading gating transducer. The scanners are sampled continuously until the train exits the site. The signals from the gating transducers indicate to the system when each axle is in the scan path of the scanners. While an axle is between the two gating transducers, it is said to be "in the gate." The heat samples from the bearing and wheel scanners are allocated to a given axle for the time periods immediately preceding the axle entering the gate, while the axle travels through the gate, and immediately following the axle exiting the gate.

The SmartScanNG² system implements a Dynamic Scan Rate (DSR) for sampling of the temperatures detected by the scanners. The rate of scan (sampling) is adjusted, based upon the real-time speed of the train, so that the temperature of each bearing and wheel is sampled once for each half-inch of travel. For every axle, a total of 96 samples are collected from each scanner. Forty-eight samples are collected for the time that the axle is between the gating transducers (in the gate), twenty-four samples are collected from the time immediately before the axle entered the gate, and twenty-four samples are collected from the time immediately after the axle exited the gate.

2.7 Hot Bearing Alarms

The SmartScanNG² system checks for hot bearings during the scanning process.

There are four types of Hotbox alarms.

- **Absolute**. To trigger an Absolute alarm, a bearing temperature must exceed the limit that was established using the Absolute option. This alarm limit is an offset, <u>in</u> <u>degrees Fahrenheit</u>, above the ambient temperature.
- **Differential**. To trigger a Differential alarm, a bearing temperature must exceed the opposite side bearing temperature of the same axle by a differential amount established using the Differential option.
- **Pyrometer Saturation**. To trigger a Pyrometer Saturation alarm, an interaxle bearing temperature must exceed the limit that was established using the Absolute option. If an Absolute alarm or a Differential alarm has already been triggered for the axle, a Pyrometer Saturation alarm isn't generated.
- **Carside Slope**. To trigger a Carside Slope alarm, a bearing temperature must meet or exceed a calculated alarm level and a minimum heat value. The bearing temperature must also be at least twice the opposite bearing's temperature. If an Absolute alarm or a Differential alarm has already been triggered for the axle, a Carside Slope alarm isn't generated. The minimum heat value is established using the Carside Minimum option.

2.7.1 Bearing Scan Process

Bearing scanners are mounted in the center of the crib of two ties spaced at least 14 inches (35.6 centimeters) apart. Both bearing scanners are mounted in the crib immediately ahead of the gating transducers (that is, in the crib immediately to the south or west of the gating transducers). They are mounted directly opposite each other, one on each rail of the track. The hole on the top of the scanner covers faces north or east.





The <u>Type II</u> bearing scanners are aligned to scan the bottom 3.5 inches (8.9 centimeters) of the bearing housing, about 7.25 inches (18.4 centimeters) from the gauge line.

The <u>Type III</u> bearing scanners are aligned to scan the bottom 3.5 inches (8.9 centimeters) of the bearing housing, about 7.25 inches (18.4 centimeters) from the gauge line.



Bearing temperatures are sampled for a short period before the gate opens, to support the detection of Pyrometer Saturation alarms, and while the gate is open.

2.7.2 Referencing System

Pyrometers measure rapid changes in infrared energy emitted from objects passing through their field of view. The rail-mounted scanners are aligned to take advantage of this characteristic.

When no axle is present between the gating transducers, the scanner typically sees only the undersides of the cars passing over the site. The undersides of the cars are at or near ambient temperature, thus establishing the reference from which the elevated temperatures of bearings are measured. The pyrometers normalize during this time, producing a zero-level signal.

Occasionally, the scanners are exposed to infrared emissions that are colder than the underside of the cars. Typically, this occurs in the gaps between cars when the scanners may reference on clear sky. This could present an erroneous reference if a bearing was scanned immediately following a sky shot, resulting in an abnormally high reading for the bearing. The pyrometers have internal circuitry to prevent the reference from shifting below the established zero reference.

When a bearing passes through the field of view of the scanner, a rapid change in temperature is presented to the internal lithium tantalite crystal. This causes the signal level from the pyrometer to increase proportionally to the amount of exposed infrared energy. When an axle is between the gating transducers, the pyrometer signal is sampled at every ½ inch (1.27 centimeters) of wheel movement for a total of 48 samples, and the maximum signal level is stored. This signal level measured in volts is converted to a digital value and expressed in degrees Fahrenheit above ambient temperature. This value is the basis for the alarm analysis done by the system.

2.7.3 Pyrometer Linearity

The output of the pyrometers is linear across most of the operating speed range of the system. However, the output of the pyrometers is nonlinear at either end of the operating speed range. To compensate for this nonlinear output, the firmware applies a correction factor to the sampled heat value. The correction factor applied to each bearing sample is based on the speed of the bearing (axle's ON time) as it passes through the gate and on the actual value read by the pyrometer. The correction factor is derived from a table that is keyed by the axle's ON time and heat value. Due to the fast nature of this lookup table, linearity compensation is done in real-time so that detected alarms reflect the heat value after the linearity step has been done.

2.8 Hotwheel Alarms

When used, wheel scanners are mounted in the center of the crib of two ties spaced at least 14 inches (35.6 centimeters) apart. Both wheel scanners are mounted in the crib between the two gating transducers. They are mounted directly opposite each other, one on each rail of the track. The hole on the top of the scanner covers faces the center of the track.



The Type II wheel scanners are aligned to scan about 4 inches (10 centimeters) above the rail.



The SmartScanNG² system checks for hotwheels during the scanning process. Scan timing is controlled the same as for the bearing scanners.

Wheel scanning alarms are limited to absolute only. To trigger a Hotwheel alarm, wheel scanners must be properly installed, hotwheel detection must be enabled, and a wheel temperature must exceed the limit that was established using the Hotwheel option on the Alarm Settings menu. This alarm limit is an offset, in degrees Fahrenheit, above the ambient temperature. Hotwheel detection is enabled using the Hotwheel option on the Equipment Settings menu. When enabled, the SmartScanNG² system detects and records every Hotwheel alarm that occurs. However, it only announces a maximum of four per train. For example, if a train contains nine Hotwheel alarms, the Train Detail report will show all nine, but only the first four will be announced.

2.9 Auxiliary Alarms

The SmartScanNG² system can support input from as many as four external alarm devices. Any device that provides an open relay contact upon alarm detection can be supported by the system. Auxiliary alarms supported by the SmartScanNG² system are:

- Dragging Equipment. To trigger a Dragging-Equipment alarm, a dragging-equipment detector must be properly installed, dragging-equipment detection must be enabled, and the SmartScanNG² system must sense an open relay contact from the dragging-equipment detector. Dragging-equipment detection is enabled using the Dragger option on the Equipment Settings menu. When enabled, the SmartScanNG² system detects and records every Dragging-Equipment alarm that occurs on a given train. However, it only announces the first two.
- High Load (oversized loads). To trigger a High-Load alarm, a high-load detector must be properly installed, high-load detection must be enabled, and the SmartScanNG² system must sense an open relay contact from the high-load detector. High-load detection is enabled using the High-Load option on the Equipment Settings menu.

When a high-load detector is configured for tripwire operation, the SmartScanNG² system only records one High-Load alarm, regardless of the high-load signal status. This is because you can only break a wire once.

When a high-load detector is configured for light-beam operation, the SmartScanNG² system records every High-Load alarm that occurs. This involves a caveat that the system won't flag High-Load alarms on consecutive axles. At least one unalarmed axle must separate the alarmed axles. Regardless of the number of detected High-Load alarms, it only announces a maximum of two.

The mode of operation (light beam or tripwire) isn't relevant when the SmartScanNG² system finds a Stuck High-Load Detector Pretrain alarm. When this occurs, the system flags the pretrain condition as an integrity failure, disables high-load scanning for the remainder of the train, and doesn't assign a high-load condition to any of the axles.

 Wide Load (shifted loads). To trigger a Wide-Load alarm, two wide-load detectors (one on each side of the track) must be properly installed, wide-load detection must be enabled, and the SmartScanNG² system must sense an open relay contact from either of the wide-load detectors. Wide-load detection is enabled using the Wide-Load option on the Equipment Settings menu.

When a wide-load detector is configured for tripwire operation, the SmartScanNG² system only records one Wide-Load alarm, regardless of the wide-load signal status. This is because you can only break a wire once.

When a wide-load detector is configured for light-beam operation, the SmartScanNG² system records every Wide-Load alarm that occurs. This involves a caveat that the system won't flag Wide-Load alarms on consecutive axles. At least one unalarmed axle must separate the alarmed axles. Regardless of the number of detected Wide-Load alarms, it only announces a maximum of two.

The mode of operation (light beam or tripwire) isn't relevant when the SmartScanNG² system finds a Stuck Wide-Load Detector Pretrain alarm. When this occurs, the system flags the pretrain condition as an integrity failure, disables wide-load scanning for the remainder of the train, and doesn't assign a wide-load condition to any of the axles.

 <u>Both</u> high-load detectors and wide-load detectors must be <u>either</u> trip-wire detectors or light-beam detectors. The selection of tripwire or light beam is done using the Clearance Type option on the Equipment Settings menu. Located on the front of the SmartScanNG² Controller Module is the Display Panel. Its status indicators and display module provide a snapshot of the overall system health. As a convenience, the Display Panel also provides a user interface to execute some frequently used system functions (i.e., Auto Cal, Radio Test, etc.).



SmartScanNG² Display Panel

3.1 LED Indicators

There are six LED status indicators located above the OLED display.

LED	Meaning when Lit	
TO1	Indicates wheel sensor TO1 is active.	
TO2	Indicates wheel sensor TO2 is active.	
COP-A	Indicates the status of Processor-A. If the CPU is running its program	
	correctly, the LED blinks on and off. If the program isn't operating as	
	expected, the LED is lit solid or isn't lit at all.	
COP-B	Indicates the status of Processor-B. If the CPU is running its program	
	correctly, the LED blinks on and off. If the program isn't operating as	
	expected, the LED is lit solid or isn't lit at all.	
PTT	Indicates the radio PTT is active.	
SYS WARN	Indicates that a system warning has been detected.	

3.2 Keypad & Display

The display assembly includes a 4-line, 20-character OLED display and a five-key membrane switch panel. If unused for five minutes, the display will time out to conserve power. Press any key to turn the display back on.

Keypad Switch	Function
FUNC	The function key toggles from home screen to the Main Menu. It also
	serves as "Back" key in the system submenus to return to the previous
	menu level.
▼ (Arrow Down)	Scroll down menu options.
▲ (Arrow Up)	Scroll up menu options.
SELECT	Selects the highlighted menu option.
RESET	Initiates system reset.

The home screen displays milepost, time, and temperature.

MP 1234.5	02:05:39 Temp: 72

If a system warning has been detected, the display will indicate "Check Sys. Health Menu" at the bottom of the screen.

Menu Navigation:

- Press the FUNC key to toggle from home screen to the Main Menu or to back out of submenus.
- Use the ▲UP and ▼DOWN keys to move the ► pointer next to the desired menu option.
- Press the SELECT key to choose the menu option. The "↓" symbol on the display screen indicates that there are more options available if you scroll down. Likewise, the "↑" symbol indicates more options are available if you scroll up.



3.3 System Functions

Several system functions can be performed from the display panel. Available options are:

- System Health Menu
- Radio Test
- Scanner Cal. Menu
- Network Menu
- Radio IO Status
- Volume Menu
- System IO Status
- Test Train
- Tag Reader Test

3.3.1 System Health Menu

The System Health Menu provides a snapshot of the system's general health. Each system health check displays a status of "GOOD" or "BAD" based on trending information derived from system alarms, integrity failures, and other monitored data. If a system warning has been flagged, the **SYS WARN** LED will be lit, and the "Check System Health" message will be displayed on the bottom text line of the home screen.

1. From the Main Menu, place the ▶ pointer next to Sys. Health Menu.

```
Main Menu
▶Sys. Health Menu
Radio Test
↓ Scanner Cal. Menu
```

2. Press the Select key. The status of the following system health checks are displayed:

NumTrains, LowMiscount, HighMiscount, AvgTemp0, AvgTemp1, AvgTemp2, AvgTemp3, ColdRail0, ColdRail1, ColdRail2, ColdRail3, Avg Miscount, and Batt. prcnt.

```
Sys. Health Menu

PReset Sys. Health

East Bearing Good

↓ West Bearing Good
```

If any of these system health checks indicate a "Bad" status, select that item to display more detailed information.

3. To reset system health, navigate to the Main Menu and place the ► pointer next to the Reset Sys. Health.

```
Sys. Health Menu

Preset Sys. Health

East Bearing Good

↓ west Bearing Good
```

4. Press the **Select** key. When prompted, select **Yes** to reset system warnings and zero all health check counts.

```
Are You Sure?
▶Yes
No
```

3.3.2 Radio Test

To perform a radio test, go to the Main Menu and select Radio Test

```
Main Menu

↑►Radio Test

Scanner Cal. Menu

↓ Network Menu
```

The Radio Test option is used to broadcast a short message through the speaker and through the radio. Using this option lets you verify that the speaker and radio are working properly.

At single-track sites, the text of the message is "Testing, CP Detector, milepost, (*milepost number*), testing, one, two, three, four, five, four, three, two, one, testing." At double-track sites, the text of the message is "Testing, CP Detector, milepost, (*milepost number*), track (*track designation*), testing, one, two, three, four, five, four, three, two, one, testing."

If the system isn't currently making any other voice announcements, it begins the Radio Test announcement. After the announcement finishes, the System Functions menu reappears.

If the system is currently making a voice announcement, the firmware displays the message "System Is Currently Making Voice Announcements! Try Again Later" and redisplays the System Functions menu.

While listening to the message, look at the PTT LED on the display panel.

The **PTT LED** should be lit. If this LED isn't lit, the system's ability to send a message to the radio might be inhibited by the Radio Inhibit option on the System Functions menu. If the radio is inhibited, the results of this check are invalid.

3.3.3 Scanner Cal. Menu

The SmartScanNG² system self-calibrates its pyrometer interface circuitry. You need only put a preheated calibrated heat source on a scanner and place the system in autocalibration mode. The system then scans all pyrometer inputs until the signal from the calibrated heat source is located. The necessary adjustments to the related interface circuitry are automatically made while the system monitors its own progress by analyzing changes in the heat signals.

From the Main Menu, select Auto Cal. This prompt appears.

```
Searching for heat...
Searching, 150 sec.
```

Once the procedure has been completed, autocalibration mode is disengaged, and the calibration results are displayed.

For a detailed description of the auto-calibration procedures, go to Appendix F Calibrating of Type II Scanners or Appendix G Calibrating of Type III Scanners.

3.3.4 Network Menu

From the Main Menu, select the Network Menu option to view/change network settings.

Available options are:

DHCP server, Wifi (on/off), IP Address, DHCP (on/off), TELNET port, HTTP port, and HTTPS port

3.3.5 Radio IO Status

From the Main Menu, select Radio IO Status to view the radio screen. This screen will display certain radio status information such as:

- "PTT Disabled" if Radio Inhibit is active
- "Holdoff Active" if holdoff is enabled
- "CD active" when the radio has detected an active carrier signal

Press the SELECT key to initiate Radio Test.

3.3.6 Volume Menu

From the Main Menu, select Volume Menu to view/change speaker volume.

```
Vol: 5 [||||| ]
Up/Down = change
Select = Radio test
Func = Back
```

There are ten volume settings (0 - 9) with level 9 being maximum volume. Press the \blacktriangle UP key to increase the volume level. Press the \checkmark DOWN key to decrease the volume level.

Pressing the SELECT key while in Volume Menu will initiate a radio test.

The Radio Test is used to broadcast a short message through the speaker and through the radio. Using this option lets you verify that the speaker volume is at a sufficient level. At single-track sites, the text of the message is "Testing, CP Detector, milepost, (milepost number), testing, one, two, three, four, five, four, three, two, one, testing." At double-track sites, the text of the message is "Testing, CP Detector, milepost, (milepost number), track (track designation), testing, one, two, three, four, five, four, five, four, three, two, one, testing."

Press the **FUNC** key to back out of the menu.

3.3.7 System IO Status Menu

The System IO Status Menu function is a useful tool for the diagnostic testing of inputs. From the Main Menu, select **System IO Status Menu** to monitor inputs.

```
System IO Status
DR, TO1
```

There are thirteen inputs monitored. Inputs appear on screen only while they are active. If no inputs are active, "None" appears. Available inputs are:

TO1, TO2, TC (presence), A1 (advance1), A2 (advance2), S1 –S4 (spare1 thru spare4), DR (dragger), HI (hi load), W1 (wide1), and W2 (wide2),

3.4.8 Test Train

In Test Train Mode, the system opens all the shutters and simulates transducer pulses. During this time, a person can check various aspects of the installed components. The train is marked as a test train. There won't be any voltage (simulated heat) applied to the scanner inputs.

This test gates 256 simulated axles.

From the Main Menu, select Test Train to initiate the test.

Main Menu	
Volume Menu	
System IO Status	
↓▶Test Train	

This prompt will appear:



During a test train, the TO1 & TO2 LEDs on the Display Panel will flash with each simulated axle.

3.4.9 Tag Reader Test

The Tag Reader Test function is a useful tool for verifying the operation of an attached AEI tag reader. From the Main Menu, select **Tag Reader Test**.

```
Tag Reader Test
2:00
Press Func to Exit
```

During the Tag Reader Test, the detector will sound a tone any time AEI tag passes through the AEI tag reader's RF field.

The serial interface allows **on-site** and **off-site** communication with the system. This interface is the only way to view reports and modify system parameters.

Most sites are equipped with either Ethernet or telephone service that provides remote communications capabilities. If not, you cannot communicate with the system **off-site**.

To use the interface locally, you need:

- A computer
- Communications software, which is installed on the computer
- A cable from the computer to a communications port on the Controller module

For remote access via network:

- A computer with communications software and internet connectivity
- An Ethernet connection at the SmartScanNG² controller

This section describes the serial interface for SmartScanNG² systems. It covers how to enter or change the system parameters. It is necessary to go through a complete setup the first time a SmartScanNG² system is installed at a new site. (If this is a double-track site, you also need to do this for the other SmartScanNG² system.) After that, the processor (in the Controller module) retains the setup information in flash memory. During a power outage, no setup information is lost.

4.1 Main Menu

1 If **on-site**, plug your computer into COM1..



- 2 Turn on your computer.
- **3** Be sure that your computer has installed communications software, that it is set to use full-duplex, <u>and</u> that the baud rate is set to 19,200.

Use your communications software to open a LOG file and capture the whole session to the file. When your session is complete, you may then view what you have done with an editor, print it with a printer, or store it for later retrieval.

4 On your computer, open a LOG file.

5 If off-site

- **a** From your computer, initiate a remote connection to the site modem.
- **b** Wait for the "connect" message from your modem.

To display the Main Menu:

6 Press [Esc].

If the system has been set up with security passwords, this prompt appears.

Enter password:

7 Type the appropriate password to display Main Menu.

System login with an administrative password allows all access to system menus.

System login with user password allows access to report menus and system functions menu but restricts access to the setup menu and security menu.

8 The Main Menu

```
SmartSCAN NG2, MP/KP:1234.5, Track:North
Subdivision: None
04/27/2023 07:41:34, 11.7V, 97°F
Main Menu - Comm
-----
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event Log
[K] - System Functions Menu
[L] - Replay Train
[M] - Security Menu
[X] - Exit
```

By selecting an option at the above prompt, you can:

- Produce a report.
- Replay an EOT announcement.
- Access the Setup menu. It is from the Setup menu that you can set system parameters.
- Access the System Functions menu.

If a train is at the site when the Main menu is generated, "*** Train Is Present ***" is displayed just above the menu header for the Main menu and for every other menu.

- **9** When done, close the LOG file.
- **10** To exit the serial interface and return the system to normal operation, type **X**.

4.2 Setup Menu

To display the Setup menu:

1 Be sure that the Main menu is displayed.

The Main menu looks like this.

```
SmartSCAN NG2, MP/KP:1234.5, Track:North
Subdivision: None
04/27/2023 07:41:34, 11.7V, 97°F
Main Menu - Comm
_____
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event Log
[K] - System Functions Menu
[L] - Replay Train
[M] - Security Menu
[X] - Exit
```

2 Select the **Setup** to view menu options.

If the Setup menu is password protected, this prompt appears.

```
You are not logged in with admin privileges Enter password:
```

You are given three chances to type the correct password. When you don't type the correct password in three tries, the system returns to the Main menu.

If the password is less than 20 characters long, press **[Enter]** after typing the last character. If the password is the full 20 characters in length, pressing **[Enter]** isn't necessary.

The entry of the password is **not** case-sensitive. For example, the password "abc#123" can be entered "ABC#123," "aBc#123," and so forth.

SmartSCAN NG2, MP/KP:1234.5, Track:North Subdivision: None 04/27/2023 07:45:42, 11.8V, 96°F Setup Menu _____ [A] - Date and Time [B] - MP/KP[C] - Subdivision None [D] - Track Designation North [E] - Track Direction N/S [F] - Alarm Settings [G] - Equipment Settings [H] - Messages Settings [I] - AEI Settings [J] - Units Of Measure Settings [K] - Load Default Setup Parameters [L] - COM Port Settings [M] - Network Settings [N] - Velocity Enabled [0] - GO Train Detect No [P] - Weather Settings [X] - Exit

To access any of the Setup menu options, type the letter that corresponds to the desired menu option.

At any prompt, a timeout mechanism is in place to prevent the system from remaining in that state indefinitely. When a timeout occurs, the serial interface regresses to the Main Menu or disconnects if it is a remote connection. At the Main menu, the timeout is set for ten minutes for telnet connection and 20 minutes for serial connection.

If a train is at the site when the Setup menu is generated, "*** Train Is Present ***" is displayed just above the menu header for the Setup menu.

3 To return to the Main menu, type **X**.

If you've made setup changes, when you exit the menu you will be prompted with:

"This will save the settings. Please type 'setup' to save settings. Type anything else to cancel."

Changes to the system parameters aren't reflected until after you have exited the Setup menu.

4.2.1 Date and Time

To set or change the date, the time, or both:

1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

2 Select the Date and Time submenu

A prompt like this appears.

```
Current Date: 04/27/2023
Enter New Date (mm/dd/yyyy):
```

Dates are in **mm/dd/yyyy** format, where **mm** is month, **dd** is day, and **yyyy** is year. Type the current date. You must include slashes. For days and months from 1 through 9 you must type leading zeros. Thus, for 8 July 2020, type **07/08/2020**.

If you want to keep the displayed date, press [Enter]. If you don't, type a new date.

3 Type a new date <u>or press [Enter]</u>.

A prompt like this appears.

```
Current time is: 22:47:34
Enter new time:
```

Time is in 24-hour **hh:mm:ss** format, where 8 a.m. is 08:00:00, noon is 12:00:00, 8 p.m. is 20:00:00, and midnight is 00:00:00. Thus, for 17 seconds past 3:42 p.m., type **15:42:17**. You must include colons. For hours, minutes, and seconds from 0 through 9, type leading zeros.

If you want to keep the displayed time, press **[Enter]**. If you don't, type a new time.
4 Type a new time <u>or press [Enter]</u>.

A prompt like this appears.

```
Current Time Zone: Eastern
Enter New Time Zone (E-Eastern,C-Central,M-Mountain,P-Pacific):
```

If you want to keep the displayed time zone, press **[Enter]**. If you don't, type the letter that corresponds to the time zone you want.

5 Type the letter that corresponds to the time zone you want or press [Enter].

A prompt like this appears, stating whether the daylight-saving-time adjustment is currently disabled or enabled. Daylight-saving time is the period during which clocks are set one hour ahead of local standard time.

Daylight Savings Time Enabled OK (Y/N)?

If disabled, all times throughout the year are in standard time. If enabled, all times between the second Sunday in March and the first Sunday in November are in daylight-saving time. All other times are in standard time. Any change takes effect immediately. Later, if enabled, at 2:00 a.m. on the second Sunday in March, the system will adjust the system's clock forward an hour to 3:00 a.m., and at 2:00 a.m. on the first Sunday in November, the system will adjust the system's clock backward to 1:00 a.m.

At this point, you can type **Y** (yes), type **N** (no), or press **[Enter]**. Pressing **[Enter]** has the same effect as typing **Y**. Typing **N** doesn't change the displayed time.

6 If you want to modify the adjustment, type **N**.

Typing the letter **N** toggles between disabled or enabled. A message like this appears, stating whether the daylight-saving-time adjustment is <u>now</u> disabled or enabled.

Daylight Savings Time Disabled OK (Y/N)?

7 If you don't want to modify the daylight-saving-time adjustment, type Y.

The Setup menu reappears. Information like this appears on line two of the Setup menu, where EDT is the abbreviation for Eastern Daylight Time. If it were EST instead, it would be Eastern Standard Time.

04/27/2023 22:47 EDT

8 Upon completion of the step above, you will be prompted to type the word "setup" to save any changes made.

4.2.2 Milepost/Kilometer Post (MP/KP)

To set or change the milepost/kilometer post (MP/KP) setting:

1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
SmartSCAN NG2, MP/KP:1234.5, Track:North
02/17/2020 10:53:47, 14.2V, 69°F
Setup Menu
[A] - Date and Time
[B] - MP/KP
[C] - Track Designation ..... North
[D] - Track Direction .... N/S
```

2 Select the MP/KP submenu

A prompt like this appears.

Enter the milepost in the form ####.# (use leading zeros):

MP/KP is in **nnnn.n** format. If the desired MP/KP has less than five digits, type leading zeros. If the desired MP/KP is an integer, type a trailing zero. Thus, for MP/KP 30, type **0030.0**.

- 3 To keep the displayed MP/KP:
 - a Press [Enter].

The Setup menu reappears.

- **b** Skip the remaining steps.
- **4** To <u>change</u> the displayed MP/KP, type the new five-digit MP/KP, including the decimal point.

The Setup menu reappears.

4.2.3 Subdivision

To set or change the Subdivision setting:

1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

Setup Menu [A] - Date and Time [B] - MP/KP [C] - Subdivision None [D] - Track Designation North .

2 Select the Subdivision submenu

A prompt like this appears.

Sele	ct a Service Area (current: None)
[A]	
[B]	- Alberta
[C]	- BC Interior
[D]	- Chicago
[E]	- DM&E
[F]	- Manitoba
[G]	- Montreal
[H]	- NEUS
[I]	- NOSA
[J]	- Saskatchewan (A-M)
[K]	- Saskatchewan (N-Z)
[L]	- SOSA
[M]	- St. Paul
[N]	- Vancouver
[0]	- Great Sandhills Railway
[P]	- CMQ Canadian
[Q]	- CMQ US

3 Select the appropriate service area to view the list of subdivision options. For example, if Alberta was selected, a prompt like this would appear:

```
Service Area Selected: Alberta
Select a subdivision (current: None)
_____
[A] - None
[B] - Aldersyde (6214)
[C] - Brechter (6243)
[D] - Breton (6228)
[E] - Brooks (6202)
[F] - Burstall (6209)
[G] - Crowsnest (6222)
[H] - Hatton (6210)
[I] - Hoadley (6227)
[J] - Irricana (6204)
[K] - Lacombe (6225)
[L] - Laggan (6201)
[M] - Leduc (6224)
[N] - Macleod (6213)
[0] - Maple Creek (6208)
[P] - Montana (6217)
[Q] - Pecten (6219)
[R] - Red Deer (6223)
[S] - Scotford (6231)
[T] - Shantz (6232)
[U] - Taber (6221)
[V] - Wetaskiwin (6229)
[W] - Willingdon (6230)
```

4 Type the letter that corresponds to the subdivision you want.

The Setup menu reappears.

4.2.4 Track Designation

To change the Track Designation:

1 Be sure that the Setup menu is displayed.

The Setup Menu looks like this.

```
[C] - Track Designation ..... North
[D] - Track Direction ..... N/S
[E] - Alarm Settings
[F] - Equipment Settings
```

2 Select the desired Track Designation option.

```
Select a track designation:
[A] - North
[B] - South
[C] - East
[D] - West
[E] - Connaught
[F] - Macdonald
[G] - Siding
[H] - Number 1 Track
[I] - Number 1 Track
[J] - Number 2 Track
[J] - Number 3 Track
[K] - Number 1 Main
[L] - Number 2 Main
[M] - Single
```

4.2.5 Track Direction

To change the Track Direction:

1 Be sure that the Setup menu is displayed.

The Setup Menu looks like this.

2 Select the Track Direction option to desired setting.

```
Select Track Direction:
[1] - N/S
[2] - E/W
```

4.2.6 Alarm Settings

To set or change one or more of the alarm settings (aka alarm limits):

1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
[A] - Date and Time
[B] - MP/KP
[C] - Track Designation ..... North
[D] - Track Direction ..... N/S
[E] - Alarm Settings
```

2 Select the Alarm Settings menu

A menu and prompt like this appears.

This menu option allows you to change the various alarm limits that affect system operations. The current setting for each limit is displayed. To change one of the alarm limit settings, start by typing the letter corresponding to the desired option.

- 3 To leave the Alarm Settings menu and return to the Setup menu:
 - a Press [Esc] or type X.

The Setup menu reappears.

b Skip the remaining steps.

4 To <u>change</u> the displayed **absolute-alarm limit** :

The number after the word Absolute (on the Alarm Settings menu) is an offset in <u>degrees Fahrenheit</u> above ambient temperature. When a bearing temperature exceeds this value, the system generates an Absolute alarm.

a Select Absolute from the Alarm Settings menu.

This prompt appears.

```
Absolute alarm setting (default = 180)
Enter a value from 1 to 300:
```

If the new limit has less than three digits, type leading zeros to make it three digits long <u>or press</u> [Enter] after typing one or two digits.

- **b** To <u>not</u> change the limit, press **[Esc]** <u>and</u> return to Alarm Settings Menu.
- c Type the new limit.
- 5 To change the displayed differential-alarm limit :

The number after the word Differential (on the Alarm Settings menu) is an offset in <u>degrees Fahrenheit</u> between rail1 and rail2. A bearing temperature is compared to the bearing temperature on the opposite end of the same axle. When the difference in temperatures exceeds the value on the screen, the system generates a Differential alarm. Checking for Differential alarms stops when the speed of the train drops below 7 mph (11.3 kph).

a Select **Differential** from the Alarm Settings menu.

This prompt appears.

```
Differential alarm setting (default = 150)
Enter a value from 1 to 300:
```

If the new limit has less than three digits, type leading zeros to make it three digits long <u>or press</u> [Enter] after typing one or two digits.

- **b** To <u>not</u> change the limit, press **[Esc]** <u>and</u> return to the Alarm Settings menu.
- c Type the new limit.
- 6 To change the displayed hotwheel-alarm limit :

The number after the words Hot Wheel (on the <u>Alarm Settings menu</u>) is an offset <u>in</u> <u>degrees Fahrenheit</u> above ambient temperature. When a wheel temperature exceeds this value, the system generates a Hotwheel alarm. However, when the Hotwheel option on the <u>Equipment Settings menu</u> is disabled, Hotwheel alarms aren't generated.

a Select Hot Wheel from the Alarm Settings menu.

This prompt appears.

Hot Wheel alarm setting (default = 600) Enter a value between 1 and 900:

If the new limit has less than three digits, type leading zeros to make it three digits long <u>or press</u> **[Enter]** after typing one or two digits.

- **b** To <u>not</u> change the limit, press **[Esc]** <u>and</u> return to the Alarm Settings menu.
- **c** Type the new limit.

7 To <u>change</u> the displayed **number of allowed consecutive cold rail events**:

The number after the words Cold Rails (on the Alarm Settings menu) is the maximum number (per railside) of consecutive trains having:

- Cold Rail alarms needed to generate a Successive Cold Rails Exceeded alarm.
- Cold Resistor alarms needed to generate a Successive Cold Resistors Exceeded alarm.
- Cold Wheel Scanner alarms needed to generate a Successive Cold Wheels Exceeded alarm.
- Cold Wheel Scanner Resistor alarms needed to generate a Successive Cold Wheel Resistors Exceeded alarm.

•
•
[A] - Absolute 180
[B] - Differential
[C] - Hot Wheel 600
[D] - Cold Rails 3
•
•
•

a Select Cold Rails from the Alarm Settings menu.

This prompt appears.

```
New Value ? Rails alarm setting (default = 3)
Enter a value between 1 and 9:
```

- **b** To <u>not</u> change the value, press **[Esc]** <u>and</u> return to step **3**.
- c Type the new value.
- 8 To <u>change</u> the displayed **cold rail temperature**:

The number after the words Cold Rail Temp (on the Alarm Settings menu) is an offset, in <u>degrees</u> Fahrenheit, above the ambient temperature. When no bearing on a given rail generates a delta temperature reading greater than or equal to this value, the system generates a Cold Rail alarm for the given rail. There is a different Cold Rail alarm for each rail. That is, there is a Cold North Rail alarm and a Cold South Rail alarm (or, depending on track direction, a Cold East Rail alarm, and a Cold West Rail alarm).

•
•
•
[E] - Cold Rail Temp 10
[F] - Cold Res Counter 3
[G] - Differential Enabled Yes
[H] - Advanced
[X] - Exit

a Select Cold Rail Temp from the Alarm Settings menu.

This prompt appears.

```
Cold Rails alarm setting (default = 10)
Enter a value between 1 and 30:
```

If the new value has less than two digits, type leading zero to make it two digits long <u>or</u> press **[Enter]** after typing one digit.

- **b** To <u>not</u> change the value, press **[Esc]** <u>and</u> return to step **3**.
- **c** Type the new value.
- 9 To <u>change</u> the displayed **cold resistor counter**:

The number after the words Cold Res Counter is the maximum number (per railside) of consecutive trains, having Cold Resistor alarms, allowed before generating a Successive Cold Resistors Exceeded alarm. Under normal circumstances, cold resistor conditions represent System Alarms, not Integrity Failures. However, if the number of consecutive trains bearing identical Cold Resistor alarms <u>equals or exceeds</u> the Cold Resistor Counter option on the Alarm Settings menu, this condition becomes an Integrity Failure. If the number of consecutive trains bearing identical Cold Resistor alarms section of the Train Detail and Exception Detail Report displays the message "Successive Cold Resistors Exceeded."

```
[E] - Cold Rail Temp ..... 10
[F] - Cold Res Counter ..... 3
[G] - Differential Enabled ..... Yes
[H] - Advanced
[X] - Exit
```

a Select Cold Res Counter

This prompt appears.

```
Cold Res Counter alarm setting (default = 3)
Enter a value between 1 and 9:
```

- **b** To <u>not</u> change the value, press **[Esc]** <u>and</u> return to step **3**.
- **c** Type the new value.

10 To <u>change</u> the Differential Enabled setting:

Select the Differential Enabled option to toggle between Yes & No.



11 To change the Advanced settings:

Select the Advanced option from the Alarm Settings menu.

```
[E] - Cold Rail Temp ..... 10
[F] - Cold Res Counter ..... 3
[G] - Differential Enabled ..... Yes
[H] - Advanced
[X] - Exit
```

A menu and prompt like this appears.

Alarm	Settings (Advanced)
[A] -	Carside Slope 1.60
[B] -	Carside Minimum 130
[C] -	Res Test: Minimum Rail Avg 25
[D] -	Res Test: Minimum Wheel Avg 28
[E] –	Bearing DSR Capture Temp 50
[F] -	Wheel DSR Capture Temp 150
[G] -	Max Alarms 6
[X] -	Exit

Select options as necessary to make desired changes. You will be prompted with a range of acceptable values.

4.2.7 Equipment Settings

To set or change one or more of the equipment parameters:

1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

2 Select the Equipment Settings menu.

A menu and prompt like this appears.

The current setting for each menu option is displayed. For example, the screen above shows that Wide-Load alarm detection is inactive (NO). To change one of the settings, press the letter corresponding to the desired option. Except for the Gate Distance option, which requires a value entry, all the options toggle between two or three settings.

- **3** To leave the Equipment Settings menu and return to the Setup menu:
 - a Press [Esc] or type X.

The Setup menu reappears.

- **b** Skip the remaining steps.
- 4 To <u>change</u> the current **dragger** (aka dragging-equipment) setting:

The Equipment Settings menu shows whether Dragging-Equipment alarm detection is enabled (YES) or disabled (NO). When disabled, Dragging-Equipment alarms won't be announced nor stored. Since they aren't stored, they can't be printed. When enabled, Dragging-Equipment alarms will be announced and stored. Since they are stored, they can be printed. In the presence of a continuous Dragger signal, the system alarms consecutive axles. When the system reaches the fifth consecutive Dragger alarmed axle, it flags the Stuck Dragger condition.

Equipment Settings [A] - Dragger NO [B] - High Load NO [C] - Wide Load NO . .

a Select Dragger from the Equipment Settings menu.

The dragging-equipment setting toggles between active (YES) and inactive (NO). The Dragger option on the Equipment Settings menu changes. The Equipment Settings menu reappears.

If you want Dragging-Equipment alarm detection to occur, be sure that YES appears after the word Dragger on the Equipment Settings menu.

5 To <u>change</u> the current **high-load** setting:

The Equipment Settings menu shows whether High-Load alarm detection is active (YES) or inactive (NO). To announce High-Load alarms, YES must appear after the words High Load on the Equipment Settings menu, <u>and</u> Separate must appear after the words Clearance Mode on the Equipment Settings menu. To announce High-Wide alarms, YES must appear after the words High Load on the Equipment Settings menu, <u>and</u> Multiplexed must appear after the words Clearance Mode on the Equipment Settings menu, <u>and</u> Separate must appear after the words High Load on the Equipment Settings menu, <u>and</u> Settings menu, and Multiplexed must appear after the words Clearance Mode on the Equipment Settings menu.

Equipment Settings [A] - Dragger NO [B] - High Load NO [C] - Wide Load NO

a Select High Load from the Equipment Settings menu.

The high-load setting toggles between active (YES) and inactive (NO). The High-Load option on the Equipment Settings menu changes. The Equipment Settings menu reappears.

If you want High-Load alarm detection to occur, be sure that YES appears after the word High-Load on the Equipment Settings menu.

- **b** Return to Equipment Settings.
- 6 To change the current wide-load setting:

The Equipment Settings menu shows whether Wide-Load alarm detection is active (YES) or inactive (NO).

a Select Wide Load from the Equipment Settings menu.

The wide-load setting toggles between active (YES) and inactive (NO). The Wide-Load option on the Equipment Settings menu changes. The Equipment Settings menu reappears.

If you want Wide-Load alarm detection to occur, be sure that YES appears after the word Wide-Load on the Equipment Settings menu.

7 To change the **AEI** setting:

The Equipment Settings menu shows whether the AEI subsystem is enabled (YES) or disabled (NO). When tag readers and attendant antennas and cabling are present, this parameter should be set to YES so that the system knows to configure the readers and to use the AEI data transmitted from them. When there is no installed AEI subsystem attached to the SmartScanNG² system, this parameter should be set to NO.

•	
•	
•	
[D] - Hot Wheel	Yes
[E] – AEI	No
[F] - Hot Bearing	Yes
•	
•	
•	

a Select AEI from the Equipment Settings menu.

The setting toggles between active (YES) and (NO). The Equipment Settings menu reappears.

- **b** Return to step **3**.
- 8 To change the Hot Bearing setting:

The Equipment Settings menu shows whether the Hot Bearing alarm detection is enabled (YES) or disabled (NO). When disabled, Hot Bearing alarms won't be announced nor stored. Since they aren't stored, they can't be printed. When enabled, Hot Bearing alarms will be announced and stored.

a Select Hot Bearing from the Equipment Settings menu.

The setting toggles between active (YES) and (NO). The Equipment Settings menu reappears.

- **b** Return to step **3**.
- 9 To change the Presence Hardware setting:
 - a Select Presence Hardware from the Equipment Settings menu.

The Presence Hardware setting toggles between active (Enabled) and inactive (Disabled). The Equipment Settings menu reappears.

- **b** Return to step **3**.
- 10 To change the Advance Transducer setting:
 - a Select Advance Transducer from the Equipment Settings menu.

The Advance Transducer setting toggles between active (Enabled) and inactive (Disabled). The Equipment Settings menu reappears.

- 11 To change AC Power Off Monitor setting:
 - a Select AC Power Off Monitor from the Equipment Settings menu.

The AC Power Off Monitor setting toggles between active (Enabled) and inactive (Disabled). The Equipment Settings menu reappears.

- **b** Return to step **3**.
- 12 To change Scanner Types settings:
 - a Select Select Scanner Types from the Equipment Settings menu. A menu like this appears.

```
Scanner Types (changes require calibration)
------
[A] - East Rail: Type III
[B] - West Rail: Type III
[C] - East Wheel: Type III
[D] - West Wheel: Type III
[X] - Exit
```

Select the scanner option to toggle between Type III and Type II.

b Return to step 3.

13 To change Advanced settings:

a Select Advanced from the Equipment Settings menu.

```
Equipment Settings (Advanced)
_____
[A] - Carside Slope ..... Yes
[B] - Clearance Type ..... Light Beam
[C] - Clearance Mode ..... Multiplexed
[D] - Winter Cycle ..... Oct - Mar
[E] - Transducer Gain ..... Normal
[F] - Resistor Test ..... Enabled
[G] - Gate Distance ..... 24.0 in
[H] - Dragger Debounce Time ..... 5 ms
[I] - Pre Train Dragger Dist .... 200 ft
[J] - Pre Train High/Wide Dist .... 0 ft
[K] - Presence Timeout Period ... 10 sec
[L] - System Voltage ..... 12v
[M] - Sunshot Menu
[N] - Transducer / Scanner Offset Menu
[X] - Exit
```

14 To <u>change</u> the current carside-slope setting:

The Equipment Settings (Advanced) menu shows whether Carside Slope alarm detection is enabled (YES) or disabled (NO). If disabled (NO) during train passage, no carside-slope calculation/analysis is done, and thus, no Carside Slope alarms are generated. (The Hot Bearing option on the Equipment Settings menu also has to be enabled. If it isn't, the detector won't recognize Carside alarms).

- a Select **Carside Slope** from the Equipment Settings (Advanced) menu. The carside-slope setting toggles between active (YES) and inactive (NO). The option changes. The Equipment Settings (Advanced) menu reappears.
- **b** Return to Equipment Settings (Advanced).
- 15 To change the current clearance-type setting:

The Equipment Settings (Advanced) menu shows whether clearance type is tripwire or light beam. This option is only used for high-load detectors and wide-load detectors. Both high-load detectors and wide-load detectors must be <u>either</u> tripwire detectors or light-beam detectors.

a Select Clearance Type from the Equipment Settings menu.

The clearance-type setting toggles between tripwire and light beam. The Clearance Type option on the Equipment Settings menu changes. The Equipment Settings (Advanced) menu reappears.

- **b** Return to Equipment Settings (Advanced).
- 16 To <u>change</u> the current **clearance-mode** setting:

The Equipment Settings (Advanced) menu shows whether clearance mode is separate or multiplexed. This option is only used for high-load detectors and wide-load detectors. When set to <u>separate</u>, the alarms coming from the high-load detectors are announced as High-Load alarms, <u>and</u> the alarms coming from the wide-load detectors are announced as Wide-Load alarms. When set to <u>multiplexed</u>, the alarms coming from the high-load detectors and wide-load detectors are announced as Wide-Load alarms. When set to <u>multiplexed</u>, the alarms coming from the high-load detectors and wide-load detectors are announced as High-Wide alarms.

a Select Clearance Mode from the Equipment Settings (Advanced) menu.

The clearance-mode setting toggles between separate and multiplexed. The Clearance Mode option on the Equipment Settings menu changes. The Equipment Settings menu reappears.

- **b** Return to Equipment Settings (Advanced).
- 17 To change the current winter-cycle setting:

The Equipment Settings (Advanced) menu shows whether the winter-cycle feature is enabled or disabled. To avoid errant heat readings caused by moisture on the pyrometer lenses, the scanners have heaters built into them. The heaters are made active, for varying periods of time, depending on the ambient temperature.

The table below lists the heater activation times for both normal and winter-cycle operation, grouped by ambient temperature.

Temperature Range in degrees Fahrenheit		Out of every ten seconds, the number of seconds the scanner heaters are active	
Low	High	Winter Cycle Disabled	Winter Cycle Enabled
	16	4	8
17	35	3	7
36	51	2	2
52	80	1	1
80		Off	Off

The normal heater activation times aren't suitable for extremely cold climates, so the winter-cycle feature compensates for this. When this feature is disabled, the heater controls function normally. When enabled, the system increases the normal running time for the scanner heaters. The winter-cycle feature doesn't affect all the temperature ranges that the scanner heaters will activate on. It affects just the ones that are considered extremely cold.

a From the Equipment Settings (Advanced) submenu, select Winter Cycle.

The Winter Cycle option on the submenu changes.

If you <u>disabled</u> the winter-cycle setting, the Equipment Settings (Advanced) submenu reappears. If you <u>enabled</u> the winter-cycle setting, a prompt similar to this appears.

```
Choose a starting month and ending month. (Make them the same to enable year-round.)
Starting month, currently: 10
New value (1-12):
```

If the new start value is one digit long, you can type a leading zero to make it two digits long, <u>or</u> you can press **[Enter]** after typing one digit.

- **b** If you <u>disabled</u> the winter-cycle setting, skip the steps below <u>and</u> return to step **3**.
- c To <u>not</u> change the <u>starting</u> and <u>ending</u> values, press [Esc] and return to step 3.
- **d** Type the new starting value.

If you type zero or a value <u>greater than</u> 12, an error message and prompt similar to this appear.

```
Invalid range specified
Starting month, currently: 10
New value (1-12):
```

If you type an acceptable value, a prompt similar to this appears.

```
Ending month, currently: 3
New value (1-12):
```

- e If you get an error message, return to step c.
- f To <u>not</u> change the <u>ending</u> value, press [Esc] <u>and</u> return to step 3.
- g Type the new ending value.

If you type zero or a value <u>greater than</u> 12, an error message and prompt similar to this appear.

```
Invalid range specified
Ending month, currently: 3
New value (1-12):
```

If you type an acceptable value, the Equipment submenu reappears, displaying the start and end months that the snow cycle is enabled. For example, if you type 11 for the start month and 01 for the end month, you'll see a line like this.

```
D) Winter Cycle..... Nov - Jan
```

If you entered the same value (that is, the same month) for both the start and end months, the heaters are enabled year-round. For example, if the start month is 12 and the end month is 12, the heaters are enabled year-round. If the start month is 12 and the end month is 11, the heaters are also enabled year-round. If the start month is 11 and the end month is 12, the heaters are only enabled for November and December.

- h If you get an error message, return to step f.
- i Return to Equipment Settings (Advanced).
- **18** To <u>change</u> the current **transducer-gain** setting:

The Equipment Settings (Advanced) menu shows whether the transducer-gain setting is normal or high. Regardless of the setting, the SmartScanNG² system starts every train with the transducer input comparator set to high mode. Then, if the train is traveling 20 mph (32 kph) or more <u>and</u> if the transducer gain is set to normal mode, the transducer input comparator switches to normal mode. This means that it is rarely necessary to set this option to high.

When the comparator is in <u>high</u> mode, the comparator converts lower voltage pulses from the transducer into output pulses. This causes the system to be more sensitive to transducer output. When the comparator is in <u>normal</u> mode, the comparator has a better chance of filtering transducer pulses not caused by a wheel.

a Select Transducer Gain from the Equipment Settings (Advanced) menu.

The transducer-gain setting toggles between normal and high. The Transducer Gain option on the Equipment Settings menu changes. The Equipment Settings menu reappears.

- **b** Return to Equipment Settings (Advanced).
- 19 To change the current resistor-test setting:

The Equipment Settings (Advanced) menu shows whether the resistor-test setting is enabled <u>or</u> disabled.

After a train clears a site, the system does an integrity test (when enabled) to verify that the scanners are operational and that the system can read alarm-level heat. This test consists of reading the temperature of power resistors mounted to the back of the scanner shutters after the shutters close. The recorded temperature of the shutter resistors is compared against expected values, which are calculated using a combination of the amount of time the shutters were open and the system battery voltage.

When the resistor integrity test is <u>enabled</u>, a system algorithm determines the minimum acceptable resistor temperature values for a given train. When <u>disabled</u>, the resistor integrity test is not performed.

The minimum required resistor temperatures for a given train are determined by the train's duration at the site and the resistor temperature baseline profile. This profile was established 20 minutes after the user calibrated the scanners with the autocalibration function. Twenty minutes is the cooling period required to allow the resistors to return to ambient temperature after autocalibration.

```
[E] - Transducer Gain ..... Normal
[F] - Resistor Test .... Enabled
[G] - Gate Distance ..... 24.0 in
```

a Select Resistor Test from the Equipment Settings (Advanced) menu.

The resistor-test setting toggles from enabled to disabled.

- **b** Return to Equipment Settings (Advanced).
- 20 To <u>change</u> the current value for gate distance (aka gate width):

The Equipment Settings (Advanced) menu shows the number of inches between the centers of the gating transducers.

```
[E] - Transducer Gain ..... Normal
[F] - Resistor Test .... Enabled
[G] - Gate Distance .... 24.0 in
```

a Select Gate Distance from the Equipment Settings (Advanced) menu.

This prompt appears.

```
Gate Distance equipment setting (default = 0.0)
Enter a value from 0.0 and 48.0:
```

The gate distance is in **nn.n** format. You must type the decimal point. If the new value has less than three digits, type leading zeros, trailing zeros, or both. Thus, for 2, type **02.0**. The gate distance (it is usually 24.0) can be recorded in 1/10-inch increments to reflect the actual transducer spacing. Accurate gating-transducer spacing results in accurate speed calculations and train length calculations.

b Type the number in the **nn.n** format.

The Gate Distance option on the Equipment Settings (Advanced) menu changes. The Equipment Settings menu reappears.

- c Return to Equipment Settings (Advanced).
- 21 The Dragger Debounce Time parameter defines the amount of time the Dragger signal must be active before the system flags a Dragger alarm. The detector ignores Dragger activations with durations shorter than this time limit. To <u>change</u> this parameter:
 - a Select Dragger Debounce Time from the Equipment Settings (Advanced) menu.

This prompt appears.

Dragger Debounce Time equipment setting (default = 100 ms) Enter a value from 0 and 999:

If the new value has less than three digits, type leading zeros to make it three digits long or press [Enter] after typing one or two digits.

- **b** Return to Equipment Settings (Advanced).
- 22 The **Pre Train Dragger** distance defines the amount of space in front of a train in which a detected dragger alarm is assigned to the first axle rather than as a pre-train alarm. To <u>change</u> the Pre Train Dragger Distance:
 - a Select **Pre Train Dragger Dist** from the Equipment Settings (Advanced) menu.

This prompt appears.

```
Pre Train Dragger Dist equipment setting (default = 0 ft)
Enter a value from 0 and 999:
```

If the new value has less than three digits, type leading zeros to make it three digits long or press [Enter] after typing one or two digits.

b Return to Equipment Settings (Advanced).

- **23** The **Pre Train High/Wide** distance defines the amount of space in front of a train in which a detected high-load alarm or wide-load alarm is assigned to the first axle rather than as a pre-train alarm. To <u>change</u> the Pre Train High/Wide Distance:
 - a Select Pre Train High/Wide Dist from the Equipment Settings (Advanced) menu.

This prompt appears.

```
Pre Train High/Wide Dist equipment setting (default = 0 ft)
Enter a value from 0 and 999:
```

If the new value has less than three digits, type leading zeros to make it three digits long or press [Enter] after typing one or two digits.

- **b** Return to Equipment Settings (Advanced).
- **24 Presence Timeout Period** defines the period of time that Presence must be inactive before a train is finalized and stored. To <u>change</u> the Presence Timeout Period:
 - **a** Select **Presence Timeout Period** from the Equipment Settings (Advanced) menu. This prompt appears.

Presence Timeout Period equipment setting (default = 10 sec)

Enter a value from 5 to 30:

- **b** Return to Equipment Settings (Advanced).
- **25** The **System Voltage** parameter should be set to match the voltage of the battery subsystem currently powering your SmartScanNG² (either 24V or 12V). This setting determines the battery levels used to flag Low Battery and Dead Battery conditions. To change this setting:
 - a Select System Voltage o toggle between 24V and 12V settings.
 - **b** Return to Equipment Settings (Advanced).

26 To view the Sunshot Menu:

Select **Sunshot Menu** from the Equipment Settings (Advanced) menu.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
03/16/2023 11:35:57, 11.6V, 76°F
Equipment Settings (Advanced)
 _____
[A] - Carside Slope ..... No
[B] - Clearance Type ..... Trip Wire
[C] - Clearance Mode ..... Multiplexed
[D] - Winter Cycle ..... Jan - Jan
[E] - Transducer Gain ..... Normal
[F] - Resistor Test ..... Enabled
[G] - Gate Distance ..... 24.0 in
[H] - Dragger Debounce Time ..... 100 ms
[I] - Pre Train Dragger Dist ..... 0 ft
[J] - Pre Train High/Wide Dist .... 0 ft
[K] - Presence Timeout Period ... 10 sec
[L] - System Voltage ..... 24v
[M] - Sunshot Menu
[N] - Transducer / Scanner Offset Menu
[X] - Exit
```

27 To change the Sunshot Menu settings:

Sunshot Menu
[A] - Sunshot Filter Disabled
[B] - Bearing Scanner Orientation 0 degrees
[C] - Latitude 35.0456
[D] - Longitude -85.3097
[E] - Print Sunshot Season
[X] - Exit

- **a** Select the Sunshot Filter option to toggle from Enabled to Disabled.
- **b** Select the Bearing Scanner Orientation option to change compass direction.

This prompt appears.

```
Bearing Scanner Orientation -
The compass direction in degrees that the scanners are facing.
Enter a value from 0 to 359:
```

c Select the Latitude option to change the value.

This prompt appears.

```
Latitude -
The geographic latitude of your site in degrees.
Enter a value from 0.0000 to 90.0000:
```

d Select the Longitude option to change the value.

This prompt appears.

```
Longitude -
The geographic longitude of your site in degrees.
Enter a value from -180.0000 to 180.0000:
```

28 To view the Transducer / Scanner Offset Menu:

Select **Transducer / Scanner Offset Menu** from the Equipment Settings (Advanced) menu.

```
SmartSCAN NG2, MP/KP:1234.5, Track:Single
03/16/2023 11:35:57, 11.6V, 76°F
Equipment Settings (Advanced)
_____
[A] - Carside Slope ..... No
[B] - Clearance Type ..... Trip Wire
[C] - Clearance Mode ..... Multiplexed
[D] - Winter Cycle ..... Jan - Jan
[E] - Transducer Gain ..... Normal
[F] - Resistor Test ..... Enabled
[G] - Gate Distance ..... 24.0 in
[H] - Dragger Debounce Time ..... 100 ms
[I] - Pre Train Dragger Dist ..... 0 ft
[J] - Pre Train High/Wide Dist .... 0 ft
[K] - Presence Timeout Period ... 10 sec
[L] - System Voltage ..... 24v
[M] - Sunshot Menu
[N] - Transducer / Scanner Offset Menu
[X] - Exit
```

29 To change the Transducer / Scanner Offset Menu settings:

a Select the **Transducer Type** option to change the setting (toggles from Magnetic to Frauscher).

NOTICE!

When using Frauscher transducers, the settings for rail size and scanner offset <u>MUST</u> be entered in order for the system firmware to accurately calculate the "Virtual Gate" of each scanner. As depicted below, The scanner offset is measured from the center of the transducer bracket to the center of the scanner mounting bracket.



b To change the rail size, select the menu option. A prompt like this appears:



Select the appropriate setting for your site.

c To set the scanner offset value for each scanner, select the menu option. A prompt like this appears.

```
North Rail Scanner Offset transducer setting (default = 0 inches)
Enter an OFFSET value from 0 to 100 inches:
```

Enter the appropriate offset setting for each scanner to the nearest inch.

Next, you will be prompted to select scanner orientation (this information is also necessary for "Virtual Gate" calculations).

```
Is the scanner closer to TO1 or TO2?
[1] - TO1
[2] - TO2
```

Enter the appropriate selection.

d Return to step 3.

4.2.8 Messages

To set or change any of the message parameters:

1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
SmartSCAN NG2, MP/KP:1234.5, Track:North
Subdivision: None
04/28/2023 15:28:31, 11.8V, 101°F
Setup Menu
_____
[A] - Date and Time
[B] - MP/KP
[C] - Subdivision ..... None
[D] - Track Designation ..... North
[E] - Track Direction ..... N/S
[F] - Alarm Settings
[G] - Equipment Settings
[H] - Messages Settings
[I] - AEI Settings
[J] - Units Of Measure Settings
[K] - Load Default Setup Parameters
[L] - COM Port Settings
[M] - Network Settings
[N] - Velocity ..... Enabled
[0] - GO Train Detect ..... No
[P] - Weather Settings
[X] - Exit
```

2 Select the Messages menu

A menu and prompt like this appears. The options on the Messages menu are used to affect the phrases broadcast to a passing train or are used to modify the parameters associated with the rebroadcast function.

Messages Settings
<pre>[A] - Axles Yes [B] - Speed No [C] - Temperature Yes [D] - Length No [E] - Slow Yes [F] - Power Off Yes</pre>
[G] - Repeat No Defects No [H] - Cars Count No
<pre>[I] - Customer Name Yes [J] - Arrival Message No [K] - Lft/Rt Alarm Ref No [L] - Car ID With Alarm Yes [M] - US Speech Options No [N] - Primary Broadcast Language English_Matthew [O] - Secondary Broadcast Language . None [P] - Advanced [X] - Exit</pre>

Enabling one or more of these options generates the ancillary messages: A (axle count), B (train speed), C (site ambient temperature), D (train length), E (slow train), F (power off), and H (number of cars). The other options of the Messages menu aren't used to generate ancillary messages.

- **3** To leave the Messages menu and return to the Setup menu:
 - a Press [Esc] or type X.

The Setup menu reappears.

- **b** Skip the remaining steps.
- 4 To <u>change</u> the **announce-axles** setting:

The Messages menu shows whether the <u>total axle count</u> is to be part of (YES) or not part of (NO) post-train announcements. When the Highrange Transducer Miscounts alarm <u>or</u> Very Slow Train alarm occurs, the system won't announce axle count, even when this option is enabled.

a Select Axles from the Messages menu.

The announce-axles setting toggles between announce (YES) or not announce (NO). The Announce Axles option on the Messages menu changes. The Messages menu reappears.

- **b** Return to step **3**.
- 5 To <u>change</u> the **announce-speed** setting:

The Messages menu shows whether the <u>exit speed</u> of the train is to be part of (YES) or not part of (NO) post-train announcements.

Messages Settings	
[A] - Axles YES	
[B] - Speed NO	
[C] - Temperature YES	
•	

a Select **Speed** from the Messages menu.

The announce-speed setting toggles between announce (YES) or not announce (NO). The Announce Speed option on the Messages menu changes. The Messages menu reappears.

b Return to step **3**.

6 To <u>change</u> the **announce-temperature** setting:

The Messages menu shows whether the ambient temperature (taken at the site by the shielded temperature probe as the train leaves the site) is to be part of (YES) or not part of (NO) post-train announcements.

a Select **Temperature** from the Messages menu.

The announce-temperature setting toggles between announce (YES) or not announce (NO). The Announce Temperature option on the Messages menu changes. The Messages menu reappears.

- **b** Return to step **3**.
- 7 To change the announce-train-length setting:

The Messages menu shows whether the train length is to be part of (YES) or not part of (NO) post-train announcements. When the Highrange Transducer Miscounts alarm <u>or</u> Very Slow Train alarm occurs, the system won't announce the length of the train, even when this option is enabled.

a Select Length from the Messages menu.

The announce-train-length setting toggles between announce (YES) or not announce (NO). The Announce Train Length option on the Messages menu changes. The Messages menu reappears.

- **b** Return to step **3**.
- 8 To change the announce-slow-train setting:

The Messages menu shows whether a message indicating a slow train (one going 7 mph or slower) is to be part of (YES) or not part of (NO) post-train announcements.

a Select **Slow** from the Messages menu.

The announce-slow-train setting toggles between announce (YES) or not announce (NO). The Announce Slow Train option on the Messages menu changes. The Messages menu reappears.

- **b** Return to step **3**.
- 9 To <u>change</u> the **announce-power-off** setting:

The Messages menu shows whether the power-off message is to be part of (YES) or not part of (NO) post-train announcements. The generation of this message depends on battery voltage, not AC power. It is generated whenever the voltage coming from the battery is less than 12.6 VDC. AC power need have never been off to cause this to happen. However, most times, it does indicate that the AC power has been off, causing the battery to be drained.

a Select Power Off from the Messages menu.

The announce-power-off setting toggles between announce (YES) or not announce (NO). The Announce Power Off option on the Messages menu changes. The Messages menu reappears.

10 To change the repeat-no-defect-message setting:

The Messages menu shows whether the no-defect message is to be repeated (YES) or not repeated (NO).



a Select Repeat No Defects from the Messages menu.

The repeat-no-defect-message setting toggles between enabled (YES) and disabled (NO). The Repeat No Defects option on the Messages menu changes. The Messages menu reappears.

b Return to step **3**.

```
11 To change the announce-number-of-cars setting:
```

The Messages menu shows whether the number of cars is to be part of (YES) or not part of (NO) post-train announcements.

a Select Cars Count from the Messages menu.

The announce-number-of-cars setting toggles between announce (YES) or not announce (NO). The Announce Number of Cars option on the Messages menu changes. The Messages menu reappears.

- **b** Return to step **3**.
- 12 To <u>change</u> the **announce-customer-name** setting:

The Messages menu shows whether the customer's railroad name is to be part of (YES) or not part of (NO) of all announcements.



a Select **Customer Name** from the Messages menu.

The announce-customer-name setting toggles between announce (YES) or not announce (NO). The Announce Customer Name option on the Messages menu changes. The Messages menu reappears.

13 To change the announce-arrival-message setting:

The Messages menu shows whether an arrival message announces (YES) or doesn't announce (NO) train arrival at the site.

a Select Arrival Message from the Messages menu.

The announce-arrival-message setting toggles between announce (YES) or not announce (NO). The Announce Train Arrival option on the Messages menu changes. The Messages menu reappears.

b Return to step **3**.

14 To change the left-right-alarm-reference setting:

The Messages menu shows whether the alarm reference is announced as left or right (YES) <u>or</u> as north, south, east, or west (NO).

a Select Lft/Rt Alarm Ref from the Messages menu.

The left-right-alarm-reference setting toggles between YES and NO. The Announce Left-Right Alarm Reference option on the Messages menu changes. The Messages menu reappears.

b Return to step **3**.

15 To change the announce-car-identification setting:

The Messages menu shows whether car-identification information is to be announced (YES) or not announced (NO). When this option is set to YES <u>and</u> an Exception Alarm is found on a car, the car-identification information is included in the post-train announcement for the train having the Exception Alarm. This, of course, will only happen if the AEI option on the Equipment Settings menu is enabled (YES) <u>and</u> the AEI subsystem is functioning properly during train passage.

• • • • • • • • • • • • • • • • • • • •
<pre>[L] - Car ID With Alarm NO [M] - US Speech Options No [N] - Primary Broadcast Language English_Matthew [O] - Secondary Broadcast Language . None</pre>
[P] - Advanced [X] - Exit

a Select Car ID With Alarm from the Messages menu.

The announce-car-identification setting toggles between enabled (YES) and disabled (NO). The Announce Car Identification option on the Messages menu changes. The Messages menu reappears.

b Return to step **3**.

16 To change the US Speech Options setting:

The Messages menu shows whether US Speech Options are enabled (YES) or not enabled (NO). When this option is set to YES, the words "Sticking Brake" and "Milepost" are used in announcements. When this option is set to NO, the words "Hotwheel" and "Mile" are used instead.

a Select US Speech Options from the Messages menu.

The US Speech Options setting toggles between (YES) or (NO). The Messages menu reappears.

- **b** Return to step **3**.
- 17 To change the Primary Broadcast Language setting:

The Messages menu displays the current setting for Primary Broadcast Language.

a Select Primary Broadcast Language from the Messages menu.

This prompt appears.

```
Select a language:
[A] - French_Mathieu
[B] - English_Matthew
[C] - None
```

Select desired setting. The Messages menu reappears.

b Return to step **3**.

18 To change the Secondary Broadcast Language setting:

The Messages menu displays the current setting for Secondary Broadcast Language Language.

a Select Secondary Broadcast Language from the Messages menu.

This prompt appears.

```
Select a language:
[A] - French_Mathieu
[B] - English_Matthew
[C] - None
```

Select desired setting. The Messages menu reappears.

- **b** Return to step **3**.
- 19 To view/change Advaced message settings:
 - a Select Advanced from the Messages menu.

This prompt appears.

```
Messages Settings (Advanced)
[A] - Announce Hot Wheels ...... Yes
[B] - Announce Differential ..... Yes
[C] - Announce High Load ..... Yes
[D] - Announce Wide Load ..... Yes
[E] - Request EOT Timer .... 0 min
[F] - Rebroad DTMF Code ..... 0 min
[G] - Num EOT Repeats .... 0
[H] - EOT Repeat Delay .... 5 sec
[X] - Exit
```

a Select desired option to change announcement settings for **Hot Wheel**, **Differential**, **High Load**, and **Wide Load**. This prompt will appear:

```
Select "xxx" Announcement Mode:

[1] - Yes

[2] - N/E Only

[3] - S/W Only

[4] - No
```

Select desired setting. The Messages Settings (Advanced) menu reappears.

b Return to step 3.

20 To change the repeat-EOT-message-timeout-period setting:

The Messages menu shows a value for the repeat-timeout-period setting. If a nonzero value is shown, the value is the number of minutes that you have to request a repeat of the last end-of-train (EOT) message. If zero is shown, the last EOT message is always available for rebroadcast. The train crew makes the actual request for rebroadcast. The repeated message has the word "rebroadcast" at the beginning and end of the message.

a Select **Request EOT Timer** from the Messages menu.

This prompt appears.

```
Request EOT Timer message setting (default = 0 min)
Enter a value between 0 and 999:
```

If the new limit has less than three digits, type leading zeros.

b Type the three-digit value.

If you type 000, the last EOT message is always available for rebroadcast. If you type 240, the train crew has four hours (that is, 240 minutes) to request a repeat of the last EOT message.

21 To change the rebroadcast-DTMF-code setting:

The Messages menu shows the rebroadcast-DTMF-code setting. The stored DTMF code is the touchtone digits that trigger a rebroadcast. Up to three digits may be entered into this setup parameter. The SmartScanNG² system monitors radio traffic. When it receives the proper DTMF code, it will rebroadcast the last end-of-train message, provided the request EOT timer hasn't expired.

```
[E] - Request EOT Timer ..... 0 min
[F] - Rebroad DTMF Code ..... <None>
[G] - Num EOT Repeats ..... 0
[H] - EOT Repeat Delay ..... 5 sec
[X] - Exit
```

a Select Rebroad DTMF Code from the Messages menu.

This prompt appears.

```
Rebroad DTMF Code message setting (default = )
Enter a dtmf code (Esc to clear):
```

- **b** Type the new DTMF code or press [Esc].
- c If you typed one or two digits, press [Enter].

The Rebroadcast DTMF Code option on the Messages menu changes and the Messages menu reappears. If you typed only nondigits and then pressed **[Enter]**, the rebroadcast function would be turned off.

d Return to step 3.

22 To change the number-of-repeats setting:

The Messages menu shows a value for how many times the EOT announcement should be repeated. Valid values range from 0 through 5. When set to zero, the EOT announcement is spoken once with no repeats. When set to five the EOT announcement is spoken once with five repeats for a total number of six times.

```
[E] - Request EOT Timer ..... 0 min
[F] - Rebroad DTMF Code ..... <None>
[G] - Num EOT Repeats ..... 0
[H] - EOT Repeat Delay ..... 5 sec
[X] - Exit
```

a Select Num EOT Annc Repeats from the Messages menu.

This prompt appears.

```
Num EOT Repeats message setting (default = 0)
Enter a value between 0 and 5:
```

- **b** To <u>not</u> change the value, press **[Esc]** and return to step **3**.
- **c** Type a digit less than 6.

All typed nondigits are ignored.

If you type a value greater than 5, this error message and prompt appear.

Invalid value specified

If you type an acceptable value, the Number of Repeats option on the Messages menu changes, and the Messages menu reappears.

- **d** If you get an error message, return to step **b**.
- e If you don't get an error message, return to step 3.
- 23 To <u>change</u> the time-between-repeats setting:

The Messages menu shows a value for how many <u>seconds</u> should elapse between EOT announcement repeats. Valid values range from 0 through 360.

```
[G] - Num EOT Repeats ..... 0
[H] - EOT Repeat Delay ..... 5 sec
[X] - Exit
```

a Select EOT Repeat Delay from the Messages menu.

This prompt appears.

EOT Repeat Delay message setting (default = 5 sec) Enter a value between 0 and 999:

If the new value has less than three digits, type leading zeros to make it three digits long <u>or</u> press **[Enter]** after typing one or two digits.

b To <u>not</u> change the value, press **[Esc]** <u>and</u> return to step **3**.

4.2.9 AEI Reader Parameters

The AEI reader parameters directly affect how the AEI readers operate to acquire tags while a train is passing the site.

To set or change any of the AEI reader parameters:

1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
[G] - Messages Settings
[H] - AEI Settings
[I] - Load Default Setup Parameters
```

2 Select AEI Settings to access menu options.

```
AEI Settings
[A] - ID Separation ..... 2 IDs
[B] - Consecutive Reads ..... 2 Reads
[C] - RF Frequency (MHz) ..... 915.000
[D] - RF Attenuation (dB) ..... 0
[E] - Multi-Track Tag Filter .. Disabled
[F] - AEI Reader Interface
[G] - Tag Reader Test
[H] - Antenna 0 Offset .. 0 inches (TO1)
[I] - Antenna 1 Offset .. 0 inches (TO1)
[X] - Exit
```

ID Separation specifies the number of intervening tags that must be read and reported before a given tag is reported again. Valid values are 1, 2, 3, and 4. The default is 2.

Consecutive Reads specifies the number of times that a tag must be read before it is considered a valid (reportable) tag. Valid values are 1, 2, 3, and 4. The default is 2.

MPRR Frequency specifies the transceiver frequency of the MPRR reader.

MPRR Attenuation sets the RF attenuation in 1 dB increments over a range of 10 dB from a maximum output of 2 W at 0-dB attenuation to a minimum of 200 mW output at 10-dB attenuation.

The **Multi-Track Tag Filter**, when enabled, uses firmware algorithms to filter crosstrack reads based on appended timestamps and tag data shared from adjacent readers.

The **AEI Reader Interface** allows for direct communication with the AEI reader and is used primarily for diagnostic purposes.

The Tag Reader Test allows the user to perform an on-sight functionality verification.

The **Antenna 0 Offset** specifies the distance in inches Antenna 0's read zone is from the center of the scanning gate.
The **Antenna 1 Offset** specifies the distance in inches Antenna 1's read zone is from the center of the scanning gate.

3 To <u>change</u> the **ID Separation** parameter:

Select the **ID Separation** option to toggle from 1 to 2, from 2 to 3, from 3 to 4, or from 4 to 1.

4 To change the **Consecutive Reads** parameter:

Select the **Consecutive Reads** option to toggle from 1 to 2, from 2 to 3, from 3 to 4, <u>or</u> from 4 to 1.

5 Select the **MPRR Frequency** setting to change the operating frequency.

This message appears.

Select a frequency: [A] - 903.750 MHz [B] - 911.500 MHz [C] - 915.000 MHz [D] - 918.500 MHz [E] - 921.500 MHz

Enter frequency selection. The AEI Reader Parameters menu reappears.

6 Select MPRR Attenuation to attenuate the RF output signal.

This message appears.

MPRR Attenuation AEI setting (default = 0) Enter a value between 0 and 10:

Enter a value "NN" (between 1 and 10), including leading zeros. This parameter sets the RF attenuation in 1 dB increments over a range of 10 dB from a maximum output of 2 W at 0 dB attenuation to a minimum of 200 mW output at 10 dB attenuation.

- 7 Select Multi-Track Tag Filter to toggle between Enabled and Disabled. When enabled, firmware algorithms are utilized to filter out cross-track reads.
- 8 To enter the AEI reader interface, select the option.

This message appears.

```
Entering AEI Reader Interface <Type EXIT to quit>
```

9 To <u>initiate</u> the **Tag Reader Test**, select the option.

This message appears.

The Tag Reader Test will allow you to wave a tag in front of the reader and the detector will produce an audible beep and print out the tag information. The detector will simulate a track circuit signal and energize the antennas. Afterwards the log will show a Train Canceled event. Are you sure you want to continue? (y/n)

During the Tag Reader Test, data from AEI tags passed through the RF field will be displayed beneath this prompt.

10 To set the Antenna Offset, select the option (Antenna 0 Offset or Antenna 1 Offset).

This message appears.

Antenna 0 gate offset setting (default = 0 inches) *** The OFFSET is the distance from the center of the scanning gate to the *** center of the AEI antenna read zone. Enter an OFFSET value from 0 to 240 inches:

Measure and enter the offset distance from the center of the scanning gate to the center of the antenna. If the measurement is other than zero, the following prompt will appear.

```
Is the Antenna closer to TO1 or TO2? (Current setting is TO1)
[1] - TO1
[2] - TO2
```

Enter the wheel sensor designator closest to the antenna (TO1 or TO2).

- **11** To leave the AEI reader interface:
 - a Type EXIT.
 - b Press [Enter].
- 12 To leave the AEI Reader Parameters menu and return to the Setup menu, type X.

This prompt appears.

Initialize Reader now (Y/N)

13 To initialize the reader, type Y.

The Setup menu reappears.

14 To not initialize the reader, type N.

The Setup menu reappears.

4.2.10 Units of Measure

To set or change any of the units-of-measure parameters:

- 1 Be sure that the Setup menu is displayed.
- 2 Go to the Units of Measure Menu.

A prompt like this appears.

Shown above are the parameters currently defined in the system. They define how the system will show the location, date, ambient temperature, speed, and length of train <u>in</u> the reports and how voice announcements are made.

Location is reported in either **Milepost** or **Kilometerpost** format. Select **Location** to toggle between what is shown and its other possibility.

Date is reported in either **English** or **Metric** format. Select **Date** format to toggle between what is shown and its other possibility.

Temperature is reported in either **Metric** (degrees Celsius (C)) or **English** (degrees Fahrenheit (F)). Select **Temperature** to toggle between what is shown and its other possibility. If you select <u>Metric</u>, the ambient temperature will be announced in Celsius. If you selected <u>English</u>, the ambient temperature will be announced in Fahrenheit.

Speed is reported in either **English** (miles per hour (mph)) or **Metric** (kilometers per hour (kph)). Select **Speed** to toggle between what is shown and its other possibility. If you select <u>English</u>, the speed of the train will be announced in miles per hour. If you selected <u>Metric</u>, the speed of the train will be announced in kilometers per hour.

Length of train is reported in either **English** (feet (ft)) or **Metric** (meters (m)). Select **Length** to toggle between what is shown and its other possibility. If you select <u>English</u>, the length of the train will be announced in feet. If you selected <u>Metric</u>, the length of the train will be announced in meters.

3 To leave the Units of Measure submenu and return to the Setup menu, type X.

4.2.11 Load Default Setup Parameters

An option to load default setup parameters is intended to assist installers in setting up a new system. When this menu item is selected, you will be prompted to load Canadian or US defaults. The parameters listed below are assigned. A "yes" after a parameter means that it is "enabled." A "no" means that it is "disabled."

Alarm Settings _____ Absolute..... 180 Differential..... 150 Cold Journal Counter..... 3 Hot Wheel..... 600 Cold Journal Temp..... 10 Cold Res Counter..... 3 Differential Enabled..... Yes Alarm Settings (Advanced) _____ Carside Slope..... 1.60 Carside Minimum..... 130 Res Test: Minimum Rail Avg..... 25 Res Test: Minimum Wheel Avg..... 28 Bearing DSR Capture Temp..... 50 Wheel DSR Capture Temp..... 150 Max Alarms..... 6 Equipment Settings _____ Dragger..... Yes Hot Wheel..... Yes High Load..... No Hot Bearing..... Yes Wide Load..... No AEI..... No Presence Hardware..... Yes Advance Transducers..... No AC Power Off Monitor..... Yes Equipment Settings (Advanced) _____ Carside Slope..... Yes Winter Cycle..... Oct - Mar Gate Distance..... 24.0 in Dragger Debounce Time..... 5 ms Pre Train Dragger Dist..... 200 ft Pre Train High/Wide Dist..... 0 ft Presence Timeout Period..... 10 sec System Voltage..... 12 V Resistor Test..... Enabled Clearance Mode..... Multiplexed Transducer Gain..... Normal Clearance Type..... Light Beam Transducer Type..... Magnetic Message Settings _____ Arrival Message..... No Customer Name..... Yes Axles..... Yes Speed..... No Temperature..... Yes Slow..... Yes Repeat No efects..... No Power Off..... Yes Length..... Yes Cars Count..... No Lft/Rt Alarm Ref..... No Car ID With Alarm..... Yes US Speech Options..... Yes Primary Language..... English_Matthew Secondary Language..... None Message Settings (Advanced) _____ Announce Differential..... Yes Announce Hot Wheels..... Yes Announce High Load..... Yes Announce Wide Load..... Yes Request EOT Timer..... 0 min Rebroad DTMF Code..... Num EOT Repeats..... 0 EOT Repeat Delay..... 5 sec .

•	
Network Settings	
Use Static Address	Static IP
Sunshots	
Sunshot Filter Disabled Latitude 35.0456	Scanner Orientation 0 Longitude
Weather Settings	
Barometric Pressure Sensor. Not Installed Wind Monitor Not Installed Display Wind Diagnostics No Slow Wind Speed Limit 2 mph Lower Interval Identical Limit 360 min Suspicious Temp. Interval 720 min Wind Alarm Reporting Interval 5 min	Altitude for Relative Pressure 0 ft High Wind Alarm Limit 50 mph Wind Poll Interval 15 sec Upper Interval Identical Limit 30 min Wind Gust Interval 5 min Re-enable Wind Updates 10 min
Port Settings	
COM1 (Serial Interface) Baud 19200 None COM3 (Velocity) Baud 19200 None COM5 (AEI) Baud 19200 None RS485 (Not Used) Baud 9600 None	COM2 (Not Used) Baud 19200 None COM4 (Not Used) Baud 19200 None COM6 (FlashHost) Baud 57600 None Page Lines 30
AEI Settings	
Tag Reader Type None Consecutive Reads 2 RF Attenuation (dB) 0 Antenna 0 Offset 0 (TO1)	ID Separation
Units Of Measure Settings	
Location Milepost Speed English Length English	Date Format English Temperature English
Scanner Calibration Date / Digital Potention	
Rail 1 Type III 05/16/2022 11:22 / 41 Wheel 1 Type III 04/28/2022 09:09 / 41	Rail 2 Type III 04/28/2022 09:07 / 40 Wheel 2 Type III 04/28/2022 09:11 / 42
Resistor Baseline	
Rail 1 Type III Valid Wheel 1 Type III Valid	Rail 2 Type III Valid Wheel 2 Type III Valid

To load the default setup parameters:

1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.

```
[I] - AEI Settings
[J] - Units Of Measure Settings
[K] - Load Default Setup Parameters
[L] - COM Port Settings
```

2 Select Load Default Setup Parameters.

This menu appears:

```
Load Defauts:
[1] - Canadian
[2] - US
[3] - Exit
```

Select either Canadian or US defaults. This prompt appears.

3 To not load default setup parameters:

Туре **N**.

4 To load default setup parameters:

Type Y.

This message appears.

```
This will save the settings.
Please type 'setup' to save settings.
Press escape to abandon changes.
```

Loading takes about a second. When finished, a prompt like this appears.

```
Saving settings
Settings saved
```

4.2.12 COM1, COM2, COM3, COM4, COM6, & RS485

To change the parameters for serial port COMx:

1 Be sure that the Setup menu is displayed.

The Setup menu looks like this.



2 Select the COM Port Settings submenu to view options.

```
COM Port Settings

[A] - COM1 (Serial Interface) 19200 None

[B] - COM2 (Not Used)..... 19200 None

[C] - COM4 (Not Used)..... 19200 None

[D] - COM6 (FlashHost).... 57600 None

[E] - RS485 (Not Used).... 9600 None

[F] - Page Lines .... 30

[X] - Exit
```

3 Select the **COMx** option to edit current settings.

```
Uart Settings

[A] - Baud Rate ..... 19200

[B] - Flow Control ..... None

[X] - Exit
```

- 4 Select **Baud Rate** to incrementally step through the selection options. Available settings are: 150, 300, 600,1200, 2400, 4800, 9600, 19200, 38400, 57600, and 115200.
- **5** Select **Flow Control** to incrementally step through the selection options. Available settings are None, HW (hardware), and SW (software).
- 6 The **Page Lines** parameter defines the number of lines the Serial Interface outputs before pausing and asking whether the user wants to continue, abort, etc. Setting this parameter to zero disables paging (reports print in their entirety without pausing).
- 7 To leave the COM Port Settings menu and return to the Setup menu, type X.

4.2.13 Network Settings

To change the Network Settings:

1 Be sure that the Setup menu is displayed.

The Setup Menu looks like this.

```
[M] - Network Settings
[N] - Velocity ..... Enabled
[O] - GO Train Detect ..... No
[P] - Weather Settings
[X] - Exit
```

2 Select the Network Settings menu.

A menu and prompt like this appears. To access/change any of the menu options, type the letter that corresponds to the desired setting.

```
Network Settings
[A] - IP Settings
[B] - Use Wifi ..... No
[C] - Wifi Inactivity Timeout ... 10 min
[D] - HTTP Port ..... 80
[E] - HTTPS Port ..... 8080
[F] - FTP Port .... 21
[G] - TELNET Port .... 23
[H] - Load Default Network Settings
[I] - Ping
[X] - Exit
```

WARNING: Changes to any of the SmartScanNG² network settings **will not take effect** until after the system has been restarted. Before restarting the system, be certain that all changes have first been saved. After making any changes, you will be prompted to type in the word "setup" when you exit the Network Settings menu. This will save any changes made.

3 IP Settings – This option provides a menu through which you can customize the IP parameters of SmartScanNG²'s external Ethernet connection.

To view or change SmartScanNG²'s IP settings, select the <u>IP Settings</u> option. The SmartScanNG² will display the following menu:

IP Settings
[A] - Use Static Address No
[B] - Static IP 192.168.1.201
[C] - Static Mask 255.255.255.0
[D] - Default Gateway 192.168.1.1
[E] - DNS Server 192.168.1.1
[X] - Exit

Use Static Address This parameter specifies whether the SmartScanNG² uses its configured Static IP address for external Ethernet communications (Yes), or retrieves its external IP address from a DHCP server (No).

Static IP This parameter specifies the IP address to use to connect to the SmartScanNG² when the Use Static Address option is set to Yes.

Static Mask This parameter specifies the subnet mask to use when the Use Static Address parameter is set to Yes.

Default Gateway This option specifies the address of the remote server/router through which communications with the SmartScanNG² will be routed.

DNS Server This parameter specifies the Domain Name Server that the SmartScanNG² can use for lookup services.

- 4 Use Wifi This option enables or disables WiFi functionality.
- 5 Wifi Inactivity Timeout The default setting is 10 min. Enter a value from 0 to 30.
- 6 HTTP Port This parameter is used to specify the TCP port number for SmartScanNG²'s HTTP interface. This is the interface/port through which the SmartScanNG² serves its Web page interface.
- **7 HTTPS Port** This parameter is used to specify the port number for SmartScanNG²'s secure HTTP interface.
- 8 **FTP Port** This parameter is used to specify the TCP port number that SmartScanNG² uses for communication via the FTP protocol.
- **9 TELNET Port** This parameter specifies the TCP port number that the SmartScanNG² uses for communication via the Telnet protocol. The SmartScanNG²'s serial-based menus are available through this port and protocol.

10 Load Default Network Settings. To set the SmartScanNG²'s network parameters to their default configuration, select the <u>Load Default Network Settings</u> option from the Network Settings menu

This option presents a warning message and requires a Y/N confirmation before changing the parameters. Answering 'N' abandons the changes. Answering 'Y' proceeds to the

standard prompt requiring the "setup" password to save the changes.



```
SmartScanNG<sup>2</sup> Default Network Settings
HTTP port 80
HTTPS port 8080
FTP port 21
TELNET port 23
External Ethernet Default Settings
Use static address Yes
Static IP 192.168.9.191
Static mask 255.255.0
Default gateway 192.168.9.1
DNS Server 192.168.9.1
```

11 Ping. The Ping option provides for testing the ability to communicate across an Ethernet network.

A successful Ping attempt will look like this:

```
Enter an IP to ping: 10.14.22.150
Pinging '10.14.22.150'... Success! (Response took 0 ticks.)
```

An unsuccessful Ping attempt will look like this:

```
Enter an IP to ping: 10.14.22.250
Pinging '10.14.22.250'... Failed!
```

4.2.14 Velocity Settings

To change the Velocity setting:

1 Be sure that the Setup menu is displayed.

The Setup Menu looks like this.

```
[M] - Network Settings
[N] - Velocity ..... Enabled
[O] - GO Train Detect ..... No
[P] - Weather Settings
[X] - Exit
```

2 Select the menu option to change Velocity Mode. A prompt like this appears.

```
Select Velocity Mode:
[1] - Disabled
[2] - Enabled
```

4.2.15 GO Train Detect

To change the GO Train Detect setting:

1 Select GO Train Detect to change the current setting:

The Equipment menu shows whether the **GO Train Detection option** is enabled (YES) or disabled (NO). This option, when enabled, inhibits the broadcasting of hotbox alarms when a train's consist has been identified as a GO Transit train. The AEI Interface module and associated equipment are required for this option to function correctly.

If the **AEI option** on the Equipment menu is set to **YES**, the status of the GO-train-detection setting changes. The status of the GO-train-detection setting toggles from YES (active) to NO (inactive) <u>or</u> from NO to YES, depending upon the current status of the option.

If the **AEI option** on the Equipment menu is set to **NO**, the status of the GO-train-detection setting does <u>not</u> change, <u>and</u> this message appears.

```
AEI is required for GO Train functionality
```

2 After the above message appears, the Setup menu reappears.

4.2.16 Weather Settings

Select the Weather Settings option to change the settings:

```
[M] - Network Settings
[N] - Velocity ..... Enabled
[O] - GO Train Detect ..... Yes
[P] - Weather Settings
[X] - Exit
```

1 The Weather Settings menu appears.

```
Weather Settings
_____
              _____
[A] - Barometric Pressure Sensor ..... Not Installed
[B] - Altitude for Relative Pressure ..... Oft
[C] - Wind Monitor ..... Not Installed
[D] - High Wind Alarm Limit ..... 50 mph
[E] - Display Wind Diagnostics ..... No
[F] - Wind Poll Interval ..... 15 sec
[G] - Slow Wind Speed Limit ..... 2 mph
[H] - Lower Interval Identical Limit ..... 360 min
[I] - Upper Interval Identical Limit ..... 30 min
[J] - Wind Gust Interval ..... 5 min
[K] - Suspicious Temp. Interval ..... 720 min
[L] - Re-enable Wind Updates ..... 10 min
[M] - Wind Alarm Reporting Interval ..... 5 min
[X] - Exit
```

- 2 Select **Barometric Pressure Sensor** to toggle the setting between Installed (enabled) and Not Installed (disabled).
- **3** The **Altitude for Relative Pressure** setting represents the elevation above sea level. Select this menu option to change the setting:

```
Altitude for Relative Pressure
[A] - Maple Creek 10.5 (2496)
[B] - Maple Creek 32.2 (2545)
[C] - Maple Creek 54.4 (2559)
                       (2537)
[D] - Maple Creek 79.3
[E] - Maple Creek 99.6 (2518)
[F] - Maple Creek 120.8 (2477)
[G] - Maple Creek 134.6 (2416)
[H] - Swift Current 12.0 (1823)
[I] - Swift Current 30.9 (2029)
[J] - Swift Current 49.5 (2227)
[K] - Swift Current 69.3 (2358)
[L] - Swift Current 95.7 (2365)
[M] - Absolute Pressure (0)
[N] - Other
```

Select from the options available or select Other to enter an alternative setting.

```
Altitude for Relative Pressure setting (default = 0 ft)
Enter a value from 0 to 12000:
```

- 4 Select **Wind Monitor** to toggle the setting between Installed (enabled) and Not Installed (disabled).
- **5** The **High Wind Alarm Limit** is a wind speed (in MPH) at or above which the detector flags a high wind alarm. Select High Wind Alarm Limit to change the setting:

```
High Wind Alarm Limit setting (default = 50 mph)
Enter a value from 30 to 80:
```

6 Select Display Wind Diagnostics to toggle the setting between Yes (enabled) and No (disabled). When enabling diagnostic output, the firmware prompts the user whether to disable output automatically. Pressing 'Y' or 'y' starts a thirty-minute timer and displays a corresponding message. (Note that the diagnostics do not begin until the user types "setup" to save the Setup change.) Pressing 'N' or 'n' at the prompt enables the diagnostics indefinitely and produces a "Wind diagnostics enabled indefinitely" message. Pressing ESC is the same as pressing 'N.' When limiting the diagnostics to thirty minutes, a "Wind Diagnostics Automatically Disabled!" message posts to the screen and into the Event Log when their output ceases.

```
Automatically disable diagnostics after 30 minutes? (Y/N) Wind diagnostics enabled for 30 minutes.
```

7 Select **Wind Poll Interval** to modify the time interval (in seconds) at which the detector polls the wind monitor for new wind data.

```
Wind Poll Interval setting (default = 15 sec)
Enter a value from 1 to 30:
```

The detector contains logic for flagging errors if a wind monitor reports identical wind speed or wind direction readings for a specified interval. This logic uses the below three parameters. The **Slow Wind Speed Limit** parameter defines (in MPH) a wind speed considered slow for the site in question. For wind speeds below the Slow Wind Speed Limit value, if the wind monitor reports a constant wind speed or wind direction value for the time interval defined by the **Lower Interval Identical Limit** (in minutes), the detector flags a corresponding error (speed or direction). For wind speeds equal to or above the Slow Wind Speed Limit value, if the wind monitor reports a constant wind speed or wind direction value for the time interval to speed the time interval defined by the **Lower Interval Identical Limit** (in minutes), the detector flags a corresponding error (speed or direction). For wind speeds equal to or above the Slow Wind Speed Limit value, if the wind monitor reports a constant wind speed or wind direction value for the time interval defined by the **Upper Interval Identical Limit** (in minutes), the detector flags a corresponding error (speed or direction).

8 Select Slow Wind Speed Limit to modify the setting (in miles per hour).

```
Slow Wind Speed Limit setting (default = 2 mph)
Enter a value from 0 to 5:
```

9 Select Lower Interval Identical Limit to modify the setting (in minutes).

```
Lower Interval Identical Limit setting (default = 360 min)
Enter a value from 10 to 600:
```

10 Select **Upper Interval Identical Limit** to modify the setting (in minutes).

```
Upper Interval Identical Limit setting (default = 30 min)
Enter a value from 10 to 60:
```

11 A wind gust is a continuous record of the highest wind speed recorded during a defined time interval. The Wind Gust Interval parameter defines this time interval (in minutes). For example, if the Wind Gust Interval is five minutes, the wind gust value records the highest wind speed reported during the previous five minutes. Select Wind Gust Interval to modify the setting (in minutes).

```
Wind Gust Interval setting (default = 5 min)
Enter a value from 3 to 10:
```

12 Suspicious Temp. Interval: This parameter functions like the Lower Interval Identical Limit and Upper Interval Identical Limit parameters described above but for the temperature probe instead of the wind monitor. If the temperature probe reports a constant temperature value for the time interval defined by the Suspicious Temp. Interval parameter (in minutes), the detector flags a failure error for the probe. Select Suspicious Temp. Interval to modify the setting (in minutes).

```
Suspicious Temp. Interval setting (default = 720 min)
Enter a value from 10 to 720:
```

13 Re-enable Wind Updates: Time interval (in minutes) that must elapse after a train stops on the site before the detector again begins polling the wind monitor for data. When a train enters the site, the detector stops polling the wind monitor until either the train clears the site or it stops on the site, and this time interval elapses. Select **Re-enable Wind Updates** to modify the setting (in minutes).

```
Re-enable Wind Updates setting (default = 10 min)
Enter a value from 1 to 15:
```

14 Wind Alarm Reporting Interval: Time interval (in minutes) defining how often a detector repeats reporting an existing high wind alarm. Once a high wind alarm occurs, the detector repeats reporting the alarm's existence at this interval as long as the alarm condition exists. Select Wind Alarm Reporting Interval to modify the setting (in minutes).

```
Wind Alarm Reporting Interval setting (default = 5 min)
Enter a value from 2 to 15:
```

4.3 System Functions Menu

To execute one or more system functions:

1 Be sure that the Main menu is displayed.

The Main menu looks like this.

```
[I] - Setup
[J] - Event log
[K] - System Functions Menu
[L] - Replay train
[M] - Security Menu
[X] - Exit
```

•

2 Select the System Functions menu.

A menu and prompt like this appears. To access any of the System Functions menu options, type the letter that corresponds to the desired menu option.

```
System Functions Menu
_____
[A] - Radio Test
[B] - Vocabulary Test
[C] - Radio Inhibit
[D] - Start Manual Train
[E] - 1KHz Test Tone
[F] - Auto-Calibration
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[J] - Update Menu
[K] - Maintenance Menu
[L] - Volume Up (3)
[M] - Volume Down (3)
[N] - Resistor Baseline Data
[0] - Radio Programming Menu
[P] - Scanner Test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual Gate Test
[X] - Exit
```

If a train is at the site when the System Functions menu is generated, "*** **Train Is Present** ***" is displayed just above the menu header for the System Functions menu. During that time, if you select any item on the System Functions menu, you will be prompted with "**Train Is Present. Continue?**" You must type **Y** to continue. Note that most items on the Systems Functions menu should <u>not</u> be performed while a train is present at the site.

- 3 To leave the System Functions menu and return to the Main menu:
 - **a** Type **X**. The Main menu reappears.

- **b** Skip the remaining steps.
- 4 To execute the radio test:

The Radio Test option is used to broadcast a short message through the speaker and through the radio. Using this option lets you verify that the speaker and radio are working properly.

At single-track sites, the text of the message is "Testing, CP Detector, milepost, (*milepost number*), testing, one, two, three, four, five, four, three, two, one, testing." At double-track sites, the text of the message is "Testing, CP Detector, milepost, (*milepost number*), track (*track designation*), testing, one, two, three, four, five, four, three, two, one, testing."

```
System Functions Menu

[A] - Radio Test

[B] - Vocabulary Test

[C] - Radio Inhibit
```

a Select Radio Test from the System Functions menu.

If the system isn't currently making any other voice announcements, it begins the Radio Test announcement. After the announcement finishes, the System Functions menu reappears.

If the system is currently making a voice announcement, the firmware displays the message "System Is Currently Making Voice Announcements! Try Again Later" and redisplays the System Functions menu.

b While listening to the message, look at the PTT LED on the display panel.

The PTT LED should be lit.

If this LED isn't lit, the system's ability to send a message to the radio might be inhibited by the Radio Inhibit option on the System Functions menu. If the radio is inhibited, the results of this check are invalid.

c Return to step 3.

5 To execute the vocabulary test:

The Vocabulary Test option is used to enunciate all stored speech phrases. This announcement is broadcast through the speaker but <u>not through</u> the radio. Therefore, it isn't affected by the Radio Inhibit option being enabled.

The text of the message is "zero, one, two, three, four, five, six, seven, eight, niner, not-working, *beep*, CP Detector, milepost, main-3, system-working, no-defects, main-1, main-2, rebroadcast, hotwheel, defect, axle, dragging-equipment-near, north, south, rail, east, west, track, car-I-D, no, hotbox, high-wide, near, you-have-a-defect, testing, train too slow, total axles, speed, temperature, length, minus, point, middle, high-load, wide-load, power-off, excess-alarms, repeat, total-cars, detector-out, A, B, C, D, E, F, G, H, I, J, K, L, M, N, O, P, Q, R, S, T, U, V, W, X, Y, Z, first, second, third, fourth, left, right, side, load, scanner resistor test, beginning in, minutes."

```
System Functions Menu

[A] - Radio Test

[B] - Vocabulary Test

[C] - Radio Inhibit
```

a Select Vocabulary Test from the System Functions menu.

If the system isn't currently making any other voice announcements, it begins the Vocabulary Test announcement. After the announcement finishes, the System Functions menu reappears.

If the system is currently making a voice announcement, the firmware displays the "System Is Currently Making Voice Announcements! Try Again Later" message and the System Functions menu reappears.

- b Return to step 3.
- 6 To execute the radio inhibit:

The Radio Inhibit option is used to prevent radio activation for three minutes. During this time, any announcements generated by the system are broadcast through the speaker but not through the radio. This feature may be overridden by recalling this submenu and then typing \mathbf{N} .



a Select Radio Inhibit from the System Functions menu.

This prompt appears.

PTT disabled for 3 minutes

b Select Re-enable radio PTT to disable Radio Inhibit.

```
System Functions Menu
[A] - Radio Test
[B] - Vocabulary Test
[C] - Re-enable radio PTT
```

- c Return to step 3.
- 7 To initiate the Start Manual Train function:

In Manual Train Mode, the system opens all the shutters and simulates transducer pulses for about one minute. During this time, a person can check various aspects of the installed components. In this mode, the system runs the ramp function without generating heats. The train is marked as a test train. There won't be any voltage applied to the scanner inputs.

This is a timed test that should gate approximately 164 simulated axles. You can stop this test by selecting the Stop Manual Train option.

The data generated for this test train is stored in the Test Train directory, which contains data on the last test train only. The Last Test Train report gets its data from this directory.

```
System Functions Menu

[A] - Radio Test

[B] - Vocabulary Test

[C] - Radio Inhibit

[D] - Start Manual Train

[E] - 1KHz Test Tone
```

a Select Start Manual Train from the System Functions menu.

This prompt appears.

Train Arrival

There will be an arrival message broadcast through the speaker only. During test train, the TO1 & TO2 LEDs on the Display Panel will flash with each simulated axle.

After about a minute, this prompt appears and the post train announcements will be broadcast over the speaker.

Train Departure

- **b** Return to step **3**.
- 8 To generate the 1KHz test tone:

The 1KHz Test Tone option is used to generate a continuous 1KHz tone for about 5 seconds. This test tone is broadcast through the speaker and through the radio.

a Select 1KHz Test Tone from the System Functions menu.

If the system isn't currently making any other voice announcements, it begins the tone.

If the system is currently making a voice announcement, the firmware displays the message "System Is Currently Making Voice Announcements! Try Again Later" and redisplays the System Functions menu.

b While listening to the tone, look at the PTT LEDs on the display panel.

The **PTT LED** should be lit.

If this LED isn't lit, the system's ability to send a tone to the radio might be inhibited by the Radio Inhibit option on the System Functions menu. If the radio is inhibited, the results of this check are invalid.

- c Return to step 3.
- 9 To start Auto-Calibration:

The SmartScanNG² system self-calibrates its pyrometer interface circuitry. You need only put a preheated calibrated heat source on a scanner <u>and</u> place the system in autocalibration mode by using the Auto-Calibration option. The system then scans all pyrometer inputs until the signal from the calibrated heat source is located. The necessary adjustments to the related interface circuitry are automatically made while the system monitors its own progress by analyzing changes in the heat signals. Once the procedure has been completed, autocalibration mode is disengaged, and the calibration results are displayed on your computer. For more details, see **Appendix F** & G - Calibration of Type II/Type III Scanners.

- a Place a preheated calibrated heat source on the scanner to be calibrated.
- **b** Select **Auto-Calibration** from the System Functions menu.

The SmartScanNG² system will now calibrate the channel associated with the scanner on which the heat source has been placed. Follow along on your interface screen until you see "Auto-Calibration Disengaged." This message is an indication that the system is done with the calibration procedure. To abort the process, press **[Esc]** (on your computer) or remove the heat source (from the scanner).

c When "Auto-Calibration Disengaged" is displayed on your computer, remove the calibrated heat source.

Upon completion of autocalibration, the system acquires the scanner resistor temperature baseline values. The process begins with a 20-minute wait period in which the resistors are allowed to cool down. The system counts down during this period, sounding a tone each minute. After the 20-minute cooldown period, the system opens and closes the shutters for a period of 8 minutes.

d Return to step 3.

10 To force a system reset:

The Remote System Reset option allows you to force a system reset through a remote connection. It can also be used locally.

a Select **Remote System RESET** from the System Functions menu.

This prompt appears.

Remote System RESET Are you sure? (y/n)

- **b** To not reset the system:
 - Type N.

The System Functions menu reappears.

- Return to step 3.
- **c** To reset the system, type **Y**.

This message appears.

```
Restarting in 2 seconds
Waiting 2sec to start 'A' to abort
Configured IP = 0.0.0.0
Configured Mask = 0.0.0.0
MAC Address= 00:03:f4:08:8c:fe
Comm is booting...
Starting telnet task on port 23... running.
The system has finished booting.
```

After a few seconds, the Main menu reappears.

d Return to step 3.

11 To delete all stored train data:

The Delete All Stored Train Data option allows you to erase all stored train data. This encompasses all data on the trains in the Trains directory, Exceptions directory, and Test Train directory. After deleting all the train data, there isn't any way of regenerating it. The data is gone forever.

```
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[K] - Update Menu
```

a Select Delete All Stored Train Data from the System Functions menu.

This prompt appears.

Are you sure? (y/n)

- **b** To not delete all stored train data:
 - Type N.

The System Functions menu reappears.

- Return to step 3.
- **c** To delete all stored train data, type **Y**.

This message appears.

Train data cleared.

d Return to step **3**.

12 To delete all events stored in the Event Log:

The Clear Event Log option is used to erase all events stored in the Event Log and displayed on the Event Log report. After deleting the log, there isn't any way of regenerating it. The data is gone forever.

[G] - Reboot System [H] - Delete All Stored Train Data [I] - Clear Event Log [K] - Update Menu .

a Select Clear Event Log from the System Functions menu.

This prompt appears.

Are you sure? (y/n)

- **b** To not delete all events stored in the Event Log:
 - Type N.

The System Functions menu reappears.

- Return to step 3.
- **c** To delete all events stored in the Event Log, type **Y**.

The System Functions menu reappears.

d Return to step 3.

13 Update Menu:

```
.
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[K] - Update Menu
```

a Select **Update Menu** from the System Functions menu.

This prompt appears.

```
Update Menu
[A] - Select Update File
[X] - Exit
```

b Choose the **Select Update File** from the Update Functions menu.

This prompt appears.

```
Select update file:
[A] - CP_00-00.ng
[B] - CP_01-00.ng
```

d Select the appropriate file from the menu options.

14 To view the maintenance menu:

.

	•
	•
[K] -	Maintenance Menu
[L] -	Volume Up (3)
[M] -	Volume Down (3)
[N] -	Resistor Baseline Data
[0] -	Radio Programming Menu
[P] -	Scanner Test
[Q] -	Calibrate Frauscher Transducers
[R] -	Virtual Gate Test
[X] -	Exit

Select the Maintenance Menu from the System Functions menu.

A prompt like this appears.

Maintenance Menu
[A] - View Maintenance Statistics
[B] - Reset System Health
[C] - Re-evaluate Last 40 Trains.
[D] - Maintenance Email List
[X] - Exit

15 To view maintenance statistics:

Select the View Maintenance Statistics option from the maintenance menu.

Information like this is displayed.

Metric (per day)	percent change	Wei	ghted value	Limit	Problem	
Number of Trains	0	(0.000000)	0	No	
Low Miscount	0	(0.000000)	50	No	
High Miscount	0	(0.000000)	50	No	
Average Temperature 0	0	(0.000000)	50	No	
Average Temperature 1	0	(0.000000)	50	No	
Average Temperature 2	0	(0.000000)	50	No	
Average Temperature 3	0	(0.000000)	50	No	
Cold Rail O	0	(0.000000)	50	No	
Cold Rail 1	0	(0.000000)	50	No	
Cold Rail 2	0	(0.000000)	50	No	
Cold Rail 3	0	(0.000000)	50	No	
Average miscount	0	(0.000000)	0	No	
Average voltage percentage	0	(0.000000)	0	No	

16 To reset system health:

```
Maintenance Menu
[A] - View Maintenance Statistics
[B] - Reset System Health
[C] - Re-evaluate Last 40 Trains.
[D] - Maintenance Email List
[X] - Exit
```

a Select **Reset System Health** from the Maintenance menu.

A prompt like this appears.

Are you sure? (y/n)

- **b** To not reset system health:
 - Type **N**.

The Maintenance Menu reappears.

c To reset system health, type **Y**. This prompt appears.

System health cleared

The Maintenance Menu reappears.

17 To Re-evaluate Last 40 Trains:

```
Maintenance Menu

[A] - View Maintenance Statistics

[B] - Reset System Health

[C] - Re-evaluate Last 40 Trains.

[D] - Maintenance Email List

[X] - Exit
```

a Select Re-evaluate Last 40 Trains from the Maintenance menu.

The Maintenance Menu reappears.

18 To access Maintenance email list:

```
Maintenance Menu

[A] - View maintenance statistics

[B] - Reset System Health

[C] - Maintenance email list

[X] - Exit
```

a Select Maintenance email list from the Maintenance menu.

A prompt like this appears.

```
Maintenance email list

[A] - user@southern-tech.com

[P] - New email address

[X] - Exit
```

- **b** Select **New email address** to add a new address or select an existing address to edit or delete from the list.
- **c** Type X to return to the Maintenance menu.
- **19** To adjust speaker volume:



There are ten selectable volume levels (0-9). Level-0 is the minimum volume, and Level-9 is the maximum volume. The current volume setting is indicated in parentheses.

- **a** From the System Functions menu, select **Volume up** to increment the current volume level or **Volume down** to decrement level.
- **b** Return to step **3**.
- 20 To view Resistor Baseline Data:

```
[N] - Resistor Baseline Data
[O] - Radio Programming Menu
[P] - Scanner Test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual Gate Test
[X] - Exit
```

a Select **Resistor Baseline Data** from the System Functions menu. Data like this appears.

Resistor Data VOLTS AMB DATE TIME STATUS 30 40 50 60 70 80 90 100 110 120 130 Offset 140 160 180 200 220 240 260 280 300 320 340 360 380 400 420 440 460 480 _____ Rail 1 (Type III) 13.4 56 05/16/22 11:49 VALID 172,174,178,178,180,182,183,186,187,189,190 192,194,199,200,206,205,210,214,217,219,222,225,228,232,235,238,241,244 0 Rail 2 (Type III) 13.0 56 04/28/22 09:26 VALID 205,208,209,212,214,215,217,220,221,224,226 227, 231, 236, 240, 244, 248, 251, 256, 260, 263, 267, 271, 275, 279, 283, 288, 292, 296 1 Wheel 1 (Type III) 13.0 56 04/28/22 09:26 VALID 316,317,318,318,324,322,326,331,332,334,338 339, 342, 347, 354, 358, 362, 366, 371, 378, 381, 385, 390, 395, 399, 404, 409, 414, 418 15 Wheel 2 (Type III) 13.0 56 04/28/22 09:26 VALID 328,330,332,334,335,337,343,345,346,350,350 351, 357, 361, 367, 372, 376, 381, 384, 389, 393, 398, 403, 407, 412, 416, 421, 425, 430 0

b Return to step **3**.

21 To access Radio Programming Menu:

On the Systems Functions menu is the Radio Programming Menu. This menu includes submenus that allow you to select active radio channels, program the operating frequencies, adjust audio deviation levels, and select carrier detect levels. Programming is available only for Ritron DTX radios. When using the model 2300-375 Dual-Track Interface, the Ritron DTX radio is programmable from the Track-1 SmartSCAN NG² Defect Detector.

```
[0] - Radio Programming Menu
[P] - Scanner test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual Gate Test
[X] - Exit
```

Select Radio Programming Menu from the System Functions menu.

For Ritron radios, a menu like this appears (the displayed values are the defaults).

```
Identifying radio type... ...
                        . . .
Reading radio data... ...
                    ... ...
                              . . .
SmartSCAN NG2, MP/KP:0001.2, Track:Single
03/19/2023 13:41:27, 24.5V, 54°F
DTX-160
                      Firmware version: 1.05
Radio Programming Menu
                           Transmit Receive
_____
[A] - Channel 1..... 160.320 160.320
[B] - Channel 2..... 160.410
                                 160.410
[C] - Channel 3..... 160.515
                                  160.515
[D] - Channel 4..... 160.470 160.470
[E] - Channel 5..... 160.785 160.785
[F] - Channel 6..... 160.830 160.830
[G] - Channel 7..... 160.875 160.875
[H] - Channel 8..... 161.550 161.550
[I] - Carrier Detect On/Off (-dBm) ..... 110.0 / 115.0
[J] - Current channel ..... 1
[X] - Exit
```

Note: The radio menu cannot be accessed unless a Ritron DTX radio is plugged into the internal radio connector.

Radio Frequency Setup

The transmit and receive frequencies can be programmed for each of the eight available channels. Select the channel number to change its frequency designations. A prompt like this will appear.

```
Transmit Receive

Transmit Receive

Channel 1 - 160.515 160.515

Enter new transmit frequency (###.###): 160.515

Enter new receive frequency (###.###): 160.515

Radio will not be programmed until you leave the menu and save

settings.

Enter new receive frequency (###.###):
```

Input format **###.###** where '#' may be 0-9. Include leading and trailing zeroes. These values must be between 160.215 and 161.565. Once you have made your changes, you must exit the radio menu and the equipment menu and save the settings. The radio will then begin programming the new frequencies. If you attempt to enter the Radio Frequency Menu when the radio is not plugged in or is not responding, you will receive the message "Radio channels not available, radio not responding." You can also check to see if the Radio is not responding by looking at the System Status Report under System Warnings. After booting up, the system takes about a minute to recognize the radio.

Carrier Detect On/Off Level

The CD (Carrier Detect) LED is an indication that the system is experiencing radio traffic. It operates similarly to squelch. If the CD LED is lit when there is no activity on the frequency, then it is recommended that the sensitivity be reduced by changing the Carrier Detect On and Off levels. The factory default settings are 110 -dBm for carrier detect on, and 105 -dBm for carrier detect off. These settings rarely need to be adjusted and should be done so only by a qualified radio technician. For proper operation, the carrier detect on value should always be <u>higher</u> than the carrier detect off value. The difference between the two values represents the squelch hysteresis and is used to prevent squelch chatter when the received signal is near the squelch setting values. Typical hysteresis should be 5 dB.

Select Carrier Detect ON/OFF, and a prompt like this will appear.

```
The default value for Carrier Detect On is 110.0 (-dBm)
Enter new Carrier Detect On (-dBm) value between 060.0 and 127.0 (###.#):
```

Select **Current Channel** to activate the desired channel, and a prompt like this will appear.

Select a channel: [A] - Channel 1 [B] - Channel 2 [C] - Channel 3 [D] - Channel 4 [E] - Channel 5 [F] - Channel 6 [G] - Channel 7 [H] - Channel 8 [I] - Hardware control 22 To initiate the Scanner Test:

```
[O] - Radio Programming Menu
[P] - Scanner test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual Gate Test
[X] - Exit
```

The scanner test function allows you to verify scanner accuracy. Place a calibrated heat source over a scanner's aperture and initiate the test. The detector will scan and display the temperature.

Select Scanner Test from the System Functions menu.

Test results like these appear.

```
East rail bearing scanner pot: 75
West rail bearing scanner pot: 72
The test will time out after 10 minutes
You can end the test early by pressing any key.
Beginning test...
East bearing West bearing
180 3
```

23 To perform a Calibrate Frauscher Transducers:

```
[P] - Scanner test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual gate test
[X] - Exit
```

a Select Calibrate Frauscher Transducers from the System Functions menu.

A prompt like this appears.

```
Which transducer?
[A] - Transducer 1
[B] - Transducer 2
[C] - Both
```

Select a transducer (or both) to initiate calibration.

```
Are you sure? (y/n)
Sending calibration signal...
Calibration started, please wait up to 60 seconds...
Calibration complete
Transducer 1: Success
```

b Type any key to return to the System Functions menu.

24 To perform a Virtual gate test:

```
[P] - Scanner test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual gate test
[X] - Exit
```

a Select Virtual gate test from the System Functions menu.

A prompt like this appears.

```
Select a scanner:
[1] - East Rail
[2] - West Rail
[3] - East Wheel
[4] - West Wheel
```

Select a scanner to initiate the test.

```
Are you sure? (y/n)
You have 2 minutes to test.
Test running, press any key to abort the test...
```

While in Virtual Gate Test Mode, the goal is to simulate a wheel that passes over the gating transducers and then continues moving to the scanner under test. The system notifies you when the simulated wheel is in the virtual gate area by cycling the shutters. The following steps describe how to use the Virtual Gate Test Mode.

- From the Virtual Gate Test Mode menu, select a scanner in which you want to see its Virtual Gate position.
- Swipe across the Gating Transducers with a metal object in the direction of the scanner under test. Maintain a speed faster than 1.6 seconds between sensors.
- Swipe across the sensors again. However, this time continue moving the metal object to the scanner under test while maintaining a constant speed.

- The shutters rapidly cycle one time to indicate when the system is looking for heat in the virtual window located at the scanner, which should be at the time that the metal object (simulated axle) passes the scanner. *If the shutters do not cycle, the entry for the closest transducer (TO1 or TO2) may be incorrect.*
- Simulating various axle speeds, repeat as needed to confirm settings.

The test mode runs for two minutes before timing out. Otherwise, any keypress ends the session. Rapid shutter flutter is an indication that two minutes have expired and the test has ended automatically. The event log records a canceled train at the end of the testing session.

b Type any key to return to the System Functions menu.

4.4 Replay Train Announcement

The Replay Train option provides a means for playing the messages that were broadcast as a train passed a site through the SmartScanNG²'s speaker and/or for displaying the text for those messages in the user's terminal.

To replay the train announcement for a given train:

1 Be sure that the Main menu is displayed.

The Main menu looks like this.

```
SmartSCAN NG2, MP/KP:1234.5, Track:North
Subdivision: None
05/02/2023 14:12:59, 11.8V, 93°F
Main Menu - Comm
_____
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event Log
[K] - System Functions Menu
[L] - Replay Train
[M] - Security Menu
[X] - Exit
```

2 Select Replay train.

This prompt appears.

Enter train number:

3 Type the train number.

If you typed a three-digit valid train number, you'd hear the EOT announcement through the speaker.

4 If you typed one or two digits, press [Enter].

If the typed train number is valid, pressing [Enter] produces the announcement.

4.5 System Security

This menu is only available during the initial setup or when logged in with an administrative password.

To view or change system security settings:

Be sure that the Main menu is displayed.

The Main menu looks like this.

```
SmartSCAN NG2, MP/KP:1234.5, Track:North
Subdivision: None
05/02/2023 14:12:59, 11.8V, 93°F
Main Menu - Comm
_____
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event Log
[K] - System Functions Menu
[L] - Replay Train
[M] - Security Menu
[X] - Exit
```

Select the Security Menu. This menu/prompt appears.

```
Security Menu
[A] - Admin password not set
[B] - User password not set
[C] - Change wifi password
[X] - Exit
```

System login with an administrative password allows all access to system menus.

System login with a user password allows access to report menus and system functions menu but restricts access to the setup menu and security menu.

Select an option to set or change the password.

```
Enter a new password (20 character maximum):
```

The web/WiFi interface allows **on-site** and **off-site** access to the system. This interface allows the user to view reports and modify system parameters.

To use the WiFi interface locally, you need the following:

- A phone, tablet, or computer with WiFi capability
- Communications browser, which is installed on the device

For remote access via a web browser:

- A computer with internet connectivity
- A SmartScanNG² with Ethernet connectivity

The SmartScanNG² web interface provides the following:

- Train Summary report
- Train Detail reports
- System Status report
- System configuration
- Event Log report
- Software update

To access the SmartScanNG2 web interface, you must establish a network connection. A network connection can be established through the SmartScanNG2's Ethernet port or Wifi interface. The Ethernet port can be used to connect the SmartScanNG2 to a router for off-site access or to establish an on-site network connection. The Wifi interface can be used to establish an on-site network connection. **Appendix R On-Site Network Access** gives more details about establishing network access on-site.

To view the web page for your SmartScanNG², open a web browser on your computer. Enter the unit's IP address in the address bar of your browser.

See the example below. The contents of your web page will be different.

SMARTSCAN NG ²																		
Milep	ost: 1234.5	Track	: North	Subdi	vision	: None	9	05/0	3/2023,	14:38	1				Bat	tery: 13	8.6V T	emp: 2C
															Logo	ged in as	admin.	Logout)
Train	Data Syste	em Status	Con	figuration	Log	is M	ainter	nance	Info	System	n Functi	ons	oftware	e Update	Cali	bration		
Train	Summa	ary Da	ata (Trains St	ored: 1	(00									(Refresh)	
Axte Alarms Integrity Failures System Alarms + DSR Records Speed Bearing Avg Wheel Max AEI																		
Tm#	Date	Time	Cars	Axles	TO1	TO2	Dir	Min	Speed Max			ng Avg West	Whee East	el Max West	AEI Tags	Temp	Bat	Alarms
464			95	388	388	388	N	8	17	8	3	1	18	18	95	+39F	13.5v	
+ 463	05/03/23	13:14	70	396	396	396	Ν	26	39	26	8	5	117	18	67	+40F	13.6v	
462	05/03/23	12:40	102	412	412	412	s	41	45	44	3	2	44	18	101	+37F	13.7v	
461	05/03/23	12:23	107	434	434	434	Ν	23	34	23	9	5	42	18	104	+38F	13.7v	
460	05/03/23	11:31	64	306	306	306	Ν	20	25	25	5	3	15	15	64	+37F	13.8v	
459	05/03/23	10:28	94	380	380	380	Ν	27	40	27	7	5	15	18	92	+37F	13.8v	
458	05/03/23	09:21	33	258	258	258	S	25	29	27	6	2	126	18	33	+39F	13.9v	
457	05/03/23	08:59	121	490	490	490	Ν	24	30	24	9	5	46	18	119	+39F	13.9v	
456	05/03/23	08:17	101	408	408	408	S	16	19	18	6	3	26	15	100	+38F	14.0v	
455	05/03/23	07:51	32	210	210	210	Ν	36	37	36	13	5	30	15	32	+39F	13.9v	
454	05/03/23	07:23	104	422	422	422	Ν	24	30	24	7	4	8	15	102	+40F	13.9v	
453	05/03/23	06:41	92	374	374	374	Ν	36	39	36	7	3	18	15	92	+38F	13.9v	
452	05/03/23	05:55	44	178	178	178	N	32	38	32	10	4	12	18	43	+39F	13.9v	A
451	05/03/23	05:18	111	454	454	454	Ν	33	39	33	7	4	29	18	105	+37F	13.9v	
450	05/03/23	04:16	45	278	278	278	S	29	44	29	15	7	106	15	45	+39F	13.8v	
449	05/03/23	03:49	93	376	376	376	Ν	20	29	20	14	7	15	15	91	+40F	13.8v	
448	05/03/23	02:47	38	156	156	156	Ν	34	37	37	9	4	8	18	38		13.8v	
447	05/03/23	01:00	62	254	254	254	S	44	48	48	7	3	15	15	62	+39F	13.7v	
446		_	63	256	256	256	S	42	48	47	21	10	24	18	63		13.7v	
445		100010	93	378	378	378	S	30	31	30	18	9	36	18	94		13.7v	
444	05/02/23	21:13	125	506	506	506	Ν	29	43	29	7	4	15	15	124	+39F	13.6v	
443		a canada a seria a	70	340	340	340	S	12	29	14	12	5	21	18	70		13.5v	
442	05/02/23	19:38	33	250	250	250	Ν	41	46	41	13	6	46	18	30	+41F	13.5v	
+ 441	05/02/23	19:16	69	370	370	370	Ν	35	38	35	14	6	52	18	69	+42F	13.6v	
440	05/02/23	16:48	137	554	554	554	S	29	31	29	11	5	78	15	137	+43F	13.5v	
							-	> (More									

Click the "More" button at the bottom to load more train data.

The web page header includes the site's Milepost, Track designator, Date, Time, Battery voltage, Temperature, and Log in.

The main page includes eight tabs. Train Data, System Status, Configuration, Logs, Maintenace Info, Systems Functions, Software Update, and Calibration.
5.1 Train Data

To view the train data, left-click the **Train Data** tab. The Train Summary Data will be displayed as depicted in the example on the previous page.

To view a train detail report, slide the mouse pointer to highlight the desired train number in Train Summary Report. Left-click to select the train. A new window pops up for the **Train Details** report. See the example below.

Train De	tails -	Train #4	64			Subo	livsion	: None	Milepost:	1234.	5 / North
Date: 05 Time: 13 Dir: N	3:39	Axles: T01: T02: Cars:	388 388	peed Min: 8 Max: 17 Avg: 12 Exit: 8		Length: s Open:			temp.: +39F attery: 13,5		
Software	Versio	n: CP_00	-00 202	3-04-13							
Scanner	Perfor	mance			Alarm	Limits			AEI Syster	n Data	
East Be West Be East V	aring aring Vheel Vheel	18 10	281 3 313 18		Carsic Cold F Annou Annou Annou	ntial heel de Slope) Wheels Load Load	Limit 180 150 600 1.60 130 10 Yes Yes Yes Yes	Tags Rea Antenna 0 Antenna 1 Length(AE GO Train D	I)	0 95 6742 No
AEI Subs VERY SIG Cold We Cold We Cold We Integri Dead We Success	ow Train st Rail st Resi st When ty Fail est Res	n stor el Scann i ures istor	er Resi	istor ors Excee	ded						
Axle Al	arm S	ummar	у								
None.			_								
Car Ax	В	earing	W	DSR Charts heel West O		PW1 F	W2 AI	arms			
NS 4608 1	1	0 1	0	8	87 4591	47	45				
	2	0 1	12	8	88 162	46	46				
	3	1 1		-	88 162 88 1174		46 46				
	5	1 1	0	12	88 163	47	46				
	6	0 1	0	12	88 163	47	46				
UP 2668 2	7	0 1	8	12	89 444	47	45				
	8	1 1			89 164		46				
				•							

5.2 System Status

To view the system status, left-click the **System Status** tab. Grab and drag the slider bar to view the full range of system settings. See the example depicted below.

	2			^	
SMARTSCAN NO					
Milepost: 1234.5 Track: North Su	bdivision: None 05/02/2023, 14:	21	Battery: 11.6V Tem	p: 94F	
			Logged in as admin. Lo	ogout	
Train Data System Status Configu	ration Logs Maintenance Info S	System Functions S	oftware Update Calibra	tion	
System Status					\mathbf{N}
-				_	
Site Information	A				Slider
Subdivision	None				
Milepost Track Designator	1234.5 North				
Track Direction	North/South				
Time Zone	Eastern				
Daylight Savings Time	Disabled				
Software Version	CP 00-00 2023-04-13				
Speech Version #0	CP Matthew 1.0				
Speech Version #1	CP Mathieu 1.0				
Speech Version #2	CP Subdivisions 1.0				
Velocity	Enabled				
GO Train Detect SICM Board Rev	No 1.2 or lower				
	1.2 OF TOWER				
Alarm Settings Absolute	180				
Differential	150				
Hot Wheel	600				
Cold Rails	3				
Cold Rail Temp	10				
Cold Res Counter	3				
Differential Enabled	Yes	_			
Alarm Settings (Advanced)	A				
Carside Slope	1.60				
Carside Minimum	130				
Res Test: Minimum Rail Avg	25				
Res Test: Minimum Wheel Avg Bearing DSR Capture Temp	28 50				
Wheel DSR Capture Temp	150				
Max Alarms	6				
Equipment Settings	A				
Dragger	Yes				
Hot Wheel	Yes				
Hot Bearing	Yes				
High Load	No				
Wide Load AEI	No				
Presence Hardware	No Yes				
Advance Transducers	Yes				
AC Power Off Monitor	Yes				
Equipment Settings (Advance	d)				
Carside Slope	Yes				
Winter Cycle	Oct - Mar				
Gate Distance	24.0 in				
Dragger Debounce Time	5 ms				
Pre Train Dragger Dist	200 ft				
Pre Train High/Wide Dist	0 ft				
Presence Timeout Period System Voltage	10 sec 12 V				
Resistor Test	Enabled				
Clearance Mode	Multiplexed				
Clearance Type	Light Beam			~	

5.3 Configuration

To view the system configuration settings, left-click the **Configuration** tab. Then left-click the category tabs to view or edit the various parameters. If necessary, grab and drag the slider bar to view the full range of system settings. See the samples depicted below.

To modify the current setting, click on the parameter field and type the new value. The **Apply Changes b**utton will be outlined in red when changes have been entered. Left-click the **Apply Changes** button to save changes. An Update Successful message will appear.

Milepost: 1234.5	rack: North Subdivision	n: None 05/02	2/2023, 14:22	Battery: 11.7V Temp	: 94F
				Logged in as admin. Lo	gout
Train Data System	Status Configuration L	.ogs Maintenand	e Info System Functions	Software Update Calibration	
Configuration			Load De	fault Setup Parameters	
Date/Time	Date/Time		7		
Site Parameters	Date	05/02/2023			
Alarm Settings	Time	14:22			
Alarm Settings	Time Zone	Eastern V			
(Advanced)	Daylight Savings Time	Disabled V			
Equipment Settings	and drawn)				
Equipment Settings (Advanced)	Apply Changes				
Messages					
Messages Settings (Advanced)					
Network Settings					
Weather Settings					
COM Port Settings					

Date/Time Tab

Milepost: 1234.5 1	Frack: North Subdivi	ision: None	05/02	2023, 14:22	Battery:	11.7V Temp: 94F
					Logged in a	as admin. Logout)
Train Data System	Status Configuration	Logs	aintenano	e Info System Functions	Software Update	Calibration
Configuration				Load De	fault Setup Parameters)
Date/Time	Site Paramete	ers			J	
Site Parameters	Subdivision	None		Change Subdivision)		
Alarm Settings	Milepost	1234.5				
Alarm Settings	Track Designation	North	~			
(Advanced)	Track Direction	N/5 ¥				
Equipment Settings	Velocity	Enabled ~				
Equipment Settings (Advanced)	GO Train Detect	no v				
Messages	Apply Changes					
Messages Settings (Advanced)						
Network Settings						
Weather Settings						
COM Port Settings						

Site Parameters Tab

Milepost: 1234.5 T	rack: North Subdivis	ion: Non	05/02/2023, 1	4:25	Battery:	11.7V Temp: 94F
					Logged in a	as admin. Logout)
Train Data System	Status Configuration	Logs	Maintenance Info	System Functions	Software Update	Calibration
Configuration				Load Defa	ult Setup Parameters)
Date/Time	Alarm Settings					
Site Parameters	Absolute	180	min = 1, max = 30			
Alarm Settings	Differential	150	min = 1, max = 30	2		
Alarm Settings	Hot Wheel	600	min = 1, max = 90	5		
(Advanced)	Cold Rails	3	min = 1, max = 9			
Equipment Settings	Cold Rail Temp	10	min = 1, max = 30			
Equipment Settings	Cold Res Counter	3	min = 1, max = 9			
(Advanced)	Differential Enabled	yes v				
Messages Messages Settings (Advanced)	Apply Changes					
Network Settings						
Weather Settings						
COM Port Settings						
AEI Settings						

Alarm Settings Tab

Milepost: 1234.5	Track: North Subdivision: None	05/	02/2023, 14:27	Battery:	11.7V Temp: 94F
				Logged in a	as admin. Logout)
Train Data System	Status Configuration Logs M	laintena	nce Info System Functions	Software Update	Calibration
Configuration			(Load Defa	ault Setup Parameters)
Date/Time	Alarm Settings (Advan	ced)			
Site Parameters	Carside Slope	1.60	min = 0.01, max = 2.55		
Alarm Settings	Carside Minimum	130	min = 0, max = 300		
Alarm Settings	Res Test: Minimum Rail Avg	25	min = 0, max = 300		
(Advanced)	Res Test: Minimum Wheel Avg	28	min = 0, max = 900		
Equipment Settings	Bearing DSR Capture Temp	50	min = 0, max = 300		
Equipment Settings	Wheel DSR Capture Temp	150	min = 0, max = 900		
(Advanced)	Max Alarms	6	min = 1, max = 11		
Messages	Apply Changes				
Messages Settings (Advanced)	The stander				
Network Settings					
Weather Settings					
COM Port Settings					

Alarm Settings (Advanced) Tab

Milepost: 1234.5	Track: North Subdivision: No	one 05/02/20	23, 14:27	Battery: 11.6V Temp: 94F
				Logged in as admin. Logout)
Train Data System	Status Configuration Logs	Maintenance II	nfo System Functions	Software Update Calibration
Configuration			Load Defa	ult Setup Parameters
Date/Time	Equipment Settings]	
Site Parameters	Dragger	yes Y		
Alarm Settings	Hot Wheel	ves v		
Alarm Settings	Hot Bearing	yes v		
(Advanced)	High Load	no v		
Equipment		no v		
Settings	AEI	no Y		
Equipment Settings (Advanced)	East Rail Scanner Type	Type III 🗸		
	West Rail Scanner Type	Type III 🗸		
Messages	East Wheel Scanner Type	Type III 🗸		
Messages Settings (Advanced)	West Wheel Scanner Type	Type III 🗸		
Network Settings	Presence Hardware	yes Y		
	Advance Transducers	yes v		
Weather Settings	AC Power Off Monitor	yes ~		
COM Port Settings				
AEI Settings	Apply Changes			

Equipment Settings Tab

			4:28	Battery: 11.6	i iompion
				Logged in as ad	min. Logout)
for an and the second second					
Train Data System	n Status Configuration Logs Mainte	enance Info	System Funct	ions Software Update Ca	libration
Configuration			6		
Configuration			Load	Default Setup Parameters	
Date/Time	Environment Continuer (Ash				
Site Parameters	Equipment Settings (Adv	-			
Alarm Settings	Clearance Mode	Multiplexed			
	Clearance Type	Light Beam	~		
Alarm Settings (Advanced)	Carside Slope	yes 🗸			
	Winter Cycle	yes v			
Equipment Settings	Winter Cycle Start Month	October	~		
Equipmen		March	*		
Settings (Advanced		Normal ~			
	Resistor Test	Enabled ~			
Messages	Gate Distance (inches)	24.0			
Messages Settings	Dragger Debounce Time (mS)	5		min = 0, max = 999	
(Advanced)	Pre Train Dragger Dist (feet)	200		min = 0, max = 999	
Network Settings	Pre Train High/Wide Dist (feet)	0		min = 0, max = 999	
Weather Settings	Presence Timeout Period (seconds)	10		min = 5, max = 30	
COM Port Settings	System Voltage	12 ~			
AEI Settings	Transducer Type	Magnetic	~		
Units Of Measure					
	Apply Changes				

Equipment Settings (Advanced) Tab

Milepost: 1234.5 1	Track: North Subdivisio	n: None 05/02/202	23, 14:30	Battery: 11.7V Temp: 94F
				Logged in as admin. Logout)
Train Data System	Status Configuration	Logs Maintenance In	fo System Functions	Software Update Calibration
Configuration			Load Def	ault Setup Parameters
Date/Time	Messages]	
Site Parameters	Axles	ves Y	-	
Alarm Settings	Speed	no v		
Alarm Settings	Temperature	yes v		
(Advanced)	Length	yes v		
Equipment Settings	Slow	yes v		
Equipment Settings	Power Off	yes ~		
(Advanced)	Repeat No Defects	no v		
Messages	Cars Count	no v		
Messages Settings	Customer Name	yes Y		
(Advanced)	Arrival Message	no v		
Network Settings	Lft/Rt Alarm Ref	no Y		
Weather Settings	Car ID With Alarm	yes v		
COM Port Settings	US Speech Options	yes V		
AEI Settings	PrimaryLanguage	English_Matthew V		
Units Of Measure	SecondaryLanguage	None v		

Messages Tab

	Track: North Subdivision: None	e 05/	02/2023, 14:	:31	Battery: 11.7V Temp: 94F
				<u>L</u>	ogged in as admin. Logout)
Train Data System	Status Configuration Logs	Maintena	nce Info S	system Functions Softwar	e Update Calibration
Configuration				Load Default Setup	Parameters)
Date/Time					<u></u>
Site Parameters	Messages Settings (A	Advand	ced)		-
	Announce Hot Wheels	Yes	~		
Alarm Settings	Announce Differential	Yes	~		
Alarm Settings (Advanced)	Announce High Load	Yes	~		
	Announce Wide Load	Yes	~		
Equipment Settings	Request EOT Timer (minutes)	0		min = 0, max = 999	
Equipment Settings	Rebroad DTMF Code				
(Advanced)	Num EOT Repeats	0		min = 0, max = 5	
Messages	EOT Repeat Delay (seconds)	5	-	min = 0, max = 999	
Messages Settings	Apply Changes				
(Advanced)	(the country				
Network Settings					
Weather Settings					
COM Port Settings					
comit on bearings					

Messages Settings (Advanced) Tab

Milepost: 1234.5	Frack: North Subdivision: No	ne 05/02/2023	3, 14:32		11.8V Temp: 94F as admin. Logout)
Train Data System	Status Configuration Logs	Maintenance Info	System Functions	Software Update	Calibration
Configuration			Load Defa	ult Setup Parameters)
Date/Time	Network Settings				
Site Parameters	Use Static Address	no Y		_	
Alarm Settings	Static IP	192,168,1,101			
Alarm Settings	Static Mask	255.255.255.0	1		
(Advanced)	Default Gateway	192.168.1.1			
Equipment Settings	DNS Server	192.168.1.1			
Equipment Settings	TELNET Port	23	min = 0, max = 6553	5	
(Advanced)	FTP Port	21	min = 0, max = 6553	5	
Messages	HTTP Port	80	min = 0, max = 6553	5	
Messages Settings	HTTPS Port	8080	min = 0, max = 6553	5	
(Advanced)	Use Wifi	no v			
Network Settings	Wifi Inactivity Timeout (min)	10	min = 0, max = 30		
Weather Settings					
COM Port Settings	Apply Changes				

Network Tab

Milepost: 1234.5	Track: North Subdivision: None 05/0	2/2023, 1	4:33	Battery: 11.7V Temp: 94F Logged in as admin. Logout)
Train Data System	Status Configuration Logs Maintenan	ce Info	System Functions Softw Load Default Setu	are Update Calibration
Date/Time	Weather Settings			
Site Parameters	Barometric Pressure Sensor			-
Alarm Settings	Altitude for Relative Pressure	no Y	Change Altitude Setting	.)
Alarm Settings	Wind Monitor	no v	Change Mintade Setting	
Advanced)	High Wind Alarm Limit (mph)	50	min = 30, max = 80	
Equipment Settings	Display Wind Diagnostics	no Y		
Equipment Settings	Wind Poll Interval (seconds)	15	min = 1, max = 30	
Advanced)	Slow Wind Speed Limit (mph)	2	min = 0, max = 5	
Messages	Lower Interval Identical Limit (minutes)	360	min = 10, max = 600	
Messages Settings	Upper Interval Identical Limit (minutes)	30	min = 10, max = 60	
Advanced)	Wind Gust Interval (minutes)	5	min = 3, max = 10	
letwork Settings	Suspicious Temp. Interval (minutes)	720	min = 10, max = 720	
Neather Settings	Re-enable Wind Updates (minutes)	10	min = 1, max = 15	
COM Port Settings	Wind Alarm Reporting Interval (minutes)	5	min = 2, max = 15	
OW Fort settings				

Weather Settings Tab

		None 0	5/02/2023, 14:34	Battery: 11.7V Temp: 94F
				Logged in as admin. Logout)
Train Data System Sta	tus Configuration Lo	gs Mainte	nance Info System Fu	nctions Software Update Calibration
Configuration			(oad Default Setup Parameters
Date/Time	COM Port Setting	c .]
Site Parameters	COM1 (Serial Interface)	19200 ~	1	
	COM2 (Not Used)	19200 ~		
Alarm Settings (COM4 (Not Used)	19200 ~		
(Advanced)	COM6 (FlashHost)	57600 V		
Equipment Settings	RS485 (Not Used)	9600 ~	1	
Equipment Settings (Advanced)	Page Lines	30	min = 0, max = 9999	
Messages	Apply Changes			
Messages Settings (Advanced)				, ,
Network Settings				
Weather Settings				
COM Port Settings				

COM Port Settings Tab

Train Data System Status Configuration Logs Maintenance Info System Functions Software Update Calibration Configuration Load Default Setup Parameters Load Default Setup Parameters Load Default Setup Parameters Date/Time D Separation 2 min = 1, max = 4 Alarm Settings D Separation 2 min = 1, max = 4 Alarm Settings RF Frequency (MHz) 915.000 v RF Attenuation (dB) 0 min = 0, max = 10 Equipment Settings Antenna 0 Offset 0 min = 0, max = 240 Antenna 1 Offset 0 min = 0, max = 240 Messages Antenna 1 Offset 0 min = 0, max = 240 Antenna 1 Nearest Txd T01 v Metwork Settings Mether Settings COM Port Settings COM Port Settings Com Settings	
Date/Time Site Parameters Alarm Settings Alarm Settings Alarm Settings (Advanced) Equipment Settings (Advanced) Equipment Settings (Advanced) Multi-Track Tag Filter Nutersages (Advanced) Messages Metsoages (Advanced) Messages Network Settings Weather Settings Weather Settings	m
Site Parameters ALEI Settings Site Parameters D Separation 2 min = 1, max = 4 Alarm Settings Consecutive Reads 2 min = 1, max = 4 Alarm Settings RF Frequency (MHz) 915.000 v RF Attenuation (dB) 0 Equipment Settings Multi-Track Tag Filter no v Antenna 0 Offset 0 min = 0, max = 240 Antenna 0 Offset 0 min = 0, max = 240 Antenna 1 Offset 0 min = 0, max = 240 Messages Settings Antenna 1 Offset 0 min = 0, max = 240 Metwork Settings Apply Changes Veather Settings COM Port Settings	
Site Parameters D Separation 2 min = 1, max = 4 Alarm Settings Consecutive Reads 2 min = 1, max = 4 Alarm Settings RF Frequency (MHz) 915,000 v (Advanced) RF Attenuation (dB) 0 min = 0, max = 10 Equipment Settings Multi-Track Tag Filter no v Antenna 0 Offset 0 min = 0, max = 240 Antenna 0 Nearest Txd T01 v Messages Antenna 1 Offset 0 Metwork Settings Antenna 1 Nearest Txd T01 v Weather Settings Apply Changes	
Alarm Settings Consecutive Reads 2 min = 1, max = 4 Alarm Settings RF Frequency (MHz) 915,000 v (Advanced) RF Attenuation (dB) 0 min = 0, max = 10 Equipment Settings Multi-Track Tag Filter no v Antenna 0 Offset 0 min = 0, max = 240 Antenna 0 Nearest Txd T01 v Messages Antenna 1 Offset 0 Metwork Settings Mathema 1 Nearest Txd T01 v Metwork Settings Apply Changes	
Alarm Settings (Advanced) RF Frequency (MHz) 915.000 V Equipment Settings RF Attenuation (dB) 0 min = 0, max = 10 Equipment Settings (Advanced) Multi-Track Tag Filter no V no V Messages Antenna 0 Offset 0 min = 0, max = 240 Antenna 0 Nearest Txd T01 V Antenna 1 Offset 0 Messages Settings Antenna 1 Nearest Txd T01 V Network Settings Apply Changes Apply Changes	
Equipment Settings RF Attenuation (db) 0 min = 0, max = 10 Equipment Settings Multi-Track Tag Filter no Equipment Settings Antenna 0 Offset 0 min = 0, max = 240 Antenna 0 Nearest Txd T01 Messages Antenna 1 Offset 0 min = 0, max = 240 Antenna 1 Offset 0 min = 0, max = 240 Antenna 1 Nearest Txd T01 Network Settings Apply Changes Weather Settings COM Port Settings	
Equipment Settings (Advanced) Antenna 0 Offset 0 min = 0, max = 240 Antenna 0 Nearest Txd T01 × Messages Antenna 1 Offset 0 min = 0, max = 240 Antenna 1 Offset 0 min = 0, max = 240 Antenna 1 Offset 0 min = 0, max = 240 Antenna 1 Nearest Txd T01 × Antenna 1 Nearest Txd T01 × Metwork Settings Apply Changes	
(Advanced) Antenna 0 Nearest Txd T01 ~ Messages Antenna 1 Offset 0 min = 0, max = 240 Antenna 1 Nearest Txd T01 ~	
Messages Antenna 0 Nearest 1xd T01 ~ Messages Antenna 1 Offset 0 min = 0, max = 240 Messages Settings Antenna 1 Nearest Txd T01 ~ Antenna 1 Nearest Txd T01 ~ Network Settings Weather Settings COM Port Settings	
Messages Settings Antenna 1 Onset 0 Intenna 2 Onset (Advanced) Antenna 1 Nearest Txd T01 ~ Network Settings Apply Changes COM Port Settings	
(Advanced) Network Settings Weather Settings COM Port Settings	
Weather Settings	
COM Port Settings	
AEI Settings	
Units Of Measure	
Import/Export	

AEI Settings Tab

Milepost: 1234.5 1	Track: North Sul	bdivision: Nor	1e	5/02/2023, 14:37 Battery: 11.8V Temp: 95F Logged in as admin. Logout)
			_	
Train Data System	Status Configur	Logs	Mai	nance Info System Functions Software Update Calibration
Configuration				Load Default Setup Parameters
Date/Time	Units Of M	leasure		
Site Parameters	Location	Milepost	~	
Alarm Settings	Date Format	English ~		
Alarm Settings	Speed	English 🗸		
(Advanced)	Temperature	English 🗸		
Equipment Settings	Length	English 🗸		
Equipment Settings (Advanced)	Apply Changes	;)		
Messages				
Messages Settings (Advanced)				
Network Settings				
Weather Settings				
COM Port Settings				
AEI Settings				

Units of Measure Tab

Milepost: 1234.5 1	rack: North Subdivision: None	e 05/02/2023, 1	4:37	Battery: 11.8V Temp: 95F
				Logged in as admin. Logout)
Train Data System	Status Configuration Logs	Maintenance Info	System Functions	Software Update Calibration
Configuration			Load Defa	ult Setup Parameters
Date/Time	Import/Export			
Site Parameters	General Settings			
Alarm Settings	Network Settings			
Alarm Settings	Security Settings			
(Advanced)	Calibration Settings			
Equipment Settings	Export Import			
Equipment Settings (Advanced)				
Messages				
Messages Settings (Advanced)				
Network Settings				
Weather Settings				
COM Port Settings				
AEI Settings				

Imprt/Export Tab

5.4 System Event Log

The Event Log report is used for diagnostics. As certain system events occur, entries are posted into the event log. Each time an entry is made into this log, it receives an event number, the date and time that the event was recorded, and the event description.

The entries are stored in a section of SRAM that can hold up to 300 separate entries. Each time an event is recorded which exceeds this maximum, the new one overwrites the oldest recorded event. The entries are saved during a power outage but can be deleted with the Clear Event Log option on the System Functions menu. Producing the report at this time produces a "No Events" message. If events have been recorded and not cleared, they're listed in chronological order, beginning with the most recently recorded event.

To view the system event log, left-click the **Log** tab. Grab and drag the slider bar to view the full report. See the Event Log sample depicted below.

Milepost: 1234.5 Track: North Subdivision: None 05/02/2023, 15:40	Battery: 11.7V Temp: 97F Logged in as admin. Logout)
Train Data System Status Configuration Logs Maintenance Info System Function	s Software Update Calibration
System Event Log	Refresh
<pre>0001: [05/02/2023 14:35:53] (54) - Serial Connection timed out: id-3 0002: [05/02/2023 14:08:04] (54) - Admin logged in: id-3, serial interface 0003: [05/02/2023 13:12:45] (54) - Serial Connection timed out: id-3 0004: [05/02/2023 13:12:45] (54) - Admin logged in: id-3, serial interface 0005: [05/02/2023 11:28:24] (54) - Serial Connection timed out: id-3 0006: [05/02/2023 11:28:24] (54) - Admin logged in: id-3, serial interface 0007: [05/02/2023 09:43:66] (54) - Serial Connection timed out: id-3 0008: [05/02/2023 09:43:66] (54) - Setup password entry: Success 0009: [05/02/2023 09:42:52] (47) - Analyzer: Tag Reader Type None detected 0010: [05/02/2023 09:42:28] (54) - Setup password entry: Success 0011: [05/02/2023 09:42:28] (54) - Setup password entry: Success 0011: [05/02/2023 09:61:28] (54) - Admin logged in: id-3, serial interface 0013: [05/02/2023 09:61:28] (54) - Setup password entry: Success 0011: [05/02/2023 09:61:28] (54) - Setup password entry: Success 0011: [05/02/2023 09:61:28] (54) - Setup password entry: Success 0011: [05/02/2023 09:61:28] (54) - Setup password entry: Success 0011: [05/02/2023 09:61:28] (54) - Admin logged in: id-3, serial interface 0013: [05/02/2023 09:61:28] (54) - Setup password entry: Success 0014: [05/02/2023 09:61:28] (54) - Serial Connection timed out: id-3 0014: [05/02/2023 09:61:24] (54) - Serial Connection timed out: id-3 0015: [05/01/2023 15:45:13] (54) - Serial Connection timed out: id-3 0016: [05/01/2023 15:45:15] (54) - Setup nassword entry: Success 0017: [05/01/2023 15:45:15] (54) - Setup nassword entry: Success</pre>	tup Menu)



Each line of text (that is, each event) contains these fields.

- The sequential number assigned to the event as it was generated
- The date at which the event was recorded (date is in dd/mm/yy format)
- The time at which the event was recorded (time is in 24-hour hh:mm:ss format, where 8 a.m. is 08:00:00, noon is 12:00:00, 8 p.m. is 20:00:00, and midnight is 00:00:00)
- The event description

5.5 System Functions

Some but not all system functions can be accessed remotely. Left-click the Systems Functions tab to view available options. Left-click the corresponding button to initiate the desired function.



System Functions Tab

5.6 Software Update

To perform a remote software update, left-click the Software Update tab.

Milepost: 1234.5	Track: North Subdivision: None	05/02/2023, 15:42	Battery: 11.8V Tem	p: 96F
			Logged in as admin.	ogout
Train Data System	Status Configuration Logs Maint	enance Info System Functions	Software Update Calil	bration
Updates: Update Delete CP Upload	<u>00-00.ng</u> 5673 kb		Use websocket	s: 🗆

Software Update Tab

To upload a new file, left-click on the **Upload** button. Search for and select a software file on your computer. Only two files can be stored at a time. If there are already two files, you must delete one before uploading another.

When the upload is complete, left-click the **Update** button and follow the instructions in the prompts.

5.7 Calibration

To perform the automatic scanner calibration function, left-click the Auto Cal tab.

Milepost. 12	34.0 Ira	CK: NORTH	Subdivisior	I: None	15/02/202	23, 15:45		7V Temp: 97f admin. Logout)
Train Data Sy	/stem Stat	us Confi	guration Logs	Maintenan	ce Info	System Functions	Software Update	Calibration
Scanner A	uto Ca	libratio	n					
Calibration								
Scanner	Scanner Type	Potention Prev.	Current	Last Calib Date	Time			
East Bearing	111		41	05/16/2022	11:22			
West Bearing	111		40	04/28/2022	09:07			
East Wheel	111		41	04/28/2022	09:09]		
West Wheel	III		42	04/28/2022	09:11]		
		hogin o	alibration ***	INSTALL BL	ACK FI	TER BEFORE C	ALIBRATING TYP	

Calibration Tab

Left-click the command buttons to Start/Stop calibration.

The SmartScanNG² system provides:

- Train Summary report
- Train Detail report
- Exception Summary report
- extended Exception Detail report
- abbreviated Exception Detail report
- System Status report
- AEI Diagnostic Detail report
- Event Log report
- Maintenance report

This section shows a sample of each report with a description of each field. It also lists stepby-step instructions on producing each report, both **on-site** and **off-site**. The instructions for each report start with you being at the Main menu, which is described below.

1 If **on-site**, plug your computer into the SmartScanNG² serial port COM1.



- 2 Turn on your computer.
- **3** Be sure that your computer has installed communications software, that it is set to use full-duplex, <u>and</u> that the baud rate is set to 19,200.

Use your communications software to open a LOG file and capture the whole session to the file. When your session is complete, you may then view what you have done with an editor, print it with a printer, or store it for later retrieval.

- 4 On your computer, open a LOG file.
- 5 If off-site, establish communications with the SmartScanNG² via Ethernet or modem as appropriate.

6 Press [Esc].

This prompt appears.

Enter password:

7 Type the assigned password.

The entry of this word is **not** case-sensitive.

8 To get the serial interface to come up, press [Esc].

The Main menu appears.

```
SmartSCAN NG2, MP/KP:1234.5, Track:North
Subdivision: None
05/02/2023 16:13:04, 11.8V, 98°F
Main Menu - Comm
_____
[A] - Train Summary
[B] - Train Detail
[C] - Exception Summary
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event Log
[K] - System Functions Menu
[L] - Replay Train
[M] - Security Menu
[X] - Exit
```

At the above prompt, you can produce one of the listed reports by selecting the appropriate option.

If a train is at the site when the Main menu is generated, "*** Train Is Present ***" is displayed just above the menu header for the Main menu.

- 9 When done, close the LOG file.
- **10** To exit the serial interface and return the system to normal operation, type **X**.

When a session ends, if a modem was used, the system sends various commands to the modem to prepare it for future use. If, at any time during the disconnect procedure, lines such as "+++ATH0" appear on your screen, these are merely commands preparing the modem for further use. They shouldn't be construed as anything that is meant for the user.

6.1 Train Summary Report

The Train Summary report lists all trains currently stored in the Trains directory. A train number is shown for each train entry so that a Train Detail report may easily be produced for any train listed on the summary.

The report is divided into a header section and a detail section. The <u>header</u> section contains general information about the site. The <u>detail</u> section contains summary information on each train that passed the site.

The SmartScanNG² system calculates a checksum for each train. This checksum is stored with the train data. Later, when the system retrieves this data, it recalculates the checksum. If the two checksums don't match, the Train Summary report so states in the detail section. So, instead of getting a train record, you'll get a checksum-error line.

Below is a sample of part of a Train Summary report when Hotwheel alarm detection was <u>disabled</u> during report processing <u>and</u> when the AEI subsystem was <u>disabled</u> during train passage. (When the report is run, if the Hotwheel option on the Equipment Settings menu is disabled, the hotwheel information is hidden. When the report is run, if the AEI option is disabled, the tag information isn't hidden.) The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

Software	Version:	-00 G		123-04-	-13			Subdi	iviei	on:	Winder	moro /	6104)				
Current Absolute	Alarm Sett. 190 tial 117	– ings Car:	side	Slope.	2.	30	L	Jubus				MP/KP: Track:	1234.				
	1 900			il Temp													
_				-													
Total Tr	ains: 100																
							D				Bear	ing	Bear	ing			
					TxD C							age			AEI	Amb	
Train#	Date	Time (Cars	Axles	T01	т02	r	Min	Max	Xit	East						Bat
229S	05/03/23	04:56	136	 548	548	548	N	8	 17		18		42		261		13.9v
228	05/03/23								31	31			36		153		13.9v
227	05/03/23	01:26	100	422	422	422	Ν	15	38	15	26	27	60	58	199	41F	13.8v
226	05/03/23	00:53	68	432	432	432	S	28	37	28	18	18	60	63	135	41F	13.8v
225	05/03/23	00:31	81	328	328	328	S	25	28	25	12	12	29	29	151	40F	13.7v
224	05/02/23	21:17	24	158	158	158	N	13	22	13	18	16	51	45	50	41 ह	13.6v
223	05/02/23								25	19					91		13.6v
222	05/02/23				490										233		13.6v
222	03/02/23	10.70	•	190	190	190	1,	10	20	10			20	20	200	151	10.00
			•														

Below is a sample of part of a Train Summary report when the Hotwheel option on the Equipment Settings menu is <u>enabled</u>. The contents of your report will be different.

. • Current Alarm Settings Absolute..... 150 Carside Slope... 1.31 Differential.. 255 Minimum...... 90 Hot Wheel.... 500 Cold Rail Temp.. 10 Total Trains: 20 -----_____ _____ D Bearing Wheel i Speed Average Maximum Amb Train# Date Time Cars Axles TO1 TO2 r Min Max Xit East West East West Temp Bat _____ • • • END OF REPORT - Press any key...

The table below lists the fields from the header section and the contents of each field.

Heading	Contents of Field
Version Info	The version numbers of the firmware and their release dates, which are in mm/dd/yy format. This firmware resides on the processor modules.
MP/KP	The five-digit milepost/kilometer post of the site. Section 4.0 - Serial Interface tells how to change this value using the MP/KP submenu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. Section 4.0 - Serial Interface tells how to set this value using the Track Number submenu of the Setup menu.
Alarm Limits	 The alarm parameters currently defined in the system setup. These values were in place at the time this report was run. The value after Absolute is set by the Absolute option on the Alarm Settings menu. The value after Differential is set by the Differential option on the Alarm Settings menu. The heading Hot Wheel only appears when the Hotwheel option on the Equipment Settings menu is <u>enabled</u>. The value after Hot Wheel is set by the Hotwheel option on the Alarm Settings menu. The value after Carside Slope is set by the Carside Slope option on the Alarm Settings menu. The value after Minimum is set by the Carside Minimum option on the Alarm Settings menu. The value after Cold Rail Temp is set by the Cold Rail Temperature option on the Alarm Settings menu.
Total Trains	The total number of trains visiting the site since the Trains directory was last cleared.

The table below lists the fields from the \underline{detail} section and the contents of each field.

Heading	Contents of Field
Train#	The number that identifies the train in the Trains directory.
	There is one unlabeled column between those labeled "Train#" and "Date." This column can contain A , B , I , S , or nothing. If "A," an Exception Alarm was detected on the train. If "I," an Integrity Failure was detected. If "B," both an Exception Alarm and an Integrity Failure were detected. If "S," a System Alarm was detected, but Exception Alarms and Integrity Failures weren't. If blank, no Exception Alarm, Integrity Failure, or System Alarm was detected.
Date	The date the train arrived at the site. Date is in mm/dd/yy format. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time the train arrived at the site. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Cars	The total number of cars counted by the SmartScanNG ² system.
Axles	The total number of axles counted by the SmartScanNG ² system.
TO1	The total number of hits counted by gating transducer TO1. TO1 is the first gating transducer going north or east from the bearing scanner. It is the gating transducer <u>closest</u> to the bearing scanner.
TO2	The total number of hits counted by gating transducer TO2. TO2 is the second gating transducer going north or east from the bearing scanner. It is the gating transducer <u>farthest</u> from the bearing scanner.
AEI Tags	The total number of AEI tags stored. The number of tag pairs found plus those single tags that lack a match. This heading always appears, even if the AEI subsystem is disabled using the AEI option on the Equipment Settings menu.
Speed (mph)	The train's exit speed in miles per hour.
Dir	The direction the train was traveling. Valid values are N, S, E, and W.
Rail Average	Under this heading are two columns, one for each bearing scanner, containing the average temperature read by the bearing scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west.
Wheel Maximum	Under this heading are two columns, one for each wheel scanner, containing the maximum temperature read by the wheel scanners. If the track orientation is east and west, the wheel scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. This field appears only when the Hotwheel option on the Equipment Settings menu is enabled.
Amb Temp	The ambient temperature, in degrees Fahrenheit, at the time the train arrived at the site.
Bat	The system battery voltage at the time the train passed the site.

To produce a Train Summary report:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

- 2 Select Train Summary.
- **3** To exit the serial interface and return the SmartScanNG² system to normal operation, type **X**.

6.2 Train Detail Report

The Train Detail report provides detailed information on a single train. When choosing this report, you'll be prompted for a train number. When prompted, enter a train number from the Train Summary report. The train number appears under the column titled "Train#" in the <u>detail</u> section of the Train Summary report.

Carside Slope alarm detection is enabled/disabled using the Carside Slope option on the Equipment Settings menu. Hotwheel alarm reporting is enabled/disabled using the Hotwheel option on the Equipment Settings menu. The AEI subsystem is enabled/disabled using the AEI option on the Equipment Settings menu.

Where wheel scanners are properly installed, wheel temperatures are always recorded, even if the Hotwheel option is disabled. On the other hand, if the AEI option is disabled during train passage, no AEI information is recorded. If the Carside Slope option is disabled during train passage, no Carside Slope alarms are generated. But, if it is enabled at the time a report is requested, a carside-slope alarm-limit line is generated for each car of the train.

Below is a sample of part of a Train Detail report when both the AEI option and the Hotwheel option on the Equipment Settings menu were <u>enabled</u> at the time the report was requested. The Carside Slope option on the Equipment Settings menu was <u>disabled</u>. Also, both the AEI and Hotwheel options were <u>enabled</u> while the specified train was passing the site. The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

	Southern Technologie Next Generation Det TRAIN DETA	ector System	
Train#: 228 Date: 05/03/23 Time: 04:04 Sł	Axles: 370 Cars: 77 Direction: North Shutters Open: 176 Length: 7516	SpeedMEMin: 28TrMax: 31TemperatAvg: 30BattExit: 31	/KP: 1234.5 rack: Single ure: +40F ery: 13.9v
	Subdiv		mere (6104)
Scanner Max Avg Re	Resistor Txdr Read Req CF Counts	Alarm Limit Ca	rside Parms
East Brng 36 12 3 West Brng 29 12 3 East Whl 50 0 West Whl 41 0 Resistor Test Mode: H	300 231B 0 TO1 370 300 240B 0 TO2 370 28 0B 0 33 0B 0	Absolute 190 Sl Differential 117 Mi Hot Wheel 652 Cold Rail Temp 10	ope: 2.30 nimum: 120
Software Version: CP	200-00 2023-04-13		
AEI System Data			
Tags Read Ta	Tags Stored: 153		
Antenna 0: 76 Antenna 1: 77			
GO Train Detect: Yes	3		
System Alarms			
None			
Integrity Failures			
None			
Axle Alarm Summary			
NONE			
Announcements Made			
" CP Detector Mile 1	l 2 3 4 Point 5 Windemere	4 0 Degrees Axles 3 7 0	No Alarms Repeat No Alarms Speed 3 1 No Alarms Repeat No Alarms Speed 3 1
(continued on next	• • t page)		

Train Detail - Extended

					•					
Car	Axle	Rail East		ON	OFF	PW1	PW2	Ala	rms	
	1			48					 5926	
	2 3				109 109	19 19				
	4	2	8	48	741	19				
	5 6	5 2	7 6	48 48	109 108	18 17				
2	7	19	11	48	266	18			4528	
2	8	17	8	48		18		OP	4520	
	9 10	11 5	7 3	48 48	119 715	19 19	22 21			
	11	11	14	48	119	19	21			
	12	8	6	48	110	19	21			
3	13	19	16	47	197	18		TTAX	553787	
	14 15	10 19	15 15	47 47	87 1093	19 18				
	16 17	10 36		47 48	87 1159	18 15				
	18	19	8	48	86	15				
	19 20	16 5	7 3	48 47	1155 86	15 18	18 20			
	21		6 7		1154	18	20			
	22 23	5 14	7 16	47 47	86 1087	17 18				
	24	3	3	47	86	20	21			
4	25	б	5	47	136	18		DTTX	730056	
	26 27	10 10	10 10	47 47	85 1310	17 19				
	28	14	19	47	93	17	20			
	29 30	16 12	12 14	47 47	1309 94	18 19				
	31 32	11 8	7 8		1303 86	19 19				
_										
5	33 34	6 11	10 12	46 47	142 85	19 17		DTTX	727307	
	35	10	14	47	1291	17	19			
	36 37	8 7	10 8	46 46	93 1294	20 19	22 21			
	38 39	7 7	6 5	46 46	93 1285	19 19				
	40	8	5		85	19	21			
6	41	11	10	46	150	17	19	FEC	55567	
	42	12	10	46		18	19			
	43 44	19 6	17 6	46 46	93		21 21			
	45 46	7 11	7 8	46 46	1282 93	19 19	21 21			
	47	12	11	46	1274	19	21			
	48	20	11	46	83	16	19			
7	49 50	6 5	7 5	46 46	143 84	19 16	21 19	DTTX	786348	
	51	16	8	46	1275	17	19			
	52 53	12 14	16 12	46 46	92 1278	18 18	20 20			
	54	11	14	46	92	19	21			
	55 56	8 8	6 10	45 45	1269 83	18 19	19 21			
					•					
					•					
					•					

Train Detail - Extended (continued)

The Train Detail report is divided into three sections. The <u>header</u> section contains general information about the site (like the MP/KP) and some detail information about the specific train (like the train's exit speed) that passed the site. The <u>detail</u> section contains more detailed information (like the car number) about the specific train. In between these two sections is the <u>system-events</u> section, which contains all System Alarms and Exception Alarms associated with the train.

The SmartScanNG² system calculates a checksum for <u>each train</u>. This checksum is stored with the train data. Later, when the system retrieves this data, it recalculates the checksum. If the two checksums don't match, the Train Detail report so states (as shown below).

	Southern Technologies Corporation Next Generation Detector System TRAIN DETAIL
CHECKSUM ERROR:	StartAddr 134879 EndAddr 134930

In addition, <u>each axle</u> has a checksum associated with it. If an axle is determined to have an invalid checksum, the Train Detail report so states in the associated axle's row (as shown below).

Southern Technologies Corporation Next Generation Detector System TRAIN DETAIL										
				• •						
Car			North			OFF			Alarms	
1	1	0	56	21	25	0	6	6		
	2	0	57	21	25	59	6	6		
	3	0		21			8		11 101105	
	4 5			ERROR: 21				EndA 6	ddr 136427	
	5	1		21 21						
	0	T	20	21	25	59	0	o		
2	7	2	56	20	25	162	6	6		
	8	2		21	25			6		

The table below lists the fields from the <u>header</u> section and the contents of each field.

Heading	Contents of Field			
Train#	The number that identifies the train in the Trains directory.			
Date	The date the train arrived at the site. Date is in mm/dd/yy format. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.			
Time	The time the train arrived at the site. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.			
Length	The length of the train in feet.			
Speed	The train's minimum, maximum, average, and exit speeds in miles per hour.			
Axles	The total number of axles counted by the SmartScanNG ² system.			
Direction	The direction the train was traveling. Valid values are North, South, East, and West.			
Shutters Open	The number of seconds it took the train to pass over the site.			
MP/KP	The five-digit milepost/kilometer post of the site. Section 4.0 - Serial Interface tells how to change this value using the MP/KP submenu of the Setup menu.			
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. Section 4.0- Serial Interface tells how to set this value using the Track Number submenu of the Setup menu.			
Temperature	The ambient temperature at the time the train arrived at the site. Temperature is in degrees Fahrenheit.			
Battery	The system battery voltage at the time the train passed the site.			
Brng	Location of the bearing scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west			
Max	The maximum temperature, above the ambient temperature in degrees Fahrenheit, recorded by the bearing scanner on a given railside. For example, if the ambient temperature (at the time the train arrived at the site) is 77°F (25°C) and the value in this field is 112, the maximum temperature would be 189°F (87.2°C).			
Avg	The average temperature, above the ambient temperature in degrees Fahrenheit, calculated from all recorded temperatures from the bearing scanner on a given railside. For example, if the ambient temperature (at the time the train arrived at the site) is 86°F (30°C) and the value in this field is 55, the average temperature would be 141°F (60.6°C).			

Heading	Contents of Field
Resistor Read	The scanner resistor temperature (read after train passage), in degrees Fahrenheit, recorded by the bearing scanner on a given railside.
Resistor Req	The resistor temperature, in degrees Fahrenheit, required by the bearing scanner on a given railside to avoid a Cold Resistor alarm. This value was calculated using the amount of time the shutters were open and the Resistor Test Mode option in effect at the time the train exits the site. If the Resistor Test Mode option is <u>disabled</u> , a zero appears in this field.
	One of five uppercase letters follows the Resistor Req temperature.
	 B The baseline resistor integrity test method was used for this train. D The resistor integrity test (that is, the Resistor Test Mode option) was disabled by the user. I The interim resistor integrity test method was used for this train. T For this train, the shutters were open for less than 30 seconds. V For this train, the battery voltage (measured with the shutters open) was less than 12.5 volts.
	For D , T , and V , the required resistor heat is set to zero (that is, a zero appears in the Resistor Read field). A T or V indicates that the integrity test was not performed due to low voltage or insufficient shutter open time, which could result in an invalid resistor integrity test if it was performed.
CF	The percentage difference between the required resistor value and the value that was actually read. For example, if the required resistor temperature is 180 and the actual resistor temperature is 135 the correction factor would be 25% (1 - (135 / 180) = .25), and 25 would appear in this field.
Txdr Counts	The gating transducer designator (either TO1 or TO2) followed by the total number of hits on that transducer.
Alarm Limit	The Hotwheel alarm level; the Hotbox alarm levels for Absolute and Differential; and the Cold Rail Temperature offset. These values were in place at the time the train arrived at the site.
	 The value after Absolute is set by the Absolute option on the Alarm Settings menu. The value after Differential is set by the Differential option on the Alarm Settings menu. The value after Hot Wheel is set by the Hotwheel option on the Alarm Settings menu. The value after Cold Rail Temp is set by the Cold Rail Temperature option on the Alarm Settings menu.
	Section 4.0 - Serial Interface tells how to set these values.

Heading	Contents of Field
Carside Parms	 The Carside Slope alarm parameter values that were in place at the time the train arrived at the site. The value after Carside Slope is set by the Carside Slope option on the Alarm Settings menu. The value after Minimum is set by the Carside Minimum option on the Alarm Settings menu. Section 4.0 - Serial Interface tells how to set these values.
Resistor Test Mode	The status of the post-train resistor integrity test at the time the train arrived at the site. Valid values (aka modes) are Enabled, Reduced, and Disabled. Section 4.0 - Serial Interface tells how to set this value using the Resistor Test Mode option on the Equipment Settings menu.
Wheel	The location of the wheel scanners. If the track orientation is east and west, the wheel scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. This field only appears when Hotwheel alarm reporting is <u>enabled</u> using the Hotwheel option on the Equipment Settings menu.
Max	The maximum temperature, above the ambient temperature in degrees Fahrenheit, recorded by the wheel scanner on a given railside. This field only appears when Hotwheel alarm reporting is <u>enabled</u> using the Hotwheel option on the Equipment Settings menu.
Avg	The average temperature, above the ambient temperature in degrees Fahrenheit, calculated from all recorded temperatures from the wheel scanner on a given railside. This field only appears when Hotwheel alarm reporting is <u>enabled</u> using the Hotwheel option on the Equipment Settings menu.
Resistor Read	The scanner resistor temperature (read after train passage), in degrees Fahrenheit, recorded by the wheel scanner on a given railside. This field only appears when Hotwheel alarm reporting is <u>enabled</u> using the Hotwheel option on the Equipment Settings menu.
Resistor Req	The resistor temperature, in degrees Fahrenheit, required by the wheel scanner on a given railside to avoid a Cold Wheel Scanner Resistor alarm. This value was calculated using the amount of time the shutters were open and the Resistor Test Mode option in effect at the time the train exits the site. If the Resistor Test Mode option is <u>disabled</u> , a zero appears in this field. This field only appears when Hotwheel alarm reporting is <u>enabled</u> using the Hotwheel option on the Equipment Settings menu.

Heading	Contents of Field
	One of five uppercase letters follows the Resistor Req temperature.
	 B The baseline resistor integrity test method was used for this train. D The resistor integrity test (that is, the Resistor Test Mode option) was disabled by the user. I The interim resistor integrity test method was used for this train. T For this train, the shutters were open for less than 30 seconds. V For this train, the battery voltage (measured with the shutters open) was less than 12.5 volts.
	For D , T , and V , the required resistor heat is set to zero (that is, a zero appears in the Resistor Read field). A T or V indicates that the integrity test was not performed due to low voltage or insufficient shutter open time, which could result in an invalid resistor integrity test if it was performed.
CF	The percentage difference between the required resistor value and the value that was actually read. For example, if the required resistor temperature is 180 and the actual resistor temperature is 135 the correction factor would be $25\% (1 - (135 / 180) = .25)$, and 25 would appear in this field.
AEI System Data	The number of AEI tags read (by antenna0 and antenna1) and the total number of tags stored for the train. Where both tags of a tag pair are operational, each antenna will read one tag of the pair. The total number of tags stored represents the number of tag pairs found plus those single tags that lack a match. This heading and the columns under it appear only when the AEI subsystem is <u>enabled</u> using the AEI option on the Equipment Settings menu.
Firmware Versions	The version numbers of the firmware and their release dates, which are in mm/dd/yy format. This firmware resides on the processor modules.

The table below lists the fields from the system-events section and the contents of each field.

Heading	Contents of Field
System Alarms	Lists any System Alarms and Integrity Failures detected at the time the train passed the site. If none were detected, this header is followed by the word "none." <i>Appendix A - System Alarms</i> describes the conditions and events that the system flags as System Alarms. <i>Appendix B - Integrity Failures</i> describes the conditions and events that the system flags as Integrity Failures.
Axle Alarm Summary	Lists each Exception Alarm found on the train and the axle on which it was found. If none were found, this header is followed by the word "none."

The table below lists the fields from the <u>detail</u> section and the contents of each field.

Heading	Contents of Field
Car	The car number as determined by the firmware.
Axle	The axle number.
Trk	The truck number. Each railroad vehicle has two or more trucks (that is, wheel assemblies). The trucks are numbered, starting with 0, and increasing from the beginning of the train to the end. Each axle record is associated with one of these trucks. The axles are assigned the number of the truck with which they've been associated. These assigned truck numbers appear in this field. If the Hotwheel option on the Equipment Settings menu is <u>enabled</u> , this field doesn't appear.
Rail	Under this heading are two columns, one for each bearing scanner, containing the temperature read by the bearing scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. If the Hotwheel option on the Equipment Settings menu is <u>disabled</u> , the word "Rail" doesn't appear, but the two columns do.
Wheel	Under this heading are two columns, one for each wheel scanner, containing the temperature read by the wheel scanners. If the track orientation is east and west, the wheel scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. This heading and the two columns under it appear only when the Hotwheel option on the Equipment Settings menu is <u>enabled</u> .
ON	The number of milliseconds a bearing was scanned.
OFF	The number of milliseconds between axles (when no axle was between the gating transducers).
PW1	The recorded width of the pulse generated by gating transducer TO1. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.
PW2	The recorded width of the pulse generated by gating transducer TO2. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.
Alarms	Any Exception Alarm found on the given axle.

To produce an extended Train Detail report:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

2 Select Train Detail.

This prompt appears.

Enter Train Number:

- **3** Type the train number.
- 4 If you typed one or two digits, press [Enter].

This prompt appears.

Abbreviated? (y/n)

- 5 Type N to produce an extended Train Detail report.
- 6 To exit the serial interface and return the SmartScanNG² system to normal operation, type **X**.

6.3 Train Detail Report (Abbreviated)

The abbreviated Train Detail report is like the extended Train Detail report. However, the abbreviated report doesn't display all the recorded axle data. It only displays axle data for:

- The car immediately preceding a car with an alarmed axle.
- The car containing the alarmed axle.
- The car immediately following the car with the alarmed axle.

Like the extended Exception Detail report, the abbreviated Exception Detail report is divided into three sections. The header section contains general information about the site (like the MP/KP) and some detail information about the specific train (like the train's exit speed) that passed the site. The detail section contains more detailed information (like the car number) about the specific train. In between these two sections is the system events section, which contains all System Alarms and Exception Alarms associated with the train.

Southern Technologies Corporation Next Generation Detector System TRAIN DETAIL ABBREVIATED _____ Train#: 18 Axles: 276 Speed MP/KP: 1234.5 Date: 02/11/23 Cars: 68 Min: 24 Track: North Time: 04:13 Direction: North Max: 33 Temperature: +27F Shutters Open: 112 Avg: 26 Battery: 13.1v Length: 4069 Exit: 32 Subdivision: Windermere (6104) _____ Resistor Txdr Scanner Max Avg Read Req CF Counts Alarm Limit Carside Parms
 East Brng 29 15 300 288B
 TO1 276
 Absolute
 150
 Slope:
 1.31

 West Brng 30 13 278 256B
 TO2 276
 Differential
 255
 Minimum:
 90
 Hot Wheel 500 Cold Rail Temp 10 Resistor Test Mode: Disabled High/Wide Alarm Direction: BOTH _____ Software Version: CP_00-00 2023-04-13 _____ _____ System Alarms Integrity Failure Stuck Dragger During Train Passage _____ Axle Alarm Summary 1 Dragging Equipment • Announcements made " CP Detector Mile 1 2 3 4 point 5 north track " " CP Detector Mile 1 2 3 4 point 5 north track you have a defect " " CP Detector Mile 1 2 3 4 point 5 north track dragging equipment near axle 1 total axles 2 7 6 temperature 2 7 not working " " CP Detector Mile 1 2 3 4 point 5 north track dragging equipment near axle 1 total axles 2 7 6 temperature 2 7 not working detector out _____ Rail Car Axle East West ON OFF PW1 PW2 Alarms _____ 0 0 0 0 55 0 21 20 Dragging Equipment 55 128 21 20 1 1 2 3 5 2 55 127 18 18 3 55 902 20 19 2 55 128 20 19 0 55 127 18 17 4 3
 55
 128
 20
 19

 55
 127
 18
 17
 5 3 0 6 Carside Ave: East 2 West 1 Carside Alarms: East 92 West 91 55 334 21 21 2 7 9 10 8 6 55 128 21 21 3 5 10 55 128 21 20 1 9 55 944 21 20 9 9 55 944 21 20 9 55 128 21 21 10 6 11 5 14 55 128 21 20 12 Carside Ave: East 6 West 10 Carside Alarms: East 97 West 103

Train Detail - Abbreviated
To produce an abbreviated Train Detail report:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

2 Select Train Detail.

This prompt appears.

Enter Train Number:

- **3** Type the train number.
- 4 If you typed one or two digits, press [Enter].

This prompt appears.

Abbreviated? (y/n)

- 5 Type Y to produce an abbreviated Train Detail report.
- 6 To exit the serial interface and return the SmartScanNG² system to normal operation, type **X**.

6.4 Exception Summary Report

The Exception Summary report lists all trains currently stored in the Exceptions directory. (A train is stored in the Exceptions directory if either an Exception Alarm or an Integrity Failure was detected on it as it passed the site.) A train number is shown for each train entry so that an Exception Detail report may easily be produced for any train listed on the summary.

The report is divided into a header section and a detail section. The <u>header</u> section contains general information about the site. The <u>detail</u> section contains summary information on each exception train (that is, on each train having an Exception Alarm, an Integrity Failure, or both) that passed the site.

The SmartScanNG² system calculates a checksum for each train. This checksum is stored with the train data. Later, when the system retrieves this data, it recalculates the checksum. If the two checksums don't match, the Exception Summary report so states in the <u>detail</u> section. So, instead of getting a train record, you'll get a checksum-error line.

Below is a sample of part of an Exception Summary report when Hotwheel alarm detection was <u>disabled</u> during report processing <u>and</u> when the AEI subsystem was <u>disabled</u> during train passage. (When the report is run, if the Hotwheel option on the Equipment Settings menu is disabled, the hotwheel information is hidden. When the report is run, if the AEI option is disabled, the tag information isn't hidden.) The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

	Southern Technologies Corporation Next Generation Detector System EXCEPTION SUMMARY																		
So	Software Version: CP_00-00 2023-04-13												rmere MP/KP		.5				
Ab Di Ho	Current Alarm Settings Absolute 190 Carside Slope 2.30 Differential 117 Minimum 120 Hot Wheel 900 Cold Rail Temp 10 Total Trains: 20																		
									D				Bear	0		5			
Tr	ain#	Ref#	Date	Time	Cars		TxD C TO1				-	Xit	Aver East	West	East	West	-	-	
	6I	210	05/01/23	19:12	0	2	0	0	N	0	0		0	0	0		0		0.0v
в	51		04/17/23			352	352	352	Ν	15			16	17	60	67	174	7F	13.9v
В	4I	46	04/17/23	08:23	52	386	386	386	Ν	36	39		21	23	46	59	103	11F	13.9v
В	3I		04/17/23			278	278	278					23	24	59		125		13.9v
	21		04/17/23			564	564				30		15	16	29				13.8v
	11		04/17/23			434	434	434				34	12	13	28				13.8v
	201		04/17/23			454	454		~	16	30	16	13	13	30		215		13.7v
В	19I	41	04/17/23	00:24	95	386	386	386	Ν	30	36	30	20	20	49	55	167	-50F	13.6v
В	181	40	04/16/23	22:24	83	350	350	350	Ν	37	42	37	28	28	62	61	165	11F	13.6v
В	17I	39	04/16/23	20:26	60	342	342	342	Ν	11	21	11	21	21	52	43	118	13F	13.5v
	16I	38	04/16/23	19:45	131	528	528	528	S	21	35	21	12	12	49	38	259	9F	13.5v
			•																
			•																
			•																

Below is a sample of part of an Exception Summary report when the Hotwheel option on the Equipment Settings menu is <u>enabled</u>. The contents of your report will be different.

				•									
				•									
				•									
Current Alarm	Settin	qs											
Absolute		-	e Slope.	2.3	0								
Differential.			-										
Hot Wheel	. 900	Cold Ra	ail Temp	10)								
Total Trains:	20												
						 D		Bear	ina	Whe	 el		
								DCur	1119	11110			
						i	Speed	Aver	age	Maxi	miim	Amb	
Train# Ref#	Date	Time Ca	ars Axle	s TO1	то2	i r	Speed Min Max Xit		-			Amb Temp	Bat
Train# Ref#	Date	Time Ca	ars Axle	s TO1	T02	-	Speed Min Max Xit		-		.mum West	Amb Temp	Bat
Train# Ref# 	Date	Time Ca	ars Axle	s TO1 	TO2	-	-		-				Bat
Train# Ref# 	Date 	Time Ca	ars Axle	s TO1 	TO2	-	-		-				Bat
Train# Ref# 	Date	Time Ca	ars Axle	s TO1 	TO2	-	-		-				Bat

The table below lists the fields from the <u>header</u> section and the contents of each field.

Heading	Contents of Field
Version Info	The version numbers of the firmware and their release dates, which are in mm/dd/yy format. This firmware resides on the processor modules.
MP/KP	The five-digit milepost/kilometer post of the site. Section 4.0 - Serial Interface tells how to change this value using the MP/KP submenu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. Section 4.0 - Serial Interface tells how to set this value using the Track Number submenu of the Setup menu.
Alarm Limits	 The alarm parameters currently defined in the system setup. These values were in place at the time this report was run. The value after Absolute is set by the Absolute option on the Alarm Settings menu. The value after Differential is set by the Differential option on the Alarm Settings menu. The heading Hot Wheel only appears when the Hotwheel option on the Equipment Settings menu is enabled. The value after Hot Wheel is set by the Hotwheel option on the Alarm Settings menu. The value after Carside Slope is set by the Carside Slope option on the Alarm Settings menu. The value after Minimum is set by the Carside Minimum option on the Alarm Settings menu. The value after Cold Rail Temp is set by the Cold Rail Temperature option on the Alarm Settings menu.
Total Trains	The total number of trains visiting the site since the Trains directory was last cleared.

The table below lists the fields from the <u>detail</u> section and the contents of each field.

Heading	Contents of Field
Train#	The number that identifies the train in the Exceptions directory.
	There is one unlabeled column between those labeled "Train#" and "Date." This column can contain A , B , I , S , or nothing. If "A," an Exception Alarm was detected on the train. If "I," an Integrity Failure was detected. If "B," both an Exception Alarm and an Integrity Failure were detected. If "S," a System Alarm was detected, but Exception Alarms and Integrity Failures weren't. If blank, no Exception Alarm, Integrity Failure, or System Alarm was detected.
Date	The date the train arrived at the site. Date is in mm/dd/yy format. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time the train arrived at the site. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Cars	The total number of cars counted by the SmartScanNG ² system.
Axles	The total number of axles counted by the SmartScanNG ² system.
TO1	The total number of hits counted by gating transducer TO1. TO1 is the first gating transducer going north or east from the bearing scanner. It is the gating transducer <u>closest</u> to the bearing scanner.
TO2	The total number of hits counted by gating transducer TO2. TO2 is the second gating transducer going north or east from the bearing scanner. It is the gating transducer <u>farthest</u> from the bearing scanner.
AEI Tags	The total number of AEI tags stored. The number of tag pairs found plus those single tags that lack a match. This heading always appears, even if the AEI subsystem is disabled using the AEI option on the Equipment Settings menu.
Speed (mph)	The train's exit speed in miles per hour.
Dir	The direction the train was traveling. Valid values are N, S, E, and W.
Bearing Average	Under this heading are two columns, one for each bearing scanner, containing the average temperature read by the bearing scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west.
Wheel Maximum	Under this heading are two columns, one for each wheel scanner, containing the maximum temperature read by the wheel scanners. If the track orientation is east and west, the wheel scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. This field appears only when the Hotwheel option on the Equipment Settings menu is enabled.
Amb Temp	The ambient temperature, in degrees Fahrenheit, at the time the train arrived at the site.
Bat	The system battery voltage at the time the train passed the site.

To produce an Exception Summary report:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

- 2 Select the Exception Summary report.
- **3** To exit the serial interface and return the SmartScanNG² system to normal operation, type **X**.

6.5 Exception Detail Report

The Exception Detail report provides detailed information on a single train. When choosing this report, you'll be prompted for a train number. When prompted, enter a train number from the Exception Summary report. The train number appears under the column titled "Train#" in the detail section of the Exception Summary report.

Carside Slope alarm detection is enabled/disabled using the Carside Slope option on the Equipment Settings menu. Hotwheel alarm reporting is enabled/disabled using the Hotwheel option on the Equipment Settings menu. The AEI subsystem is enabled/disabled using the AEI option on the Equipment Settings menu.

Where wheel scanners are properly installed, wheel temperatures are always recorded, even if the Hotwheel option is disabled. On the other hand, if the AEI option is disabled during train passage, no AEI information is recorded. If the Carside Slope option is disabled during train passage, no Carside Slope alarms are generated. But, if it is enabled at the time a report is requested, a carside-slope alarm-limit line is generated for each car of the train. Below is a sample of part of an Exception Detail report when both the Hotwheel option and Carside Slope option were <u>enabled</u> at the time the report was requested. The AEI option was <u>disabled</u>. The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

Southern Technologies Corporation Next Generation Detector System
EXCEPTION DETAIL Train#: 47 Axles: 352 Speed MP/KP: 1234.5
Train#: 47 Axles: 352 Speed MP/KP: 1234.5 Date: 04/17/23 Cars: 87 Min: 15 Track: East Time: 08:47 Direction: North Max: 22 Temperature: +7F Shutters Open: 196 Avg: 18 Battery: 13.9v Length: 5124 Exit: 16 Subdivision: Windermere (6104)
Resistor Txdr Scanner Max Avg Read Req CF Counts Alarm Limit Carside Parms
East Brng 60 16 300 231B 0 TO1 352 Absolute 180 Slope: 1.60 West Brng 67 17 300 240B 0 TO2 352 Differential 150 Minimum: 130 East Whl 12 4 4 185B 98 Hot Wheel 600 West Whl 15 8 8 147B 95 Cold Rail Temp 10 Resistor Test Mode: Enabled
Software Version: CP_00-00 2023-04-13
AEI System Data
Tags Read Tags Stored: 174
Antenna 0: 87 Antenna 1: 87
GO Train Detect: No
System Alarms
Presence Hardware Failure Cold East Wheel Scanner Resistor Cold West Wheel Scanner Resistor
Integrity Failures
Successive Cold Wheel Resistors Exceeded
Axle Alarm Summary
NONE
Announcements Made
" CP Detector Mile 1 2 3 4 Point 5 Windemere East Track 7 Degrees Axles 3 5 2 System not worki " Mile 1 2 3 4 Point 5 Out "
• • •
(continued on next page)

		Rai	1	Whee	el							
Car	Axle	East					OFF	PW1	PW2	Alar	ms 	
1	1	1	2	12	15					NS	8105	
	2	6	6	4		73		21				
	3 4	5 2	5 6	4 4		73 72		21 22	27 27			
	4 5	2 2	5	4		72		22 22	27			
	6	5	3		8	72		22	27			
		ide Ave			West					East	134 West	136
2	7	7	5	4	8	71	410	25	29	NS	4555	
-	8	6	6		8	71		24			1000	
	9	5	10	4	8	71	160	24	28			
	10	5	9	4	8 8	71		24	28			
	11	6	10	4		71	159	23	28			
	12	3	6		8	70		23		_		
	Cars	ide Ave	e: East	5	West	7	Carside	Ala	arms:	East	138 West	141
3	13	30	30	4		70		23		STLX	6535	
	14	22	21		8	70		23				
	15 16	10 29	18 10	4 4	8 8	69 69		24 23	27 26			
		ide Ave								Fact	170 West	160
	Cars	JUE AV	e. Last	. 25	WEBL	17	Carside	ATC	at 1115 •	Last	170 West	100
4	17	22	26	4		69				STLX	6010	
	18	15	10	4		69		23				
	19 20	14 27	11 29	4 4	8 8	69 68		20 24	24 27			
		ide Ave								East	158 West	158
5	21	10	9	4	8	69	211	22	26	STLX	6094	
-	22	9	9	4 4	8	68		23	26			
	23	14	15	4		68	1278	22	26			
	24	10	14	4	8	68	128	21	25			
	Cars	ide Ave	e: East	10	West	11	Carside	Ala	arms:	East	146 West	147
б	25	14	13	4	8	67	181	23	26	STLX	2080	
	26	36	32	4		67		22	26			
	27	11	9	4		67		23	27			
	28 Cars	19 ide Ave	11 -: East	4	8 West	66 12		23 Ala	26 arms:	East	155 West	149
7	29	30	27	4			179			STLX	6018	
	30 21			4	8 8	67 66						
	31 32	23 43	26 40		8 8							
										East	187 West	182
8	33	30	29	4	R	66	204	21	25	AOKX	65562	
5	34	34	35	4	0	66	105	21	25		00000	
	35	7	5	4	8	65	125	23	27			
	36	27	28		8	65	124	21	25			
	Cars	ide Ave	e: East	28	West	28	Carside	Ala	arms:	East	174 West	174
9	37	33	31		8		175			CAIX	520172	
	38	11	13	4	8	65	123 1152	23	26			
	39	5	11									
	40	38	33				122			_		
	Cars	ide Ave	e: East	22	West	22	Carside	Ala	arms:	East	165 West	165

The <u>extended</u> Exception Detail report is divided into three sections. The <u>header</u> section contains general information about the site (like the MP/KP) and some detail information about the specific train (like the train's exit speed) that passed the site. The <u>detail</u> section contains more detailed information (like the car number) about the specific train. In between these two sections is the <u>system-events</u> section, which contains all System Alarms and Exception Alarms associated with the train.

The SmartScanNG² system calculates a checksum for <u>each train</u>. This checksum is stored with the train data. Later, when the system retrieves this data, it recalculates the checksum. If the two checksums don't match, the <u>extended</u> Exception Detail report so states (as shown below).

```
Southern Technologies Corporation
Next Generation Detector System
EXCEPTION DETAIL
CHECKSUM ERROR: StartAddr 134879 EndAddr 134930
```

In addition, <u>each axle</u> has a checksum associated with it. If an axle is determined to have an invalid checksum, the <u>extended</u> Exception Detail report so states in the associated axle's row (as shown below).

				Southern Next Ge	enerat	ion De		Sys		 	===:
				•							
Car	Axle	Trk	North	South	ON	OFF	PW1	 PW2	Alarms	 	
1	1	0	56	21	25	0	6	6		 	
	2	0	57	21	25	59	6	6			
	3			21			8				
	4								ddr 136427		
	5	1	56	21			6				
	6	1	56	21	25	59	б	б			
2	7	2	56	20	25	162	6	6			
	8	2	56	21				6			
				•							
				•							

The table below lists the fields from the <u>header</u> section and the contents of each field.

Heading	Contents of Field
Train#	The number that identifies the train in the Exceptions directory.
Date	The date the train arrived at the site. Date is in mm/dd/yy format. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time the train arrived at the site. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Length	The length of the train in feet.
Speed	The train's exit speed in miles per hour.
Axles	The total number of axles counted by the SmartScanNG ² system.
Direction	The direction the train was traveling. Valid values are North, South, East, and West.
Shutters Open	The number of seconds it took the train to pass over the site.
MP/KP	The five-digit milepost/kilometer post of the site. Section 4.0 - Serial Interface tells how to change this value using the MP/KP submenu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. Section 4.0 - Serial Interface tells how to set this value using the Track Number submenu of the Setup menu.
Temperature	The ambient temperature at the time the train arrived at the site. Temperature is in degrees Fahrenheit.
Battery	The system battery voltage at the time the train passed the site.
Rail	Location of the bearing scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west
Max	The maximum temperature, above the ambient temperature in degrees Fahrenheit, recorded by the bearing scanner on a given railside. For example, if the ambient temperature (at the time the train arrived at the site) is 77°F (25°C) and the value in this field is 112, the maximum temperature would be 189°F (87.2°C).
Avg	The average temperature, above the ambient temperature in degrees Fahrenheit, calculated from all recorded temperatures from the bearing scanner on a given railside. For example, if the ambient temperature (at the time the train arrived at the site) is 86°F (30°C) and the value in this field is 55, the average temperature would be 141°F (60.6°C).

Heading	Contents of Field
Resistor Read	The scanner resistor temperature (read after train passage), in degrees Fahrenheit, recorded by the bearing scanner on a given railside.
Resistor Req	The resistor temperature, in degrees Fahrenheit, required by the bearing scanner on a given railside to avoid a Cold Resistor alarm. This value was calculated using the amount of time the shutters were open and the Resistor Test Mode option in effect at the time the train exits the site. If the Resistor Test Mode option is <u>disabled</u> , a zero appears in this field.
	One of five uppercase letters follows the Resistor Req temperature.
	 B The baseline resistor integrity test method was used for this train. D The resistor integrity test (that is, the Resistor Test Mode option) was disabled by the user. I The interim resistor integrity test method was used for this train. T For this train, the shutters were open for less than 30 seconds. V For this train, the battery voltage (measured with the shutters open) was less than 12.5 volts.
	For D , T , and V , the required resistor heat is set to zero (that is, a zero appears in the Resistor Read field). A T or V indicates that the integrity test was not performed due to low voltage or insufficient shutter open time, which could result in an invalid resistor integrity test if it was performed.
CF	The percentage difference between the required resistor value and the value that was actually read. For example, if the required resistor temperature is 180 and the actual resistor temperature is 135 the correction factor would be $25\% (1 - (135 / 180) = .25)$, and 25 would appear in this field.
Txdr Counts	The gating transducer designator (either TO1 or TO2) followed by the total number of hits on that transducer.
Alarm Limit	The Hotwheel alarm level; the Hotbox alarm levels for Absolute and Differential; and the Cold Rail Temperature offset. These values were in place at the time the train arrived at the site.
	 The value after Absolute is set by the Absolute option on the Alarm Settings menu. The value after Differential is set by the Differential option on the Alarm Settings menu. The value after Hot Wheel is set by the Hotwheel option on the Alarm Settings menu. The value after Cold Rail Temp is set by the Cold Rail Temperature option on the Alarm Settings menu. Section 4.0 - Serial Interface tells how to set these values.

Heading	Contents of Field
Carside Parms	 The Carside Slope alarm parameter values that were in place at the time the train arrived at the site. The value after Carside Slope is set by the Carside Slope option on the Alarm Settings menu. The value after Minimum is set by the Carside Minimum option on the Alarm Settings menu. Section 4.0 - Serial Interface tells how to set these values.
Resistor Test Mode	The status of the post-train resistor integrity test at the time the train arrived at the site. Valid values (aka modes) are Enabled, Reduced, and Disabled. Section 4.0 - Serial Interface tells how to set this value using the Resistor Test Mode option on the Equipment Settings menu.
Wheel	The location of the wheel scanners. If the track orientation is east and west, the wheel scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. This field only appears when Hotwheel alarm reporting is <u>enabled</u> using the Hotwheel option on the Equipment Settings menu.
Max	The maximum temperature, above the ambient temperature in degrees Fahrenheit, recorded by the wheel scanner on a given railside. This field only appears when Hotwheel alarm reporting is <u>enabled</u> using the Hotwheel option on the Equipment Settings menu.
Avg	The average temperature, above the ambient temperature in degrees Fahrenheit, calculated from all recorded temperatures from the wheel scanner on a given railside. This field only appears when Hotwheel alarm reporting is <u>enabled</u> using the Hotwheel option on the Equipment Settings menu.
Resistor Read	The scanner resistor temperature (read after train passage), in degrees Fahrenheit, recorded by the wheel scanner on a given railside. This field only appears when Hotwheel alarm reporting is <u>enabled</u> using the Hotwheel option on the Equipment Settings menu.
Resistor Req	The resistor temperature, in degrees Fahrenheit, required by the wheel scanner on a given railside to avoid a Cold Wheel Scanner Resistor alarm. This value was calculated using the amount of time the shutters were open and the Resistor Test Mode option in effect at the time the train exits the site. If the Resistor Test Mode option is <u>disabled</u> , a zero appears in this field. This field only appears when Hotwheel alarm reporting is <u>enabled</u> using the Hotwheel option on the Equipment Settings menu.

Heading	Contents of Field
	One of five uppercase letters follows the Resistor Req temperature.
	 B The baseline resistor integrity test method was used for this train. D The resistor integrity test (that is, the Resistor Test Mode option) was disabled by the user. I The interim resistor integrity test method was used for this train. T For this train, the shutters were open for less than 30 seconds. V For this train, the battery voltage (measured with the shutters open) was less than 12.5 volts.
	For D , T , and V , the required resistor heat is set to zero (that is, a zero appears in the Resistor Read field). A T or V indicates that the integrity test was not performed due to low voltage or insufficient shutter open time, which could result in an invalid resistor integrity test if it was performed.
CF	The percentage difference between the required resistor value and the value that was actually read. For example, if the required resistor temperature is 180 and the actual resistor temperature is 135 the correction factor would be $25\% (1 - (135 / 180) = .25)$, and 25 would appear in this field.
AEI System Data	The number of AEI tags read (by antenna0 and antenna1) and the total number of tags stored for the train. Where both tags of a tag pair are operational, each antenna will read one tag of the pair. The total number of tags stored represents the number of tag pairs found plus those single tags that lack a match. This heading and the columns under it appear only when the AEI subsystem is <u>enabled</u> using the AEI option on the Equipment Settings menu.
Firmware Versions	The version numbers of the firmware and their release dates, which are in mm/dd/yy format. This firmware resides on the processor modules.

The table below lists the fields from the system-events section and the contents of each field.

Heading	Contents of Field
System Alarms	Lists any System Alarms and Integrity Failures detected at the time the train passed the site. If none were detected, this header is followed by the word "none." <i>Appendix A - System Alarms</i> describes the conditions and events that the system flags as System Alarms. <i>Appendix B - Integrity Failures</i> describes the conditions and events that the system flags as Integrity Failures.
Axle Alarm Summary	Lists each Exception Alarm found on the train and the axle on which it was found. If none were found, this header is followed by the word "none."

The table below lists the fields from the \underline{detail} section and the contents of each field.

Heading	Contents of Field
Car	The car number as determined by the firmware.
Axle	The axle number.
Trk	The truck number. Each railroad vehicle has two or more trucks (that is, wheel assemblies). The trucks are numbered, starting with 0, and increasing from the beginning of the train to the end. Each axle record is associated with one of these trucks. The axles are assigned the number of the truck with which they've been associated. These assigned truck numbers appear in this field. If the Hotwheel option on the Alarm Settings menu is <u>enabled</u> , this field doesn't appear.
Rail	Under this heading are two columns, one for each bearing scanner, containing the temperature read by the bearing scanners. If the track orientation is east and west, the bearing scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. If Hotwheel alarm detection is <u>disabled</u> , the word "Rail" doesn't appear, but the two columns do.
Wheel	Under this heading are two columns, one for each wheel scanner, containing the temperature read by the wheel scanners. If the track orientation is east and west, the wheel scanners are labeled north and south. If the track orientation is north and south, they are labeled east and west. This heading and the two columns under it appear only when Hotwheel alarm detection is enabled.
ON	The number of milliseconds a bearing was scanned.
OFF	The number of milliseconds between axles (when no axle was between the gating transducers).
PW1	The recorded width of the pulse generated by gating transducer TO1. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.
PW2	The recorded width of the pulse generated by gating transducer TO2. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.
Alarms	Any Exception Alarm found on the given axle.

To produce the extended Exception Detail report:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

2 Select Exception Detail.

This prompt appears.

Enter Train Number:

3 Type the train number.

If you type a three-digit <u>invalid</u> train number, the Main menu reappears. If you type a three-digit <u>valid</u> train number, the prompt below appears.

4 If you typed one or two digits, press [Enter].

If you type a three-digit <u>invalid</u> train number, the Main menu reappears. If you type a three-digit <u>valid</u> train number, this prompt appears.

Abbreviated? (y/n)

5 To produce the <u>extended</u> Exception Detail report, type N.

If you type an <u>invalid</u> train number, the Main menu reappears. If the typed train number is <u>valid</u>, a report for that train is produced. The last line of the report reads: "END OF REPORT - Press any key..."

6 To exit the serial interface and return the SmartScanNG² system to normal operation, type **X**.

6.6 Abbreviated Exception Detail Report

The <u>abbreviated</u> Exception Detail report is like the <u>extended</u> Exception Detail report. However, the abbreviated report doesn't display all the recorded axle data. It only displays axle data for:

- The car immediately preceding a car with an alarmed axle.
- The car containing the alarmed axle.
- The car immediately following the car with the alarmed axle.

For example, assume that a train consisted of 3 locomotives and 20 cars, and Exception Alarms were found on cars 3, 10, 15, and 17. The Abbreviated Exception Detail report for this train would only list axle data for cars 2, 3, 4, 9, 10, 11, 14, 15, 16, 17, and 18. These car numbers comprise the alarmed cars themselves and all cars immediately before and immediately after them.

Like the <u>extended</u> Exception Detail report, the <u>abbreviated</u> Exception Detail report is divided into three sections. The <u>header</u> section contains general information about the site (like the MP/KP) and some detail information about the specific train (like the train's exit speed) that passed the site. The <u>detail</u> section contains more detailed information (like the car number) about the specific train. In between these two sections is the <u>system-events</u> section, which contains all System Alarms and Exception Alarms associated with the train.

Below is a sample of part of an <u>abbreviated</u> Exception Detail report when the AEI option, the Carside Slope option and the Hotwheel option were all <u>disabled</u> at the time the report was requested. The contents of your report will be different.

Southern Technologies Corporation Next Generation Detector System EXCEPTION DETAIL ABBREVIATED _____ Axles: 278 Speed Cars: 68 Min: 46 MP/KP: 1234.5 Track: East Train#: 45 Date: 04/17/23 Direction: North Max: 49 Time: 06:16 Temperature: +12F Shutters Open: 67 Avg: 47 Length: 4058 Exit: 47 Battery: 13.9v Windermere (6104) Subdivision: _____ System Alarms VERY Slow Train Integrity Failure Stuck Dragger During Train Passage -----Axle Alarm Summarv 1 Dragging Equipment _____ Announcements made " CP Detector Mile 1 2 3 4 point 5 north track " " CP Detector Mile 1 2 3 4 point 5 north track dragging equipment near axle 1 temperature 2 4 train too slow not working " " CP Detector Mile 1 2 3 4 point 5 north track dragging equipment near axle 1 temperature 2 4 train too slow not working detector out " _____ Rail Car Axle East West ON OFF PW1 PW2 Alarms ____ _____ 1 1 0 0 44 0 18 18 Dragging Equipment 0 3 44 100 18 17 2 29 24 44 101 18 18 3 44 684 18 17 44 100 16 16 27 25 4 17 29 5 $6 \quad 26 \quad 27 \quad 44 \quad 101 \quad 16 \quad 16 \\$ Carside Ave: East 18 West 20 Carside Alarms: East 113 West 116 7 44 257 17 16 2 1 0 8 9 10 11 1 0 44 102 17 17 12 1 0 44 101 17 16 Carside Ave: East 1 West 0 Carside Alarms: East 91 West 90

To produce the abbreviated Exception Detail report:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

2 Select Exception Detail.

This prompt appears.

Enter Train Number:

3 Type the train number.

If you type a three-digit <u>invalid</u> train number, the Main menu reappears. If you type a three-digit <u>valid</u> train number, the prompt below appears.

4 If you typed one or two digits, press [Enter].

If you type a three-digit <u>invalid</u> train number, the Main menu reappears. If you type a three-digit <u>valid</u> train number, this prompt appears.

Abbreviated? (y/n)

5 To produce the <u>abbreviated</u> Exception Detail report, type Y.

If you type an <u>invalid</u> train number, the Main menu reappears. If the typed train number is <u>valid</u>, a report for that train is produced. The last line of the report reads: "END OF REPORT - Press any key..."

6 To exit the serial interface and return the SmartScanNG² system to normal operation, type **X**.

6.7 System Status Report

The System Status report contains the system's current setup configuration. Once a SmartScanNG² system is set up properly, print this report. Then, keep it in the wayside enclosure for future reference. Should you ever need to set up the system again, you'll have most of the information you'll need in this report.

Below is an example of the top half of a System Status report. Your report will be different.

Southern Technologies Corporation Next Generation Detector System SYSTEM STATUS REPORT		
Date:05/03/23 Time:15:36 Batte	ry: 11.8v Ambient Temp.: +91F	
SICM Board Rev 1.2 or lower Time Zone Eastern Daylight Savings Time Disabled AC Power On Velocity Enabled Software Version	Subdivision None MP/KP 1234.5 Track North Track Dir N/S GO Train Detect No	
CP_00-00 2023-04-13		
Speech Version		
0. CP Matthew 1.0 1. CP Mathieu 1.0 2. CP Subdivisions 1.0		
Alarm Settings		
Absolute	Differential 150 Cold Rails 3 Cold Res Counter 3	
Alarm Settings (Advanced)		
Carside Slope	Carside Minimum 130 Res Test: Minimum Wheel Avg 28 Wheel DSR Capture Temp 150	
Equipment Settings		
Dragger	Hot WheelYes High LoadNo AEINo Advance TransducersYes	
Equipment Settings (Advanced)		
Carside Slope Yes Gate Distance 24.0 in Pre Train Dragger Dist 200 ft Presence Timeout Period 10 sec Resistor Test Enabled Clearance Type Light Beam Transducer Type Magnetic	Winter CycleOct - MarDragger Debounce Time	
Message Settings		
Arrival Message	Customer Name	

:	
Message Settings	
Arrival Message.NoAxles.YesTemperature.YesPower Off.YesLength.YesLft/Rt Alarm Ref.NoUS Speech Options.YesSecondary Language.None	Customer Name
Message Settings (Advanced)	
Announce Hot Wheels Yes Announce High Load Yes Request EOT Timer 0 min Num EOT Repeats 0	Announce Differential Yes Announce Wide Load Yes Rebroad DTMF Code 5 sec EOT Repeat Delay 5 sec
Network Settings	
Use Static Address No Static Mask	Static IP
Sunshots	
Sunshot Filter Disabled Latitude 35.0456	Scanner Orientation 0 Longitude85.3097
Weather Settings	
Barometric Pressure Sensor Not Installed Wind Monitor Not Installed Display Wind Diagnostics No Slow Wind Speed Limit 2 mph Lower Interval Identical Limit 360 min Suspicious Temp. Interval 720 min Wind Alarm Reporting Interval 5 min	Altitude for Relative Pressure 0 ft High Wind Alarm Limit 50 mph Wind Poll Interval 15 sec Upper Interval Identical Limit 30 min Wind Gust Interval 5 min Re-enable Wind Updates 10 min
Port Settings	
COM1 (Serial Interface) Baud 19200 None COM3 (Velocity) Baud 19200 None COM5 (AEI) Baud 19200 None RS485 (Not Used) Baud 9600 None	COM2 (Not Used) Baud 19200 None COM4 (Not Used) Baud 19200 None COM6 (FlashHost) Baud 57600 None Page Lines 30
AEI Settings	
Tag Reader Type.NoneConsecutive Reads.2RF Attenuation (dB).0Antenna 0 Offset.0 (TO1)	ID Separation2 RF Frequency (MHz)915.000 Multi-Track Tag FilterDisabled Antenna 1 Offset0 (TO1)
Units Of Measure Settings	
Location Milepost Speed English Length English	Date Format English Temperature English
Scanner Calibration Date / Digital Potentiometer	Settings
Rail 1 Type III 05/16/2022 11:22 / 41 Wheel 1 Type III 04/28/2022 09:09 / 41	Rail 2 Type III 04/28/2022 09:07 / 40 Wheel 2 Type III 04/28/2022 09:11 / 42
Resistor Baseline	
Rail 1 Type III Valid Wheel 1 Type III Valid	Rail 2 Type III Valid Wheel 2 Type III Valid

The table below lists the fields on the System Status report and the contents of each field.

Heading	Contents of Field
Date	The date at the time this report was generated. Date is in mm/dd/yy format. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time at the time this report was generated. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Battery	The system battery voltage at the time this report was generated.
Ambient Temp	The ambient temperature at the time this report was generated. Temperature is in degrees Fahrenheit.
SICM Bd Rev	The revision of the 2300-110 System Interface board.
Subdivision	CP Subdivision identification currently assigned in system setup.
Time Zone	The time zone that is currently defined in the system setup. Valid values are Eastern, Central, Mountain, and Pacific. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu.
MP/KP	The five-digit milepost/kilometer post of the site. Section 4.0 - Serial Interface tells how to change this value using the MP/KP submenu.
Daylight Savings Time	Whether daylight-saving time is to be observed or not. If disabled, all times throughout the year are in standard time. If enabled, all times between the second Sunday in March and the first Sunday in November are in daylight-saving time. All other times are in standard time. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. Section 4.0 - Serial Interface tells how to change this value using the Track Number submenu of the Setup menu.
AC Power	Indicates if AC power is present.
Track Dir	The track direction of the site. Valid values are N/S (for north/south) and E/W (for east/west).
Velocity	Indicates if Velocity support is enabled or disabled.
Go Train Detect	Indicates if Go Train Detect is enabled or disabled.
Software Ver	Indicates software version currently installed.
Speech Version	Indicates speech version currently installed.
Alarm Settings	The alarm parameters and limits as they are currently defined in the system setup. Section 4.0 - Serial Interface tells how to change these parameters and limits using the Alarm Settings menu of the Setup menu.
Equipment	Equipment configuration as currently defined in the system setup. Section 4.0 - Serial Interface tells how to change this configuration using the Equipment Settings menu of the Setup menu.

Heading	Contents of Field
Messages	Message configuration as currently defined in the system setup. Section 4.0 - Serial Interface tells how to change this configuration using the Messages menu of the Setup menu.
Network	The network parameters as they are currently defined in the system setup. Section 4.0 - Serial Interface tells how to change these parameters using the Network Settings menu of the Setup menu.
Sunshots	The Sunshot parameters as they are currently defined in the system setup. Section 4.0 - Serial Interface tells how to change these parameters using the Sunshot Settings menu of the Setup menu.
Weather Settings	The Weather parameters as they are currently defined in the system setup. Section 4.0 - Serial Interface tells how to change these parameters using the Weather Settings menu of the Setup menu.
Port Settings	Communications port parameter settings as currently defined in system setup. These parameters reflect the baud rate and parity settings for each communications port. <i>Section 4.0 - Serial Interface</i> tells how to change these parameter settings using the Setup menu.
AEI Reader Parameters	This heading appears when the AEI subsystem is enabled using the AEI option on the Equipment Settings menu.
	 Below are the AEI Reader Parameters currently defined in the system setup. These values were in place at the time this report was run. ID Separation specifies the number of intervening tags that must be read and reported before a given tag is reported again. Valid values are 1, 2, 3, and 4. The default is 2. Consecutive Reads specifies the number of times that a tag must be read before it is considered a valid (reportable) tag. Valid values are 1, 2, 3, and 4. The default is 2. Decode as ASCII Tags specifies whether the tag data is to be interpreted as ASCII characters or in the encoded format. Section 4.0 - Serial Interface tells how to set these values using the AEI Reader Parameters menu of the Setup menu.
Units of	The Units of Measure parameters as they are currently defined in the system
Measure Scanner Calibration Date	setup. Section 4.0 - Serial Interface tells how to change these parameters. Date and time each scanner was last calibrated. The autocalibration function maintains these fields.
Resistor Data	See explanation below.

For the resistor integrity test that is performed after train passage, there are two methods used to calculate the expected resistor temperature. The baseline resistor integrity test method requires the prerequisite of valid resistor baseline data to be stored in nonvolatile memory. Until the system acquires this data, it applies the interim resistor integrity test method to each train. The resistor data used in the baseline resistor integrity test method appears at the bottom of the System Status report, as shown below.

 Resistor Data

 VOLTS AMB DATE
 TIME STATUS
 30
 40
 50
 60
 70
 80
 90
 100
 110
 120
 130

 140
 160
 180
 200
 220
 240
 260
 280
 300
 320
 340
 360
 380
 400
 420
 440
 460
 480

 RAIL 1 (TypeII)

 13.2
 043
 12/02/09
 15:57
 VALID
 56,
 71,
 82,
 91,100,105,111,116,118,122,124
 127,130,134,136,137,140,141,142,144,145,147,148,149,150,151,152,154,154

 RAIL 2 (TypeII)

 13.2
 043
 12/02/09
 15:57
 VALID
 58,
 71,
 81,
 89,
 96,101,105,109,110,112,115

 13.2
 043
 12/02/09
 15:57
 VALID
 58,
 71,
 81,
 89,
 96,101,105,109,110,112,115

 13.2, 123,125,125,125,128,129,130,131,132,134,134,135,137,137,138,138
 137,137,138,138

Included in the data above is a resistor heat profile of each scanner resistor, which covers a period of 30 to 480 seconds, in 10 and 20-second intervals. The differences in resistor heat between the two scanners are due to the cable lengths used in this example. A 65-foot (19.8-meter) cable for the rail1 bearing scanner and a 100-foot (30.5-meter) cable for the rail2 bearing scanner. Additional items in the data are the battery voltage measured with the shutters open, the date and time of the data acquisition, and the status of the heat profile data.

In this example, the status of both sets of resistor data is **VALID**. Meaning they are being used in the baseline integrity test for each train. There are two other possibilities for status, pending and invalid. If the word **PENDING** appears in the status column, the system is waiting for the resistors to cool before acquiring resistor data or for the battery to charge to 12.5 volts. **INVALID** indicates that the system has tried twice and could not acquire valid resistor data. In either case, the system applies the interim integrity test to passing trains, which doesn't require resistor baseline data.

The system acquires the resistor data 20 minutes after the user calibrates the scanners with the autocalibration function. The resistor data acquisition runs unattended. Twenty minutes is the cooling period required to allow the resistors to return to ambient temperature after autocalibration. If a train should interrupt the cooling period, the resistor data acquisition runs 20 minutes after the shutters close following the passage of the train.

During the resistor-cooling period, the system announces through the speaker the following. These announcements aren't broadcast over the radio.

- A beep sounds once per minute until two minutes before the resistor test.
- At two minutes until the test, "Scanner resistor test beginning in 2 minutes" is voiced.
- At one minute until the test, "Scanner resistor test beginning in 1-minute" is voiced.

After the resistor cooling period:

- As the test begins, "Testing" is voiced. During this time, the word PENDING appears in the status column of the Resistor Data section.
- If the test was successful, "System working" is voiced. The word VALID appears in the status column of the Resistor Data section, signifying that the baseline test applies to each passing train.
- If the test wasn't successful, "Scanner resistor test beginning in two-zero minutes" is voiced, meaning that the system will try once more after 20 minutes to acquire an accurate resistor heat profile. During this time, the word PENDING appears in the status column of the Resistor Data section. If the test fails a second time, the word INVALID appears in the same column. The system applies the interim integrity test to each passing train while either PENDING or INVALID appears.

To produce a System Status report:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

- 2 Select System Status.
- 3 After producing the report, you are returned to the Main menu.

At this time, you can produce another report by selecting the appropriate option.

- 4 When done, close the LOG file.
- **5** To exit the serial interface and return the SmartScanNG² system to normal operation, type **X**.

6.8 Last Train Report

The Last Train report is identical to the Train Detail report except for this report, you don't specify a train. A report on the most current train is produced.

To produce a Last Train report:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

```
[D] - Exception Detail
[E] - System Status Report
[F] - Last Train
[G] - Train DSRs
[H] - AEI Diagnostic
```

2 Select Last Train to produce the report.

This prompt appears.

Abbreviated? (y/n)

- **3** To produce the abbreviated Last Train report, type Y. To produce an extended Last Train report, type **N**.
- 4 To exit the serial interface and return the SmartScanNG² system to normal operation, type **X**.

6.9 Train DSRs

Train DSR (Dynamic Scan Rate) records store those temperature samples collected by a scanner that exceed the warm-bearing or warm-wheel trigger level. Only 16 bearing-related and 16 wheel-related DSR records are kept per train. When prompted, type a train number from the Train Summary report. The train number appears under the column titled "Train#" in the <u>detail</u> section of that report. Those trains with DSR records will have a single character status code in column A (see Section 6.1) of the Train Summary Report.

1 Using the serial interface, display the Main menu.

```
Main Menu - Comm

.

[F] - Last Train

[G] - Range of trains

[H] - Train DSRs
```

2 Select Train DSRs.

A prompt like this appears:

Enter train number:

3 Enter the number of the selected train. A prompt like this appears:

```
Is train from Exception Summary report? (y/n)
Separate by gate period? (y/n)
```

To display DSR samples in the single-line, format, answer 'N' to the "Separate by gate period? (y/n)" prompt. A report like this appears:

```
No bearing DSRs stored.
Warmest 16 Wheel DSRs:
Axle 13, North Wheel Scanner:
   8,8,8,8,8,8,8,8,8,8,8,8,8,8,12,15,21,30,38,52,70,88,112,140,165,190,2
   26,249,292,327,365,403,431,441,448,449,445,441,426,404,383,361,341,
   323, 305, 292, 278, 260, 249, 242, 236, 234, 231, 228, 224, 222, 221, 220, 220, 220
   ,219,219,219,220,221,224,228,231,234,236,240,246,253,268,285,295,30
   8,324,339,355,365,372,371,361,350,328,305,283,248,231,199,180,157,1
   36,112,91,74
Axle 13, South Wheel Scanner:
   8,8,8,8,8,8,8,8,8,8,8,8,8,8,12,18,26,36,46,66,88,114,146,171,197,236,
   272,310,358,404,448,492,513,527,535,536,531,519,507,487,459,439,414
   ,389,369,349,332,316,305,296,288,283,274,268,262,260,258,256,256,256
   4,254,254,256,256,260,264,268,276,283,289,295,303,313,327,341,357,3
   78,399,421,437,443,448,446,441,427,399,367,334,303,270,238,213,186,
   161,138,112,90
Axle 14, South Wheel Scanner:
   8,8,8,8,8,8,8,8,8,8,8,8,8,8,12,21,29,40,55,74,94,128,159,189,230,260,
   306, 352, 405, 456, 508, 553, 593, 618, 627, 629, 626, 616, 590, 568, 536, 509, 489
   ,459,439,416,395,375,359,347,334,327,321,313,310,308,306,305,305,30
   4,304,304,305,306,307,310,312,320,325,333,343,353,367,382,400,421,4
   41,458,485,504,512,518,516,509,498,467,437,398,357,321,288,246,222,
   189,163,140,112
```

The display DSR samples by gate period, answer 'Y' to the "Separate by gate period? (y/n)" prompt. Displaying an axle's 96 DSR samples by gate period separates the recorded values into three groups:

- **Pre-gate:** The 24 samples (1-24) recorded immediately before an axle passes between the transducers.
- **In-gate:** The 48 samples (25-72) recorded as an axle passes between the transducers.
- **Post-gate:** The 24 samples (73-96) recorded immediately after an axle passes between the transducers.

A report like this appears:.

```
Warmest 16 Bearing DSRs:
Axle 1, North Bearing Scanner:
In-gate :
1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,2,5,10,17,26,31,41,52,61,71,79,87,93,96,
98,97,96,93,89,84,78,71,64,56,44,34,24,21,15,10
Axle 6, South Bearing Scanner:
In-gate :
13,117,117,117,117,113,108,103,95,86,78,65,53,40,29,25
Axle 8, South Bearing Scanner:
In-gate :
1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,2,5,8,16,27,35,48,63,77,91,106,116,124
,131,136,138,137,134,130,124,117,110,102,91,76,61,46,34,29
Warmest 16 Wheel DSRs:
Axle 9, North Wheel Scanner:
Pre-gate : 8,8,8,8,8,8,8,8,8,8,8,8,8,8,8,12,15,21,30,38,52,70,88,112,140,165
In-gate :
190,226,249,292,327,365,403,431,441,448,449,445,441,426,404,383,361,341,323,
305, 292, 278, 260, 249, 242, 236, 234, 231, 228, 224, 222, 221, 220, 220, 220, 219, 219, 219,
220, 221, 224, 228, 231, 234, 236, 240, 246, 253
Post-gate:
268, 285, 295, 308, 324, 339, 355, 365, 372, 371, 361, 350, 328, 305, 283, 248, 231, 199, 180,
157,136,112,91,74
```

6.10 AEI Diagnostic Detail Report

The AEI Diagnostic Detail report provides detailed information on a single train. It contains information that can be useful in troubleshooting AEI-related problems. When choosing this report, you'll be prompted for a train number. When prompted, type a train number from the Train Summary report. The train number appears under the column titled "Train#" in the <u>detail</u> section of that report.

The AEI subsystem is enabled/disabled using the AEI option on the Equipment Settings menu. If the AEI option is disabled during train passage, no AEI information is recorded.

Below is a sample of part of an AEI Diagnostic Detail report when both the AEI option and the Hotwheel option on the Equipment Settings menu were <u>enabled</u> at the time the report was requested. The Carside Slope option on the Equipment Settings menu was <u>disabled</u>. Also, both the AEI and Hotwheel options were <u>enabled</u> while the specified train was passing the site. The contents of your report will be different. The version information in the sample below is for illustrative purposes only. It doesn't represent any real release of the firmware.

Like the Train Detail report, the AEI Diagnostic Detail report is divided into three sections. The <u>header</u> section contains general information about the site (like the MP/KP) and some detail information about the specific train (like the train's exit speed) that passed the site. The <u>detail</u> section contains more detailed information (like the car number) about the specific train. In between these two sections is the <u>system-events</u> section, which contains all System Alarms and Exception Alarms associated with the train.

Southern Technologies Corporation Next Generation Detector System AEI Diagnostic Subdivision: Windermere (6104) Train#: 240 Date: 05/04/23 Speed: 30MPH MP/KP: 1234.5 Time: 09:01 Axles: 446 Track: Single Direction: South Length: 8358ft Temperature: +41F Shutters Open: 168 Battery: 13.9v AEI System Data: Tags Read: 157 Length: 9534ft Axles: 452 Antenna 0: 78 Antenna 1: 79 _____ T94 Report Data: Locomotives - Tagged: 2 Untagged: 0 Conversion Status: A Railcars - Tagged: 78 Untagged: 1 Conversion Status: A Status Codes- Equip : G Movement: A Termination: N Min: 39 Max: 43 Avq: 42 Speed -- Length: 3 Platform: 5 Errors Software Version: CP_00-00 2023-04-13 TMSTMP Axle Truck On Off PW1 PW2 00000 Car=1, Axles=6, Trks=2, Tags=1, Spd=38, Dir=N, Len=72, AntOWindow=00000 00407
 00011
 1
 1
 34
 0
 16
 17

 00125
 2
 1
 34
 79
 15
 17
 3 1 35 78 13 16 00238 00763 *UP 5536 side=L trk=2 len=73 axls=6 S|L|0|2 hs0= 0 hs1=12 flags=201 rcvdTS=00867 00945 02666 QCnt=0 00811 4 2 34 537 16 17 2 34 79 16 17 2 34 79 16 17 5 00925 б 01039 01157 CarEnd= 1, flags=2, Ant1Window=00697 01157 01158 Car=2, Axles=6, Trks=2, Tags=2, Spd=38, Dir=N, Len=75, AntOWindow=01158 01673 01275 7 3 34 201 16 17 335781416334781517 01388 8 9 01502 *UP 7014 side=L trk=3 len=76 axls=6 S|L|0|4 hs0= 4 hs1= 9 flags=111 01521 rcvdTS=01617 | 01618 | 06267 QCnt=0 7014 side=R trk=4 len=76 axls=6 S|L|0|4 hs0= 4 hs1= 9 flags=224 02077 TIP rcvdTS=02167 02216 06267 QCnt=0
 02123
 10
 4
 34
 585
 16
 17

 02235
 11
 4
 34
 79
 16
 17
 4 34 79 16 17 12 02349 02441 CarEnd= 2, flags=6, AntlWindow=02011 | 02441 ٠ •

The table below lists the fields from the <u>header</u> section and the contents of each field.

Heading	Contents of Field
Train#	The number that identifies the train in the Trains directory.
Date	The date the train arrived at the site. Date is in mm/dd/yy format. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Time	The time the train arrived at the site. Time is in 24-hour hh:mm format, where 8 a.m. is 08:00, noon is 12:00, 8 p.m. is 20:00, and midnight is 00:00. Section 4.0 - Serial Interface tells how to change this value using the Date and Time submenu of the Setup menu.
Length	The length of the train in feet.
Speed	The train's exit speed in miles per hour.
Axles	The total number of axles counted by the SmartScanNG ² system.
Direction	The direction the train was traveling. Valid values are North, South, East, and West.
Shutters Open	The number of seconds it took the train to pass over the site.
MP/KP	The five-digit milepost/kilometer post of the site. Section 4.0 - Serial Interface tells how to change this value using the MP/KP submenu.
Track	The track designator of the site. For single-track sites, the value is Single. For double-track sites, valid values are North, South, East, West, Main 1, Main 2, Main 3, and Middle. Section 4.0 - Serial Interface tells how to set this value using the Track Number submenu of the Setup menu.
Temperature	The ambient temperature at the time the train arrived at the site. Temperature is in degrees Fahrenheit.
Battery	The system battery voltage at the time the train passed the site.
AEI System Data	This field provides total AEI tags read, total length, and total axles.
T94 Report Data	This field provides number of tagged and untagged locomotives and railcars, status codes, movements, and various other T94 related data.
Software Version	The average temperature, above the ambient temperature in degrees Fahrenheit, calculated from all recorded temperatures from the bearing scanner on a given railside. For example, if the ambient temperature (at the time the train arrived at the site) is 86°F (30°C) and the value in this field is 55, the average temperature would be 141°F (60.6°C).

The following excerpt is from the detail section of the AEI Diagnostic report

•

```
TMSTMP Axle Truck On Off PW1 PW2

00000 CarStart=1, Axles=4, Trucks=2, Tags=1, Speed=23, Len=59

00026 1 1 58 0 19 19

00285 2 1 59 203 12 10

00945 XRR 6113 side=L trk=2 len=59 axls=4 51|5|0|2 hs0= 0 hs1=13 flags=181

01030 3 2 58 685 20 20

01294 4 2 58 205 15 14

01535 CarEnd= 1
```

The table below lists the fields from the detail section and the contents of each field.

Heading	Contents of Field
TMSTMP	The timestamp of a recorded event in milliseconds after train detection.
Car	The car number as determined by the firmware.
Axle	The axle number.
Trk	The truck number. Each railroad vehicle has two or more trucks (that is, wheel assemblies). The trucks are numbered, starting with 0, and increasing from the beginning of the train to the end. Each axle record is associated with one of these trucks. The axles are assigned the number of the truck with which they've been associated. These assigned truck numbers appear in this field. If the Hotwheel option on the Equipment Settings menu is enabled, this field doesn't appear.
ON	The number of milliseconds a bearing was scanned.
OFF	The number of milliseconds between axles (when no axle was between the gating transducers).
PW1	The recorded width of the pulse generated by gating transducer TO1. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.
PW2	The recorded width of the pulse generated by gating transducer TO2. There is no fixed value for the pulse widths. Slower trains generate wider pulse widths (that is, they generate larger values) than faster-moving trains.

The AEI Diagnostic report has one line of data for every AEI tag associated with each car. See highlighted data line in the example below.

```
TMSTMP Axle Truck On Off PW1 PW2

00000 CarStart=1, Axles=4, Trucks=2, Tags=1, Speed=23, Len=59

0026 1 1 58 0 19 19

00285 2 1 59 203 12 10

00945 XRR 6113 side=L trk=2 len=59 axls=4 51 | 5 | 0 | 2 hs0= 0 hs1=13 flags=181

01030 3 2 58 685 20 20

01294 4 2 58 205 15 14

01535 CarEnd= 1

.
```

The table below defines the relevant fields in the AEI tag portion of car data.

Field Value	Field Definition
00945	Timestamp of tag read.
XRR 6113	AEI vehicle identification
side=L	Left side of car
trk=2	Truck two of car.
len=59	Car length of 59 feet.
axls=4	Four axle car.
51 5 0 2	 51 is the Data Format Code. 5 is the Equipment Group Code (5 = locomotive). 0 is the Platform Code. 2 is the Tag Type.
hs0= 0	Handshakes on antenna-0 equal zero.
hs1=13	Handshakes on antenna-1 equal thirteen.
flags=181	For diagnostic purposes.

To produce an AEI Diagnostic report:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

```
[G] - Train DSRs
[H] - AEI Diagnostic
[I] - Setup
[J] - Event log
```

2 Select AEI Diagnostic.

This prompt appears.

Enter Train Number:

3 Type the train number.

If you typed a three-digit <u>invalid</u> train number, the Main menu reappears. If you typed a three-digit <u>valid</u> train number, a report for that train is produced. The last line of the report reads: "END OF REPORT - Press any key..."

4 If you typed one or two digits, press [Enter].

If you typed an <u>invalid</u> train number, pressing **[Enter]** causes the Main menu to reappear. If the typed train number is <u>valid</u>, pressing **[Enter]** produces a report for it. The last line of the report reads: "END OF REPORT - Press any key..."

5 To exit the serial interface and return the SmartScanNG² system to normal operation, type **X**.

6.11 Event Log Report

The Event Log report is used for diagnostics. As certain system events occur, entries are posted into the event log. Each time an entry is made into this log, it receives an event number, the date and time that the event was recorded, and an event description.

The entries are stored in a section of SRAM that can hold up to 300 separate entries. Each time an event is recorded which exceeds this maximum, the new one overwrites the oldest recorded event. The entries are saved during a power outage but can be deleted with the Clear Event Log option on System Functions menu. Producing the report at this time produces a "No Events" message. If events have been recorded and not cleared, they're listed in chronological order, beginning with the most recently recorded event.

Below is a sample of part of an Event Log report. The contents of your report will be different. The date/time at the top of the report is the system date/time at the time the report was generated. Each line of text (that is, each event) contains these fields.

- The sequential number assigned to the event as it was generated
- The date at which the event was recorded (date is in dd/mm/yy format)
- The time at which the event was recorded (time is in 24-hour hh:mm:ss format, where 8 a.m. is 08:00:00, noon is 12:00:00, 8 p.m. is 20:00:00, and midnight is 00:00:00)
- The event description

```
Log: /FLASH/SYSTEM/logs/EVENTLOG.txt
[05/04/2023 09:30:57] (55) - Admin logged in: id-25, telnet ip-184.174.165.45
[05/04/2023 09:18:06] (55) - Telnet Connection timed out: id-25
[05/04/2023 09:05:36] (55) - Admin logged in: id-25, telnet ip-184.174.165.45
[05/04/2023 \ 09:04:04] (47) - Stored train #240
[05/04/2023 09:04:02] (47) - Train Departure
[05/04/2023 09:01:10] (47) - Train Arrival
[05/04/2023 08:58:07] (55) - Telnet Connection timed out: id-25
[05/04/2023 08:46:14] (55) - Admin logged in: id-25, telnet ip-184.174.165.45
[05/04/2023 06:33:47] (47) - Stored train #239
[05/04/2023 06:33:37] (47) - Train Departure
[05/04/2023 06:30:55] (47) - Train Arrival
[05/04/2023 06:16:13] (47) - Stored train #238
[05/04/2023 06:16:10] (47) - Train Departure
[05/04/2023 06:07:28] (47) - Train Arrival
[05/04/2023 04:34:38] (55) - Telnet Connection lost: id-22
[05/04/2023 00:59:36] (55) - Telnet Connection lost: id-23
[05/04/2023 00:59:36] (55) - Telnet Connection lost: id-25
[05/04/2023 00:21:53] (47) - Stored train #237
[05/04/2023 00:21:49] (47) - Train Departure
[05/04/2023 00:17:28] (47) - Train Arrival
[05/03/2023 22:04:29] (47) - Stored train #236
[05/03/2023 22:04:23] (47) - Train Departure
[05/03/2023 21:57:57] (47) - Train Arrival
[05/03/2023 21:38:15] (47) - Stored train #235
```

To produce an Event Log report:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

[G] - Train DSRs [H] - AEI Diagnostic [I] - Setup [J] - Event log

- 2 Select the **Event Log**.
- **3** To exit the serial interface and return the SmartScanNG² system to normal operation, type **X**.
Currently, the two ways of reporting defects are:

- Announcements made via the road channel
- Reports, which may be printed to provide detailed defect information

This section describes radio announcements. The prior section describes reports.

Radio announcements consist of a set of predefined spoken messages with each message triggered by a particular event or set of events. The message formats and announcement criteria are covered below.

The SmartScanNG² will monitor the Carrier Detect line from the radio to determine when the radio channel is clear. If the SmartScanNG² needs to make an announcement and the radio channel is not clear, the SmartScanNG² will delay the announcement for up to 30 seconds. If, after 30 seconds, the radio channel is still not clear, the announcement will be broadcast anyway.

NOTE: In the examples that follow, the sample message "*CP Detector*" is announced because it was <u>enabled</u> using the **Announce Customer Name option** on the Messages menu. **Section 4.0 - Serial Interface** tells how to enable and disable this message. If a subdivision is selected from the Great Sandhills Railway Service Area, the detector will announce "GSR Detector" instead of "CP Detector" for the Customer Name. The available subdivisions are "Burstall" and "Empress." "Burstall" is also in the "Alberta" Service Area. If the "Alberta" \rightarrow "Burstall" is selected, the detector will announce "CP Detector."

7.1 Arrival Messages

The arrival message is used to announce train arrival at the site. This message is optional. It is enabled or disabled using the **Announce Train Arrival option** on the Messages menu. The format of this announcement is:

[CP Detector | GSR Detector*] Mile (mile) [subdivision] [track]

At a double-track site, "track" represents the position in the message text that the track designator (such as "East Track") is inserted into the announcements. At a single-track site, no message text is inserted for the track indicator.

For example, at a single-track site, the announcement is like this. In this example, milepost 359.4 and subdivision Windermere were used.

```
CP Detector
Mile 3-5-9 Point 4
Windermere
```

At a double-track site, the announcement is like this. In this example, milepost 297.1 and subdivision Windermere was used.

```
CP Detector
Mile 2-9-7 Point 1
Windermere
South Track
```

The arrival message is only announced once per train.

7.2 Real-Time Messages

Real-time messages consist of announcements that occur as the train is passing over the site. No matter what kind of defect was detected, there is only one format for this announcement, and it is:

Tone (type of alarm)

Real-Time Message Examples:

Dragging Equipment [beep] Dragging Equipment

Multiple Alarms [beep] [alarmtype]... Repeated for up to 6 real-time alarms, regardless of alarm type. Alarmtype can be dragging equipment, dimensional shipment, hotbox, or hotwheel

HighLoad, HiWide, WideLoad1, WideLoad2 [beep] Dimensional Shipment

Hotbox Alarm [beep] Hotbox

Hotwheel Alarm [beep] Hotwheel

7.3 Post-Train Messages

Post-train (that is, end-of-train) announcements are given after the train has left the site and all the recorded train data has been processed by the SmartScanNG² system.

These messages consist of four distinct scenarios, each with its own spoken message. The scenarios are:

- Exception Alarms not detected and Integrity Failures not detected
- Exception Alarms not detected and Integrity Failures detected
- Exception Alarms detected and Integrity Failures not detected
- Exception Alarms detected and Integrity Failures detected

Exception Alarms are associated with axles. When the **Clearance Mode option** on the Messages menu is set to <u>separate</u>, there are eight Exception Alarms. They are the Absolute, Carside Slope, Differential, Dragging-Equipment, **High-Load**, Hotwheel, Pyrometer Saturation, and **Wide-Load** alarms. When the **Clearance Mode option** is set to <u>multiplexed</u>, there are seven Exception Alarms. They are the Absolute, Carside Slope, Differential, Dragging-Equipment, High-Wide, Carside Slope, Differential, Dragging-Equipment, High-Wide, Hotwheel, and Pyrometer Saturation alarms.

The four types of Hotbox alarms are Absolute alarms, Differential alarms, Pyrometer Saturation alarms, and Carside Slope alarms. When one of these four alarms occurs, a Hotbox alarm is announced. The system only announces Dragging-Equipment, High-Load, High-Wide, Hotbox, Hotwheel, and Wide-Load.

Integrity Failures are the Dead Battery, Dead Resistor, Dead Wheel Scanner Resistor, Stuck Dragger During Train Passage, Stuck Dragger Pretrain, Stuck High-Load Detector Pretrain, Stuck Wide-Load Detector Pretrain, Successive Cold Rails Exceeded, Successive Cold Resistors Exceeded, Successive Cold Wheel Resistors Exceeded, Successive Cold Wheels Exceeded, Train Present on Restart, <u>and sometimes</u> Highrange Transducer Miscounts alarms.

Below is the Messages Settings menu. The options on this submenu affect the phrases broadcast to a passing train or are used to modify the parameters associated with the rebroadcast function.

Messages Settings
<pre>[A] - Axles</pre>
[G] - Repeat No Defects No
[H] - Cars Count No
<pre>[I] - Customer Name Yes [J] - Arrival Message No [K] - Lft/Rt Alarm Ref No [L] - Car ID With Alarm Yes [M] - US Speech Options Yes [N] - Primary Broadcast Language English_Matthew [O] - Secondary Broadcast Language . None [P] - Advanced [X] - Exit</pre>

Enabling one or more of these options generates the ancillary messages: A (axle count), B (train speed), C (site ambient temperature), D (train length), E (slow train), F (power off), and H (number of cars). The other options of the Messages menu aren't used to generate ancillary messages.

In the examples that follow, not all ancillary messages are shown. This is because only axle count and train speed were <u>enabled</u>. Site ambient temperature, train length, number of cars, power off, and slow train were <u>disabled</u>. **Section 4.0 - Serial Interface** tells how to enable and disable these messages using the Messages menu of the Setup menu.

When the Highrange Transducer Miscounts alarm <u>or</u> Very Slow Train alarm occurs, the system won't announce axle count, train speed, train length, or number of cars (even if these messages are enabled).

Post-Train Message Examples:

Dragging Equipment

[beep] [CP Detector |GSR Detector*] mile 5432.1 [subdivision] [track] 24 degrees axles 118 dragging equipment near axle 13 car id TBOX 663532 mile 5432.1 out

Excessive Alarms

[beep] [CP Detector | GSR Detector*] mile 5432.1 [subdivision] [track] 24 degrees axles 118 more than 6 alarms first alarm hotbox axle 14 car id TBOX 663532 inspect entire train both sides from first alarm to rear of train or as instructed mile 5432.1 out

HighLoad, HiWide, WideLoad1, and WideLoad2

[beep] [CP Detector |GSR Detector*] mile 5432.1 [subdivision] [track] 24 degrees axles 118 dimensional shipment near axle 13 car id TBOX 663532 mile 5432.1 out

Hotbox Alarm

[beep] [CP Detector |GSR Detector*] mile 5432.1 [subdivision] [track] 24 degrees axles 118 hotbox north rail axle 14 car id TBOX 663532 mile 5432.1 out

Hotbox Alarm (Lft/Rt Alarm Ref)

[beep] [CP Detector |GSR Detector*] mile 5432.1 [subdivision] [track] 24 degrees axles 118 hotbox left side axle 14 car id TBOX 663532 mile 5432.1 out

Hotbox Alarm Integrity Failure

[beep] [CP Detector |GSR Detector*] mile 5432.1 [subdivision] [track] 24 degrees axles 118 hotbox north rail axle 14 car id TBOX 663532 system not working mile 5432.1 out

Hotwheel Alarm

[beep] [CP Detector |GSR Detector*] mile 5432.1 [*subdivision*] [*track*] 24 degrees axles 118 hotwheel axle 45 car id ETTX 820838 mile 5432.1 out

Integrity Failure

[CP Detector | GSR Detector*] mile 5432.1 [*subdivision*] [*track*] 24 degrees axles 118 system not working mile 5432.1 out

No Defects

[CP Detector | GSR Detector*] mile 5432.1 [subdivision] [track] 24 degrees axles 118 no alarms mile 5432.1 out

No Defects All Ancillary

[CP Detector | GSR Detector*] mile 5432.1 [*subdivision*] [*track*] 24 degrees axles 118 total cars 26 no alarms speed 39 length 1367 mile 5432.1 out

7.3.1 Nothing Detected

When neither an Exception Alarm nor an Integrity Failure is detected, the no-defect message is announced. The format of this announcement is:

If the **Repeat No Defects option** on the Messages menu is <u>disabled</u>, the format of this announcement is:

```
[CP Detector | GSR Detector*] Mile (mile) [subdivision] [track]
[temperature] [axlecount] [carcount] no alarms [other ancillary
messages] Mile (mile) Out
```

If the **Repeat No Defects option** is <u>enabled</u>, the format of this announcement is:

```
[CP Detector |GSR Detector*] Mile (mile) [track] [temperature]
[axlecount] [carcount] no alarms repeat no alarms [other ancillary
messages] Mile (mile) Out
```

For example, at a single-track site when the **Repeat No Defects option** is <u>disabled</u>, the announcement is like this.

```
CP Detector
Mile 3-2-1 Point 4
Maple Creek
Speed 4-5
No Alarms
Total Axles 9-8
Mile 3-2-1 Point 4 Out
```

At a double-track site, when the **Repeat No Defects option** is <u>enabled</u>, the announcement is like this.

```
CP Detector
Mile 3-9-9 Point 1
Maple Creek
South Track
Speed 5-3
No Alarms
Repeat No Alarms
Total Axles 1-4-2
Mile 3-9-9 Point 1 Out
```

7.3.2 Only an Integrity Failure Detected

Integrity failures are caused when the system determines that a condition exists that could prevent proper scanning of a train. They indicate an unusual operating condition that may require maintenance. Integrity failures appear in the header of Train Detail reports and Exception Detail reports. *Appendix B - Integrity Failures* describes the conditions and events that the SmartScanNG² system flags as Integrity Failures.

When no Exception Alarms are detected, but an Integrity Failure is detected, only Not Working is announced. When no pretrain auxiliary alarm is detected, the format of this announcement is:

```
[CP Detector|GSR Detector*] Mile (mile) [subdivision] [track]
[temperature] [axlecount] [carcount] System Not Working Mile (mile)
Out
```

For example, at a double-track site, the announcement is like this.

```
CP Detector
Mile 2-4-6 Point 8
Maple Creek
South Track
Speed 5-3
Total Axles 9-2
System Not Working
Mile 2-4-6 Point 8 Out
```

7.3.3 Only Exception Alarms Detected

When one or more Exception Alarms are detected, and an Integrity Failure isn't detected, the alarms are announced. The format of this announcement is:

```
[CP Detector |GSR Detector*] Mile (mile) [subdivision] [track]
[temperature] [axlecount] [carcount] [alarm
announcements] [inspect remainder of train] [other ancillary
messages] Mile (mile) Out
```

Per train, only the first six alarms are announced. If there is more than one alarm, an alarm count will be announced before the alarm announcements. If there are more than six alarms, "more than six alarms" will be announced for alarm count, only the first alarm will be announced, and inspect remainder of train message will follow the alarm message.

Hotwheel alarms use the same general format as Hotbox alarms. High-Load, High-Wide, and Wide-Load alarms use the same general format as Dragging-Equipment alarms.

The **Clearance Type option** on the Equipment Settings menu is either tripwire <u>or</u> light beam. This option is only used for high-load detectors and wide-load detectors. <u>Both</u> high-load detectors and wide-load detectors must be <u>either</u> trip-wire detectors or light-beam detectors. When a wide-load detector is configured for tripwire operation, the system only records one Wide-Load alarm, regardless of the wide-load signal status. This is because you can only break a wire once.

When it is configured for light-beam operation, the system records every Wide-Load alarm that occurs. However, the system won't flag Wide-Load alarms on consecutive axles. At least one unalarmed axle must separate the alarmed axles. Regardless of the number of detected Wide-Load alarms, the system only announces a maximum of two.

When a high-load detector is configured for tripwire operation, the system only records one High-Load alarm, regardless of the high-load signal status. This is because you can only break a wire once.

When it is configured for light-beam operation, the system records every High-Load alarm that occurs. However, the system won't flag High-Load alarms on consecutive axles. At least one unalarmed axle must separate the alarmed axles. Regardless of the number of detected High-Load alarms, the system only announces a maximum of two.

The **Clearance Mode option** on the Equipment Settings menu is either separate <u>or</u> multiplexed. This option is only used for high-load detectors and wide-load detectors. When this option is set to <u>separate</u>, the alarms coming from the high-load detectors are announced as High-Load alarms, <u>and</u> the alarms coming from the wide-load detectors are announced as Wide-Load alarms. When this option is set to <u>multiplexed</u>, the alarms coming from the high-load detectors are announced as Wide-Load alarms. When this option is set to <u>multiplexed</u>, the alarms coming from the high-load detectors and wide-load detectors are announced as High-Wide alarms.

The **Announce Car Identification option** on the Messages menu shows whether car-identification information is to be announced (YES) or not announced (NO). When this option is set to YES, <u>and</u> an Exception Alarm is found on a car, the car-identification information is announced right after the Exception Alarm is announced. This, of course, will only happen if the **AEI option** on the Equipment Settings menu is enabled (YES) <u>and</u> the AEI subsystem is functioning properly during train passage. In the examples that follow, the Announce Car Identification option was set to NO.

The **Announce Left-Right Alarm Reference option** on the Messages menu shows whether the alarm reference is announced as left or right (YES) <u>or</u> north, south, east, or west (NO). In the examples that follow, this option was set to NO.

For example, at a single-track site having one Hotbox alarm and no Integrity Failure, the announcement is like this.

CP Detector Mile 3-2-1 Point 4 Maple Creek Speed 4-5 Hotbox North-Rail Axle-7-5 Total Axles 9-8 Mile 3-2-1 Point 4 Out At a double-track site having one Dragging-Equipment alarm and no Integrity Failure, the announcement is like this.

```
CP Detector
Mile 3-9-9 Point 1
Maple Creek
South Track
Speed 4-5
Dragging-Equipment Near-Axle-8-4
Total Axles 8-8
Mile 3-9-9 Point 1 Out
```

At a single-track site having two Hotbox alarms and no Integrity Failure, the announcement is like this.

```
CP Detector
Mile 3-2-1 Point 4
Maple Creek
Speed 4-5
2 Alarms
First Alarm Hotbox North-Rail Axle-7-5
Second Alarm Hotbox North-Rail Axle-8-0
Total Axles 9-0
Mile 3-2-1 Point 4 Out
```

The post-train announcement for a detected Hotwheel alarm uses the same general format: "First-Hotwheel North-Rail Axle-7-5."

At a single-track site having two Dragging-Equipment alarms and no Integrity Failure, the announcement is like this.

```
CP Detector
Mile 3-2-1 Point 4
Maple Creek
Speed 5-7
2 Alarms
First Alarm Dragging-Equipment Near-Axle-8-4
Second Alarm Dragging-Equipment Near-Axle-8-8
Total Axles 9-8
Mile 3-2-1 Point 4 Out
```

At a single-track site having one Hotbox alarm, one Dragging-Equipment alarm, and no Integrity Failure, the announcement is like this.

```
CP Detector
Mile 3-2-1 Point 4
Maple Creek
Speed 4-5
2 Alarms
First Alarm Hotbox North-Rail Axle-7-5
Second Alarm Dragging-Equipment Near-Axle-8-4
Total Axles 9-8
Mile 3-2-1 Point 4 Out
```

At a single-track site having seven or more Dragging-Equipment alarms and no Integrity Failure, the announcement is like this.

```
CP Detector
Mile 3-2-1 Point 4
Maple Creek
Speed 4-5
More Than 6 Alarms
First Alarm Dragging-Equipment Near-Axle-1-2
Inspect Entire Train, Both Sides, From First Alarm To Rear Of
Train, Or As Instructed
Total Axles 9-8
Mile 3-2-1 Point 4 Out
```

Per train, only the first two Dragging-Equipment alarms are ever announced. Per train, only the first four Hotbox alarms or Hotwheel alarms are ever announced.

7.3.4 Both Exception Alarms and an Integrity Failure Detected

When one or more alarm conditions <u>and</u> an Integrity Failure are detected, both are announced. The format of this announcement is:

[CP Detector | GSR Detector*] Mile (mile) [subdivision] [track indicator] [speed indicator] [alarm count] [alarm announcements] [2nd excessive-alarms indicator] System Not Working [ancillary messages] Mile (mile) Out In the examples that follow, the **Announce Car Identification option** and the **Announce Left-Right Alarm Reference option** were set to NO.

For example, at a single-track site having one Hotbox alarm and an Integrity Failure, the announcement is like this.

```
CP Detector
Mile 3-2-1 Point 4
Maple Creek
Speed 6-0
Hotbox South-Rail Axle-7-5
Total Axles 9-8
System Not Working
Mile 3-2-1 Point 4 Out
```

At a double-track site having one Dragging-Equipment alarm and an Integrity Failure, the announcement is like this.

```
CP Detector
Mile 3-8-8 Point 1
Maple Creek
North Track
Speed 5-7
Dragging-Equipment Near-Axle-2-4
Total Axles 8-6
System Not Working
Mile 3-8-8 Point 1 Out
```

At a single-track site having seven or more Dragging-Equipment alarms and an Integrity Failure, the announcement is like this.

```
CP Detector

Mile 3-2-1 Point 4

Maple Creek

Speed 4-5

More Than 6 Alarms

First Alarm Dragging-Equipment Near-Axle-1-2

Inspect Entire Train, Both Sides, From First Alarm To Rear Of

Train, Or As Instructed

Total Axles 9-8

System Not Working

Mile 3-8-8 Point 1 Out
```

At a single-track site having one Hotbox alarm, two Dragging-Equipment alarms, and an Integrity Failure, the announcement is like this.

```
CP Detector
Mile 3-2-1 Point 4
Maple Creek
Speed 5-4
3 Alarms
First Alarm Dragging-Equipment Near-Axle-2-8
Second Alarm Dragging-Equipment Near-Axle-2-9
Third Alarm Hotbox North-Rail-7-5
Total Axles 1-0-8
System Not Working
Mile 3-2-1 Point 4 Out
```

This section lists the items that STC recommends be done during scheduled maintenance.

An up-and-running SmartScanNG² system needs to be visited from time to time to do scheduled maintenance. The frequency of these visits is up to the customer. STC recommends visits every 30 to 90 days. Maintenance requirements change with environmental conditions. For example, if the system is installed in a damp or dusty environment, it may be necessary to visit the location more frequently to clean the optics. The optical system is the item most likely to need periodic maintenance. If moisture or dust isn't a problem, you may <u>not</u> need to do scheduled maintenance more often than every 90 days.

For normal scheduled maintenance, STC recommends these steps.

- Be sure that you have on hand a 50-foot (15-meter) or longer tape measure, a #2 Phillips head screwdriver, a small slotted screwdriver, a 9/16-inch torque wrench, a laptop computer, a multimeter, and the alignment fixture.
- 2 At trackside, check track conditions on all tracks.
- 3 If any track is pumping (vertical displacement of the rails) or running (lateral displacement of the rails) more than 2 inches (5 centimeters), have it repaired before proceeding.
- **4** At trackside, check for damaged transducers, damaged transducer cables, and other damaged components.
- 5 If you find any damaged components, repair or replace them before proceeding.

STC transducers don't require a lot of care and attention. Once installed correctly, you don't need to remove them from the rail for cleaning or readjustment.

6 At trackside, check all transducer-mounting bolts on all tracks to make sure that all transducers are snug against the rail.

Four bolts are needed to hold the transducer in place. Two square-head bolts go through the mounting plate and transducer body. Two hex-head bolts go through the mounting plate and rail. If any of these bolts are sheared or missing, they must be replaced with the correct replacement bolt. Also, if any washers or nuts are missing, they must be replaced.

7 If all transducers aren't snug against the rail, fix this problem before proceeding.

Each installed transducer body should be 1-9/16 inches (3.97 centimeters) below the top of the rail <u>and</u> parallel to it. You can meet this requirement by using the transducer height bracket on the bottom of the alignment fixture.

- 8 Place the alignment fixture across both rails, centered over each transducer in turn.
- 9 Check if each transducer body just touches the bracket.



The fixture should be snug against the top and gauge of both rails. This may be impossible if the transducer body is less than 1-9/16 inches (3.97 centimeters) below the top of the rail <u>or</u> if the transducer body isn't parallel to the top of the rail.

- 10 If a transducer body doesn't just touch the bracket:
 - a Loosen the nuts holding the transducer body to its mounting plate.
 - **b** By sliding it up and down, adjust the transducer body to the proper height.
 - c Tighten each hex nut with a 9/16-inch torque wrench to a torque of 12 to 15 foot-pounds (16.3 to 20.3 newton-meters).

Don't exceed a torque of 15 foot-pounds (20.3 newton-meters). Doing so can weaken or break a bolt, requiring the bolt to be replaced.

- **11** At the trackside, check all scanner-mounting bolts on all tracks.
- **12** If all scanner mounts aren't snug against the gauge side of the rail, fix this problem before proceeding.
- **13** From under all scanners, remove ballast that could damage the scanner during train passage.
- 14 Remove all obstructions to the scan path of each scanner.
- **15** If the wayside enclosure isn't attached to a properly installed outside grounding system, fix this problem before proceeding.
- **16** At all outlets inside the wayside enclosure, check if the AC power is stable and at least 110 volts at 20 amperes.
- **17** If the AC power isn't stable <u>or</u> if it isn't at least 110 volts at 20 amperes, fix this problem before proceeding.
- **18** If not all outlets inside the wayside enclosure are grounded properly, fix this problem before proceeding.

19 If the battery is dead, damaged, or emitting a strong sulfurous odor, replace it before proceeding.

WARNING

In operation, batteries generate and release flammable hydrogen gas, which, if ignited by a burning cigarette, naked flame, or spark, may cause a battery explosion with a dispersion of casing fragments and corrosive liquid electrolyte. So, carefully follow the manufacturer's instructions for installation and service. Keep all sources of gas ignition away from the batteries, and do <u>not</u> allow metallic articles to contact the negative and positive terminals of a battery at the same time.

WARNING

A damaged or aged battery, in combination with the connected battery charger, can pose a serious health threat. The battery can produce hydrogen sulfide gas, which is characterized by its unique "rotten egg" smell. So, when a strong sulfurous odor is detected, remove power to the battery charger and check the battery for excessive heating. Do <u>not</u> inhale the fumes.

- **20** If the battery charger hasn't been properly grounded, fix this problem before proceeding.
- **21** If the SmartScanNG² enclosure hasn't been properly grounded, fix this problem before proceeding.

There are vents on the top, bottom, and sides of the charger. Blocking any of these vents could result in damage to the charger or battery.

22 Remove anything that is blocking the vents on the battery charger.

One end of the battery temperature probe cable has a three-pin plug, which plugs into a receptacle on the front of the battery charger. The other end, which has a temperature sensor sealed in it, should be attached to the negative battery post. If the battery temperature probe is defective or not installed, the red defective LED is lit.

- **23** On the front of the battery charger, if the red defective-temperature-probe LED is lit, fix the underlying problem before proceeding.
- 24 Switch the multimeter to the <u>DC volts</u> scale.

The **equipment side** of the fuse block is directly wired to the SmartScanNG² enclosure. The **battery side** of the fuse block is wired to the battery via the distribution block.

25 Touch the leads from the multimeter to the terminals on the <u>equipment side</u> of the fuse block.



- 26 If the voltage (on the <u>equipment side</u> of the fuse block) is 12.3 through 14 VDC, go to step 30.
- 27 If the voltage (on the equipment side of the fuse block) is 0 VDC:
 - **a** Touch the leads to the terminals on the <u>battery side</u> of the fuse block.
 - **b** If the voltage (on the <u>battery side</u> of the fuse block) is greater than 0 VDC, replace each fuse in the fuse block with a BAF-25 (25-amp 250-volt) fast-acting fuse <u>and</u> return to step **25**.
 - **c** If the voltage (on the <u>battery side</u> of the fuse block) is 0 VDC, fix any wiring problems between the fuse block, the distribution block, the battery, and the charger.
 - d Return to step 25.
- 28 If the voltage is less than 12.3 VDC:
 - a On the battery charger, check the input voltage switch for proper setting.



The input voltage switch can be set to 115 VAC or 230 VAC. Use 115 for input voltages between 108 and 128. Use 230 for input voltages between 216 and 256.

- **b** On the battery charger, check the output float voltage switches.
- c If the switches are set lower than 12.30 VDC, reset them to 14.00 VDC.

To reset the switches, use a small slotted screwdriver to turn each switch to the desired number. The ten's digit is always 1 and can't be changed. The top switch controls the unit's digit. The middle switch controls the tenth's digit. The bottom switch controls the hundredth's digit. The factory default is **14.00 VDC**, which is the **recommended setting**. To select 14.00 VDC, turn the top switch to 4, the middle switch to 0, and the bottom switch to 0.

d Open the small door cover on the top-right corner of the front of the charger.

Do not touch the uninsulated parts of the wires or the charger's binding posts. Doing so could result in sparks, burns, or electric shock.

- e Check that all binding post nuts are tight <u>and</u> that all wiring is correct.
- f On the battery charger, check the AC fuses to see if either is blown.
- g If blown, replace with 4-amp 250-volt fast-acting fuses.
- **h** On the battery charger, check the DC circuit breaker to see if it is open (tripped).
 - When closed, about 0.09 inch (0.23 centimeters) of the breaker's button is seen. When open, the button is popped out, showing about 0.25 inch (0.64 centimeters).
- i If open (tripped), push the breaker's button in to reset the DC circuit breaker.
- j Check to see if the battery charger is plugged in.
- **k** If the battery charger isn't plugged in, plug it in.
- I Check the battery-charging LED.

If the battery is charging properly, the yellow battery-charging LED is lit solid. If one or more of the output float voltage switches are set between numbers, the yellow battery-charging LED flashes.

- **m** If the yellow battery-charging LED is <u>not</u> lit, call STC for help in fixing this problem.
- **n** If the yellow battery-charging LED is lit solid, monitor the voltage for ten minutes.

If the voltage is gradually increasing, the battery is probably charging. After the battery has been charged for five hours, the battery voltage should be very near the float voltage setting. If the voltage isn't gradually increasing, the battery is probably not charging. This may indicate that the battery is defective and should be replaced.

- 29 If the voltage is greater than 14 VDC:
 - **a** Check the output float voltage switches on the center-left edge of the battery charger.
 - **b** Be sure that each switch is set on a number and not between numbers.
 - **c** If the switches are set to 14.00 VDC or less, cut all power to the SmartScanNG² system and call STC for help in fixing this problem.
 - **d** If the switches are set <u>higher than</u> 14.00 VDC, reset them to 14.00 VDC <u>and</u> return to step **25**.

To reset the switches, use a small slotted screwdriver to turn each switch to the desired number. The ten's digit is always 1 and can't be changed. The top switch controls the unit's digit. The middle switch controls the tenth's digit. The bottom switch controls the hundredth's digit. The factory default is **14.00 VDC**, which is the **recommended setting**. To select 14.00 VDC, turn the top switch to 4, the middle switch to 0, and the bottom switch to 0.

30 On the display panel, look at the COP-A and COP-B LEDs.



The COP LEDs indicate the condition of the CPUs. If both CPUs are running their programs correctly, their LEDs blink on and off. If a program isn't operating as expected, the LED for the affected CPU is lit solid or isn't lit at all.

- **31** If either or both of the **COP LEDs** are lit solid or aren't lit at all, call STC for help in fixing this problem.
- **32** On the display panel, look at the **SYS WARN** LED. If a system warning has been flagged, the SYS WARN LED will be lit, and the Check System Health message will be displayed on the bottom text line of the home screen. The Sys. Health Menu provides a status indicator for the various system health checks.
- **33** To see if the system is being activated by the gating transducers:
 - a Produce a Train Detail Report for the last train.

Section 4.0 - Producing Reports tells how to produce this report.

b On the Train Detail report, check under the System Alarms section of the report for the words "No Approach Track."

The No Approach Track alarm indicates that the track circuit (or the advance transducers) failed to signal the presence of a train and that the SmartScanNG² system started from the train passing over the gating transducers.

c If the words "No Approach Track" don't appear, go to step 37.

34 If your system uses <u>advance transducers</u>, go to step 36.

- 35 If your system uses a track circuit:
 - a) From the center of the gating transducers, measure the distance you want the track circuit to pick up the presence of a train.
 - b) The distance must be at least 50' (15.24 m) and no more than 150' (45.7 m).
 - c) At the point just measured, place a 0.06Ω shunt across both rails. The track must be shunted before the calibration switch is pressed.
 - d) Press and HOLD the Calibration Switch until the SOTC LED starts blinking. Release the switch, and the LED will stop blinking. The ZEPIC III will automatically begin the calibration process. NOTE: The track shunt MUST remain in place during the calibration process.





f) The relay drive will pick up (SOTC LED on) when the unit has successfully calibrated. This process can take up to 45 seconds to complete.

Verification

- a) After calibration, lift the shunt, and the relay drive should drop (LED off). Replace the shunt, and the relay drive will pick up (LED on).
- b) Move the shunt approximately 10' farther out from the calibration point. The relay drive should not pick up (LED stays off). If this test fails, perform Short Track Calibration (detailed below).
- c) The PD8-Plus is now operating properly and will activate at an equal distance on either side of the track feed point.

d) After trackside calibration procedures have been successfully completed, place a temporary shunt across the track wires inside the bungalow and verify that the signal system goes to stop. Once verified, remove the temporary shunt.

IMPORTANT: To ensure an accurate activation point, always place the shunt BEFORE pressing the Calibration Switch.

If the PD8-Plus cannot achieve calibration, it will blink the relay drive LED three (3) times in rapid succession, indicating a calibration error. The unit will continuously repeat the calibration procedure (there is no need to press the Calibration Switch), allowing you to troubleshoot the track circuit, wiring, and battery. Once the issue has been corrected, repeat the calibration procedure.

Both the ZEPIC III and Zepic PD8-Plus have a two-wire track circuit and will activate an equal distance on both sides of the track feed point.

PD8-Plus Short-Track Circuit Calibration

- a) The system may fail the 10 ft calibration verification step noted above if the installation is using 26KHz and the desired CAL point is ~30ft from the feed points (Short track circuit), and the bungalow is near the track (short track wires).
- b) If this is the case, reconfigure the PD8-Plus to a lower frequency that is compatible with other equipment that may be on the track. In general, changing from 26KHz to 20KHz or 17.5KHz should solve the short-track circuit calibration issue.
- c) Once the module has been reconfigured for the new operating frequency, repeat the normal calibration procedure detailed above.

PD8-Plus Troubleshooting and Application Notes

- a) If the unit will not calibrate, watch the relay drive LED for approx 45 seconds. If it blinks, this means the PD8-Plus has turned its receiver gain to the maximum setting and cannot see the track shunt. Look for open circuits between the PD8-Plus and the shunt on the track. I.e., track wires, bond wires, etc.
- b) The PD8-Plus will look equally in both directions. If one side of the circuit has insulated joints, the PD8-Plus will operate. However, the activation distance will not be the same. In general, track circuit equipment cannot see past insulated joints.
- c) Audio overlay systems like the PD8-Plus will not work with wideband shunts in their track circuit range.
- **d)** If the relay drive is stuck ON, look for short circuits between the PD8-Plus and the desired pick point.
- e) The greater the distance between the PD8-Plus and track connections, the greater the effects ballast will have on the PD8-Plus performance.
- f) Presence output is a dry contact configuration Form –C dry contact, 225mA max current. (N.O. contact with no train presence)

- **g)** In good track ballast conditions, a PD8-Plus circuit can travel up to 500 ft in each direction. Rotating operating frequencies to avoid interference with other equipment is recommended.
- h) The higher the operating frequency, the shorter the track circuit.
- i) Go to step 37.
- 36 If your system uses advance transducers:

You will next verify that each advance transducer is functional.

- a Using a metal wrench, stroke the top of one of the advance transducers.
 The scanner shutters should open completely for 10 seconds.
- **b** On one of the bearing scanners, check to see if the shutter opens.
- **c** If the shutter didn't open, fix this problem before proceeding.
- **d** Using a metal wrench, stroke the top of the other advance transducer.

The scanner shutters should open completely for 10 seconds.

- e On one of the bearing scanners, check to see if the shutter opens.
- f If the shutter didn't open, fix this problem before proceeding.
- 37 Produce a Train Summary report.

Section 4.0 - Producing Reports tells how to produce this report.

The Train Summary report lists all trains currently stored in the Trains directory. A line of information is shown for each train entry. The report is divided into a header section and a detail section. The <u>header</u> section contains general information about the site. The <u>detail</u> section contains summary information on each train that passed the site.

38 On the Train Summary report, check the Axles column.

Axle count should be an even number. Odd-numbered axle counts are possible indications of gating transducer problems.

39 If there is an <u>odd</u> axle count <u>and</u> if train speed was <u>always above</u> 7 mph, go to step **41**.

If at any time during train passage the train speed was less than or equal to 7 mph (11.3 kph), gating transducer problems probably don't exist. If the train speed was always above 7 mph, gating transducer problems probably do exist.

The Very Slow Train alarm indicates that, at some point during train passage, four consecutive axles crossed the gating transducers at a speed of 7 mph (11.3 kph) or less. This alarm appears on a Train Detail report.

If there are many slow trains (that is, many trains traveling less than 7 mph) at this site, it may be necessary to relocate the scanners and other track hardware to a better location. Deciding to do this should be made in consultation with STC. Relocating a site is beyond the scope of this document.

40 If there is an <u>even</u> axle count <u>and</u> the values under "Axles," "T01," and "TO2" are the same, go to step **45**.

If things are working correctly, all three values for a given train should be equal. You'll do the next step <u>only</u> if things aren't working correctly.

41 Determine which gating transducer is recording incorrect information.

Determine which gating transducer is recording incorrect axle counts <u>and</u> whether it is not counting all axles or counting extra ones. You may not be able to do this by just looking at the values under the Axles, T01, and TO2 columns of the Train Summary report. Sometimes, a transducer problem causes the number in the Axles column to be incorrect. Therefore, the true axle count may have to be determined from an alternate source, such as the next detector system that encounters the train with the transducer-count imbalance.

After you determine which gating transducer is miscounting, you'll need to change a jumper setting on the Interface board. If TO1 is the problem, you'll change the setting for J201. If TO2 is the problem, you'll change the setting for J202. If both TO1 and T02 have a problem, both jumpers will need to be changed.

Changes to the jumpers should be made <u>only</u> after all external conditions that cause transducer miscounts have been corrected. Some of these external conditions are improperly installed transducers, loose transducer bolts, incorrect transducer heights, damaged transducers, damaged transducer cables, and loose wiring connections. You should have already checked and corrected for these external conditions in steps 4 through 10 above. If you think the corrections you made in those steps fixes gating transducer miscounting, you can skip some of the steps below.

The process of adjusting the transducer loading is trial and error. Generally, if you are having too many transducer counts, lower the loading resistance to make the transducer less sensitive. Likewise, too few counts suggest that the transducer is not sensitive enough, so you would select a loading value with more resistance.

- **42** If you corrected all external conditions that negatively affect gating transducers <u>and</u> you think this fixes gating transducer miscounting, go to step **45**.
- **43** If the selected gating transducer appears to be <u>missing axles</u> (that is, the transducer that is showing a number of hits less than the true axle count):
 - **a** Toggle <u>off</u> the DC power switch on the right edge of the SmartScanNG² enclosure.



b Remove the six nuts and three screws holding the cover over the Interface board.



The Interface board is now visible.



- **c** To prevent the base assembly from falling, replace two of the just removed nuts onto the top two mounting studs on the SmartScanNG² enclosure.
- **d** Store the removed cover, three screws, and remaining four nuts in a safe place until you replace them.

The available loading sensitivities vary depending on which version of Interface board you have <u>and</u> whether resistors are attached to the jumpers or not. The version number is printed on the lower-left edge of the board.

e The table below lists the highest, middle, and lowest sensitivity for transducer loading. <u>Highest</u> is the most sensitive. The jumper's <u>top</u> position is the one closest to the external speaker.

J201 <u>or</u> J202 Jumper Position	Sensitivity Level
Тор	Lowest Sensitivity
Center	Middle Sensitivity
Bottom	Highest Sensitivity

- **f** If TO1 is the selected gating transducer <u>and</u> the J201 jumper is currently <u>on</u> the <u>lowest</u> sensitivity position, move it <u>to</u> the <u>middle</u> sensitivity position.
- **g** If TO1 is the selected gating transducer <u>and</u> the J201 jumper is currently <u>on</u> the <u>middle</u> sensitivity position, move it <u>to</u> the <u>highest</u> sensitivity position.
- **h** If TO1 is the selected gating transducer <u>and</u> the J201 jumper is currently <u>on</u> the <u>highest</u> sensitivity position, call STC for help in fixing this problem.
- i If TO2 is the selected gating transducer <u>and</u> the J202 jumper is currently <u>on</u> the <u>lowest</u> sensitivity position, move it <u>to</u> the <u>middle</u> sensitivity position.
- **j** If TO2 is the selected gating transducer <u>and</u> the J202 jumper is currently <u>on</u> the <u>middle</u> sensitivity position, move it <u>to</u> the <u>highest</u> sensitivity position.
- **k** If TO2 is the selected gating transducer <u>and</u> the J202 jumper is currently <u>on</u> the <u>highest</u> sensitivity position, call STC for help in fixing this problem.
- I Remove the two nuts holding the base assembly to the SmartScanNG² enclosure.
- **m** Using the saved six nuts and three screws, reattach the cover over the Interface board.
- **n** Toggle <u>on</u> the DC power switch on the right edge of the SmartScanNG² enclosure.

- **44** If the selected gating transducer appears to be <u>counting extra axles</u> (that is, the transducer that is showing a number of hits more than the true axle count):
 - **a** Toggle <u>off</u> the DC power switch on the right edge of the SmartScanNG² enclosure.



b Remove the six nuts and three screws holding the cover over the Interface board.



The Interface board is now visible.



- **c** To prevent the base assembly from falling, replace two of the just removed nuts onto the top two mounting studs on the SmartScanNG² enclosure.
- **d** Store the removed cover, three screws, and remaining four nuts in a safe place until you replace them.

The available loading sensitivities vary depending on which version of the Interface board you have <u>and</u> whether resistors are attached to the jumpers or not. The version number is printed on the lower-left edge of the board.

e The table below lists the highest, middle, and lowest sensitivity for transducer loading. <u>The highest</u> is the most sensitive. The jumper's <u>top</u> position is the one closest to the external speaker.

J201 <u>or</u> J202 Jumper Position	Sensitivity Level
Тор	Lowest Sensitivity
Center	Middle Sensitivity
Bottom	Highest Sensitivity

- **f** If TO1 is the selected gating transducer <u>and</u> the J201 jumper is currently <u>on</u> the <u>highest</u> sensitivity position, move it <u>to</u> the <u>middle</u> sensitivity position.
- **g** If TO1 is the selected gating transducer <u>and</u> the J201 jumper is currently <u>on</u> the <u>middle</u> sensitivity position, move it <u>to</u> the <u>lowest</u> sensitivity position.
- **h** If TO1 is the selected gating transducer <u>and</u> the J201 jumper is currently <u>on</u> the <u>lowest</u> sensitivity position, call STC for help in fixing this problem.
- i If TO2 is the selected gating transducer <u>and</u> the J202 jumper is currently <u>on</u> the <u>highest</u> sensitivity position, move it <u>to</u> the <u>middle</u> sensitivity position.
- **j** If TO2 is the selected gating transducer <u>and</u> the J202 jumper is currently <u>on</u> the <u>middle</u> sensitivity position, move it <u>to</u> the <u>lowest</u> sensitivity position.
- **k** If TO2 is the selected gating transducer <u>and</u> the J202 jumper is currently <u>on</u> the <u>lowest</u> sensitivity position, call STC for help in fixing this problem.

- I Remove the two nuts holding the base assembly to the SmartScanNG² enclosure.
- **m** Using the saved six nuts and three screws, reattach the cover over the Interface board.
- **n** Toggle <u>on</u> the DC power switch on the right edge of the SmartScanNG² enclosure.
- **45** To use the serial interface to open the scanner shutters:
 - a Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu

b Select the System Functions Menu

c To open the shutters, select the Auto-Calibration option.

The protective shutters in all scanners should open and stay open for three minutes. This might <u>not</u> be enough time to check and clean the shutters and optics. If that isn't enough time, select this option again.

- 46 In each scanner, check if its shutter opened.
- 47 If any shutter didn't open, fix this problem before proceeding.
- 48 In each scanner, check for dirty optics.
- **49** If dirty, clean the scanner optics with the supplied lens cleaning kit.

Do <u>not</u> use solvents, ammonia-based cleaning solutions, or isopropyl alcohol on the optics. Use clean water or a mild solution of dishwashing liquid. After the liquid on the optics dries, lightly wipe the optics with a clean, dry chamois patch.

50 If the date and time displayed on the top of the System Functions menu are incorrect, fix them before proceeding.

Section 4.0 - Serial Interface tells how to change the date and time.

- **51** To check the operation of the radio:
 - **a** From the System Functions menu, select Radio Test.

During a radio test, the SmartScanNG² system outputs phrases through the speaker and through the radio. Alternatively, you can output a 1kHz test tone instead of phrases. To do this, you would select the 1KHz Test Tone option.

b While listening to the message or tone, look at the display panel.

The PTT LED should be lit.

If this LED isn't lit, the system's ability to send a message or tone to the radio might be inhibited. This can happen when one uses the Radio Inhibit option on the System Functions menu. If the radio is inhibited, the results of this check are invalid.

- **c** If the PTT LED isn't lit <u>and</u> the radio isn't inhibited, call STC for help in fixing this problem.
- **52** To check the integrity of the speech data:
 - **a** Be sure that the speaker has its volume set to an audible level.
 - **b** Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu.

```
[J] - Event log
[K] - System Functions Menu
[L] - Replay train
[M] - Security Menu
[X] - Exit
```

c Select the System Functions menu.

```
System Functions Menu

[A] - Radio Test

[B] - Vocabulary Test

[C] - Radio Inhibit

[D] - Start Manual Train
```

d From the System Functions menu, select Vocabulary Test

This message appears.

Starting Vocabulary Test

If the system isn't currently making any other voice announcements, it begins the Vocabulary Test announcement. The SmartScanNG² system outputs phrases through the speaker but <u>not through</u> the radio. After the announcement finishes, the System Functions menu reappears.

If the system is currently making a voice announcement, the firmware displays the "System Is Currently Making Voice Announcements! Try Again Later" message, and the System Functions menu reappears.

- e If you hear nothing <u>or</u> speech that is too garbled to understand, call STC for help in fixing this problem.
- 53 To generate a test train to check the number of axles:
 - **a** Quickly stroke the top of each gating transducer with a metal wrench, alternating between TO1 and TO2.
 - **b** Repeat step **a** nine more times, for a total of **ten** simulated axles.
 - **c** Wait for the system to time out and the shutters to close.
 - d Produce a Train Detail report for the last train.

Section 4.0 - Producing Reports tells how to produce this report.

- **e** On the report, check that the number of axles agrees with the number of times that you stroked the gating transducers.
- **f** On the report, if the number of axles doesn't agree with the number of times that you stroked the gating transducers, call STC for help in fixing this problem.
- 54 To generate a test train to check hot bearings:

STC recommends that you use the calibrated heat source (2100-810NG) only when the outside (ambient) temperature is above 0°F (-18°C) and below 90°F (32°C). If you must use it at other times, do so only when the needle is centered on the front of the temperature meter. If the needle isn't stabilized within \pm 2-degrees of the setpoint, the heat source isn't operating properly.

a Ready the calibrated heat source.

The heat source has reached operating temperature and stabilized when the temperature meter needle remains centered.

- **b** With the power cord to the front of the scanner, place the calibrated heat source on the bearing scanner that is on the rail with the gating transducers.
- **c** Quickly stroke the top of each gating transducer with a metal wrench, alternating between TO1 and TO2 for a total of **six** simulated axles.

You should hear the real-time defect message. No matter how many defects are found, the real-time defect message is only announced once.

d Wait for the system to time out, which normally takes about 10 seconds.

You should hear an end-of-train message with three Hotbox alarms. Per train, only the first three Hotbox alarms are ever announced.

e Listen to be sure that the Hotbox alarms are announced <u>and</u> that they are announced for the <u>correct side</u>.

If you do <u>not</u> hear anything, no alarm-level heat was recorded. No measurable heat from a bearing scanner may be due to loose connections, a scanner not being connected to the bottom of the SmartScanNG² enclosure, a defective shutter motor in the scanner, or a damaged scanner.

- **f** If you do <u>not</u> hear any Hotbox alarms being announced, fix this problem before proceeding.
- **g** If the Hotbox alarms are announced for the <u>wrong side</u>, switch the bearing scanner connections on the bottom of the SmartScanNG² enclosure.

- **h** Repeat the test, this time placing the calibrated heat source on the bearing scanner on the opposite rail
- i Verify the results as before.

If the results are correct, your system should function properly when scanning the bearings of real trains.

- j Remove the calibrated heat source.
- **k** Store the calibrated heat source and its cable in the wayside enclosure.
- 55 On the Train Summary report, check the column marked "Average."

For each train, the values in the two columns under this heading should be within four degrees of each other.

56 If the columns aren't within four degrees <u>and</u> if the scanner optics are clean, recalibrate and realign the scanner.

Appendix F & G - Calibration of Type II/Type III Scanners tells how to calibrate the scanners.

57 On the Train Summary report, check the last column of the report.

The last column shows the battery voltage at the time each train passed the site. It should show values between 13.0 and 14.5 volts. Values outside this range may be caused by:

- No AC power for an extended period
- Improperly adjusted float voltage
- Defective battery
- Blown fuses
- Defective battery charger
- **58** If the most recent value isn't between 13.0 and 14.5 volts, investigate and fix any problems before proceeding.
- **59** If this is a double-track site, repeat steps **18** through **59** for the other track (that is, for the other SmartScanNG² system).

At STC, the customer is number one. STC is committed to products that work and customers that are satisfied. Nothing less is acceptable. This section tells how to get answers for questions, fixes for problems, and parts for spares.

9.1 Reaching STC

You can reach STC by mail, telephone, fax, and email. By mail, you can reach STC at:

Southern Technologies Corporation 6145 Preservation Drive Chattanooga, Tennessee 37416-3638 USA

Mail and shipments are replied to as soon as possible, normally within one working day. Equipment repair usually takes longer.

By <u>telephone</u>, you can reach STC at 423-892-3029, Monday through Friday, from 8:00 a.m. until 5:00 p.m. Eastern time. After business hours, a machine answers the calls. These calls are returned promptly the next business day. By <u>fax</u>, you can reach STC at 423-499-0045. The fax machine can receive faxes at all times. Faxes are replied to as soon as possible, normally within one working day. By <u>email</u>, you can reach STC at email@southern-tech.com. Email is replied to as soon as possible, normally within one working day.

9.2 Returning Equipment for Repair

Return any defective or malfunctioning equipment to STC for repair or replacement. You don't need a return authorization number. You don't even need to make a telephone call first. Just ship it directly to the **Repair Department** at the address above.

With the returned equipment, include:

- Complete address of where the equipment is to be returned.
- Name and telephone number of the person who should be contacted to answer questions about the equipment.
- A written explanation of the equipment defect or malfunction.
- Any reports or other data that would be helpful in diagnosing the problem.
- If out of warranty, credit card number (to be charged) with its expiration date.

9.3 Reporting Problems or Suggestions

If you have any problems, suggestions, or questions related to STC equipment, telephone the **Engineering Department** at the telephone number above. When calling, state the equipment you're calling about. Your call will then be directed to the right person.

9.4 Ordering Spare Parts

If you need any spare parts to support STC equipment, telephone or fax the **Sales Department** at the telephone numbers above.

When calling, state that you're calling to order parts. Your call will then be directed to the right person. When placing the order, reference the STC part numbers listed in this guide. However, if you don't have the part numbers, the sales staff can obtain them for you and provide you with current pricing and availability.

When faxing, include:

- Purchase Order Number for the order <u>or</u> credit card number (to be charged) with its expiration date.
- Complete address where the parts are to be shipped.
- Complete address where the invoice is to be mailed.
- Name and telephone number of the person who should be contacted to answer questions about the order.
- Your fax number, if available.
- For each item ordered, part number, complete description, and quantity needed.

9.5 Checking on Shipments and Orders

If you need to check on the status of any shipment or order, telephone or fax the **Sales Department** at the telephone numbers above.

When calling, state that you're checking the status of a shipment or order. Your call will then be directed to the right person. Have your Purchase Order Number ready when you call. However, if you don't have the order number, the sales staff can locate your order number and provide you with the status of the shipment or order.

When faxing, include:

- Purchase Order Number for the shipment or order being checked.
- Name and telephone number of the person who should be contacted after the order status is checked.
- Your fax number, if available.

This appendix describes the conditions and events that the SmartScanNG² system flags as System Alarms. These alarms provide data about passing trains and system status. These alarms are listed under the System Alarms section of the Train Detail and Exception Detail reports. *Section 4.0 - Producing Reports* tells how to produce these reports.

A.1 Cold Rail Alarm

The Cold Rail alarm indicates that the temperatures of all bearings (of the train) on the designated rail were below a given temperature. When no bearing on a given rail generates a delta temperature reading greater than or equal to the temperature set by the **Cold Rail Temperature option** on the Alarm Settings menu, the system generates a Cold Rail alarm. **Section 4.0 - Serial Interface** tells how to view or change the Cold Rail Temperature option.

 Alarm Settings

 [A] - Absolute
 180

 [B] - Differential
 150

 [C] - Hot Wheel
 600

 [D] - Cold Rails
 3

 [E] - Cold Rail Temp
 10

 [F] - Cold Res Counter
 3

 [G] - Differential Enabled
 Yes

 [H] - Advanced
 [X] - Exit

There is a different Cold Rail alarm for each rail. That is, there is a Cold North Rail alarm and a Cold South Rail alarm (or, depending on track direction, a Cold East Rail alarm and a Cold West Rail alarm).

The maximum number (per railside) of consecutive trains, having Cold Rail alarms, allowed before generating a Successive Cold Rails Exceeded alarm is set by the **Cold Rails option** on the Alarm Settings menu. If the number of consecutive trains bearing identical Cold Rail alarms equals or exceeds the cold-rail-alarm limit, the System Alarms section of the Train Detail and Exception Detail reports displays the message "Successive Cold Rails Exceeded." Successive Cold Rails Exceeded alarms are covered in the next appendix. **Section 4.0** - **Serial Interface** tells how to view or change the Cold Rails option.

Alarm	Settings
[B] -	Absolute 180 Differential 150
	Hot Wheel 600
	Cold Rails 3
[E] -	Cold Rail Temp 10
[F] -	Cold Res Counter 3
[G] –	Differential Enabled Yes
[H] —	Advanced
[X] –	Exit

A.2 Cold Resistor Alarm

A resistor is mounted to the inside of the bearing scanner's shutter. A voltage is applied to this resistor while the shutter is open, causing it to heat up. After a train has left a site and the shutters have closed, the temperature of the resistor is read by the scanner pyrometer. In this way, a check of the system's ability to read heat correctly is made. The Cold Resistor alarm indicates that the minimum value expected for the temperature of the resistor wasn't met. This minimum value is determined by the firmware and is dependent upon the time it takes a train to pass a site.

If the **minimum value** wasn't met, a second check compares the recorded resistor temperature against the limit that was established using the Absolute option on the Alarm Settings menu. (This alarm limit is an offset, <u>in degrees Fahrenheit</u>, above the ambient temperature.) If the recorded resistor temperature meets or exceeds the absolute-alarm limit, the firmware cancels any previously flagged Cold Resistor alarms. *Section 4.0 - Serial Interface* tells how to view or change the Absolute option.

```
Alarm Settings

[A] - Absolute ..... 150

[B] - Differential ..... 255

[C] - Hot Wheel ..... 500

.
```

There is a different Cold Resistor alarm for each rail. That is, there is a Cold North Resistor alarm and a Cold South Resistor alarm (or, depending on track direction, a Cold East Resistor alarm and a Cold West Resistor alarm).

The **maximum number** (per railside) of consecutive trains, having Cold Resistor alarms, allowed before generating a Successive Cold Resistors Exceeded alarm is set by the **Cold Resistor Counter option** on the Alarm Settings menu. Successive Cold Resistors Exceeded alarms are covered in the next appendix. *Section 4.0 - Serial Interface* tells how to view or change the Cold Resistor Counter option.

A.3 Cold Wheel Scanner Alarm

The Cold Wheel Scanner alarm represents the wheel scanner's equivalent of the bearing scanner's Cold Rail alarm. When no wheel on a given rail generates a delta temperature reading greater than or equal to a preset minimum, the system generates a Cold Wheel Scanner alarm. The preset minimum temperature is determined by the firmware and is currently 9°F above ambient (5°C above ambient). The customer can't change this value. Just like Cold Rail alarms, separate Cold Wheel Scanner alarms exist for each railside.

The maximum number (per railside) of consecutive trains, having Cold Wheel Scanner alarms, allowed before generating a Successive Cold Wheels Exceeded alarm is set by the **Cold Rails option** on the Alarm Settings menu. Successive Cold Wheels Exceeded alarms are covered in the next appendix. **Section 4.0 - Serial Interface** tells how to view or change the Cold Rails option.

A.4 Cold Wheel Scanner Resistor Alarm

The Cold Wheel Scanner Resistor alarm represents the wheel scanner's equivalent of the bearing scanner's Cold Resistor alarm. Evaluation of Cold Wheel Scanner Resistor alarm occurs in two stages. The first stage mimics the same logic used in the evaluation of Cold Resistor alarms. After finishing this check, and possibly flagging a Cold Wheel Scanner Resistor alarm, the firmware compares the recorded resistor temperature against a value of one-third the hot wheel alarm limit. If the recorded resistor temperature meets or exceeds this value, the firmware cancels any previously flagged Cold Wheel Scanner Resistor alarm. In this way, the system confirms the scanner's ability to read alarm level heat. Just like Cold Resistor alarms, separate Cold Wheel Scanner Resistor alarms exist for each railside.

The maximum number (per railside) of consecutive trains, having Cold Wheel Scanner Resistor alarms, allowed before generating a Successive Cold Wheel Resistors Exceeded alarm is set by the Cold Rails option on the Alarm Settings menu. Successive Cold Wheel Resistors Exceeded alarms are covered in the next appendix. **Section 4.0 - Serial Interface** tells how to view or change the Cold Rails option.

 Alarm Settings

 [A] - Absolute
 180

 [B] - Differential
 150

 [C] - Hot Wheel
 600

 [D] - Cold Rails
 3

 [E] - Cold Rail Temp
 10

 [F] - Cold Res Counter
 3

 [G] - Differential Enabled
 Yes

 [H] - Advanced
 [X] - Exit

A.5 Highrange Transducer Miscounts Alarm

The Highrange Transducer Miscounts alarm indicates that the transducer counts for TO1 and TO2 are off by seven or more. This calculation is made after each axle crosses both gating transducers. When this alarm occurs, the system won't announce axle count, exit speed, length of train, or total number of cars (even if these messages are enabled).

The Highrange Transducer Miscounts alarm <u>can be either</u> a System Alarm or an Integrity Failure, depending on the presence of a Very Slow Train alarm. If a highrange transducer miscount occurs on a train that also contains a Very Slow Train alarm, the firmware treats the miscount condition as a System Alarm. This logic assumes that the train's slow rate of travel likely caused the transducer miscount condition. If a highrange transducer miscount occurs on a train traveling faster than 7 mph (11.3 kph), the firmware treats the miscount condition as an Integrity Failure.
A.6 Integrity Failure Alarm

The Integrity Failure alarm indicates that the SmartScanNG² system determined that a condition exists that could prevent proper scanning of a train. In other words, this alarm indicates the existence of one or more conditions in which the integrity of the system, and its ability accurately to record train data, may be compromised. These unusual conditions, called Integrity Failures, may require train stoppage, later maintenance, or both. They are covered in the next appendix.

A.7 Low Battery Alarm

The Low Battery alarm indicates a <u>float voltage</u> of at least 11.8 volts, but less than 12.6 volts, on the standby battery.

A.8 Midrange Transducer Miscounts Alarm

The Midrange Transducer Miscounts alarm indicates that the transducer counts for TO1 and TO2 are off by five or six. This calculation is made after each axle crosses both gating transducers.

A.9 No Approach Track Alarm

The No Approach Track alarm indicates that the track circuit (or the advance transducers) failed to signal the presence of a train and that the SmartScanNG² system started from the train passing over the gating transducers.

NOTE: This alarm is suppressed if the Presence Hardware is set to "No" in Equipment Setup Menu.

A.10 Pyrometer Noise-Filtered Rail Alarm

The Pyrometer Noise Filtered Rail alarm indicates that a pyrometer in a bearing scanner might be becoming unreliable. This alarm isn't considered an Integrity Failure and therefore won't result in "Not Working" being part of the post-train announcement.

There is a different Pyrometer Noise Filtered Rail alarm for each rail. That is, there is a Pyrometer Noise Filtered North Rail alarm and a Pyrometer Noise Filtered South Rail alarm (or, depending on track direction, a Pyrometer Noise Filtered East Rail alarm and a Pyrometer Noise Filtered West Rail alarm).

A.11 Pyrometer Noise Filtered Wheel Alarm

The Pyrometer Noise Filtered Wheel alarm indicates that a pyrometer in a wheel scanner might be becoming unreliable. This alarm isn't considered an Integrity Failure and therefore won't result in "Not Working" being part of the post-train announcement.

There is a different Pyrometer Noise Filtered Wheel alarm for each rail. That is, there is a Pyrometer Noise Filtered North Wheel alarm and a Pyrometer Noise Filtered South Wheel alarm (or, depending on track direction, a Pyrometer Noise Filtered East Wheel alarm and a Pyrometer Noise Filtered West Wheel alarm).

A.12 Reverse Direction Detected

Trains that are being scanned correctly will have axles whose on times are less than their off times. For each axle of a passing train (except for the first axle), the system checks for an ontime that is greater than the off-time. If the axle's on time is greater than its off time, the system reverses the direction locked-in by the first gating pulse, reverses the opening and closing gate assignment for TO1 and TO2, and generates a false transducer pulse. The system considers the gate active for the next axle at the time it determines the current axle's opening gate pulse was missed.

The Reverse Direction Detected alarm indicates that the system entered a state where it is scanning for bearing temperatures when the axles are outside the scanning gate. In this state, the transducer that should be opening the scanning gate is considered by the system to be the transducer that is closing the gate. Likewise, the transducer that should be closing the scanning gate is considered the transducer that solution the transducer that solution the transducer that solution the transducer that solution the gate.

A.13 Short Train Alarm

The Short Train alarm indicates that a train had fewer than 50 axles.

A.14 Stuck Dragger Recovered Alarm

The Stuck Dragger Recovered alarm indicates that a stuck dragger was detected during train passage and, at some point later, the dragging-equipment detector returned to its neutral position. After returning to its neutral position, the firmware must scan at least eight consecutive Dragger free axles before flagging this condition again.

A.15 Test Train Alarm

The Test Train alarm indicates that a given train was generated by the SmartScanNG² system. These trains are used for testing purposes and do <u>not</u> represent actual trains passing the site.

A.16 Very Slow Train Alarm

The Very Slow Train alarm indicates that, at some point during train passage, four consecutive axles crossed the gating transducers at a speed of 7 mph (11.3 kph) or less. When this alarm occurs, the system won't announce axle count, exit speed, length of train, and total number of cars (even if these messages are enabled).

This appendix describes the conditions and events that the SmartScanNG² system flags as Integrity Failures. These alarms indicate conditions in which the integrity of the system, and its ability to record train data accurately, may be compromised. These alarms are listed under the System Alarms section of the Train Detail, and Exception Detail reports. **Section 4.0** - **Producing Reports** tells how to produce these reports.

B.1 Dead Battery Alarm

The Dead Battery alarm indicates a float voltage of less than 11.8 volts on the standby battery.

B.2 Dead Resistor Alarm

The bearing scanner's Dead Resistor alarm indicates the presence of two separate conditions. First, the train must contain a Cold Rail alarm on a given rail. Second, the recorded temperature for the bearing scanner's resistor on that rail must fall <u>below</u> the value set by the Cold Rail Temperature option on the Alarm Settings menu. **Section 4.0 - Serial Interface** tells how to view or change the Cold Rail Temperature option.

```
      Alarm Settings

      [A] - Absolute
      180

      [B] - Differential
      150

      [C] - Hot Wheel
      600

      [D] - Cold Rails
      3

      [E] - Cold Rail Temp
      10

      [F] - Cold Res Counter
      3

      [G] - Differential Enabled
      Yes

      [H] - Advanced
      [X] - Exit
```

There is a different Dead Resistor alarm for each rail. That is, there is a Dead North Resistor alarm and a Dead South Resistor alarm (or, depending on track direction, a Dead East Resistor alarm, and a Dead West Resistor alarm).

B.3 Dead Wheel Scanner Resistor Alarm

The wheel scanner's Dead Wheel Scanner Resistor alarm indicates the presence of two separate conditions. First, the train must contain a Cold Wheel Scanner alarm on a given rail. Second, the recorded temperature for the wheel scanner's resistor on that rail must fall <u>below</u> the value set by the Cold Rail Temperature option on the Alarm Settings menu. **Section 4.0 - Serial Interface** tells how to view or change the Cold Rail Temperature option.

 Alarm Settings

 [A] - Absolute
 180

 [B] - Differential
 150

 [C] - Hot Wheel
 600

 [D] - Cold Rails
 3

 [E] - Cold Rail Temp
 10

 [F] - Cold Res Counter
 3

 [G] - Differential Enabled
 Yes

 [H] - Advanced
 [X] - Exit

There is a different Dead Wheel Scanner Resistor alarm for each rail. That is, there is a Dead North Wheel Scanner Resistor alarm and a Dead South Wheel Scanner Resistor alarm (or, depending on track direction, a Dead East Wheel Scanner Resistor alarm and a Dead West Wheel Scanner Resistor alarm).

B.4 Highrange Transducer Miscounts Alarm

The Highrange Transducer Miscounts alarm indicates that the transducer counts for TO1 and TO2 are off by seven or more. This calculation is made after each axle crosses both gating transducers. When this alarm occurs, the system won't announce axle count, exit speed, length of train, or total number of cars (even if these messages are enabled).

The Highrange Transducer Miscounts alarm <u>can be either</u> a System Alarm or an Integrity Failure, depending on the presence of a Very Slow Train alarm. If a highrange transducer miscount occurs on a train that also contains a Very Slow Train alarm, the firmware treats the miscount condition as a System Alarm. This logic assumes that the train's slow rate of travel likely caused the transducer miscount condition. If a highrange transducer miscount occurs on a train traveling faster than 7 mph (11.3 kph), the firmware treats the miscount condition as an Integrity Failure.

B.5 Stuck Dragger During Train Passage Alarm

The Stuck Dragger During Train Passage alarm indicates that the preset maximum number of consecutive axles have had Dragging-Equipment alarms during train passage. The maximum number is determined by the firmware and is currently five.

B.6 Stuck Dragger Pretrain Alarm

The Stuck Dragger Pretrain alarm indicates that the dragging equipment detector was stuck before the scanners started scanning. That is, between the time of first receiving a pulse from the track circuit (or the advance transducers) and the time of first receiving a pulse from either gating transducer, the SmartScanNG² system detected an open circuit from the dragging-equipment detector.

B.7 Stuck High-Load Detector Pretrain Alarm

The Stuck High-Load Detector Pretrain alarm indicates that, before the scanners started scanning, the high-load detector was stuck. That is, between the time of first receiving a pulse from the track circuit (or the advance transducers) and the time of first receiving a pulse from either gating transducer, the SmartScanNG² system detected an open circuit from the high-load detector.

B.8 Stuck Wide-Load Detector Pretrain Alarm

The Stuck Wide-Load Detector Pretrain alarm indicates that, before the scanners started scanning, the wide-load detector was stuck. That is, between the time of first receiving a pulse from the track circuit (or the advance transducers) and the time of first receiving a pulse from either gating transducer, the SmartScanNG² system detected an open circuit from the wide-load detector.

There is a different Stuck Wide-Load Detector Pretrain alarm for each rail. That is, there is a Stuck Wide-Load Detector Pretrain North Side alarm and a Stuck Wide-Load Detector Pretrain South Side alarm (or, depending on track direction, a Stuck Wide-Load Detector Pretrain East Side alarm and a Stuck Wide-Load Detector Pretrain West Side alarm).

B.9 Successive Cold Rails Exceeded Alarm

The Successive Cold Rails Exceeded alarm indicates that at least a preset maximum number of consecutive trains, all having Cold Rail alarms on the same railside, have passed a site. The maximum number (per railside) of consecutive trains having Cold Rail alarms allowed before generating this alarm is set by the Cold Rails option on the Alarm Settings menu. **Section 4.0 - Serial Interface** tells how to view or change the Cold Rails option.

 Alarm Settings

 [A] - Absolute
 180

 [B] - Differential
 150

 [C] - Hot Wheel
 600

 [D] - Cold Rails
 3

 [E] - Cold Rail Temp
 10

 [F] - Cold Res Counter
 3

 [G] - Differential Enabled
 Yes

 [H] - Advanced
 [X] - Exit

Under normal circumstances, Cold Rail conditions represent System Alarms, not Integrity Failures. However, if the number of consecutive trains bearing the same Cold Rail alarm equals or exceeds the cold-rail-alarm limit, this condition becomes an Integrity Failure. If the number of consecutive trains bearing identical Cold Rail alarms equals or exceeds the cold-rail-alarm limit, the System Alarms section of the Train Detail and Exception Detail reports displays the message "Successive Cold Rails Exceeded."

B.10 Successive Cold Resistors Exceeded Alarm

The Successive Cold Resistors Exceeded alarm indicates that at least a preset maximum number of consecutive trains, all having Cold Resistor alarms on the same railside, have passed a site. The maximum number (per railside) of consecutive trains having Cold Resistor alarms allowed before generating an Integrity Failure alarm is set by the Cold Rails option on the Alarm Settings menu. **Section 4.0 - Serial Interface** tells how to view or change the Cold Rails option.

```
      Alarm Settings

      [A] - Absolute
      180

      [B] - Differential
      150

      [C] - Hot Wheel
      600

      [D] - Cold Rails
      3

      [E] - Cold Rail Temp
      10

      [F] - Cold Res Counter
      3

      [G] - Differential Enabled
      Yes

      [H] - Advanced
      [X] - Exit
```

Under normal circumstances, Cold Resistor conditions represent System Alarms, not Integrity Failures. However, if the number of consecutive trains bearing the same Cold Resistor alarm equals or exceeds the cold-rail-alarm limit, this condition becomes an Integrity Failure. If the number of consecutive trains bearing identical Cold Resistor alarms equals or exceeds the cold-rail-alarm limit, the System Alarms section of the Train Detail and Exception Detail reports displays the message "Successive Cold Resistors Exceeded."

B.11 Successive Cold Wheels Exceeded Alarm

The Successive Cold Wheels Exceeded alarm indicates that at least a preset maximum number of consecutive trains, all having Cold Wheel Scanner alarms on the same railside, have passed a site. The user determines the number of consecutive trains used in the comparison through the Cold Rails setup parameter. **Section 4.0 - Serial Interface** tells how to view or change the Cold Rails option.

Under normal circumstances, Cold Wheel conditions represent System Alarms, not Integrity Failures. However, if the number of consecutive trains bearing the same Cold Wheel Scanner alarm <u>equals or exceeds</u> the cold-rail-alarm limit, this condition becomes an Integrity Failure. If the number of consecutive trains bearing identical Cold Wheel Scanner alarms equals or exceeds the cold-rail-alarm limit, the System Alarms section of the Train Detail and Exception Detail reports displays the message "Successive Cold Wheels Exceeded."

B.12 Successive Cold Wheel Resistors Exceeded Alarm

The Successive Cold Wheel Resistors Exceeded alarm occurs when a specified number of consecutive trains, each containing a Cold Wheel Scanner Resistor alarm on the same railside, pass the site. The user determines the number of consecutive trains used in the comparison through the Cold Rails setup parameter. *Section 4.0 - Serial Interface* tells how to view or change the Cold Rails option.

Alarm	Settings
[B] - [C] - [D] - [E] - [F] - [G] - [H] -	Absolute 180 Differential 150 Hot Wheel 600 Cold Rails 3 Cold Rail Temp 10 Cold Res Counter 3 Differential Enabled Yes Advanced Exit

Under normal circumstances, Cold Wheel Resistor conditions represent System Alarms, not Integrity Failures. However, if the number of consecutive trains bearing the same Cold Wheel Scanner Resistor alarm <u>equals or exceeds</u> the cold-rail-alarm limit, this condition becomes an Integrity Failure. If the number of consecutive trains bearing identical Cold Wheel Scanner Resistor alarms equals or exceeds the cold-rail-alarm limit, the System Alarms section of the Train Detail and Exception Detail reports displays the message "Successive Cold Wheel Resistors Exceeded."

B.13 Train Present on Restart Alarm

The Train Present on Restart alarm indicates that a train was present at the site when the system was powering up.

Appendix C System Functions

This appendix lists the system functions provided by the SmartScanNG² system.

To access the system functions:

1 Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

SmartSCAN NG2, MP/KP:1234.5, Track:North Subdivision: None 05/04/2023 10:24:26, 11.7V, 93°F Main Menu - Comm -----[A] - Train Summary [B] - Train Detail [C] - Exception Summary [D] - Exception Detail [E] - System Status Report [F] - Last Train [G] - Train DSRs [H] - AEI Diagnostic [I] - Setup [J] - Event log [K] - System Functions Menu [L] - Replay train [M] - Security Menu [X] - Exit

2 Select System Functions menu.

The System Functions menu appears.

```
System Functions Menu
_____
[A] - Radio Test
[B] - Vocabulary Test
[C] - Radio Inhibit
[D] - Start Manual Train
[E] - 1KHz Test Tone
[F] - Auto-Calibration
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[J] - Update Menu
[K] - Maintenance Menu
[L] - Volume Up (3)
[M] - Volume Down (3)
[N] - Resistor Baseline Data
[0] - Radio Programming Menu
[P] - Scanner Test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual Gate Test
[X] - Exit
```

C.1 Radio Test

Selection of the Radio Test option broadcasts a short message through the speaker and through the radio. Using this option lets you verify that the speaker and radio are working properly.

At single-track sites, the text of the message is "Testing, CP Detector, milepost, (*milepost number*), testing, one, two, three, four, five, four, three, two, one, testing." At double-track sites, the text of the message is "Testing, CP Detector, milepost, (*milepost number*), track (*track designation*), testing, one, two, three, four, five, four, three, two, one, testing."

C.2 Vocabulary Test

Selection of the Vocabulary Test option enunciates all stored speech phrases. This announcement is broadcast through the speaker but <u>not through</u> the radio. Therefore, it isn't affected by the Radio Inhibit option being enabled.

The text of the message is "zero, one, two, three, four, five, six, seven, eight, niner, not-working, *beep*, CP Detector, milepost, main-3, system-working, no-defects, main-1, main-2, rebroadcast, hotwheel, defect, axle, dragging-equipment-near, north, south, rail, east, west, track, car-I-D, no, hotbox, high-wide, near, you-have-a-defect, testing, train too slow, total axles, speed, temperature, length, minus, point, middle, high-load, wide-load, power-off, excess-alarms, repeat, total-cars, detector-out, A, B, C, D, E, F, G, H, I, J, K, L, M, N, O, P, Q, R, S, T, U, V, W, X, Y, Z, first, second, third, fourth, left, right, side, load, scanner resistor test, beginning in, minutes."

C.3 Radio Inhibit

The selection of the Radio Inhibit option prevents radio activation for three minutes. During this time, any announcements generated by the system are broadcast through the speaker but not through the radio. This feature may be overridden by recalling this submenu and then typing \mathbf{N} .

C.4 Start Manual Train

Selection of the Manual Train Mode option opens all the shutters and simulates transducer pulses for about one minute. During this time, a person can check various aspects of the installed components. In this mode, the system runs the ramp function without generating heats. The train is marked as a test train. There won't be any voltage applied to the scanner inputs.

The test is timed, and you cannot stop this test by pressing [Esc].

The data generated for this test train is stored in the Test Train directory, which contains data on the last test train only. The Last Test Train report gets its data from this directory.

C.5 1KHz Test Tone

Selection of the 1KHz Test Tone option generates a continuous tone for about 10 seconds through the speaker and the radio. Using this option lets you verify that the speaker and radio are working properly.

C.6 Auto-Calibration

Selection of the Auto-Calibration option places the system in autocalibration mode.

The SmartScanNG² system self-calibrates its pyrometer interface circuitry. You need only put a preheated calibrated heat source on a scanner and place the system in autocalibration mode. The system then scans all pyrometer inputs until the signal from the calibrated heat source is located. The necessary adjustments to the related interface circuitry are automatically made while the system monitors its own progress by analyzing changes in the heat signals. Once the procedure has been completed, autocalibration mode is disengaged, and the calibration results are displayed on your computer. For more details, see *Appendix F* & G - Calibration of Type II/Type III Scanners.

C.7 Remote System Reset

Selection of the Remote System Reset option forces a system reset through a remote connection. It can also be used locally.

C.8 Delete All Stored Train Data

Selection of the Delete All Stored Train Data option erases all stored train data. This encompasses all data on the trains in the Trains directory, Exceptions directory, and Test Train directory. After deleting all the train data, there isn't any way of regenerating it. The data is gone forever.

C.9 Clear Event Log

Selection of the Clear Event Log option erases all events stored in the Event Log and displayed on the Event Log report. After deleting the log, there isn't any way of regenerating it. The data is gone forever.

C.10 Update Menu

a Select Update Menu from the System Functions menu.

This prompt appears.

```
Update Menu
[A] - Select Update File
[X] - Exit
```

b Choose the Select Update File from the Update menu.

This prompt appears.

```
Select update file:
[A] - GEN_00-69.ng
[B] - GEN_00-70.ng
```

d Select the appropriate file from the menu options.

C.11 View maintenance statistics

From the System Functions Menu select Maintenance Menu.

A prompt like this appears.

Maintenance Menu
[A] - View Maintenance Statistics
[B] - Reset System Health
[C] - Re-evaluate Last 40 Trains.
[D] - Maintenance Email List
[X] - Exit

Select the **View maintenance statistics** option to display diagnostic information for various system parameters.

Example:

Maintenance information gathered over 10 days Positive numbers indicate an increase, negative indicates a decrease.						
Metric (per day)	percent change	Weighted value	Limit	Problem		
Number of Trains	-11	(-11.000000)	0	 No		
Low Miscount	0	(0.00000)	50	No		
High Miscount	0	(0.00000)	50	No		
Average Temperature 0	0	(0.000000)	50	No		
Average Temperature 1	-11	(-11.000000)	50	No		
Average Temperature 2	-44	(-44.000000)	50	No		
Average Temperature 3	-44	(-44.000000)	50	No		
Cold Rail 0	22	(22.000000)	50	No		
Cold Rail 1	22	(22.000000)	50	No		
Cold Rail 2	0	(0.00000)	50	No		
Cold Rail 3	0	(0.00000)	50	No		
Average miscount	0	(0.00000)	0	No		
Average voltage percentage	0	(0.00000)	0	No		

C.12 Reset System Health

Selection of the Reset System Health option resets system warnings and zeros all health check counts.

C.13 Maintenance email list

Selection of the Maintenance email list allows you to choose or add email addresses to be recipients of maintenance reporting.

C.14 Volume up/Volume down

Selection of the Volume up/Volume down options allows for adjustment of the speaker volume.

```
[O] - Volume up (3)
[P] - Volume down (3)
[Q] - Web security settings
[X] - Exit
```

There are 10 selectable volume levels (0-9). Level-0 is minimum volume and Level-9 is the maximum volume. The current volume setting is indicated in parenthesis.

Appendix D Replacement of Type II Scanners

There are <u>Type II</u> bearing scanners and <u>Type II</u> wheel scanners. Both contain two major parts. The top part is the cover-and-module assembly. The module and its protective cover are tightly integrated and rarely should be taken apart. Except for the addition of a plastic attenuation plug on the wheel scanner cover, both types of cover-and-module assemblies are identical and can be used interchangeably. The bottom part is the mount. Bearing scanner mounts and wheel scanner mounts are different in design. They can't be interchanged.

This appendix tells how to replace scanner cover-and-module assemblies. The replacement of scanner mounts isn't covered in this guide.

D.1 Bearing Scanners

The figure below shows the major parts of a Type II bearing scanner.



To replace a <u>Type II</u> bearing scanner cover-and-module assembly:

- 1 Be sure that you have on hand a new scanner cover-and-module assembly.
- 2 Be sure that you have on hand a T-handle 1/4-inch hex-wrench.

- 3 <u>Turn off</u> all power to the SmartScanNG² enclosure.
- **4** Using a T-handle 1/4-inch hex-wrench, loosen both socket-head-cap screws on the cover of the bearing scanner.
- 5 Separate the scanner cover-and-module assembly from its mount.
- 6 Disconnect the scanner cable connector from the scanner box connector.



- 7 Store the removed scanner cover-and-module assembly in a safe place until you return it to STC for repair.
- 8 Attach the scanner cable connector to the scanner box connector (on the new scanner cover-and-module assembly).
- **9** With the hole (on top of the scanner cover) facing north or east, replace the scanner cover-and-module assembly onto its mount.



- **10** Using a T-handle 1/4-inch hex-wrench, tighten the two screws (on the scanner cover) until they are completely tight.
- 11 <u>Turn on power to the SmartScanNG² enclosure.</u>

D.2 Wheel Scanners

The figure below shows the major parts of a <u>Type II</u> wheel scanner.



To replace a <u>Type II</u> wheel scanner cover-and-module assembly:

- 1 Be sure that you have on hand a new scanner cover-and-module assembly.
- 2 Be sure that you have on hand a T-handle 1/4-inch hex-wrench.
- 3 Turn off all power to the SmartScanNG² enclosure.
- 4 Using a T-handle 1/4-inch hex-wrench, loosen the <u>two</u> socket-head-cap screws on the cover of the bearing scanner.
- 5 Separate the scanner cover-and-module assembly from its mount.
- 6 Disconnect the scanner cable connector from the scanner box connector.



- 7 Store the removed scanner cover-and-module assembly in a safe place until you return it to STC for repair.
- 8 Attach the scanner cable connector to the scanner box connector (on the new scanner cover-and-module assembly).
- **9** With the hole (on top of the scanner cover) facing the center of the track, replace the scanner cover-and-module assembly onto its mount.
- **10** Using a T-handle 1/4-inch hex-wrench, tighten the two screws (on the scanner cover) until they are completely tight.
- 11 <u>Turn on power to the SmartScanNG² enclosure.</u>

Appendix E Replacement of Type III Scanners

There are bearing scanners and wheel scanners. Both contain two major parts. The top part is the cover-and-module assembly. The module and its protective cover are tightly integrated and rarely should be taken apart. Except for the change of **filter frames** in the wheel scanner module, both types of cover-and-module assemblies are identical and can be used interchangeably. The bottom part is the mount. Bearing scanner mounts and wheel scanner mounts are different in design. They can't be interchanged.

This appendix tells how to replace scanner cover-and-module assemblies. The replacement of scanner mounts isn't covered in this guide.

E.1 Bearing Scanners

The figure below shows the major parts of a bearing scanner.



To <u>replace</u> a bearing scanner cover-and-module assembly:

- 1 Be sure that you have on hand a new scanner cover-and-module assembly.
- 2 Be sure that you have on hand a T-handle 1/4-inch hex-wrench.
- 3 <u>Turn off</u> all power to the scanners.

This requires <u>turning off</u> the DC power switch on the SmartScanNG² enclosure <u>and</u> <u>unplugging</u> the AC power cord on the bottom of the SmartScanNG² enclosure.

4 Using a T-handle 1/4-inch hex-wrench, loosen the six socket-head-cap screws on the cover of the bearing scanner.

<u>Four</u> screws attach the weather cover to the mounting plate and <u>two</u> screws attach the mounting plate to the mount.



- 5 Separate the bearing scanner cover-and-module assembly from its mount.
- 6 Disconnect the heater wiring plug.
- 7 Disconnect the scanner cable connector from the scanner box connector.



- 8 Store the removed scanner cover-and-module assembly in a safe place until you return it to STC for repair.
- **9** Attach the scanner cable connector to the scanner box connector of the <u>new</u> scanner cover-and-module assembly.
- **10** With the hole on top of the bearing scanner cover facing north or east, set the mounting plate back onto its scanner mount.
- **11** Using the T-handle 1/4-inch hex-wrench, uniformly tighten the <u>two</u> socket-head-cap screws.
- 12 Reconnect the heater wiring plug.
- **13** With the hole on top of the bearing scanner cover facing north or east, set the <u>weather</u> <u>cover</u> back onto its mounting plate.
- **14** Using the T-handle 1/4-inch hex-wrench, uniformly tighten the <u>four</u> socket-head-cap screws.



The top view of the bearing scanner mounting plate and weather cover is shown below.

15 <u>Turn on power to the scanners.</u>

An assembled bearing scanner looks like this.



E.2 Wheel Scanners



The figure below shows the major parts of a wheel scanner.

To replace a wheel scanner cover-and-module assembly:

- 1 Be sure that you have on hand a new scanner cover-and-module assembly.
- 2 Be sure that you have on hand a T-handle 1/4-inch hex-wrench.
- 3 <u>Turn off</u> all power to the scanners.

This requires <u>turning off</u> the DC power switch on the SmartScanNG² enclosure <u>and</u> <u>unplugging</u> the AC power cord on the bottom of the SmartScanNG² enclosure.

4 Using a T-handle 1/4-inch hex wrench, loosen the six socket-head-cap screws on the cover of the wheel scanner.

<u>Four</u> screws attach the weather cover to the mounting plate, and <u>two</u> screws attach the mounting plate to the mount.



- 5 Separate the wheel scanner cover-and-module assembly from its mount.
- 6 Disconnect the heater wiring plug.
- 7 Disconnect the scanner cable connector from the scanner box connector.



- 8 Store the removed scanner cover-and-module assembly in a safe place until you return it to STC for repair.
- **9** Attach the scanner cable connector to the scanner box connector of the <u>new</u> scanner cover-and-module assembly.
- **10** With the hole on top of the wheel scanner cover facing the center of the track, set the mounting plate back onto its scanner mount.
- **11** Using the T-handle 1/4-inch hex-wrench, uniformly tighten the <u>two</u> socket-head-cap screws.
- **12** Reconnect the heater wiring plug.
- **13** With the hole on top of the wheel scanner cover facing the center of the track, set the <u>weather cover</u> back onto its mounting plate.
- **14** Using the T-handle 1/4-inch hex-wrench, uniformly tighten the <u>four</u> socket-head-cap screws.
- **15** <u>Turn on</u> power to the scanners.

Appendix F Calibration of Type II Scanners

The SmartScanNG² system self-calibrates its pyrometer interface circuitry. You need only put a preheated calibrated heat source on a scanner and place the system in autocalibration mode. The system then scans all pyrometer inputs until the signal from the calibrated heat source is located. The necessary adjustments to the related interface circuitry are automatically made while the system monitors its own progress by analyzing changes in the heat signals. Once the procedure has been completed, autocalibration mode is disengaged, and the calibration results are displayed on your computer.

This appendix tells how to use the calibrated heat source to calibrate the scanners.

F.1 Bearing Scanners

STC recommends that you use the calibrated heat source (2100-810NG) only when the outside (ambient) temperature is above 0°F (-18°C) and below 90°F (32°C). If you must use it at other times, do so only when the needle is centered on the front of the temperature meter. If the needle isn't stabilized within \pm 2-degrees of the setpoint, the heat source isn't operating properly.

To calibrate a Type II/Type III bearing scanner:

- 1 Be sure that you have on hand an STC calibrated heat source (2100-810NG) and a laptop computer.
- 2 On the control panel of the calibrated heat source, toggle the **Gating** switch off.
- 3 Plug the proper end of the supplied 50-foot (15.2-meter) power cord into the **six**-contact circular connector on the front of the calibrated heat source.
- 4 Plug the other end of the power cord into a grounded three-wire 110-120 VAC outlet in the wayside enclosure.

The function connector that is not being used has live AC present.

- 5 Cover the function connector that is not being used with the supplied dust cover.
- 6 On the control panel, turn the temperature knob to **180**.
- 7 Put the heat source in a shady area, out of direct sunlight.
- 8 Wait about 8 minutes for the heat source to reach operating temperature and stabilize.

The heat source has reached operating temperature and stabilized when the temperature meter needle remains centered.

Once the temperature stabilizes, calibration may begin. Once stabilized, the temperature will change less than plus-or-minus one degree Fahrenheit.

- **9** With the power cord to the front of the scanner, place the calibrated heat source on the scanner.
- **10** Be sure that a computer is plugged into COM1 (on the side of the Controller module), that it is turned on, that it has appropriate communications software installed, that the communications software is set to use full-duplex, that the baud rate is set to 19,200, and that a LOG file is opened.
- **11** Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

12 Select the System Functions menu.

The System Functions menu appears. The Auto-Calibration option is used to calibrate the system's pyrometer interface circuitry.

[E] - 1KHz Test Tone [F] - Auto-Calibration [G] - Reboot System [H] - Delete All Stored Train Data [I] - Clear Event Log [K] - Update Menu [L] - Maintenance Menu [M] - Volume up (3) [N] - Volume down (3) [O] - Web security settings [X] - Exit **13** Select Auto-Calibration to initiate the process.

The SmartScanNG² system will now calibrate itself. Follow along on your interface screen until you see "Auto-Calibration Disengaged." This message is an indication that the system is done with the calibration procedure. To abort the process, press **[Esc]** (on your computer) or remove the heat source (from the scanner).

- **14** When "Auto-Calibration Disengaged" is displayed on your computer, remove the calibrated heat source.
- **15** To return to the Main menu, type **X**.
- 16 To exit the serial interface and return the system to normal operation, type X.
- 17 Store the calibrated heat source and its cable in the wayside enclosure.

NOTE:

Upon completion of autocalibration, the system acquires the scanner resistor temperature baseline values. The process begins with a 20-minute wait period in which the resistors are allowed to cool down. The system counts down during this period, sounding a tone each minute. After the 20-minute cooldown period, the system opens and closes the shutters for a period of 8 minutes.

Covering the apertures of all four scanners during the baseline acquisition routine should result in a more accurate baseline measurement because the reference for the scanner is stable when covered. See **Appendix K** for a detailed explanation and instructions.

F.2 Wheel Scanners

STC recommends that you use the calibrated heat source (2100-810NG) only when the outside (ambient) temperature is above 0°F (-18°C) and below 90°F (32°C). If you must use it at other times, do so only when the needle is centered on the front of the temperature meter. If the needle isn't stabilized within \pm 2-degrees of the set point, the heat source isn't operating properly.

To calibrate the Type II wheel scanners:

- 1 Be sure that you have on hand an STC calibrated heat source (2100-810NG) and a laptop computer.
- 2 On the control panel of the calibrated heat source, toggle the Gating switch off.
- 3 Plug the proper end of the supplied 50-foot (15.2-meter) power cord into the **six**-contact circular connector on the front of the calibrated heat source.
- 4 Plug the other end of the power cord into a grounded three-wire 110-120 VAC outlet in the wayside enclosure.

The function connector that is not being used has live AC present.

- **5** Cover the function connector that is not being used with the supplied dust cover.
- 6 On the control panel, turn the temperature knob to 180.
- 7 Put the heat source in a shady area, out of direct sunlight.
- 8 Wait about 8 minutes for the heat source to reach operating temperature and stabilize.

The heat source has reached operating temperature and stabilized when the temperature meter needle remains centered.

Once the temperature stabilizes, calibration may begin. Once stabilized, the temperature will change less than plus-or-minus one degree Fahrenheit.

9 Remove the attenuation plug from the wheel scanner.



10 With the power cord to the front of the scanner, place the calibrated heat source on the scanner.

- **11** Be sure that a computer is plugged into COM1 (on the side of the Controller module), that it is turned on, that it has appropriate communications software installed, that the communications software is set to use full-duplex, that the baud rate is set to 19,200, and that a LOG file is opened.
- **12** Using the serial interface, display the Main menu.

Section 4.0 - Serial Interface tells how to display the Main menu. The Main menu looks like this.

13 Select the System Functions menu.

The System Functions menu appears. The Auto-Calibration option is used to calibrate the system's pyrometer interface circuitry.

```
[E] - 1KHz Test Tone
[F] - Auto-Calibration
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[K] - Update Menu
[L] - Maintenance Menu
[M] - Volume up (3)
[N] - Volume down (3)
[O] - Web security settings
[X] - Exit
```

14 Select Auto-Calibration to initiate the process.

The SmartScanNG² system will now calibrate itself. Follow along on your interface screen until you see "Auto-Calibration Disengaged." This message is an indication that the system is done with the calibration procedure. To abort the process, press **[Esc]** (on your computer) or remove the heat source (from the scanner).

- **15** When "Auto-Calibration Disengaged" is displayed on your computer, remove the calibrated heat source.
- 16 To return to the Main menu, type X.
- 17 To exit the serial interface and return the system to normal operation, type X.

18 Replace the attenuation plug.

The attenuation plug has a direction arrow molded into the top of the plug. This arrow should be pointing toward the rail.

19 Store the calibrated heat source and its cable in the wayside enclosure.

NOTE:

Upon completion of autocalibration, the system acquires the scanner resistor temperature baseline values. The process begins with a 20-minute wait period in which the resistors are allowed to cool down. The system counts down during this period, sounding a tone each minute. After the 20-minute cooldown period, the system opens and closes the shutters for a period of 8 minutes.

Covering the apertures of all four scanners during the baseline acquisition routine should result in a more accurate baseline measurement because the reference for the scanner is stable when covered. See **Appendix K** for a detailed explanation and instructions.

Appendix G Calibration of Type III Scanners

The SmartScanNG² system self-calibrates its pyrometer interface circuitry. You need only put a preheated calibrated heat source on a scanner and place the system in autocalibration mode. The system then scans all pyrometer inputs until the signal from the calibrated heat source is located. The necessary adjustments to the related interface circuitry are automatically made while the system monitors its own progress by analyzing changes in the heat signals. Once the procedure has been completed, autocalibration mode is disengaged, and the calibration results are displayed on your computer.

This appendix tells how to use the calibrated heat source to calibrate the scanners.

G.1 Bearing Scanners

STC recommends that you use the calibrated heat source (2100-810NG) only when the outside (ambient) temperature is above -18°C (0°F) and below 32°C (90°F). If you must use it at other times, do so only when the needle is centered on the front of the temperature meter. If the needle isn't stabilized within \pm 2-degrees of the setpoint, the heat source isn't operating properly.

To calibrate a bearing scanner:

- 1 Be sure that you have on hand an STC calibrated heat source (2100-810NG) and a laptop computer.
- 2 On the control panel of the calibrated heat source, toggle the **Gating** switch <u>off</u>.
- **3** Plug the proper end of the supplied 50-foot (15-meter) power cord into the **six**-contact circular connector on the front of the calibrated heat source.

Sixty Hz is critical for proper operation. For a site that doesn't have a 120-volt 60 Hz power source, the heat source should be powered from a true sine wave inverter capable of 250 watts with an output of at least 110 volts at 60 Hz. The inverter should operate from an input voltage of 10.5 VDC to 15 VDC. A 120-volt USA socket should be provided to match the heat source power cord. The inverter should be grounded according to the manufacturer's recommendations.

WARNING

Once plugged in, both function connectors will have live AC present.

- **4** Using the supplied dust cap, cover the function connector that isn't being used.
- 5 Plug the other end of the power cord into the 120-volt USA socket.
- 6 On the control panel of the calibrated heat source, turn the temperature knob to 180°.

- 7 Put the heat source in a shady area, out of direct sunlight and out of the wind.
- 8 Wait about 8 minutes for the heat source to reach operating temperature and stabilize.

The heat source has reached operating temperature and stabilized when the temperature meter needle remains centered.

Once the temperature stabilizes, calibration may begin. Once stabilized, the temperature will change less than plus-or-minus one degree Fahrenheit.

9 With the power cord to the rear of the scanner, place the calibrated heat source on the bearing scanner.



- 10 To prepare your computer:
 - **a** Plug your computer into COM1 using a crossover (null-modem) cable.
 - **b** Turn on your computer.
 - **c** Be sure that your computer has installed communications software, that it is set to use full-duplex, and that the baud rate is set to 19,200.
- **11** Using the serial interface, display the Main menu.

The Main menu looks like this.

12 Select **Auto-calibration** to calibrate the system's pyrometer interface circuitry.

The SmartScanNG² system will now calibrate itself. **Follow along on your computer screen until you see "Auto-Calibration Disengaged."** This message is an indication that the system is done with the calibration procedure. To abort the process, press **[Esc]** on your computer <u>or</u> remove the heat source from the bearing scanner.

•
•
•
[E] - 1KHz Test Tone
[F] - Auto-Calibration
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[J] - Update Menu
[K] - Maintenance Menu
[L] - Volume Up (3)
[M] - Volume Down (3)
[N] - Resistor Baseline Data
[O] - Radio Programming Menu
[P] - Scanner Test
[Q] – Calibrate Frauscher Transducers
[R] - Virtual Gate Test
[X] - Exit

On your computer screen, an <u>acceptable calibration</u> looks like this. Your values will be different.

Auto Calibration Selected Scanner Types _____ Rail-1..... Type-II Rail-2..... Type-III Wheel-1..... Type-III Wheel-2.... Type-II Is this correct ? Signal levels in millivolts with closed shutters Rail1 Rail2 Wheel1 Wheel2 Min/Max/Average Min/Max/Average Min/Max/Average Min/Max/Average 0 80 20 0 60 20 0 60 20 20 80 40 Opening the shutters. Scanning for heat source. Press the 'Esc' key to abort. Located 187F heat source at Rail1. Auto-calibration beginning in 0 secs.Auto-Calibration Engaged..... Testing Digital-Pot U-306. Stand by. Digital-pot checks OK. Previous calibrated digital-pot. setting was 38. Adjusting digital-pot. Temp = 225F Pot = 59 Sec = 1 Pot. decremented by 1 step. Temp = 224F Pot = 58 Sec = 1 Pot. decremented by 1 step. Temp = 224F Pot = 58 Sec = 1 Pot. decremented by 1 step. Temp = 221F Pot = 57 Sec = 2 Pot. decremented by 1 step. Temp = 219F Pot = 56 Sec = 3 Pot. decremented by 1 step. Temp = 183F Pot = 35 Sec = 15 Pot. decremented by 1 step. Temp = 182F Pot = 34 Sec = 18 Pot. decremented by 1 step. Temp = 181F Pot = 33 Sec = 29 Pot. decremented by 1 step. Temp = 179F Pot = 33 Sec = 93 Monitoring heat source temperature. Raill digital-pot setting of 33 was stored in EEPROM. East Rail Scanner Calibration complete. The setpoint is 180F. The calibrated temp. is 179F. Closing the shutters. Resistor test pending.Auto-Calibration Disengaged.....

Before the shutters are opened, if you get a signal level <u>greater than</u> 200 millivolts, it usually means that there is noise on the scanner inputs, which most times is caused by an electrical problem with the scanner. If you cannot isolate and fix the cause of this problem, call STC for help.
```
Auto Calibration Selected

Signal levels in millivolts with closed shutters

Raill Rail2 Wheell Wheel2

Min/Max/Average Min/Max/Average Min/Max/Average

210 250 210 0 60 20 0 60 20 20 80 40

.

.
```

Before the shutters are closed, if you don't get a calibrated temperature in the range 178°F to 182°F, it means that the scanner wasn't calibrated. If cleaning the optics doesn't solve your problem, replace the scanner cover-and-module assembly. If this doesn't solve your problem, call STC for help in fixing the problem.

- **13** When "Auto-Calibration Disengaged" is displayed on your computer, remove the calibrated heat source.
- 14 To return to the Main menu, type X.
- 15 To exit the serial interface and return the system to normal operation, type X.
- **16** Store the calibrated heat source and its power cord in the wayside enclosure.

NOTE:

Upon completion of autocalibration, the system acquires the scanner resistor temperature baseline values. The process begins with a 20-minute wait period in which the resistors are allowed to cool down. The system counts down during this period, sounding a tone each minute. After the 20-minute cooldown period, the system opens and closes the shutters for a period of 8 minutes.

Covering the apertures of all four scanners during the baseline acquisition routine should result in a more accurate baseline measurement because the reference for the scanner is stable when covered. See **Appendix K** for a detailed explanation and instructions.

G.2 Wheel Scanners

STC recommends that you use the calibrated heat source (2100-810NG) only when the outside (ambient) temperature is above -18°C (0°F) and below 32°C (90°F). If you must use it at other times, do so only when the needle is centered on the front of the temperature meter. If the needle isn't stabilized within \pm 2-degrees of set point, the heat source isn't operating properly.

To calibrate a wheel scanner:

- 1 Be sure that you have on hand an STC calibrated heat source (2100-810NG) and a laptop computer.
- 2 On the control panel of the calibrated heat source, toggle the **Gating** switch off.
- **3** Plug the proper end of the supplied 50-foot (15-meter) power cord into the **six**-contact circular connector on the front of the calibrated heat source.

Sixty Hz is critical for proper operation. For a site that doesn't have a 120-volt 60 Hz power source, the heat source should be powered from a true sine wave inverter capable of 250 watts with an output of at least 110 volts at 60 Hz. The inverter should operate from an input voltage of 10.5 VDC to 15 VDC. A 120-volt USA socket should be provided to match the heat source power cord. The inverter should be grounded according to the manufacturer's recommendations.

WARNING

Once plugged in, both function connectors will have live AC present.

- 4 Using the supplied dust cap, cover the function connector that isn't being used.
- 5 Plug the other end of the power cord into the 120-volt USA socket.
- 6 On the control panel of the calibrated heat source, turn the temperature knob to 180°.
- 7 Put the heat source in a shady area, out of direct sunlight and out of the wind.
- 8 Wait about 8 minutes for the heat source to reach operating temperature and stabilize.

The heat source has reached operating temperature and stabilized when the temperature meter needle remains centered.

Once the temperature stabilizes, calibration may begin. Once stabilized, the temperature will change <u>less than</u> plus-or-minus one degree Fahrenheit.

9 Replace the red filter frame with the black one during calibration.



You'll need to remove the weather cover before you can replace the filter frame. Four socket head cap screws attach the weather cover to the mounting plate. Before continuing, be sure that the <u>black</u> filter frame is securely in place and that the four socket-head-cap screws on the weather cover are completely tight.

10 With the power cord to the rear of the scanner, place the calibrated heat source on the wheel scanner.



- **11** To prepare your computer:
 - **a** Plug your computer into COM1 using a crossover (null-modem) cable.
 - **b** Turn on your computer.
 - **c** Be sure that your computer has installed communications software, that it is set to use full-duplex, and that the baud rate is set to 19,200.

12 Using the serial interface, display the Main menu.

The Main menu looks like this.

13 Select the **Auto-Calibration option** to calibrate the system's pyrometer interface circuitry.

The SmartScanNG² system will now calibrate itself. **Follow along on your computer screen until you see "Auto-Calibration Disengaged."** This message is an indication that the system is done with the calibration procedure. To abort the process, press **[Esc]** on your computer <u>or</u> remove the heat source from the wheel scanner.

Before the shutters are opened, if you get a signal level <u>greater than</u> 200 millivolts, it usually means that there is noise on the scanner inputs, which most times is caused by an electrical problem with the scanner. If you cannot isolate and fix the cause of this problem, call STC for help.

•
[E] - 1KHz Test Tone
[F] - Auto-Calibration
[G] - Reboot System
[H] - Delete All Stored Train Data
[I] - Clear Event Log
[J] - Update Menu
[K] - Maintenance Menu
[L] - Volume Up (3)
[M] - Volume Down (3)
[N] - Resistor Baseline Data
[O] - Radio Programming Menu
[P] - Scanner Test
[Q] - Calibrate Frauscher Transducers
[R] - Virtual Gate Test
[X] - Exit

Before the shutters are closed, if you don't get a calibrated temperature in the range 178°F to 182°F, it means that the scanner wasn't calibrated. If cleaning the optics doesn't solve your problem, replace the scanner cover-and-module assembly. If this doesn't solve your problem, call STC for help in fixing the problem.

- **14** When "Auto-Calibration Disengaged" is displayed on your computer, remove the calibrated heat source.
- **15** To return to the Main menu, type **X**.
- 16 To exit the serial interface and return the system to normal operation, type X.
- **17** Replace the black filter frame with the red one immediately following the successful completion of the auto-calibration function.



** Before continuing, be sure that the <u>red</u> filter frame is securely in place and that the four socket-head-cap screws on the weather cover are completely tight. **

18 Store the calibrated heat source and its power cord in the wayside enclosure.

NOTE:

Upon completion of autocalibration, the system acquires the scanner resistor temperature baseline values. The process begins with a 20-minute wait period in which the resistors are allowed to cool down. The system counts down during this period, sounding a tone each minute. After the 20-minute cooldown period, the system opens and closes the shutters for a period of 8 minutes.

Covering the apertures of all four scanners during the baseline acquisition routine should result in a more accurate baseline measurement because the reference for the scanner is stable when covered. See **Appendix K** for a detailed explanation and instructions.

G.3 Heat Source: Power Cable Warning



A few years ago the power cord connector was found to be a shock hazard because the connector had pins that might be easy to touch if someone were not paying attention. If the power cord were plugged into AC that would be a startling experience! So the connectors on both the power cord and the heat source were changed. Because of that change, a new power cord was and is shipped with each new heat source.



Old style plug with pins.



New heat source with pins.

As you can see, even though the connectors will fit together, they won't work together. When the connectors are screwed together the two sets of pins touch and cause a reverse polarity situation which damages the heat source.

Appendix H Lens Cleaning of Type III Scanners

This appendix tells how to clean the optics in the scanners.

To clean the optics in the scanners:

- 1 Be sure that you have on hand a T-handle 1/4-inch hex-wrench.
- 2 <u>Turn off</u> all power to the scanners.

This requires <u>turning off</u> the DC power switch on the SmartScanNG² enclosure <u>and</u> <u>unplugging</u> the AC power cord on the bottom of the SmartScanNG² enclosure.

3 Using the T-handle 1/4-inch hex-wrench, loosen the <u>four</u> socket-head-cap screws that attach the weather cover to the mounting plate.



4 Remove the <u>weather cover</u> from its mounting plate.

Be careful not to damage the electrical connection for the cover heaters.



5 Disconnect the heater wiring plug.

On the side of the scanner module, you'll find a metal tab that protrudes about 1/4 inch outside the module.



- 6 Grasp the tab and pull the filter frame out of the scanner module.
- 7 Using the brush supplied with the tool kit, lightly dust any excess material from the filter frame glass.

Be careful not to abrade or scratch the surface of the lens.

- 8 Apply a small amount of Vallen V8L cleaning solution (included in the tool kit) directly to the glass filter to loosen any remaining contamination.
- **9** Gently polish the reflective glass surface of the filter to remove any remaining contamination.

Pay close attention to the area around the perimeter of the lens. It is important that the entire surface of the lens is clean.

- **10** Open the shutter by stroking one of the gating transducers with a piece of ferrous metal.
- 11 If the lens surface appears to have any dust on it, insert the brush from the tool kit through the baffle plates until it contacts the lens surface and apply a twisting motion to dislodge any accumulated dust.
- **12** Remove the brush and visually inspect the lens for cleanliness.
- **13** Reinstall the filter frame assembly properly (The reflective surface will be facing the viewport opening of the scanner). Reconnect the heater wiring plug.
- 14 Re-connect the scanner cover heater.
- **15** If this is a **bearing scanner**:

With the hole on top of the bearing scanner cover facing north or east, set the weather cover back onto its mounting plate. Using the T-handle 1/4-inch hex-wrench, uniformly tighten the <u>four</u> socket-head-cap screws.

16 If this is a wheel scanner:

With the hole on top of the wheel scanner cover facing the center of the track, set the weather cover back onto its mounting plate. Using the T-handle 1/4-inch hex-wrench, uniformly tighten the <u>four</u> socket-head-cap screws.

17 <u>Turn on power to the scanners.</u>

Appendix I Predictive Gate Scanning

This appendix describes the predictive gate scanning of bearings.

I.1 Overview

If a pyrometer is exposed to extreme infrared energy emission, the device itself can be driven into a saturated state. When this happens, it is blinded to subsequent changes in infrared energy emission. This blinded state can last up to 1-1/2 seconds.

Under certain circumstances, a pyrometer may be driven into saturation <u>before</u> the opening of the gate for a given axle. If the open-gate period was the only time during which pyrometer readings were sampled and processed, the system might miss an overheated bearing due to a device that was blinded before the opening of the gate. This can happen when a bearing is so overheated that it gives off infrared energy that can be seen by the pyrometer long before the bearing enters the pyrometer's field of view.

To compensate for this, the SmartScanNG² system includes special logic for processing heat seen by the pyrometers as they scan between the axle gates. The interval between axles has been divided into two parts.

The first part of this interval is the 12 inches (30.5 centimeters) that immediately precede the axle as it approaches the bearing scanners. This interval is treated as a "predictive gate" region in which the actual gate period (the time a bearing is physically in the pyrometer's field of view) is extended by 12 inches (30.5 centimeters). The remainder of the "between gate" interval forms the second part. Heat values read during this second interval are ignored.

The figure below depicts the three distinct scanning intervals (the in-gate period plus the two between-gate intervals).



The table below defines the intervals.

Interval	Description
А	The normal bearing scanning interval of about 24 inches (61 centimeters),
	depending on the transducer spacing.
В	A distance of about 12 inches (30.5 centimeters) before a given wheel.
С	The distance between wheels that doesn't fall within interval-B.

I.2 Scanning Process

Interval-A is the normal bearing scanning interval. Interval-B is an extension of interval-A. The greatest value read in either of these two intervals is recorded as the temperature for the axle. This value is checked for alarm levels in the same manner that scanned bearing temperatures are normally handled.

For interval-A: Heat values read during interval-A are processed normally.

For interval-B: Heat values read during interval-B that do not meet or exceed the Absolute alarm threshold are ignored. Values that meet or exceed the Absolute alarm threshold are handled as follows:

- If the interval-A heat value meets or exceeds the Absolute alarm threshold, it is processed normally, and the interval-B heat reading is ignored.
- If the interval-A heat value does not meet or exceed the Absolute alarm threshold, but interval-B heat value does, a Pyrometer Saturation alarm is flagged, and the interval-B heat value is stored and reported for the alarmed axle.

For interval-C: Heat values read during interval-C are ignored.

The Very Slow Train alarm indicates that, at some point during train passage, four consecutive axles crossed the gating transducers at a speed of 7 mph (11.3 kph) or less. The firmware doesn't check for Pyrometer Saturation alarms if the train has been flagged with a Very Slow Train alarm.

I.3 Reporting the Pyrometer Saturation Alarm

If a Pyrometer Saturation alarm is detected and assigned to an axle, a printed message will appear on Detail reports.

The figure below shows part of a Train Detail report with a Pyrometer Saturation alarm. The contents of your report will be different.

Southern Technologies Corporation Next Generation Detector System TRAIN DETAIL _____ . • Rail Wheel
 Car Axle East
 West
 East
 West
 ON
 OFF PW1
 PW2
 Alarms

 1
 1
 58
 30
 98
 102
 35
 0
 16
 17

 2
 58
 30
 98
 102
 35
 82
 13
 13

 3
 219
 30
 98
 102
 35

 4
 58
 30
 98
 102
 35

 5
 58
 30
 98
 102
 35
 85 13 13 839 13 13 East Rail Pyro Saturation Alarm 85 13 13 6 58 30 98 102 35 85 13 13 7 58 30 98 102 35 238 13 13 2 8 58 30 98 102 34 85 13 13 ٠ .

Appendix J 2500-402 Spacer Kit Installation

The 2500-402 Spacer Kit provides hardware necessary to lower the Type III Hotwheel Scanner assembly by either ½" or 1" for those applications that require additional rail clearance.





Appendix K Scanner Resistor Baseline Acquisition

Upon completion of autocalibration, the system will acquire the scanner resistor temperature baseline values. The process begins with a 20-minute wait period in which the resistors are allowed to cool down. The system counts down during this period, sounding a tone each minute. After the 20-minute cooldown period, the system opens and closes the shutters for a period of 8 minutes.

NOTE: For wheel scanners, it is imperative that the red filter frame is replaced immediately after autocalibration has disengaged and before resistor baseline acquisition begins.

The reason for establishing the baseline tables at the end of the Auto-Cal cycle is the assumption that the system is then at its peak operating efficiency. The system is freshly calibrated and the lenses are clean. With the baselines established, the system can then recognize and compensate for slight degradations of the lens caused by moisture or dirt accumulation on the lens surface.

K.1 Bungalow Speaker Announcements

During the resistor-cooling period, the system announces through the speaker the following. These announcements aren't broadcast over the radio.

- A beep sounds once per minute until two minutes before the resistor test.
- At two minutes until the test, "Scanner resistor test beginning in 2 minutes" is voiced.

• At one minute until the test, "Scanner resistor test beginning in 1-minute" is voiced. After the resistor cooling period:

- As the test begins, "Testing" is voiced. During this time, the word PENDING appears in the status column of the Resistor Data section.
- If the test was successful, "System working" is voiced. The word VALID appears in the status column of the Resistor Data section, signifying that the baseline test applies to each passing train.
- If the test wasn't successful, "Scanner resistor test beginning in two-zero minutes" is voiced, meaning that the system will try once more after 20 minutes to acquire an accurate resistor heat profile. During this time, the word PENDING appears in the status column of the Resistor Data section of the System Status Report. If the test fails a second time, the word INVALID appears in the same column. The system applies the interim integrity test to each passing train while either PENDING or INVALID appears.

K.2 Processing Resistor Baseline Results

Here are two rules the system uses:

- If any of the temperatures in the baseline table are less than or equal to 40°F, we consider the baseline to be invalid.
- The next sequential temperature has to increase or be no less than 6°F cooler than the last temperature. That is, if a temperature is 100°F, for example, the next temperature has to be greater than 100, equal to 100, but not less than 94.

If the system gets an invalid baseline, it will automatically try a second time. If it gets interrupted, it will also try a second time. The 300° F temperatures that show up in the baselines occasionally are more a reflection of the duty cycle controller for the shutter resistor. Some controllers cause the shutter resistors to heat up more quickly and sometimes overshoot the desired set point, whereas a controller that is operating at its optimum efficiency will ramp up to a value slightly below 300° F. Temperatures above 300° F do not result in an invalid baseline.

Look at the Resistor Data section of the System Status Report. INVALID indicates that the system has tried twice and could not acquire valid resistor data. If any of the baseline results for a scanner show INVALID, the only way to capture a new baseline is to run the Auto Cal process again. If the word PENDING appears in the status column, the system is waiting for the resistors to cool before acquiring resistor data or for the battery to charge to 13 volts. INVALID indicates that the system has tried twice and could not acquire valid resistor data. In either case, the system will apply the interim integrity test to passing trains, which doesn't require resistor baseline data.

VOLTS	AMB	DAT	TF	T	ME	STAT	TUS	30	40	50	60	70	80	90	100	110	120	130
								280				360			420	440	460	480
RAIL	1																	
15.3	-008	01/	/11/1	2 12	2:53	INV	ALID	300	,300,	300	,300	,300,300,	300	, 300.	,300	,300	,300	, 300
	300.	300.	.300.	300.	300	.300	,300	.300	300	300	,300	,300.	300	300	300	,300	,300	300
RAIL	2 '																	
15.3	-008	01	/11/1	2 17	:53	INV	ALTD	300	.300.	300	. 300	.300	300	. 300	.300	. 300	. 300	. 300
	300.	300	300	300.	300	. 300	.300	. 300	300	300	300	,300	300	300	300	300	300	300
WHEEL																		
15.3	-009	01	/11/1	2 12	.26	VAL	D	155	152	155	152	150	150	149	149	148	147	147
	148	149	150	149	150	151	150	151	151	151	151	,151,	150	151	152	152	152	154
WHEEL	2	***	1230		2.30	1222	1230	12.22		1.21	1222	1222	1230	1222	1232	1235	1235	
	-	01	/11/1	2 12	.26	VAL	TD	160	156	157	162	,157	157	155	155	156	155	156
												158						

Examples: Resistor Baseline Results

VOLTS	AMB	DAT	E	Т	IME	STAT	rus	30	40	50	60	70	80	90	100	110	120	130
	140	160	180	200	220	240	260	280	300	320	340	360	380	400	420	440	460	480
RAIL	1																	
13.4	057	09/	30/	11 1	1:59	INVA	ALID	285,	285,	289,	294	,289,	288	289	288,	287	,287	,288
	287,3	289,	290	,290	,272	270,	277,	294	297,	297	297	298,	300	300	300,	300	,300	,300
RAIL	2																	
13.4	055	09/	30/	11 1	0:50	VAL	D	272	271,	274	280	277,	275	270	264,	262	,264	,271
	277,3																	
WHEEL	. 1																	
13.4	055	09/	30/	11 1	0:50	VAL	D	145,	148,	154,	155	156,	157	156	156,	157	,160	,158
	160,																	
WHEEL								1										
13.4	055	09/	30/	11 1	0:50	VAL	D	128,	132,	137	137	138,	137	141,	138,	138	,141	,140
	141,																	

VOLTS	AMB	DAT	Έ	т	IME	ST	ATU	s	30	40	50	60	70	80	90	100	110	120	130
	140	160	180	200	220	24	0 2	60	280	300	320	340	360	380	400	420	440	460	480
RAIL	1																		
13.5	061	05/	25/	11 1	5:25	VA	LID		242,	251	,258,	263	,264	,265,	267	,268	,268,	270	,271
	272,	275,	277	,278	,280	,28	1,2	83,	284,	284	,284,	285	,287	,287,	288	,287	287,	287	289
RAIL	2																		
13.5	061	05/	25/	11 1	5:25	VA	LID		262,	268	,274,	282	,282	,282,	282	,283	,284,	285	,285
	288,	289,	291	,294	,296	,29	7,2	97,	298,	300	,300,	300	, 300	,300	300	,300	,300,	300	, 300
WHEEL	L 1																		
13.7	063	06/	27/	11 1	4:09	IN	VAL	ID	112,	116	,117,	117	,116	,116,	114	,114	,112,	112	,111
	110,	112,	111	,112	,114	,11	0,1	04,	100,	96	94	85	, 87	, 76	69	, 63	61	63	. 58
WHEEL	L 2																		
13.7	063	06/	27/	11 1	4:09	IN	VAL	ID	135,	2	, 2,	2	, 2	, 2,	148	, 2	2,	2	, 2
														, 2					

Appendix L 2500-536 Red Filter Frame - New Design

The STC hot wheel scanner application utilizes the specialized red filter frame. The "old-style" red filter frames (manufactured prior to 2012) can be identified by their round openings. A design flaw in this version can result in the reporting of overinflated heat values.

The new revision of the red filter frame (manufactured in 2012 and after) has a slotted aperture. This new design has proven to provide much greater accuracy, thus reducing the possibility of errant temperature readings.

Replacement of any "old-style" red filter frames should be considered a high priority. Upgrade as soon as possible to reduce the possibility of generating a false hot wheel alarms which could result in unnecessary train stops and crew inspections.



Installation:

- Recalibrate the wheel scanner (see Appendix G for procedural instructions).
- Replace the old red filter frame with the new red filter frame.
- Return old red filter frames to STC for salvage.



Appendix M Communications Ports

		COM1 COM2 COM3/Velocity COM4 COM5 COM6 RS485 Molex Conn Ethernet		default setting COM1 – To us modem cables This is the sta COM2, COM4 COM3 – Used database. CO COM5 – At sys Module to COI RS485 – Usec ETHERNET –	for the RS se the seria and set the andard loc , & COM6 to commu M3 is conr stems with M5 (DTE) o to commu	485 port i l interface commur al acces - Current nicate with aected to AEI, atta of the Cor nicate wi	is 9,600 e, conne nications s port. ly unuse th the V Port 2 c ch a nu ntroller r th auxili ernet co	ect a local compu s software to use ed. elocity Modem bo on the Velocity Mo	ter (DTE) full-duple pard's insi odem boa om the A om the A uch as wir ed a netv	truction seard. EI (DTE)	et and Interface r.
	Data Ci	rcuit-Terminati	na	functionality.	-	ata Term		Connecting		(Data Te	
	Equipm	ent) Modem		Cable	Equipme			Cable		oment) Co	
Pins on Mode				Inside the Straight-		Pins o Comp		*Inside the			on the nputer
Female DB25	DB9	Name ai Abbreviat	-	Through Connecting Cable	Abbr.	Male DB25	DB9	Null-Modem Connecting Cable	Abbr	Male DB25	DB9
1	-	Frame Ground (Chassis)	FG		FG	1	-		FG	1	-
2	3	Transmitted Data (TD)	TxD	↓	TxD	2	3	\langle	TxD	2	3
3	2	Received Data (RD)	RxD		RxD	3	2	\leftarrow	RxD	3	2
4	7	Request to Send	RTS	┥	RTS	4	7	\sim	RTS	4	7
5	8	Clear to Send	CTS	\rightarrow	CTS	5	8	↓ ∕	CTS	5	8
6	6	Data Set Ready	DSR	$\stackrel{\bullet}{\frown}$	DSR	6	6		DSR	6	6
7	5	Signal Ground	SG		SG	7	5		SG	7	5
8	1	Data Carrier Detect	DCD or CD	$\mathbf{\uparrow}$	DCD or CD	8	1	Å	DCD or CD	8	1
20	4	Data Terminal Ready	DTR		DTR	20	4		DTR	20	4
22	9	Ring Indicator	RI		RI	22	9		RI	22	9

Appendix N Calibration of the PD8-Plus Presence Detector

- 1. Obtain track & time authority.
- 2. From the center of the gating transducers, measure the distance you want the track circuit to pick up the presence of a train.
- 3. The recommended distance is at least 50' (15.24 m) and no more than 150' (45.7 m).
- **4.** At the point just measured, place a 0.06Ω shunt across both rails. The track must be shunted before the calibration switch is pressed.
- 5. Press and HOLD the Calibration Switch until the relay drive LED starts blinking. Release the switch, and the LED will stop blinking. The ZEPIC III will automatically begin the calibration process. NOTE: The track shunt MUST remain in place during the calibration process.



6. The relay drive will pick up (LED on) when the unit has successfully calibrated. This process can take up to 45 seconds to complete.

Verification

- 1. After calibration, lift the shunt, and the relay drive should drop (LED off). Replace the shunt, and the relay drive will pick up (LED on).
- 2. Move the shunt approximately 10' farther out from the calibration point. The relay drive should not pick up (LED stays off). If this test fails, perform Short Track Calibration (detailed below).
- 3. The PD8-Plus is now operating properly and will activate at an equal distance on either side of the track feed point.

4. After trackside calibration procedures have been successfully completed, place a temporary shunt across the track wires inside the bungalow and verify that the signal system goes to stop. Once verified, remove the temporary shunt.

IMPORTANT: To ensure an accurate activation point, always place the shunt BEFORE pressing the Calibration Switch.

If the PD8-Plus cannot achieve calibration, it will blink the relay drive LED three (3) times in rapid succession, indicating a calibration error. The unit will continuously repeat the calibration procedure (there is no need to press the Calibration Switch), allowing you to troubleshoot the track circuit, wiring, and battery. Once the issue has been corrected, repeat the calibration procedure.

Both the ZEPIC III and Zepic PD8-Plus have a two-wire track circuit and will activate an equal distance on both sides of the track feed point.

PD8-Plus Short-Track Circuit Calibration

- 1. The system may fail the 10 ft calibration verification step noted above if the installation is using 26KHz and the desired CAL point is ~30ft from the feed points (Short track circuit), and the bungalow is near the track (short track wires).
- 2. If this is the case, reconfigure the PD8-Plus to a lower frequency that is compatible with other equipment that may be on the track. In general, changing from 26KHz to 20KHz or 17.5KHz should solve the short-track circuit calibration issue.
- **3.** Once the module has been reconfigured for the new operating frequency, repeat the normal calibration procedure detailed above.

PD8-Plus Troubleshooting and Application Notes

- 1. If the unit will not calibrate, watch the relay drive LED for approx 45 seconds. If it blinks, this means the PD8-Plus has turned its receiver gain to the maximum setting and cannot see the track shunt. Look for open circuits between the PD8-Plus and the shunt on the track. I.e., track wires, bond wires, etc.
- 2. The PD8-Plus will look equally in both directions. If one side of the circuit has insulated joints, the PD8-Plus will operate. However, the activation distance will not be the same. In general, track circuit equipment cannot see past insulated joints.
- 3. Audio overlay systems like the PD8-Plus will not work with wideband shunts in their track circuit range.
- 4. If the relay drive is stuck ON, look for short circuits between the PD8-Plus and the desired pick point.
- 5. The greater the distance between the PD8-Plus and track connections, the greater the effects ballast will have on the PD8-Plus performance.
- 6. Presence output is a dry contact configuration Form –C dry contact, 225mA max current. (N.O. contact with no train presence)
- 7. In good track ballast conditions, a PD8-Plus circuit can travel up to 500 ft in each direction. Rotating operating frequencies to avoid interference with other equipment is recommended.
- 8. The higher the operating frequency, the shorter the track circuit.

Appendix O Track Circuit Frequency Configuration

The Zepic PD8-Plus module is capable of outputting the following track drive frequencies: 8.2K, 10K, 11.5K, 13.2K, 15K, 17.5K, 20K, 26KHz. These track frequencies can be configured in the field without the need for specialized tools. The figure below details the switch and TAP setting required to configure the unit for each frequency.



Note: Perform the calibration procedure after changing the track frequency.

Example:



NOTE: Older model track circuit boards have a fixed drive frequency and are not configurable.

Appendix P 15A Breaker Upgrade in SmartScanNG Chassis (Pre-2012)

This appendix applies only to those SmartScanNG systems (manufactured prior to 2012) that are to be upgraded with a SmartScanNG² Controller Module.

Current model Type-3 scanners have higher wattage heaters than those previously used. The pre-2012 controller chassis was originally equipped with a 10A breaker which may trip while connected to four Type-3 scanners.

STC recommends returning any pre-2012 chassis for retrofit **if four Type-3 scanners** are to be used. This upgrade kit (2300-500E) includes a 14 AWG power cord, a 15A breaker, and associated wiring.

The pre-2012 controller chassis can be easily identified in the field by the AC power cord. All controller chassis manufactured before 2012 were equipped with a grey 18 AWG 3 conductor power cord with a flexible cordgrip. Post-2012 controller chassis have a black 14/3 power cord and a strain relief with dome nut.



Post-2012 Controller Chassis



14/3 Power Cord Strain Relief with Dome Nut

For scanners manufactured prior to 2013:

Where required due to water accumulation, a 0.25" drain hole can be drilled in the bottom of the scanner base.



R.1 On-Site Network Access Using Wifi (802.11xx)

To use the WiFi interface locally, you need:

- A phone, tablet, or computer with WiFi capability
- Communications browser, which is installed on the device
- 1. Turn on the detector's Wifi broadcasting.
 - a. On the SmartScanNG² Controller Module Display Panel press the <down arrow> key until "Network Menu" is selected and then press <SELECT> key.

```
Main Menu
↑ Radio Test
Scanner Cal. Menu
↓▶Network Menu
```

b. On the "Network Menu", Press the <down arrow> key until, "Wifi: Off", is selected.

```
Network Menu

↑ ► Wifi: Off

Laptop Direct: Off

↓ IP Address
```

c. Press the <SELECT> key until "Wifi: On" is displayed.



Note: when the Wifi is switched from "Off" to "On", there could be a delay of as much as 10 seconds before the LCD reflects the actual "On" status.

- 2. Connect your laptop to the detector's Wifi network. The SmartScanNG²'s Wifi network should appear in your laptop's list of available networks as, "CP MP [milepost] Track: [track designation]". Where [milepost] is the milepost of your detector site and [track designation] the track designation for the site (e.g., Single, North, South, East, etc.). An example of a SmartScanNG² Wifi network name might be "CP MP 9876.5 Track: North". Note that the network name and password are configurable in the detector's text based interface (serial port or Telnet). The default password for the NG2 Wifi interface is: password
- Open a web browser and enter www.wifi.stc in the browser's address line (alternatively, 192.168.1.4 can be used for the address). You should be presented with the NG2's home page or a login prompt.

R.2 On-Site Network Access Using the Ethernet Port

To use the WiFi interface locally, you need:

- A portable computer with an RJ45 network port.
- Communications browser installed on the porbable computer.
- 1. Turn on the detector's "Laptop Direct" mode.
 - a. On the SmartScanNG² Controller Module Display Panel press the <down arrow> key until "Network Menu" is selected and then press <SELECT> key.

```
Main Menu
↑ Radio Test
Scanner Cal. Menu
↓▶Network Menu
```

b. Press the <down arrow> until, "Laptop Direct: Off", is selected.

```
Network Menu
↑ Wifi: Off
▶Laptop Direct: Off
↓ IP Address
```

c. Press the <SELECT> key until "Laptop Direct: On" is displayed.

```
Network Menu
↑ Wifi: Off
▶Laptop Direct: On
↓ IP Address
```

Note: "Laptop Direct" mode uses the NG2's built in DHCP server. To avoid potential IP address conflicts, "Laptop Direct" mode polls every five seconds for the existence of other DHCP servers on the network attached to the Ethernet port. If another DHCP server is discovered, "Laptop Direct" mode will shut down.

- 2. Connect your portable computer to the detector's Ethernet port.
- 3. Open a web browser and enter <u>www.wired.stc</u> in the browser's address line (alternatively, 192.168.3.4 can be used for the address). You should be presented with the NG2's home page or a login prompt.



Ethernet

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